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Arduino Mega: PWM Pin and Frequency Timer Control

<u>Arduino</u>



By Myself!!

Want to change the frequency on your your arduino mega?

I have painstakingly Spend many hours today going through every timer one by one and checking them on the Oscilloscope.

I can now accurately say these are all guaranteed within .05% precise...

A lot of this info is out there on the web but not much of it is all in one place and as easy to find as right here VS. Arduino's Forums.

Getting all this data together for my projects has taken me much effort since a lot of it was hard to completely understand when every place said refer to the datasheet.

That's great! The french in the data sheet says yes there are timer's and yes they can be changed, but there was no dumb dumb version in there to say, Do this, Type this here.

There is a lot of info on this for other boards like UNO etc... but they don't work the same on the mega's.

Ok So.....

Arduino mega pins and hardware Timers

```
Pin
         Timer
46
        OC5B
        OC5B
45
44
        OC<sub>5</sub>B
13
         OC0B //Caution: this one directly effects major timing { i.e delay and millis}
12
         OC<sub>1</sub>B
         OC1A
11
10
         OC2A
9
         OC<sub>2</sub>B
8
         OC4C
7
         OC4B
6
         OC4A
5
         OC<sub>3</sub>A
4
                   //Caution: this one directly effects major timing { i.e delay and millis}
         OC_{0}B
3
         OC<sub>3</sub>C
2
         OC<sub>3</sub>B
```

All that is really important above is the numbers. They tell you what timers there on. For example pin 2 is OC3B which is timer 3.

```
another way to look at this is:
```

```
timer 0 — pin 4, 13
timer 1 — pin 11, 12, <del>13</del>
timer 2 — pin 9, 10
timer 3 — pin 2, 3, 5
timer 4 — pin 6, 7, 8
timer 5 — pin 44, 45, 46

*there's alot of misinfo about Pin-13 but after checking 13
it is in fact on Timer 0 "Thx Max K."
```

TIMER 0	(Pin 4, 13)	
Value	Divisor	Frequency
0×01	1	62.5035 KHz
0×02	8	7.8125 KHz

```
0 \times 03
                            64
                                                    976.5 Hz
                                                                       // default
                            256
0\times04
                                                    244.1 Hz
0×05
                            1024
                                                     61.0 Hz
                 TCCR_{0}^{0}B = (TCCR_{0}^{0}B \& 0xF8) | value;
Code:
TIMER 1
               (Pin 11, 12)
Value
                                                 Frequency
                         Divisor
                                                   31.374 KHz
0 \times 01
                            1
                            8
0 \times 02
                                                   3.921 KHz
0 \times 03
                            64
                                                   490.1 Hz
                                                                 // default
0 \times 04
                            256
                                                   122.5 Hz
0×05
                            1024
                                                    30.63 Hz
Code:
                 TCCR_{1B} = (TCCR_{1B} \& 0xF_{8}) | value;
               (Pin 9, 10)
TIMER 2
Value
                         Divisor
                                                 Frequency
0 \times 01
                            1
                                                   31.374 KHz
                            8
                                                   3.921 KHz
0 \times 02
0 \times 03
                            32
                                                  980.3 Hz
                                                                      // default
                            64
                                                  490.1 Hz
0 \times 04
0 \times 05
                            128
                                                  245 hz
0×06
                            256
                                                  122.5 hz
0 \times 07
                            1024
                                                   30.63 hz
Code:
                 TCCR_{2B} = (TCCR_{2B} \& 0xF_{8}) | value;
```

Timers 3, 4, 5 Oddly do not use the divisors the data sheet says: Below are actual measured values!

Value 0×01 0×02 0×03 0×04 0×05 Code:	(Pin 2, 3, 5) Divisor 1 8 64 256 1024 TCCR3B = (TCCR3B)	Frequency 31.374 KHz 3.921 Khz 490.1 Hz 122.5 Hz 30.63 Hz 3 & 0xF8) value;	// default
TIMER 4 Value 0×01 0×02 0×03 0×04 0×05 Code:	(Pin 6, 7, 8) Divisor 1 8 64 256 1024 TCCR4B = (TCCR4E	Frequency 31.374 KHz 3.921 Khz 490.1 Hz 122.5 Hz 30.63 Hz 3 & 0xF8) value;	// default
TIMER 5 Value 0×01 0×02 0×03 0×04 0×05 Code:	(Pin 44, 45, 46) Divisor 1 8 64 256 1024 TCCR5B = (TCCR5B	Frequency 31.374 KHz 3.921 Khz 490.1 Hz 122.5 Hz 30.63 Hz 3 & 0xF8) value;	// default

To set your timer just add it to your sketch: Here's and example for Pins 9 and 10 on Timer 2 @ 490.1Hz;

```
void setup () {
TCCR2B = (TCCR2B & 0xF8) | 0×04;
}
```

I know there is more that can be done with these And there are other ways as well but this is what i know works thus far

Hope this is helpful to someone.

1. Kristabelle says:
January 22, 2012 at 1:17 pm

As Chalrie Sheen says, this article is "WINNING!"

Reply

2. nogdgmrkgt says:

January 23, 2012 at 3:15 am

f8Pt9G lipgizfvlkkh

Reply

3. 🎢 TurboNick says:

February 26, 2012 at 3:25 pm

Thank you for that information, it was very useful.

After testing out the other timers (3,4,5) It looks like the divisor matches the frequency of Timer 2

1 31250 hz 8 3926.25 hz 64 488.28125 hz // default 128 244.140625 hz 1024 30.517578125 hz

Reply

SobiGuy says: February 26, 2012 at 5:52 pm

Thank you TurboNick. I will check that out and add them to the list...

<u>Reply</u>

4. *** Rasmus says:

April 2, 2012 at 9:43 am

Very useful, thank you!

<u>Reply</u>

5. 距 Dante says:

May 24, 2012 at 3:30 am

And how can i set arduino mega 2560 pin 9 and 10 to 20khz?

Reply

 SobiGuy says: May 30, 2012 at 1:19 am

Hey there! Dante,

I have started writing a nice walk through but, I Found a nice article covering the mega 2560. It explains exactly what pins your trying to change hope this helps. http://arduino.cc/forum/index.php?topic=72092.0

Reply

6. **Carlan** says:

September 21, 2012 at 8:12 am

Thank you so much for figuring this out and posting the information! It works great and I am sure you have saved me a few hours of work.

Reply

7. *Max K.* says:

April 1, 2013 at 1:07 pm

Thanks for the information! It saved me a lot of time.

But I think there is a small error:

Pin13 belongs to Timer0 and not to Timer1.

I monitored the PWM-output of Pin13 with an oscilliscope. The frequenz of Pin13 didn't change until I set the register of Timer0. Bevore that, I have set the registers of all other timers. My board verion is R3.

Reply

8. <u>SobiGuy</u> says:

April 1, 2013 at 10:53 pm

Thx Max K.

I spent a Special Day Check each and very one on the Oscilloscope. And turns out you are right. I made the changes above. I also took the time to check timers 3, 4, 5. As What I have before was no check for myself but given to me by turbo nick. Turns out they were all Wrong. As the the Divisor's were all inaccurate. They are all Confirmed myself now!

Again Thx Max for getting me off my lazy bum and finally getting these all Checked.. SobiGuy

Reply

9. Shahd says:

July 22, 2013 at 8:16 am

Hi thankx informative stuff

But one question can we generate the frequency what we want or we cannot do anything other then u said

I want to control 4 transistors they have different switching frequencies so for this i need 4 output from micro controller all with different frequencies... adjestable duty cycle ofcourse..

Frequencies like: 20K, 2K, 100 to 200 HZ

```
Reply
10. Sergio says:
    November 3, 2013 at 5:55 am
    I have a question...I'm a noob: D. If I change timer 4 in order to use pins 7 and 8 as pwm output:
    TCCR4B=(TCCR4B\&0xF8)|0\times02;
    after that, in the loop can I use the analogWrite() function normally? And what about the mills() function?
    <u>Reply</u>
    J.F.
11. Fernando Garcia says:
    March 1, 2014 at 6:58 pm
    Hi!
    You have some errors.
    46 = OCRA;
    45 = OCRB;
    44 = OCRC.
    Best regards.
    <u>Reply</u>
12. Fernando Garcia says:
    March 1, 2014 at 6:59 pm
    Hi!
    You have some errors.
    46 = OCR5A;
    45 = OCR5B;
    44 = OCR5C.
    Best regards.
    Reply
       🔨 ilan says:
    January 5, 2015 at 11:22 am
    Thank you, thank you, Nathan.
    Great post here, huge value for lazy people like me.
    <u>Reply</u>
14. Stefan says:
    June 10, 2015 at 8:23 am
    I need some help. i have 2 libraries that use one timer, How can I change the timer on one of them. This is
    the function that use a timer.
    prescaler = timer calc(speed, (uint16 t)-1, &nticks);
    if (!prescaler)
    return; // fault
```

```
}
    TCCR1A = 0; // Output Compare pins disconnected
    TCCR1B = BV(WGM12); // Turn on CTC mode
    // convert prescaler index to TCCRnB prescaler bits CS10, CS11, CS12
    TCCR1B |= prescaler;
    // Caution: special procedures for setting 16 bit regs
    // is handled by the compiler
    OCR1A = nticks;
    // Enable interrupt
    #ifdef TIMSK1
    // atmega168
    TIMSK1 = BV(OCIE1A);
    #else
    // others
    TIMSK = BV(OCIE1A);
    #endif // TIMSK1
    #endif // AVR ATtiny85
    // Set up digital IO pins
    pinMode(vw_tx_pin, OUTPUT);
    pinMode(vw rx pin, INPUT);
    pinMode(vw ptt pin, OUTPUT);
    digitalWrite(vw_ptt_pin, vw_ptt_inverted);
    #endif // ARDUINO
    thanks in advance
    Reply
                           Name (required)
                           E-Mail (will not be published) (required)
Verify your real existence
Drag the correct plug to the socket
Reset
                                  Powered by sweetCaptcha
```

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