
Interior-point methods

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INNER_POINT

ALGORITHMS MODULE

gradient(*f*, *x*, *delta_x=1e-08*)

Returns the gradient of the function at a specific point *x*

A two-point finite difference formula that approximates the derivative

$$\frac{\partial f}{\partial x} \approx \frac{f(x+h) - f(x-h)}{2h} \quad (2.1)$$

Gradient

$$\nabla f = \left[\frac{\partial f}{\partial x_1} \quad \frac{\partial f}{\partial x_2} \quad \cdots \quad \frac{\partial f}{\partial x_n} \right]^T \quad (2.2)$$

Parameters

- **f** (*Callable*[*numpy.ndarray*], *numbers.Real*) – function which depends on *n* variables from *x*
- **x** (*numpy.ndarray*) – *n* - dimensional array
- **delta_x** (*numbers.Real*) – precision of two-point formula above (*delta_x = h*)

Returns

Return type *numpy.ndarray*

jacobian(*f_vector*, *x*, *delta_x=1e-08*)

Returns the Jacobian matrix of a sequence of *m* functions from *f_vector* by *n* variables from *x*.

$$\nabla f = \left[\frac{\partial f}{\partial x_1} \quad \frac{\partial f}{\partial x_2} \quad \cdots \quad \frac{\partial f}{\partial x_n} \right]^T \quad (2.3)$$

Parameters

- **f_vector** (*Sequence*[*Callable*[*numpy.ndarray*], *numbers.Real*]) – a flat sequence, list or tuple or other containing *m* functions
- **x** (*numpy.ndarray*) – an *n*-dimensional array. The specific point at which we will calculate the Jacobian
- **delta_x** (*numbers.Real*) – precision of gradient

Returns the Jacobian matrix according to the above formula. Matrix *n x m*

Return type *numpy.ndarray*

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