Lecture: Pipelining Extensions

- Topics: control hazards, multi-cycle instructions, pipelining equations

Summary

- For the 5-stage pipeline, bypassing can eliminate delays between the following example pairs of instructions:

```
add/sub          R1, R2, R3
add/sub/lw/sw    R4, R1, R5

lw       R1, 8(R2)
sw       R1, 4(R3)
```

- The following pairs of instructions will have intermediate stalls:

```
lw                R1, 8(R2)
add/sub/lw        R3, R1, R4      or   sw   R3, 8(R1)

fmul      F1, F2, F3
fadd      F5, F1, F4
```

Problem 8

- Consider this 8-stage pipeline (RR and RW take a full cycle)

- For the following pairs of instructions, how many stalls will the 2nd instruction experience (with and without bypassing)?

  - ADD R3 ← R1+R2
    ADD R5 ← R3+R4
  - LD R2 ← [R1]
    ADD R4 ← R2+R3
  - LD R2 ← [R1]
    SD R3 → [R2]
  - LD R2 ← [R1]
    SD R2 → [R3]

Problem 8

- Consider this 8-stage pipeline (RR and RW take a full cycle)

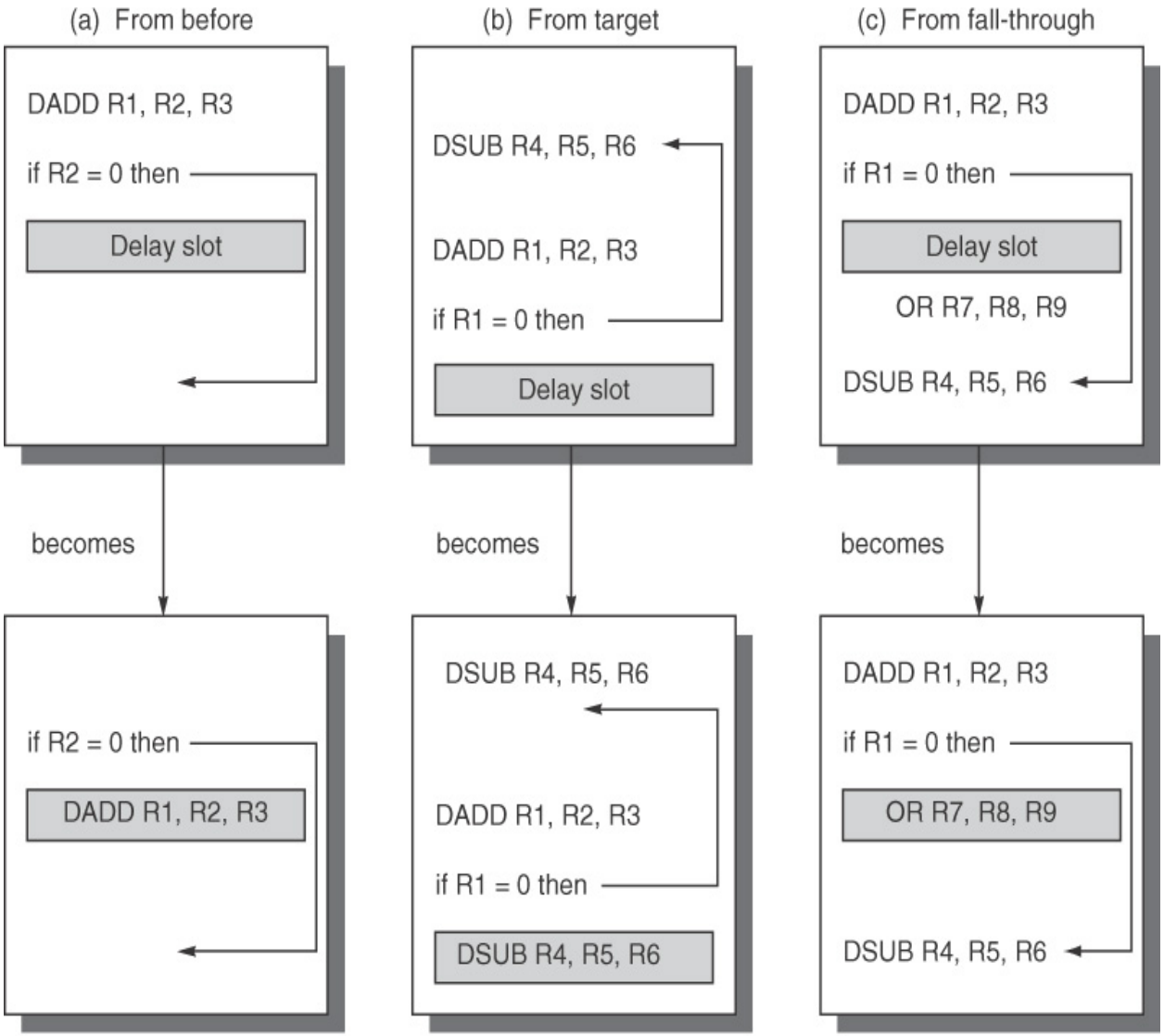
- For the following pairs of instructions, how many stalls will the 2nd instruction experience (with and without bypassing)?

  - ADD R3 ← R1+R2
    ADD R5 ← R3+R4 — without: 5 with: 1
  - LD R2 ← [R1]
    ADD R4 ← R2+R3 — without: 5 with: 3
  - LD R2 ← [R1]
    SD R3 → [R2] — without: 5 with: 3
  - LD R2 ← [R1]
    SD R2 → [R3] — without: 5 with: 1

Control Hazards

- Simple techniques to handle control hazard stalls:
  - for every branch, introduce a stall cycle (note: every 6th instruction is a branch on average!)
  - assume the branch is not taken and start fetching the next instruction – if the branch is taken, need hardware to cancel the effect of the wrong-path instructions
  - predict the next PC and fetch that instr – if the prediction is wrong, cancel the effect of the wrong-path instructions
  - fetch the next instruction (branch delay slot) and execute it anyway – if the instruction turns out to be on the correct path, useful work was done – if the instruction turns out to be on the wrong path, hopefully program state is not lost

Branch Delay Slots



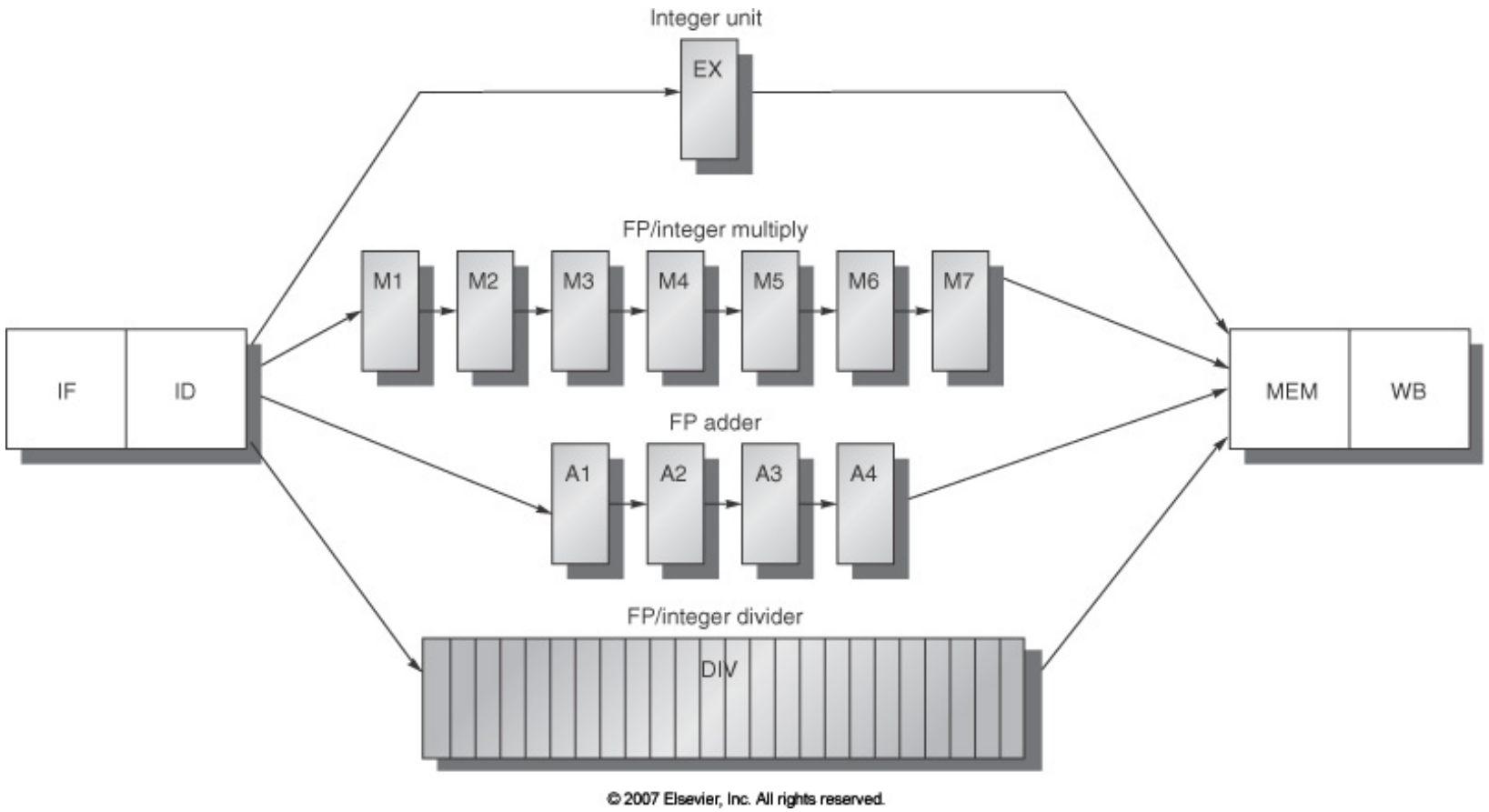
Problem 1

- Consider a branch that is taken 80% of the time. On average, how many stalls are introduced for this branch for each approach below:
  - Stall fetch until branch outcome is known
  - Assume not-taken and squash if the branch is taken
  - Assume a branch delay slot
    - You can't find anything to put in the delay slot
    - An instr before the branch is put in the delay slot
    - An instr from the taken side is put in the delay slot
    - An instr from the not-taken side is put in the slot

Problem 1

- Consider a branch that is taken 80% of the time. On average, how many stalls are introduced for this branch for each approach below:
  - Stall fetch until branch outcome is known – 1
  - Assume not-taken and squash if the branch is taken – 0.8
  - Assume a branch delay slot
    - You can't find anything to put in the delay slot – 1
    - An instr before the branch is put in the delay slot – 0
    - An instr from the taken side is put in the slot – 0.2
    - An instr from the not-taken side is put in the slot – 0.8

Multicycle Instructions



Effects of Multicycle Instructions

- Potentially multiple writes to the register file in a cycle
- Frequent RAW hazards
- WAW hazards (WAR hazards not possible)
- Imprecise exceptions because of o-o-o instr completion

Note: Can also increase the “width” of the processor: handle multiple instructions at the same time: for example, fetch two instructions, read registers for both, execute both, etc.

Precise Exceptions

- On an exception:
  - must save PC of instruction where program must resume
  - all instructions after that PC that might be in the pipeline must be converted to NOPs (other instructions continue to execute and may raise exceptions of their own)
  - temporary program state not in memory (in other words, registers) has to be stored in memory
  - potential problems if a later instruction has already modified memory or registers

- A processor that fulfils all the above conditions is said to provide precise exceptions (useful for debugging and of course, correctness)

Dealing with these Effects

- Multiple writes to the register file: increase the number of ports, stall one of the writers during ID, stall one of the writers during WB (the stall will propagate)
- WAW hazards: detect the hazard during ID and stall the later instruction
- Imprecise exceptions: buffer the results if they complete early or save more pipeline state so that you can return to exactly the same state that you left at

Slowdowns from Stalls

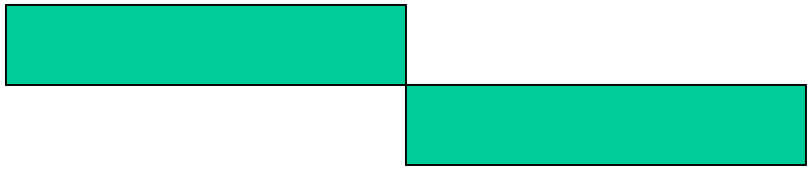
- Perfect pipelining with no hazards → an instruction completes every cycle (total cycles ~ num instructions)
  → speedup = increase in clock speed = num pipeline stages

- With hazards and stalls, some cycles (= stall time) go by during which no instruction completes, and then the stalled instruction completes

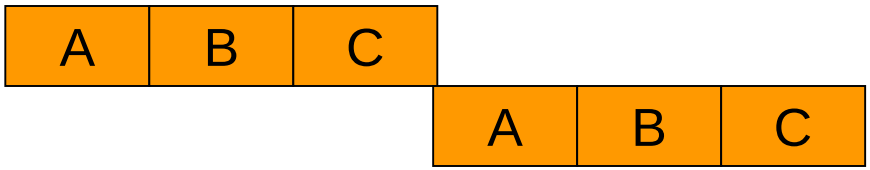
- Total cycles = number of instructions + stall cycles

- Slowdown because of stalls = 1/ (1 + stall cycles per instr)

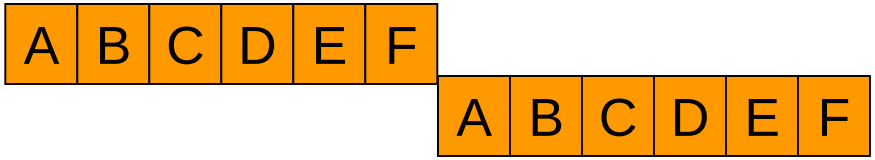
Pipelining Limits



Gap between indep instrs: $T + T_{ovh}$
Gap between dep instrs: $T + T_{ovh}$



Gap between indep instrs:
$T/3 + T_{ovh}$
Gap between dep instrs:
$T + 3T_{ovh}$



Gap between indep instrs:
$T/6 + T_{ovh}$
Gap between dep instrs:
$T + 6T_{ovh}$

Assume that there is a dependence where the final result of the first instruction is required before starting the second instruction

Problem 2

- Assume an unpipelined processor where it takes 5ns to go through the circuits and 0.1ns for the latch overhead. What is the throughput for 20-stage and 40-stage pipelines? Assume that the P.O.P and P.O.C in the unpipelined processor are separated by 2ns. Assume that half the instructions do not introduce a data hazard and half the instructions depend on their preceding instruction.

Problem 2

- Assume an unpipelined processor where it takes 5ns to go through the circuits and 0.1ns for the latch overhead. What is the throughput for 1-stage, 20-stage and 50-stage pipelines? Assume that the P.O.P and P.O.C in the unpipelined processor are separated by 2ns. Assume that half the instructions do not introduce a data hazard and half the instructions depend on their preceding instruction.
  - 1-stage: 1 instr every 5.1ns
  - 20-stage: first instr takes 0.35ns, the second takes 2.8ns
  - 50-stage: first instr takes 0.2ns, the second takes 4ns
  - Throughputs: 0.20 BIPS, 0.63 BIPS, and 0.48 BIPS

ILP

- Instruction-level parallelism: overlap among instructions: pipelining or multiple instruction execution

- What determines the degree of ILP?
  - dependences: property of the program
  - hazards: property of the pipeline

Static vs Dynamic Scheduling

- Arguments against dynamic scheduling:
  - requires complex structures to identify independent instructions (scoreboards, issue queue)
    - high power consumption
    - low clock speed
    - high design and verification effort
  - the compiler can “easily” compute instruction latencies and dependences – complex software is always preferred to complex hardware (?)

Title

- Bullet