

Seminar săptăm. 11

Transformări ortogonale. Endomorfisme simetrice

8. $(\mathbb{R}^3, g_0), f \in \text{End}(\mathbb{R}^3)$

$$A = [f]_{\mathcal{B}_0, \mathcal{B}_0} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

a) f transform. ort. de gradul 2 $f = r \circ R_\varphi$

b) $\varphi = ?$ axa de rotație?

c) Să se det. R ortomorfism, $[f]_{\mathcal{B}, \mathcal{B}} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & \cos \varphi & -\sin \varphi \\ 0 & \sin \varphi & \cos \varphi \end{pmatrix}$

Sol:

a) $f \in O(\mathbb{R}^3) \Leftrightarrow A \in O(3)$

$$A \cdot A^t = I_3 \quad \checkmark$$

$\det A = -1 \Rightarrow f$ este de gradul 2

$$\text{tr} A = 1 = -1 + 2 \cos \varphi \Rightarrow 2 \cos \varphi = 2 \Rightarrow \cos \varphi = 1 \Rightarrow \varphi = 0^\circ$$

Axa: $f(x) = -x$

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}^3, f(x) = (x_2, x_1, x_3)$$

$$f(x) = -x \Rightarrow x_2 = -x_1 \quad \Rightarrow x_1 = -x_2$$

$$x_3 = -x_3 \Rightarrow x_3 = 0$$

$$(x_1, x_2, x_3) = (-x_2, x_2, 0) = x_2(-1, 1, 0)$$

$e_1 = \frac{1}{\sqrt{2}}(-1, 1, 0)$ versorul axei de rotație

$$\begin{aligned} c) e_1^\perp &= \{x \in \mathbb{R}^3 \mid g_0(x, e_1) = 0\} = \{(x_1, x_2, x_3) \mid x_1, x_2, x_3 \in \mathbb{R}\} = \\ &= \{(1, 1, 0), (0, 0, 1)\} = \{l_2, l_3\} \end{aligned}$$

$\{l_2, l_3\}$ reper în e_1^\perp mod. realor canonice

$\langle l_2, l_3 \rangle = 0 \Rightarrow$ reper ortomorfism, altfel aplicăm Gram-Schmidt

$$e_2 = \frac{1}{\sqrt{2}}(1, 1, 0)$$

$$e_3 = (0, 0, 1)$$

$R = \{e_1, e_2, e_3\}$ reper ortonormat, $R^3 = \langle \{e_1\} \rangle \oplus \langle \{e_1\} \rangle^\perp$

$$[P]_{R,R} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$[P]_{R,R} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

2/2. (R^3, g_0) n.v.e.n., $u = (1, -1, 2)$

a) $\langle \{u\} \rangle^\perp = ?$ Precizați un reper ortonormat

b) Se alege det. transform. ortogonala, de yeta 1, care este
rotatie de φ orientat $\varphi = \frac{\pi}{2}$ și axa $\langle \{u\} \rangle$

$$\begin{aligned} (x_1, x_1 + 2x_3, x_3) \\ x_2 = x_1 + 2x_3 \end{aligned}$$

Sol.:

$$\begin{aligned} a) u^\perp &= \{x \in R^3 \mid g_0(x, u) = 0\} = \{x \in R^3 \mid x_1 - x_2 + 2x_3 = 0\} = \\ &= \left\{ \underbrace{(1, 1, 0)}_{f_2}, \underbrace{(0, 2, 1)}_{f_3} \right\} \end{aligned}$$

$\{f_2, f_3\}$ reper arbitrar, $\{e_2', e_3'\}$ ortogonal

$$e_2' = f_2 = (1, 1, 0)$$

$$e_3' = f_3 - \frac{\langle f_3, e_2' \rangle}{\langle e_2', e_2' \rangle} \cdot e_2' = (0, 2, 1) - \frac{2}{2} (1, 1, 0) = (-1, 1, 1)$$

$\{e_2 = \frac{1}{\sqrt{2}}(1, 1, 0), e_3 = \frac{1}{\sqrt{3}}(-1, 1, 1)\}$ reper ortonormat

$$e_1 = \frac{1}{\sqrt{6}}(1, -1, 2) \text{ versorul axei}$$

$$R^3 = u \oplus u^\perp$$

$R = \{e_1, e_2, e_3\}$ reper ortonormat în R^3 a.i.

$$A' = [P]_{R,R} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \varphi & -\sin \varphi \\ 0 & \sin \varphi & \cos \varphi \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\mathcal{R}_0 = \{e_1^0, e_2^0, e_3^0\} \xrightarrow{C} \mathcal{R} = \left\{ \frac{1}{\sqrt{6}}(1, -1, 2), \frac{1}{\sqrt{2}}(1, 1, 0), \frac{1}{\sqrt{3}}(-1, 1, 1) \right\}$$

$$A' = C^{-1}AC \Rightarrow A = CA' C^t$$

$$C = \frac{1}{\sqrt{6}} \begin{pmatrix} 1 & \sqrt{3} & \sqrt{2} \\ -1 & \sqrt{3} & \sqrt{2} \\ 2 & 0 & \sqrt{2} \end{pmatrix}$$

$$A = \frac{1}{6} \begin{pmatrix} 1 & \sqrt{3} & -\sqrt{2} \\ -1 & \sqrt{3} & \sqrt{2} \\ 2 & 0 & \sqrt{2} \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & -1 & 2 \\ \sqrt{3} & \sqrt{3} & 0 \\ -\sqrt{2} & \sqrt{2} & \sqrt{2} \end{pmatrix} =$$

$$= \frac{1}{6} \begin{pmatrix} 1 & -1-2\sqrt{6} & 2-\sqrt{6} \\ -1+2\sqrt{6} & 1 & -2-\sqrt{6} \\ 2+\sqrt{6} & -2-\sqrt{6} & 4 \end{pmatrix}$$

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}^3, f(x) = \frac{1}{6} (x_1 + x_2(-1-2\sqrt{6}) + x_3(2-\sqrt{6}), \\ x_1(-1+2\sqrt{6}) + x_2 + x_3(-2-\sqrt{6}), \\ x_1(2+\sqrt{6}) + x_2(-2-\sqrt{6}) + 4x_3)$$

4/3. $(\mathbb{R}^3, g_0), f: \mathbb{R}^3 \rightarrow \mathbb{R}^3, f(x) = g_0(x, u)u$, unde $u = (1, -1, 2)$

a) Să se arate că $f \in \text{Sim}(\mathbb{R}^3)$, $f = ?$

b) Să se afle $Q: \mathbb{R}^3 \rightarrow \mathbb{R}$ formă pătratică asociată. Să se aducă Q la o formă canonică, efectuând o transformare ortogonală h (adică o schimbare de repere ortonormate).

Sol:

a) $g_0(x, u) = x_1 - x_2 + 2x_3$

$$f(x) = (x_1 - x_2 + 2x_3, -x_1 + x_2 - 2x_3, 2x_1 - 2x_2 + 4x_3)$$

$$A = \begin{pmatrix} 1 & -1 & 2 \\ -1 & 1 & -2 \\ 2 & -2 & 4 \end{pmatrix} = A^t \Rightarrow f \in \text{Sim}(\mathbb{R}^3)$$

$$\langle f(x), x \rangle = Q(x)$$

$$b) Q(x) = x_1^2 + x_2^2 + 4x_3^2 - 2x_1x_2 + 4x_1x_3 - 4x_2x_3$$

c) Methode der Eigenwerte

$$P_A(\lambda) = \det(A - \lambda I_3) = \begin{vmatrix} 1-\lambda & -1 & 2 \\ -1 & 1-\lambda & -2 \\ 2 & -2 & 4-\lambda \end{vmatrix} \xrightarrow{L_1+L_2} \begin{vmatrix} -\lambda & -\lambda & 0 \\ -1 & 1-\lambda & -2 \\ 2 & -2 & 4-\lambda \end{vmatrix} =$$

$$= -\lambda \begin{vmatrix} 1 & 1 & 0 \\ -1 & 1-\lambda & -2 \\ 2 & -2 & 4-\lambda \end{vmatrix} = -\lambda \left(\begin{vmatrix} 1-\lambda & -2 \\ -2 & 4-\lambda \end{vmatrix} - \begin{vmatrix} -1 & -2 \\ 2 & 4-\lambda \end{vmatrix} \right) =$$

$$= -\lambda(-4 + 4 - 5\lambda + \lambda^2 - (\lambda - 4 + 4))$$

$$= -\lambda(\lambda^2 - 6\lambda)$$

$$= -\lambda^2(\lambda - 6) = 0$$

$$\lambda_1 = 0, m_1 = 2 \Rightarrow \dim V_{\lambda_1} = 2$$

$$\lambda_2 = 6, m_2 = 1 \Rightarrow \dim V_{\lambda_2} = 1$$

$$\mathbb{R}^3 = V_{\lambda_1} \oplus V_{\lambda_2}$$

$$\mathcal{B} = \mathcal{B}_1 \cup \mathcal{B}_2$$

$$V_{\lambda_1} = \{x \in \mathbb{R}^3 \mid AX = 0X\} = \ker A = \{(x_1, x_1 + 2x_3, x_3)\} = \langle \underbrace{(1, 1, 0)}_{p_1}, \underbrace{(0, 2, 1)}_{p_2} \rangle$$

$$x_1 - x_2 + 2x_3 = 0 \Rightarrow x_2 = x_1 + 2x_3$$

$$e_1 = p_1 = (1, 1, 0)$$

$$e_2 = p_2 - \frac{\langle p_2, e_1 \rangle}{\langle e_1, e_1 \rangle} e_1 = (0, 2, 1) - \frac{2}{2} (1, 1, 0) = (-1, 1, 1)$$

$$e_1' = \frac{1}{\sqrt{2}} (1, 1, 0), e_2' = \frac{1}{\sqrt{3}} (-1, 1, 1)$$

$$\mathcal{B}_1 = \{e_1', e_2'\} \text{ - orthonormalbasis in } V_{\lambda_1}$$

$$V_{\lambda_2} = \{x \in \mathbb{R}^3 \mid AX = 6X\}$$

$$b) \begin{pmatrix} -5 & -1 & 2 \\ -1 & -5 & -2 \\ 2 & -2 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\det B = \begin{vmatrix} -5 & -6 & -3 \\ -1 & -6 & -3 \\ 2 & 0 & 0 \end{vmatrix} = 0$$

$$\begin{cases} -5x_1 - x_2 = -2x_3 \\ -x_1 - 5x_2 = 2x_3 \end{cases} \quad (+)$$

$$-6(x_1 + x_2) = 0 \Rightarrow x_2 = -x_1, \dots$$

$$V_{\lambda_2} = \langle \left\{ \left(\frac{1}{2}, -\frac{1}{2}, 1 \right) \right\} \rangle = \langle \{ (1, -1, 2) \} \rangle$$

$$R_2 = \{ e_3' = \frac{1}{\sqrt{6}} (1, -1, 2) \}$$

$$R = R_1 \cup R_2 \text{ repuz ortonormat în } \mathbb{R}^3 \text{ a.c.}$$

$$[f]_{R,R} = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 6 \end{pmatrix} \quad Q(x) = 6x_3'^2, \text{ min } (1, 0)$$

$$R_0 = \{ e_1^0, e_2^0, e_3^0 \} \xrightarrow{C} R = \{ e_1' = \frac{1}{\sqrt{2}} (1, 1, 0), e_2' = \frac{1}{\sqrt{3}} (-1, 1, 1), e_3' = \frac{1}{\sqrt{6}} (1, -1, 2) \}$$

$$h \in O(\mathbb{R}^3), h(e_i^0) = e_i', \forall i=1,3$$

$$C = \frac{1}{\sqrt{6}} \begin{pmatrix} \sqrt{3} & -\sqrt{2} & 1 \\ \sqrt{3} & \sqrt{2} & -1 \\ 0 & \sqrt{2} & 2 \end{pmatrix}$$