

# Gamut Mapping for Tone Mapping Operations

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Engineering

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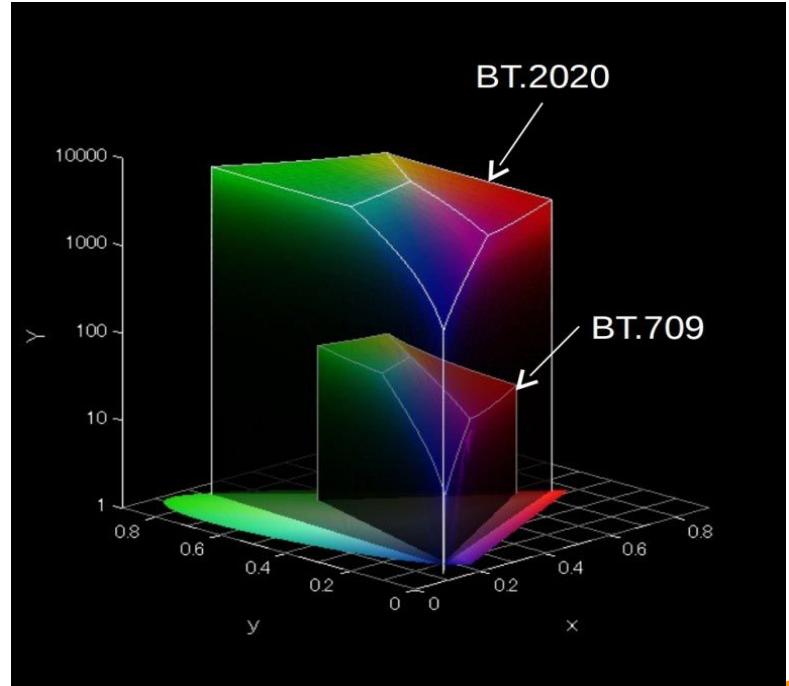
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# 1. Introduction

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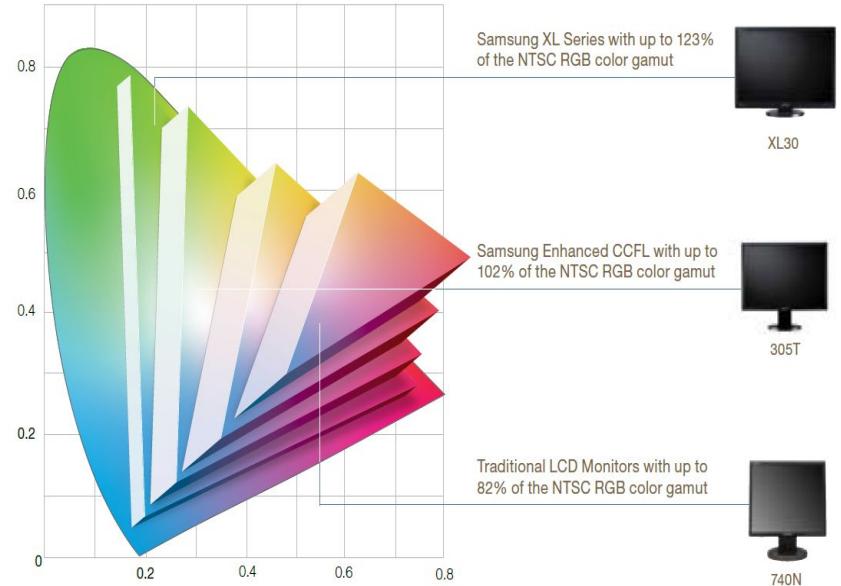
# Introduction

- To map each color from the BT.2020 gamut to BT.709 gamut
- To find the best combination of color space and projection technique that yields the minimum possible color error and improve the QOE



# Introduction

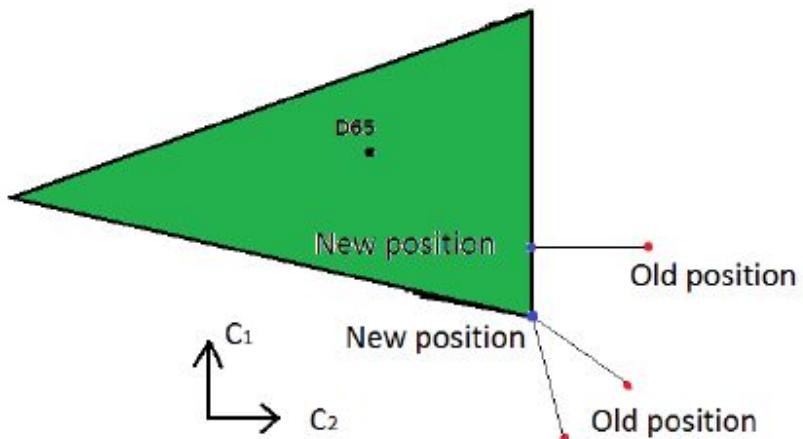
- To ensure that the colors shown by a TV are as close as possible to original colors, we use a Gamut Mapping approach.
- To guarantee global compatibility between the content and display, it is essential to convert the content from wide gamut to smaller gamut.



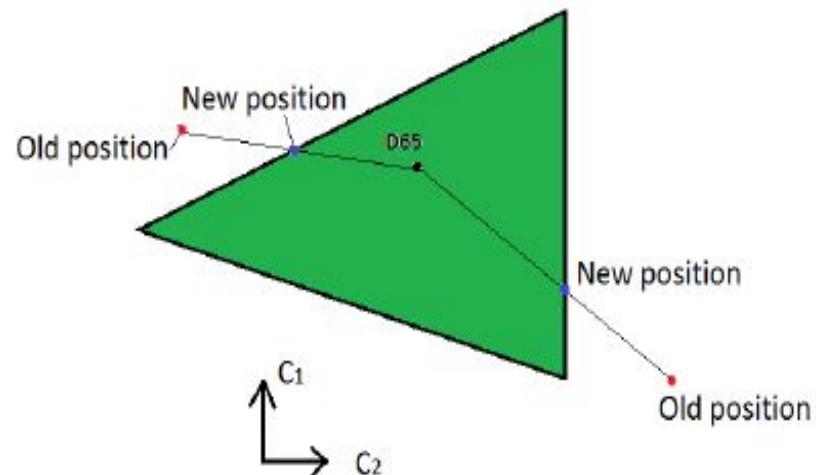
## 2. Existing Techniques

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## Closest Point



## Towards White Point



The existing method finds the combination of color space and projection technique results in the least perceptual difference. Each color being mapped in different color space and projection method.

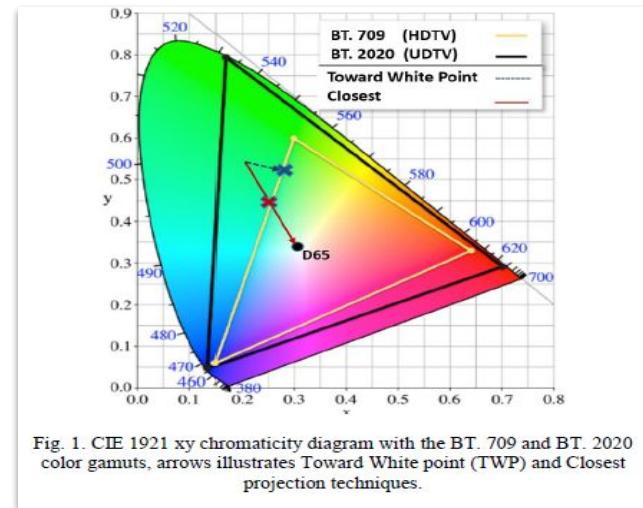
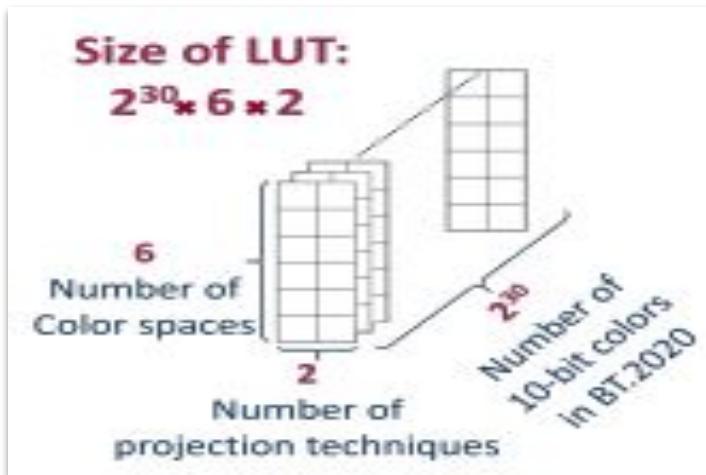


Fig. 1. CIE 1921 xy chromaticity diagram with the BT. 709 and BT. 2020 color gamuts, arrows illustrates Toward White point (TWP) and Closest projection techniques.

Gamut Mapping Method	Mean Error (CIE ΔE2000)	Number of pixels with error < 1
TWP-CIELAB	3.80	8388395
<b>Proposed hybrid approach</b>	2.93	8481814

Algorithm	Color Space	Mean Error	STD Error	Time taken [s]
TWP	$Yxy$	4.283	2.731	209
TWP	$Yu'v'$	4.272	2.719	190
TWP	$Yuv$	4.264	2.706	167
TWP	$L^*u^*v^*$	4.279	2.716	151
TWP	$L^*a^*b^*$	4.135	2.622	4890
TWP	$LCH_{u^*v^*}$	4.277	2.740	34
TWP	$LCH_{a^*b^*}$	4.158	2.647	2838
TWP	$LCH_{xy}$	4.244	2.725	29
TWP	$LCH_{uv}$	4.289	2.745	30
TWP	$IC_aC_b$	4.18	2.671	14808
Closest	$IC_aC_b$	4.15	2.63	76298
Closest	$Yxy$	4.406	2.786	180
Closest	$Yu'v'$	4.407	2.786	168
Closest	$Yuv$	4.753	3.188	146
Closest	$L^*u^*v^*$	4.407	2.791	136
Closest	$L^*a^*b^*$	4.506	3.061	7249

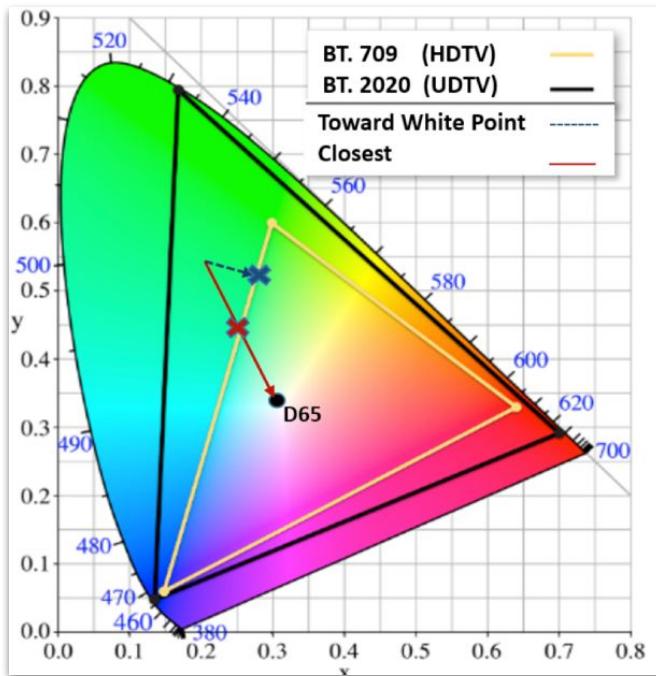
### 3. Proposed Method

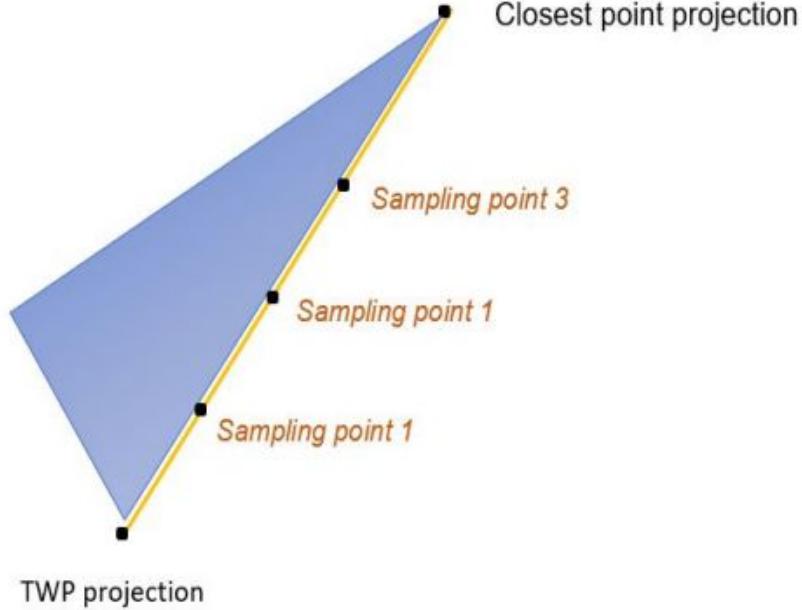
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# PROPOSED METHOD

- Instead of using 6 color spaces, Compute points on one color space and take more samples
- Compute error for both Closest point and Towards White Point and assign the lower error as lower bound and more error one as upper bound
- Calculate error of median on the line joining Closest Point and TWP.
- Subsequently calculate error of three points between median and lower bound and error for points between median and upper bound.
- Make a Lookup Table for lowest error points.

# Mapping a pixel using TWP and CP projection





- Calculate Mid-Point between TWP and CP
- Calculate Mid-Point between TWP and Mid-point
- Calculate Mid-Point between Mid-Point and Closest Point

## 4. Performance Metrics

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# Performance Metrics

- DeltaE is a metric to understand how human eyes perceives color
- There are three standard DeltaE Algorithms.
- DeltaE76 is a simple approach of taking Euclidean distance in the 3D space. But its biggest fault is it doesn't take hue into account while calculating the error
- DeltaE94 will take into account certain weighting factors for each lightness, chroma, and hue value. It also introduced the ability to add a modifier according to the use case: either textile, or graphic arts. But it still falls short when calculating the perceived lightness of two colors.
- DeltaE00 is currently the most complicated yet most accurate CIE color difference algorithm. Although the most accurate we have today, dE00 is not without fault. The most significant discontinuity occurs when compared hues are 180° from each other.
- For our proposed method we need the most accurate color difference algorithm so we have used DeltaE00 as our preferred performance matrix.

## 5. Workflow

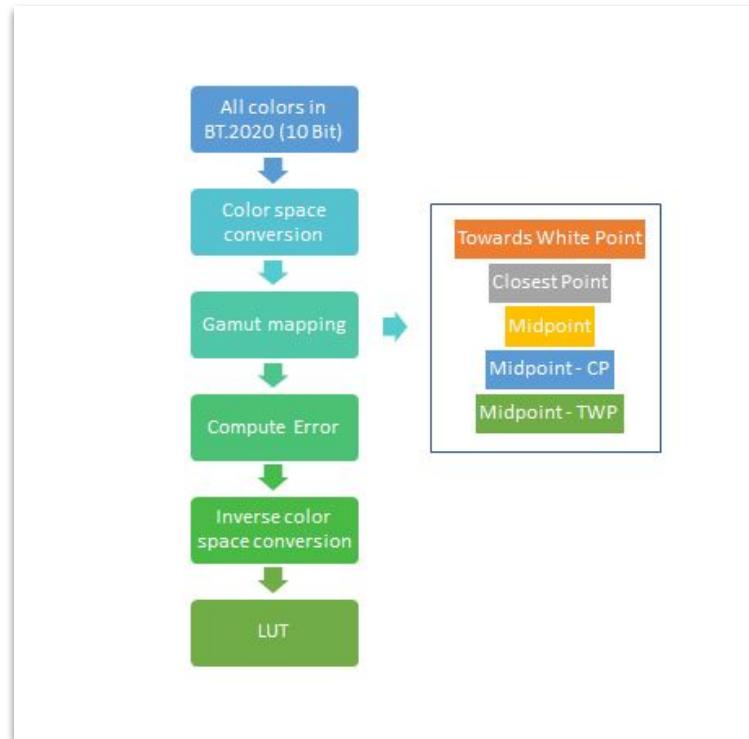
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# WORKFLOW

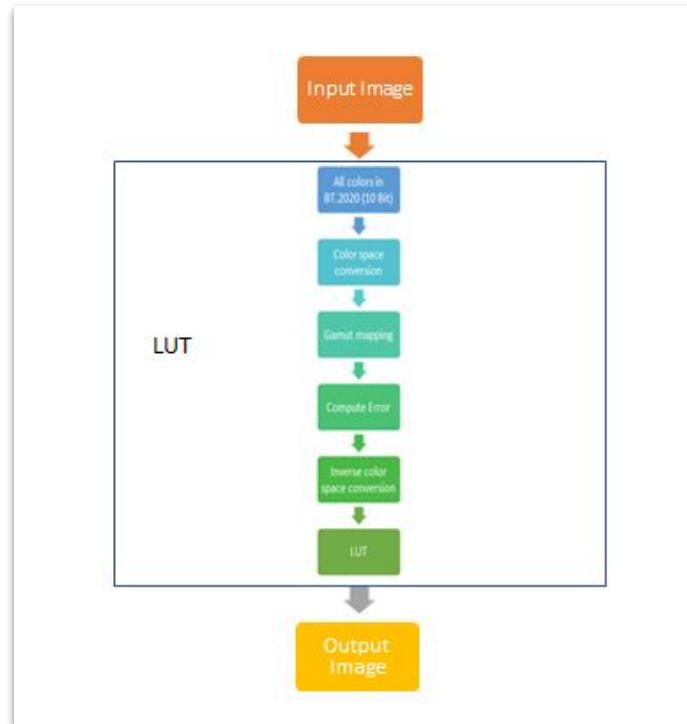
1. Evaluation of the 10 bit color space and mapping of each point in BT.2020 to BT.709 using various projection techniques in **Lab** color space
2. Projection to lower gamut using Towards White Point, Closest Point, Mid-Point, Midpoint-CP and Midpoint-TWP techniques
3. Calculation of CIE  $\Delta E2000$  metric for each projection technique
4. Create LUT for all colors in BT.2020 along with projected points and their CIE  $\Delta E2000$
5. Compare the pixels of Input image with the LUT and get projected point with least CIE  $\Delta E2000$
6. The output of the algorithm is the image in BT.709 gamut with least color error



# WORKFLOW



# WORKFLOW



## 6. Results

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# CLOSEST POINT LUT

MATLAB R2019b - academic use

HOME PLOTS APPS VARIABLE VIEW

New from Selection Open Print Rows Columns Insert Delete Transpose Sort

VARIABLE SELECTION EDIT

C: > Users > DELL > Desktop > multimedia201 >

Variables - finalTable

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
522	521	0	80	466	192	112	5.9986										
523	522	0	80	469	188	106	5.8291										
524	523	0	80	469	188	106	5.8616										
525	524	0	80	469	189	107	5.8655										
526	525	0	80	473	191	109	5.8255										
527	526	0	80	473	191	109	5.8688										
528	527	0	80	473	192	109	5.9165										
529	528	0	80	473	192	110	5.9271										
530	529	0	80	473	192	110	5.9386										
531	530	0	80	476	194	112	5.9023										
532	531	0	80	476	194	112	5.9130										
533	532	0	80	476	195	112	5.9730										
534	533	0	80	476	195	107	6.1929										
535	534	0	80	476	196	108	6.2334										
536	535	0	80	480	197	109	6.1692										
537	536	0	80	480	198	109	6.2371										
538	537	0	80	480	198	110	6.2139										
539	538	0	80	480	199	110	6.2867										
540	539	0	80	483	195	111	5.8749										
541	540	0	80	483	196	112	5.8822										
542	541	0	80	486	197	113	5.8842										

# TOWARDS WHITE POINT LUT

The screenshot shows the MATLAB R2019b interface. The top menu bar includes HOME, PLOTS, APPS, VARIABLE (selected), and VIEW. The toolbar has options like New from Selection, Open, Print, Insert, Delete, Transpose, Sort, and Variable Selection. The current workspace path is C:\Users\DELL\Desktop\multimedia201. The Variables editor displays two tables: 'finalMidLut' and 'finalTable'. The 'finalTable' variable is selected, showing a 265x6 matrix. The matrix has columns labeled 1 through 6. Column 6 is highlighted in gray. The data in column 6 is as follows:

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
1355	330	1	120	295	121	137	4.5649										
1356	331	1	120	295	121	133	4.6183										
1357	332	1	120	295	121	133	4.6530										
1358	333	1	120	298	123	133	4.6214										
1359	334	1	120	299	123	137	4.6747										
1360	335	1	120	299	123	137	4.7115										
1361	336	1	120	299	124	137	4.8004										
1362	337	1	120	301	121	137	4.4536										
1363	338	1	120	301	121	137	4.5152										
1364	339	1	120	305	123	137	4.4444										
1365	340	1	120	305	123	137	4.5035										
1366	341	1	120	305	124	141	4.5943										
1367	342	1	120	305	124	141	4.6639										
1368	343	1	120	305	124	141	4.7064										
1369	344	1	120	308	126	141	4.6385										
1370	345	1	120	308	126	138	4.6615										
1371	346	1	120	308	127	138	4.7407										
1372	347	1	120	308	127	138	4.7769										
1373	348	1	120	308	128	138	4.8618										
1374	349	1	120	312	129	138	4.7765										

# MID-POINT LUT

MATLAB R2019b - academic use

HOME PLOTS APPS VARIABLE VIEW

New from Selection Open Print Rows Columns Insert Delete Sort Transpose

VARIABLE SELECTION EDIT

C: > Users > DELL > Desktop > multimedia201 >

Variables - finalMidLut2

finalMidLut finalTable time2 sum\_lessThan1 sum\_lessThan1\_Twp delEMP in2 finalMidLut2

8388608x4 double

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
1	0	0	0	0													
2	1.4448e-04	0	0	0													
3	0.0011	3	1	1													
4	1.4604e-04	3	1	1													
5	0.0021	3	1	1													
6	0.0063	7	3	1													
7	0.0027	7	3	1													
8	0.0026	7	3	1													
9	0.0082	7	3	1													
10	0.0042	10	4	2													
11	0.0051	10	4	2													
12	0.0141	10	4	2													
13	0.0054	13	5	3													
14	0.0084	13	5	3													
15	0.0211	13	5	3													
16	0.0181	17	7	4													
17	0.0079	17	7	4													
18	0.0189	17	7	4													
19	0.0219	20	8	4													
20	0.0119	20	8	4													
21	0.0266	20	8	4													

# MID-POINT LUT-CP

Screenshot of MATLAB interface showing a variable editor window.

Variable Editor Window:

- HOME PLOTS APPS VARIABLE VIEW**
- Open** (New from Selection) **Rows** **Columns** **Insert** **Delete** **Transpose**
- Sort**

File Path: C:\Users\DELL\Desktop\multimedia201\Variables - finalMidLut2

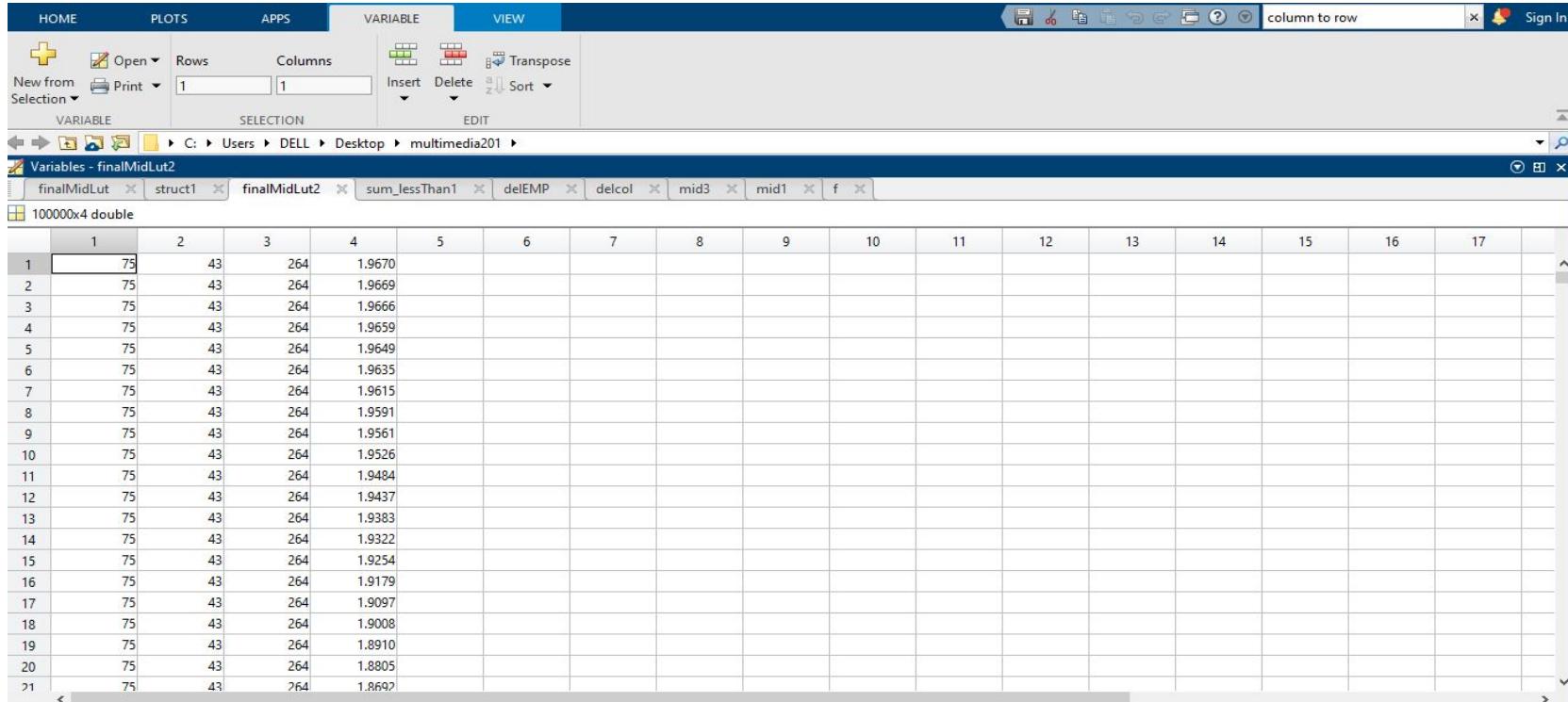
Variables:

- finalMidLut
- struct1
- finalMidLut2
- sum\_lessThan1
- delEMP
- delcol
- mid3
- mid1

8388608x4 double

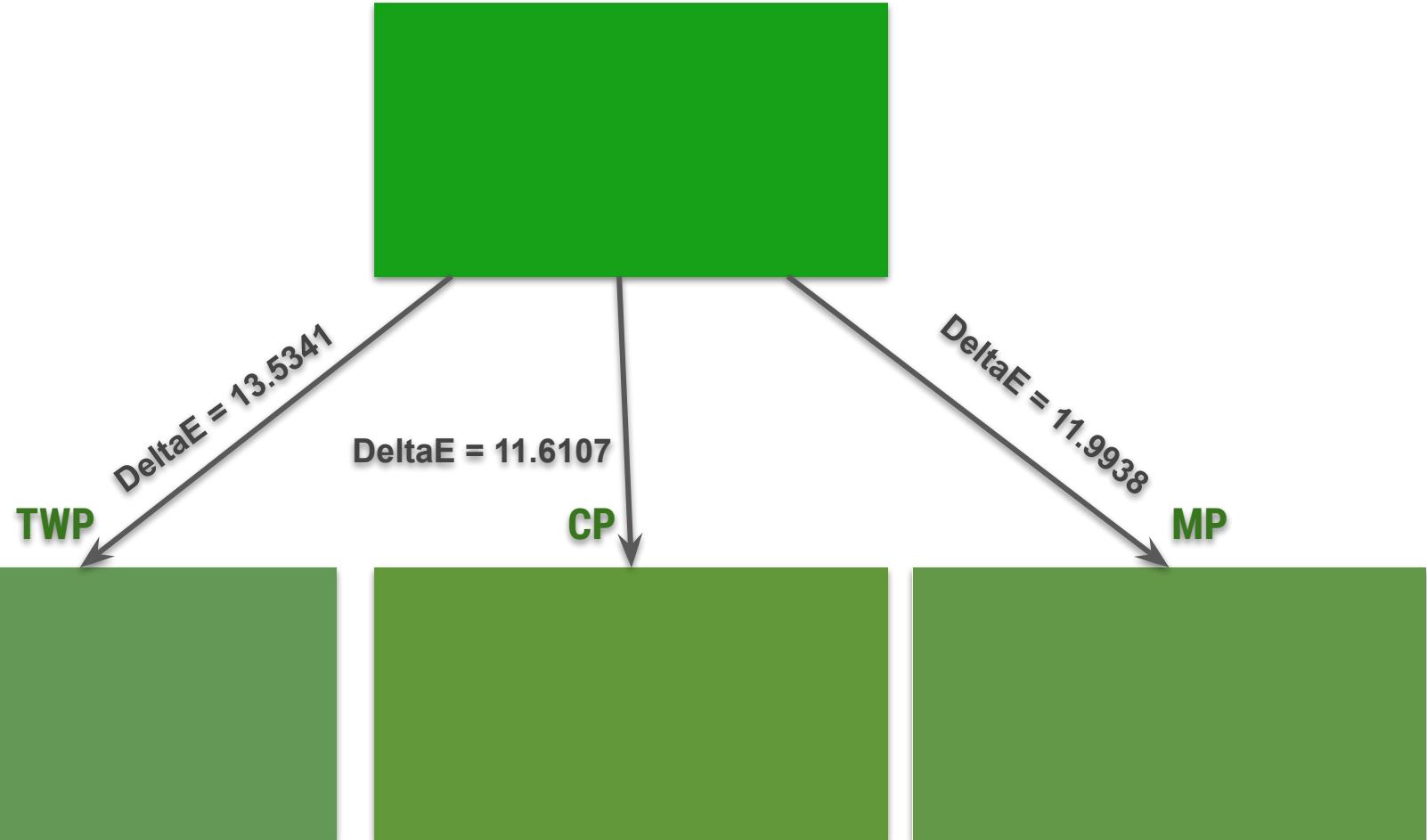
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17
1	75	43	264	0													
2	75	43	264	1.4448e-04													
3	75	43	264	0.0011													
4	75	43	264	1.4604e-04													
5	75	43	264	0.0021													
6	75	43	264	0.0063													
7	75	43	264	0.0027													
8	75	43	264	0.0026													
9	75	43	264	0.0082													
10	75	43	264	0.0042													
11	75	43	264	0.0051													
12	75	43	264	0.0141													
13	75	43	264	0.0054													
14	75	43	264	0.0084													
15	75	43	264	0.0211													
16	75	43	264	0.0181													
17	75	43	264	0.0079													
18	75	43	264	0.0189													
19	75	43	264	0.0219													
20	75	43	264	0.0119													
21	75	43	264	0.0266													

# MID-POINT LUT-TWP



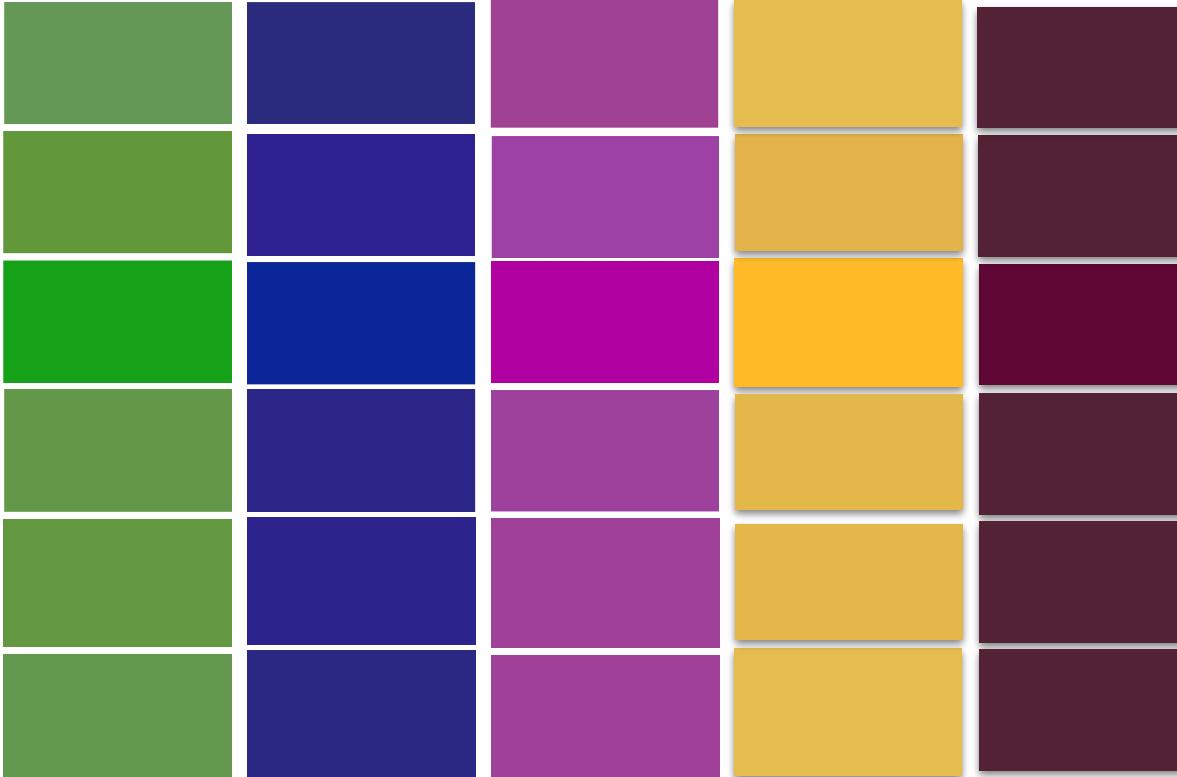
The screenshot shows a MATLAB interface with a toolbar at the top. The 'VARIABLE' tab is selected. Below the toolbar, there are buttons for New from Selection, Open, Print, Insert, Delete, Transpose, Sort, and EDIT. The path bar indicates the current location is C:\Users\DELL\Desktop\multimedia201\. The variable browser shows 'Variables - finalMidLut2' with entries: finalMidLut, struct1, finalMidLut2, sum\_lessThan1, delEMP, delcol, mid3, mid1, f. A preview window displays a 100000x4 double matrix. The first few rows of the matrix are:

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	
1	75	43	264	1.9670														
2	75	43	264	1.9669														
3	75	43	264	1.9666														
4	75	43	264	1.9659														
5	75	43	264	1.9649														
6	75	43	264	1.9635														
7	75	43	264	1.9615														
8	75	43	264	1.9591														
9	75	43	264	1.9561														
10	75	43	264	1.9526														
11	75	43	264	1.9484														
12	75	43	264	1.9437														
13	75	43	264	1.9383														
14	75	43	264	1.9322														
15	75	43	264	1.9254														
16	75	43	264	1.9179														
17	75	43	264	1.9097														
18	75	43	264	1.9008														
19	75	43	264	1.8910														
20	75	43	264	1.8805														
21	75	43	264	1.8692														



**CP - Best Results; Mid point gives better results than TWP**

TWP



MID Pt.

MID Pt. CP

MID Pt.TWP

$\Delta E = 12.5739$

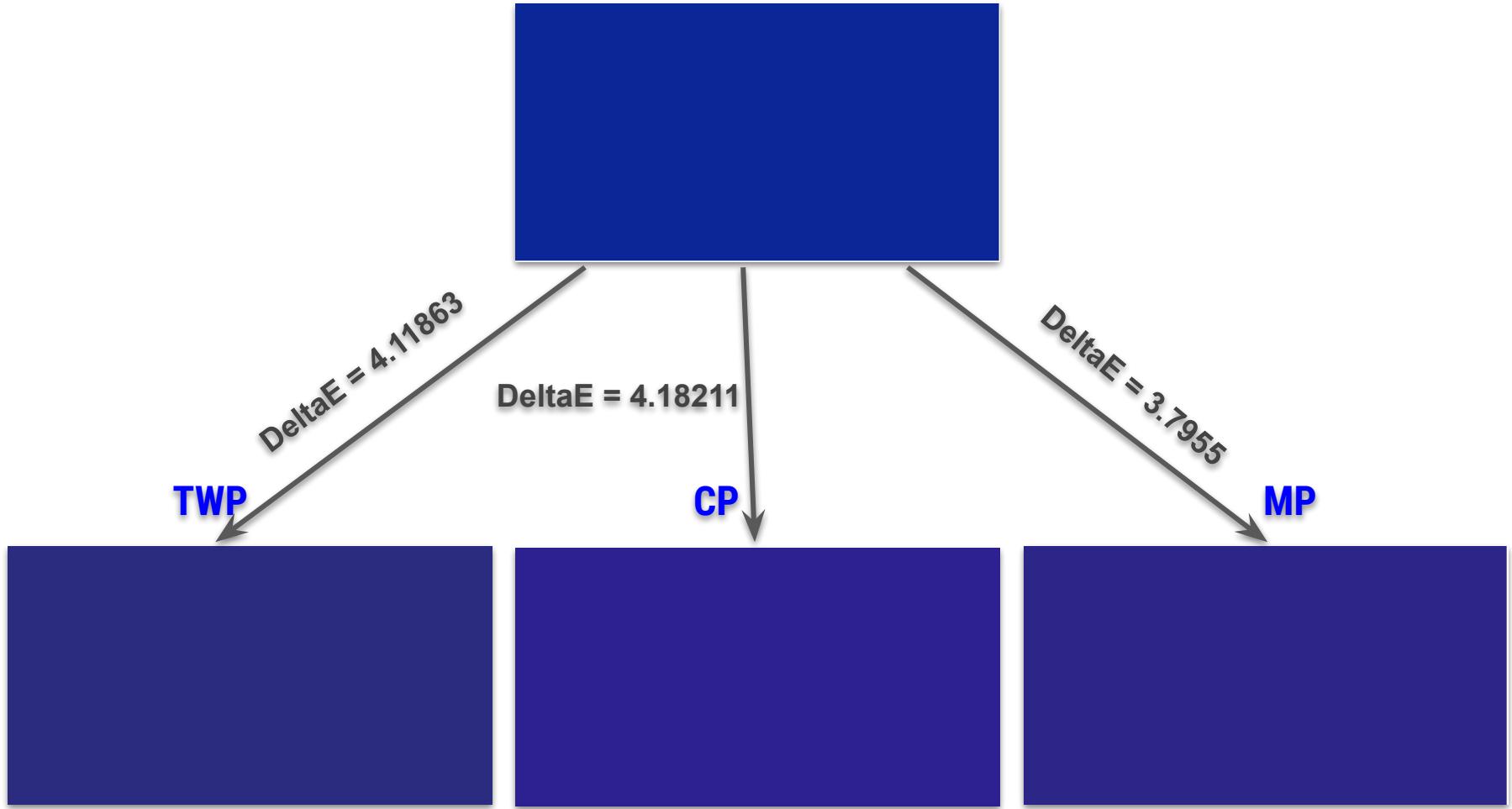
**Midpoint with  
MP and TWP**

$\Delta E = 11.6126$

**Midpoint with  
MP and CP**



Mid-point with MP and CP better than MP near to CP



Mid-Point -Best Results ; TWP better than CP

$\Delta E = 3.9458$

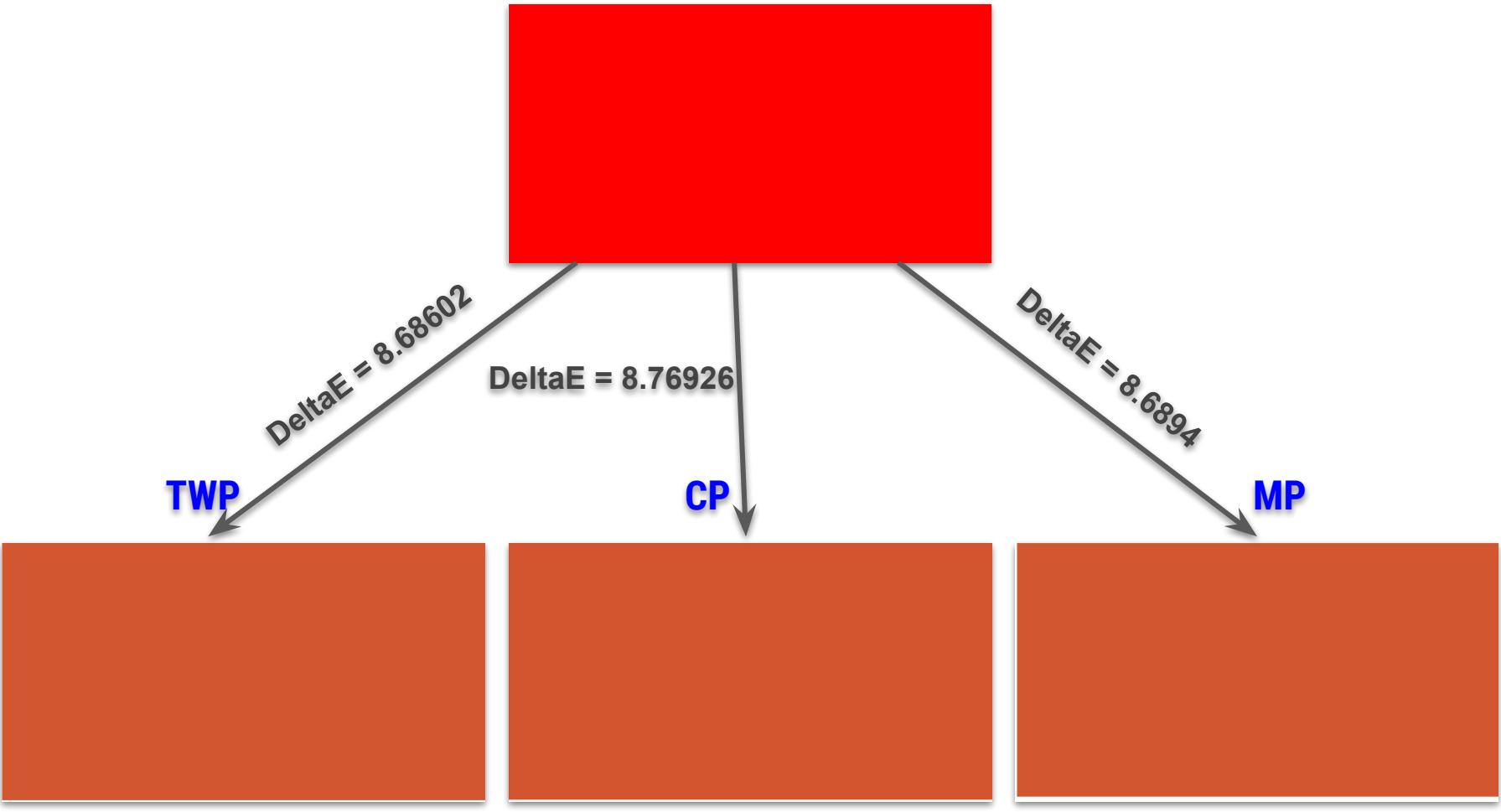
**Midpoint with  
MP and TWP**

$\Delta E = 3.9977$

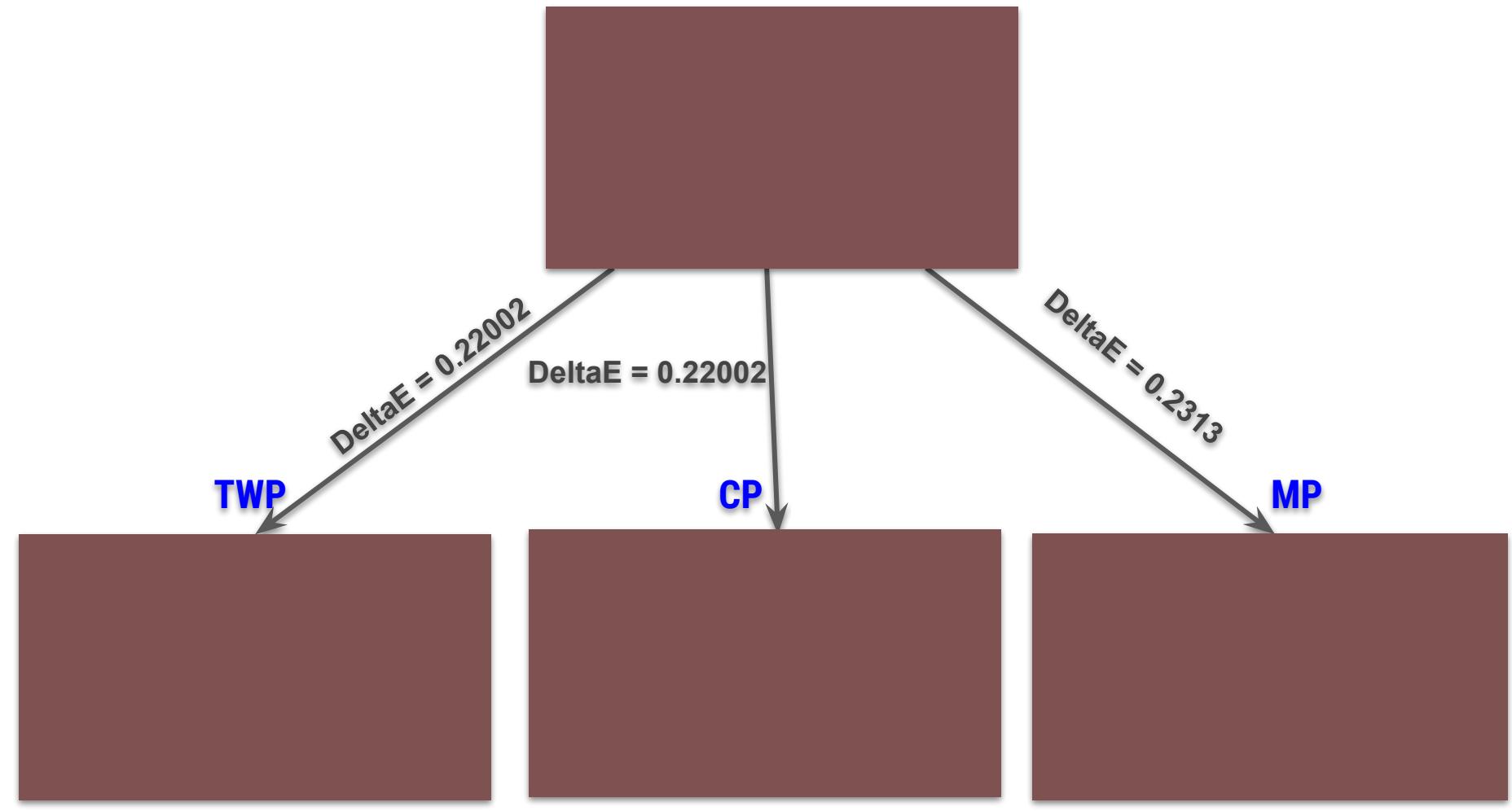
**Midpoint with  
MP and CP**

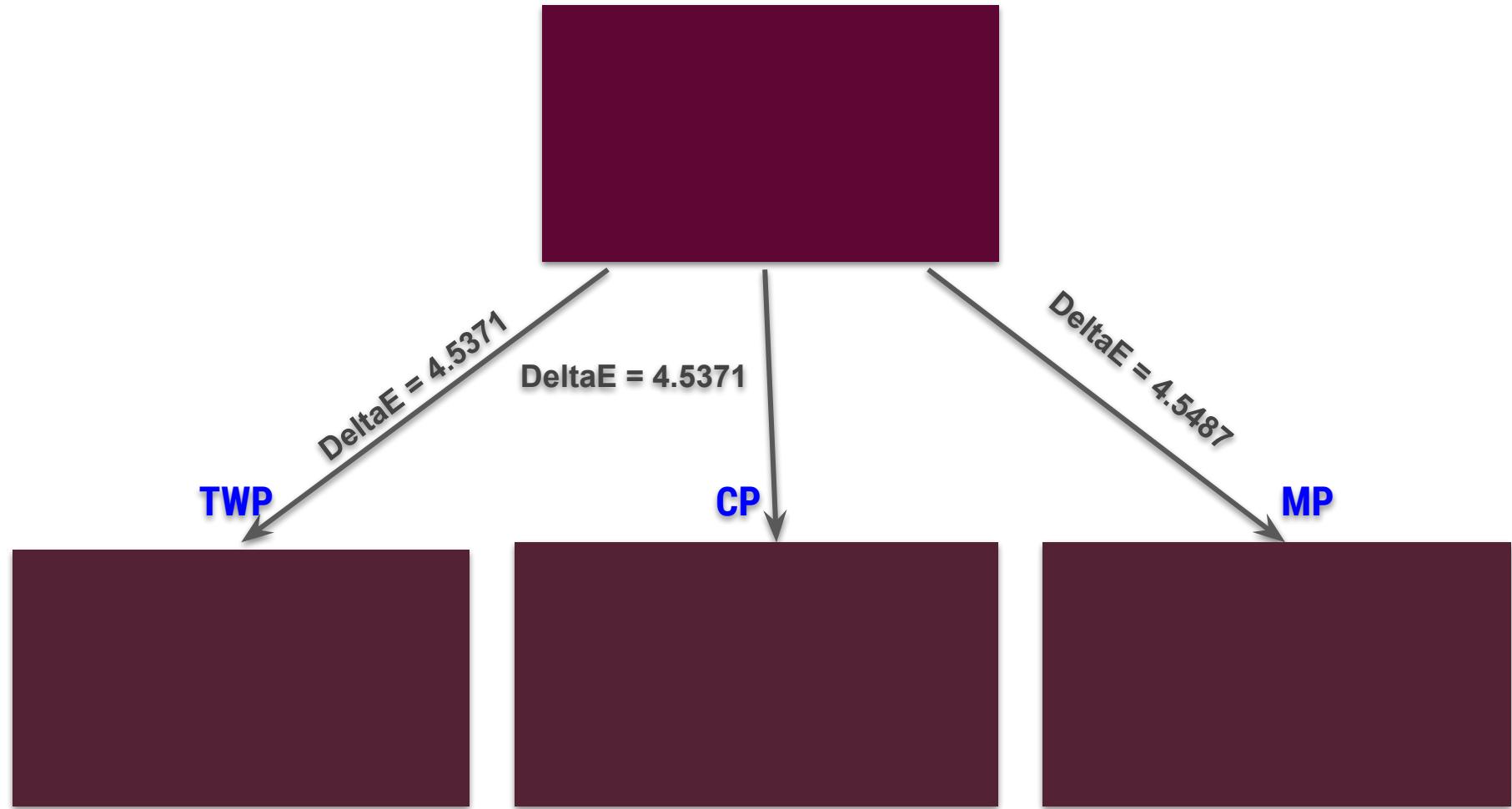


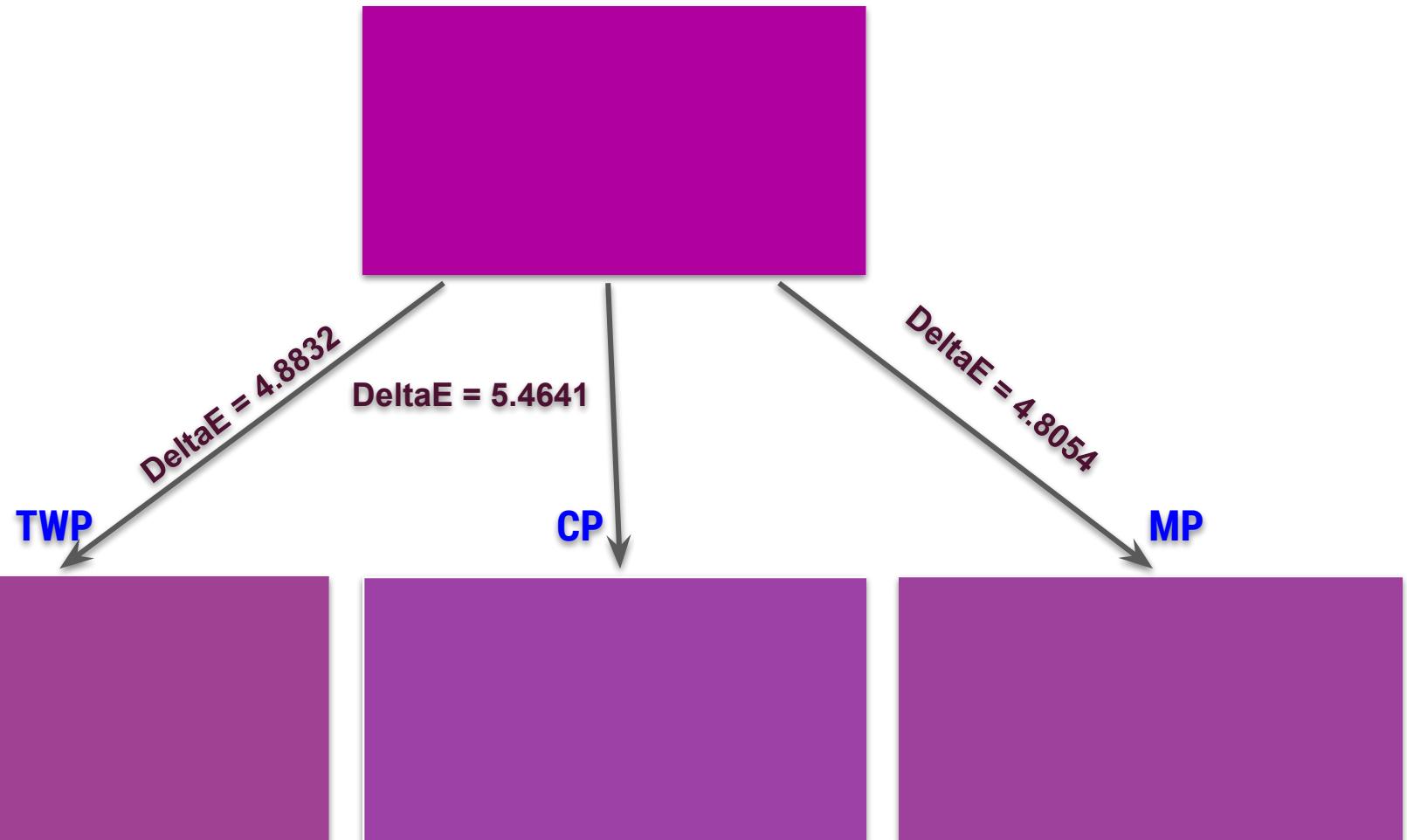
**Both Mid-Points worse than MP**



Very close Results; though QOE decreases







Mid-Point is better than TWP and CP

$\Delta E = 4.5165$

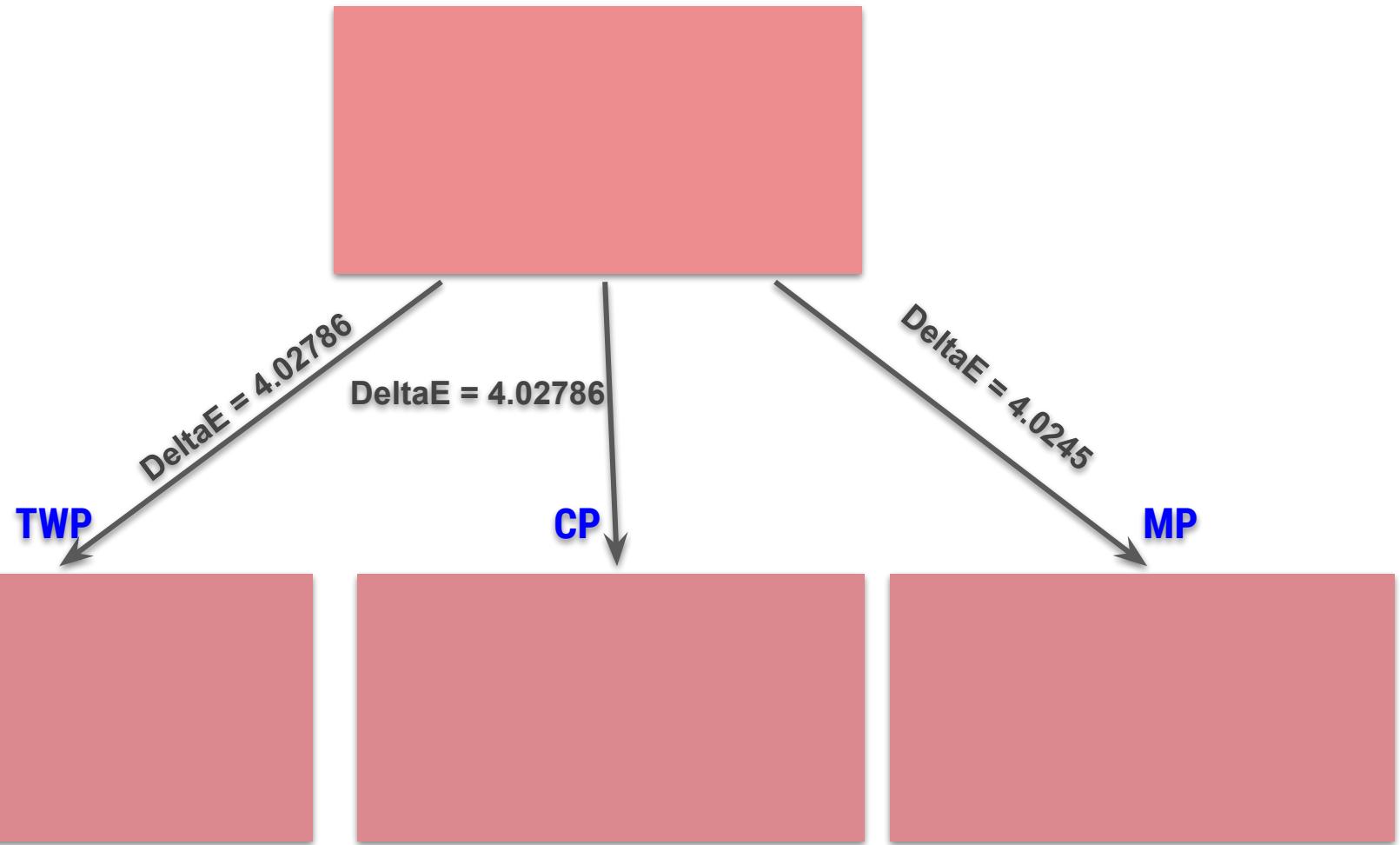
**Midpoint with  
MP and TWP**

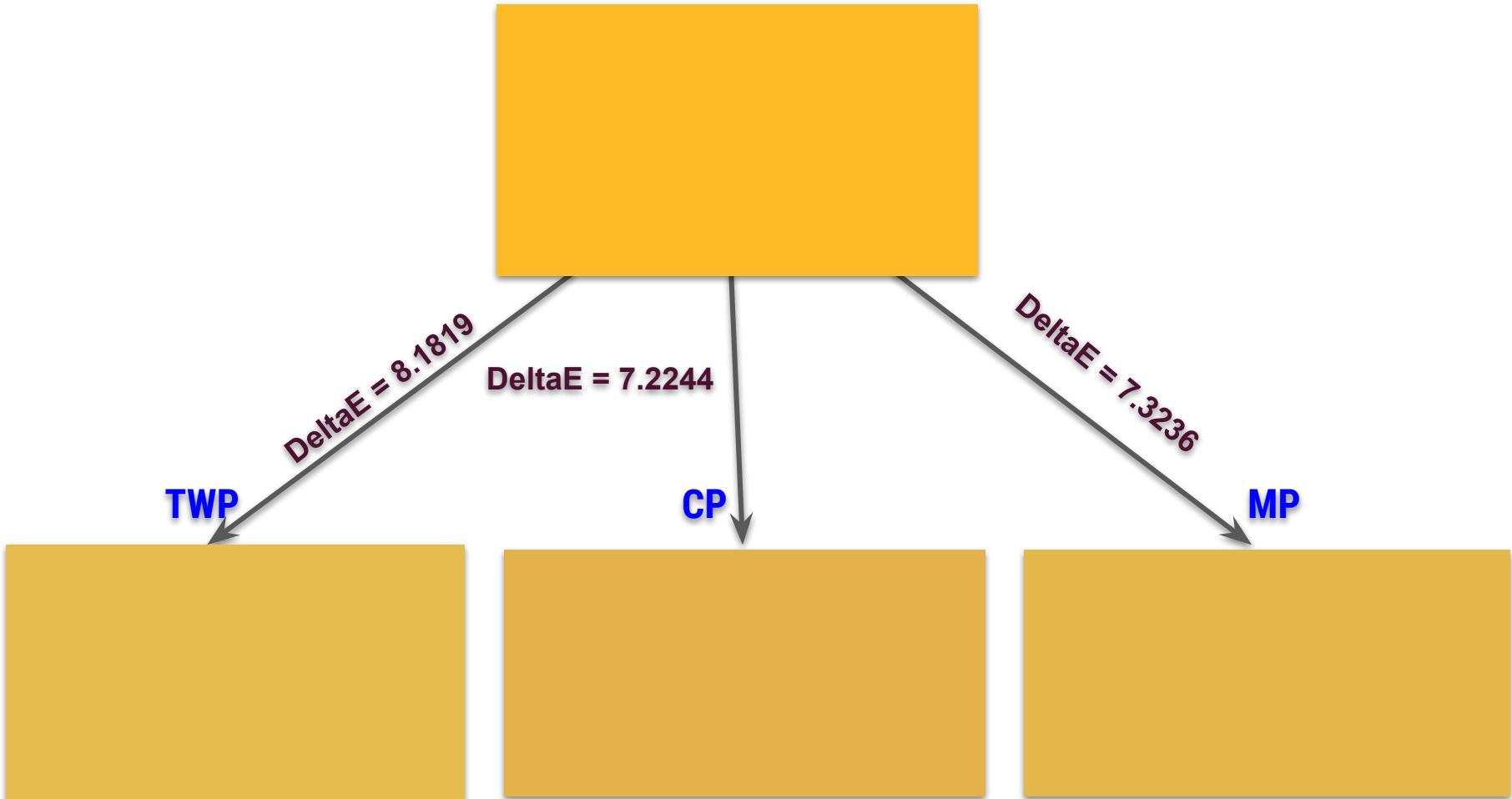
$\Delta E = 5.005$

**Midpoint with  
MP and CP**



**Mid-point with MP and TWP gives best result**





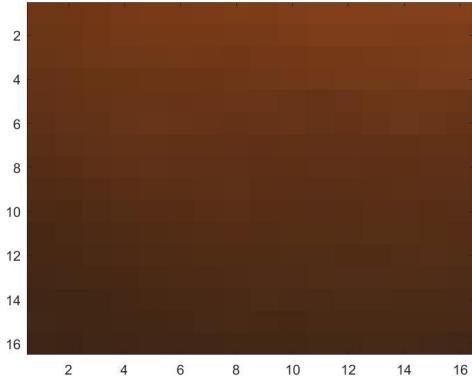
Cp -Best results , MP better than TWP

# Results

Original Image			Towards White Point				Closest Point				MidPoint				TWP_MP_MidPoint				CP_MP_MidPoint					
R	G	B	R	G	B	Delta E	R	G	B	Delta E	R	G	B	Delta E	R	G	B	Delta E	R	G	B	DeltaE		
1017	747	156	92	0	756	308	8.181	909	714	296	7.224	915	735	302	7.323	918	746	305	7.676	912	725	299	7.1928	
949	566	572	87	8	550	568	4.027	878	550	568	4.027	878	550	568	4.024	878	550	568	4.024	878	550	568	4.0245	
41	153	606	17	1	172	511	4.446	181	129	579	4.339	176	151	545	3.799	174	162	528	3.945	179	140	562	3.9977	
707	707	640	63	9	264	594	4.883	629	260	665	5.464	634	262	630	4.805	637	256	612	4.516	632	259	648	5.005	
85	644	95	39	9	608	344	13.53	394	608	232	11.61	397	608	288	11.99	398	608	316	12.57	396	608	260	11.612	
1017	747	156	92	0	756	308	8.181	9	909	714	296	7.224	915	735	302	7.323	918	746	305	7.676	912	725	299	7.1928
508	326	330	50	8	327	329	0.22	508	327	329	0.22	508	327	329	0.231	508	327	329	0.231	508	327	329	0.2313	
1023	0	0	84	4	348	192	8.686	843	342	191	8.769	844	345	191	8.689	844	347	192	8.690	844	344	192	8.724	

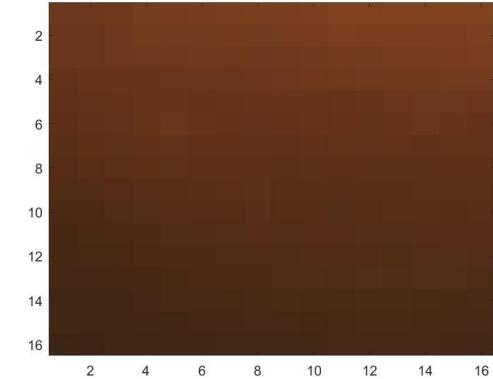
# Results



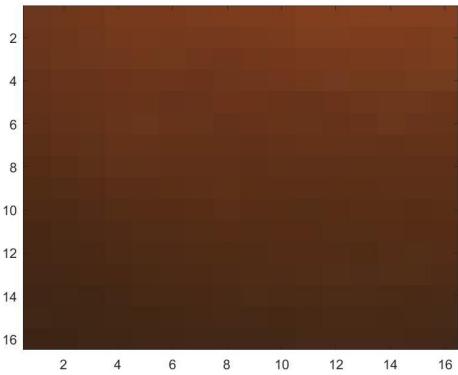


Original

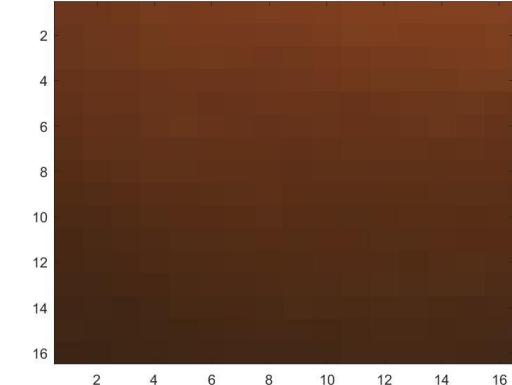
# 16X16 Patch



TWP

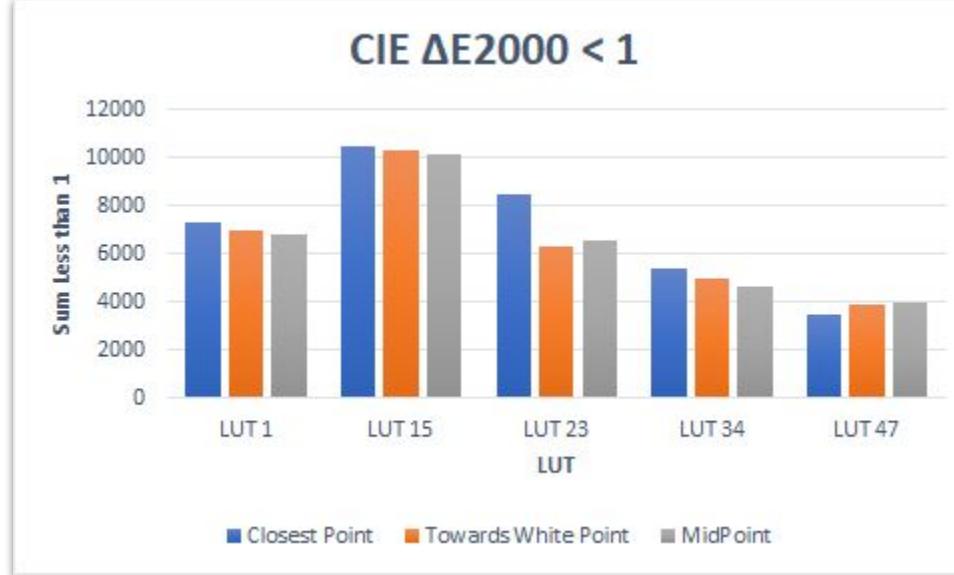


Closest Point

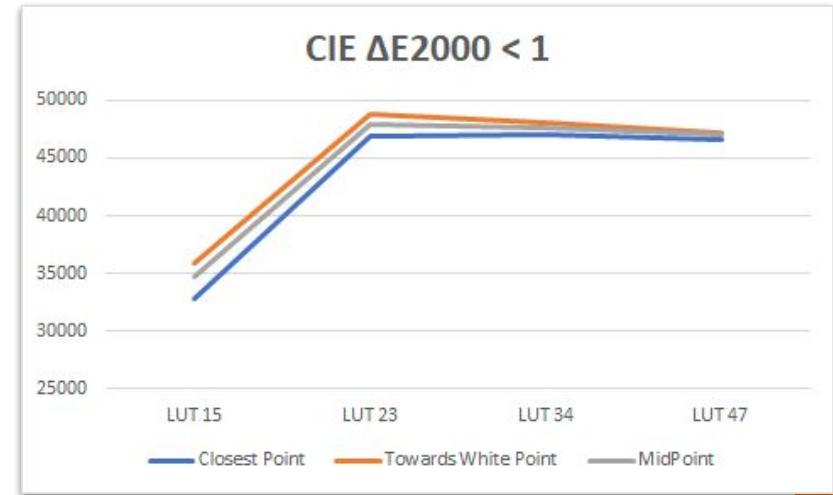
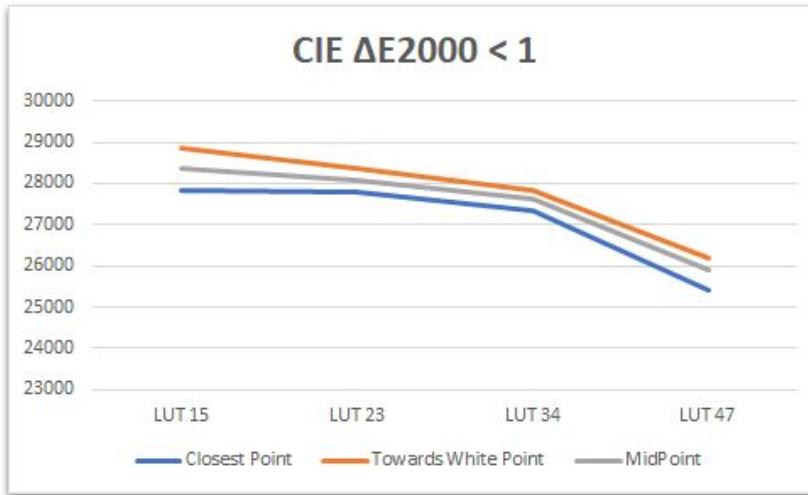


Mid Point

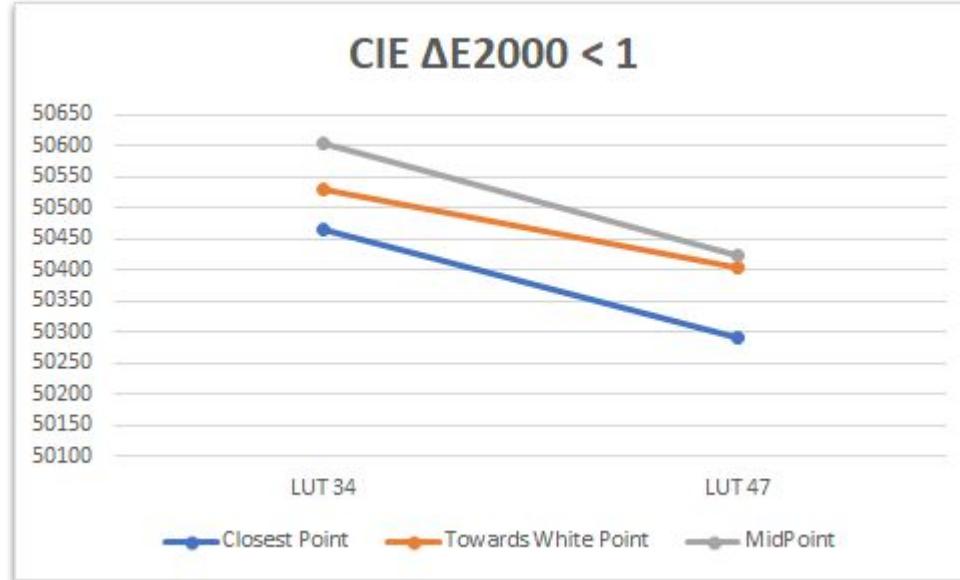
## Comparison of Projection Method



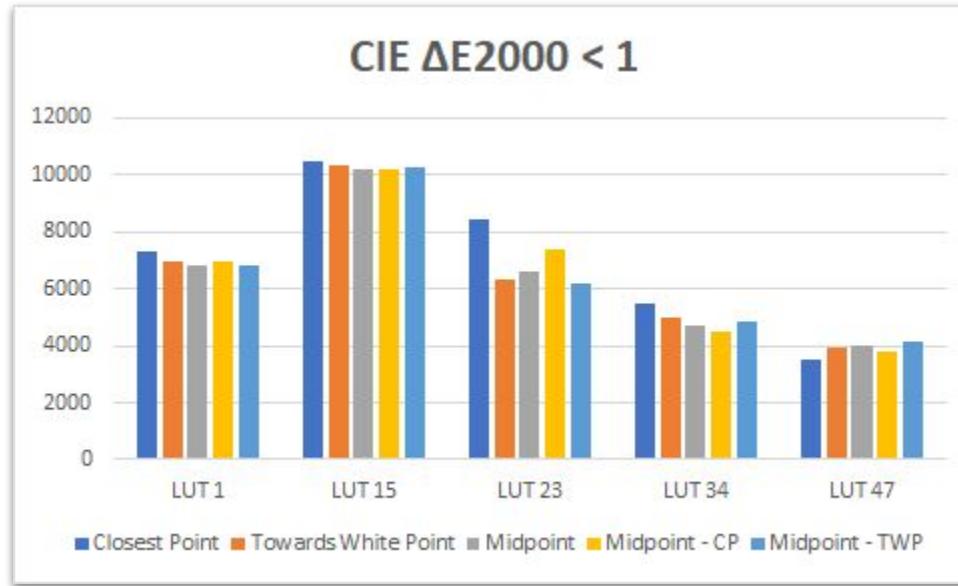
## Comparison of Projection Method



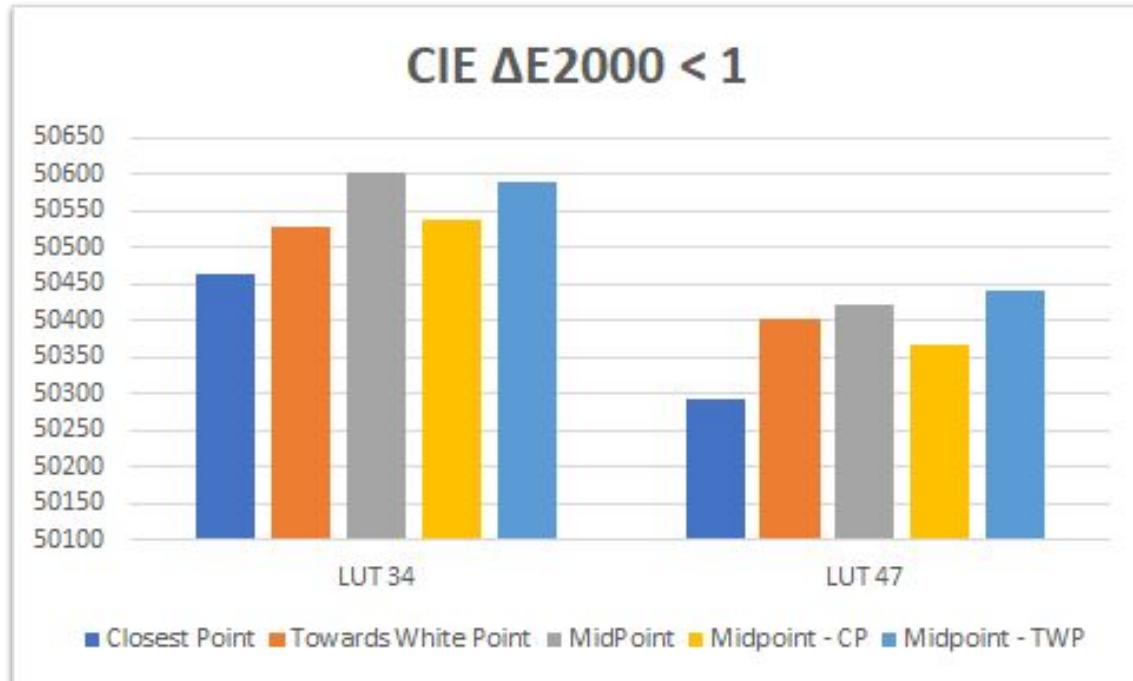
## Better results with Midpoint Projection



## Better results with Midpoint Projection



## Better results with Midpoint - TWP Projection



## 7. Conclusion

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# Conclusion

- The proposed method of using 3 more sampling points between TWP and CP has showed that there is **no one best projection method**.
- Our study shows that for some colors Closest Point projection performs better, for some TWP and for some Mid-Points outperforms them

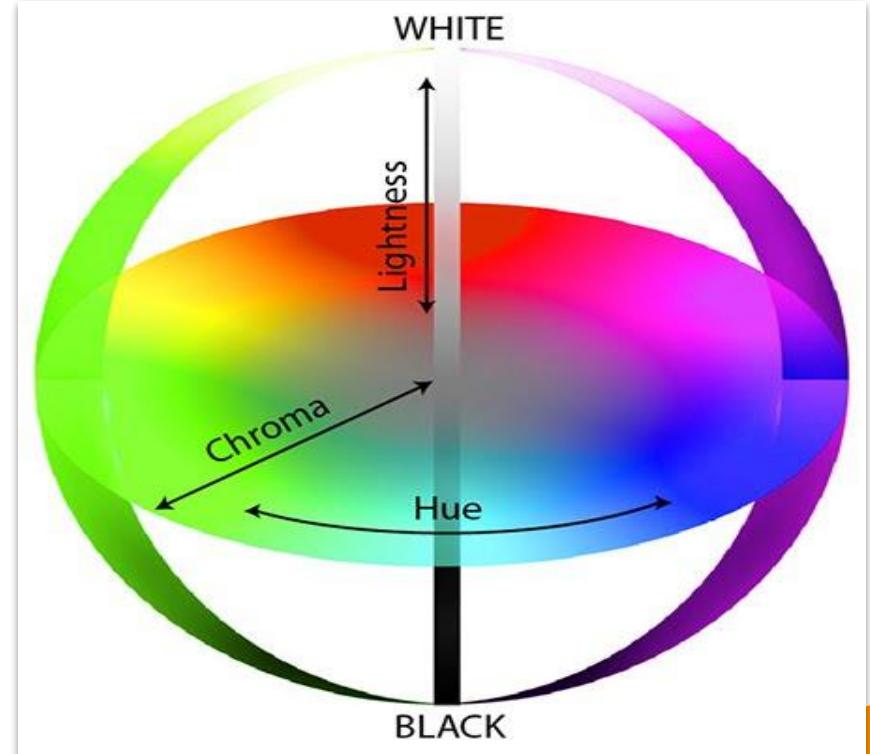
Original Image			Towards White Point				Closest Point				MidPoint				TWP_MP_MidPoint				CP_MP_MidPoint			
R	G	B	R	G	B	DeltaE	R	G	B	DeltaE	R	G	B	DeltaE	R	G	B	DeltaE	R	G	B	DeltaE
1017	747	156	920	756	308	8.1819	909	714	296	7.2244	915	735	302	7.3236	918	746	305	7.6768	912	725	299	7.1928
949	566	572	878	550	568	4.0278	878	550	568	4.0278	878	550	568	4.0245	878	550	568	4.0245	878	550	568	4.0245
41	153	606	171	172	511	4.4446	181	129	579	4.339	176	151	545	3.7995	174	162	528	3.9458	179	140	562	3.9977
707	707	640	639	264	594	4.8832	629	260	665	5.4641	634	262	630	4.8054	637	256	612	4.5165	632	259	648	5.005

# Conclusion

- The results from trials indicate that as error increases, Mid-Point projection tends to perform better than Towards White Point and Closest Point.
- A major trend is the Mid-Point towards TWP performs better as compared to all other approaches.
- Though the size of LUT makes our method computationally infeasible with the currently commonly available computational resources. Hence our method is not suitable currently for videos.
- Although with categorizing color codes with B-values, the amount of computation required can be decreased and the time required can be reduced.

# FUTURE SCOPE

1. Decreasing the LUT size
2. Usage of LCH space for HUE correction



# Thanks!

Does anyone have any questions?