## **COURSE 4**

## 2.3. Hermite interpolation

**Example 1** In the following table there are some data regarding a moving car. We may estimate the position (and the speed) of the car when the time is t = 10 using Hermite interpolation.

Let  $x_k \in [a,b], \ k = 0,1,...,m$  be such that  $x_i \neq x_j$ , for  $i \neq j$  and let  $r_k \in \mathbb{N}, \ k = 0,1,...,m$ . Consider  $f:[a,b] \to \mathbb{R}$  such that there exist  $f^{(j)}(x_k), \ k = 0,1,...,m; \ j = 0,1,...,r_k$  and  $n = m + r_0 + ... + r_m$ .

The Hermite interpolation problem (HIP) consists in determining the polynomial P of the smallest degree for which

$$P^{(j)}(x_k) = f^{(j)}(x_k), \quad k = 0, ..., m; \ j = 0, ..., r_k.$$

**Definition 2** A solution of (HIP) is called **Hermite interpolation polynomial**, denoted by  $H_nf$ .

**Hermite interpolation polynomial**,  $H_nf$ , satisfies the interpolation conditions:

$$(H_n f)^{(j)}(x_k) = f^{(j)}(x_k), \quad k = 0, ..., m; \ j = 0, ..., r_k.$$

Hermite interpolation polynomial is given by

$$(H_n f)(x) = \sum_{k=0}^m \sum_{j=0}^{r_k} h_{kj}(x) f^{(j)}(x_k) \in \mathbb{P}_n,$$
 (1)

where  $h_{kj}(x)$  denote the Hermite fundamental interpolation polynomials. They fulfill the relations:

$$h_{kj}^{(p)}(x_{\nu}) = 0, \quad \nu \neq k, \quad p = 0, 1, ..., r_{\nu}$$

$$h_{kj}^{(p)}(x_k) = \delta_{jp}, \quad p = 0, 1, ..., r_k, \quad \text{for } j = 0, 1, ..., r_k \text{ and } \nu, k = 0, 1, ..., m,$$
with  $\delta_{jp} = \begin{cases} 1, & j = p \\ 0, & j \neq p. \end{cases}$ 

We denote by

$$u(x) = \prod_{k=0}^{m} (x - x_k)^{r_k + 1}$$
 and  $u_k(x) = \frac{u(x)}{(x - x_k)^{r_k + 1}}$ .

We have

$$h_{kj}(x) = \frac{(x - x_k)^j}{j!} u_k(x) \sum_{\nu=0}^{r_k - j} \frac{(x - x_k)^{\nu}}{\nu!} \left[ \frac{1}{u_k(x)} \right]_{x = x_k}^{(\nu)}.$$
 (2)

**Example 3** Find the Hermite interpolation polynomial for a function f for which we know f(0) = 1, f'(0) = 2 and f(1) = -3 (equivalent with  $x_0 = 0$  multiple node of order 2 or double node,  $x_1 = 1$  simple node).

**Sol.** We have  $x_0 = 0, x_1 = 1, m = 1, r_0 = 1, r_1 = 0, n = m + r_0 + r_1 = 2$ 

$$(H_2f)(x) = \sum_{k=0}^{1} \sum_{j=0}^{r_k} h_{kj}(x) f^{(j)}(x_k)$$
  
=  $h_{00}(x) f(0) + h_{01}(x) f'(0) + h_{10}(x) f(1)$ .

We have  $h_{00}, h_{01}, h_{10}$ . These fulfills relations:

$$h_{kj}^{(p)}(x_{\nu}) = 0, \ \nu \neq k, \ p = 0, 1, ..., r_{\nu}$$
  
 $h_{kj}^{(p)}(x_k) = \delta_{jp}, \ p = 0, 1, ..., r_k, \quad \text{for } j = 0, 1, ..., r_k \text{ and } \nu, k = 0, 1, ..., m.$ 

We have  $h_{00}(x)=a_1x^2+b_1x+c_1\in\mathbb{P}_2$ , with  $a_1,b_1,c_1\in\mathbb{R}$ , and the system

$$\begin{cases} h_{00}(x_0) = 1 \\ h'_{00}(x_0) = 0 \\ h_{00}(x_1) = 0 \end{cases} \Leftrightarrow \begin{cases} h_{00}(0) = 1 \\ h'_{00}(0) = 0 \\ h_{00}(1) = 0 \end{cases}$$

that becomes

$$\begin{cases} c_1 = 1 \\ b_1 = 0 \\ a_1 + b_1 + c_1 = 0. \end{cases}$$

Solution is:  $a_1 = -1, b_1 = 0, c_1 = 1$  so  $h_{00}(x) = -x^2 + 1$ .

We have  $h_{01}(x) = a_2x^2 + b_2x + c_2 \in \mathbb{P}_2$ , with  $a_2, b_2, c_2 \in \mathbb{R}$ . The system

is

$$\begin{cases} h_{01}(x_0) = 0 \\ h'_{01}(x_0) = 1 \\ h_{01}(x_1) = 0 \end{cases} \Leftrightarrow \begin{cases} h_{01}(0) = 0 \\ h'_{01}(0) = 1 \\ h_{01}(1) = 0 \end{cases}$$

and we get  $h_{01}(x) = -x^2 + x$ .

We have  $h_{10}(x)=a_3x^2+b_3x+c_3\in\mathbb{P}_2$ , with  $a_3,b_3,c_3\in\mathbb{R}$ . The system is

$$\begin{cases} h_{10}(x_0) = 0 \\ h'_{10}(x_0) = 0 \\ h_{10}(x_1) = 1 \end{cases} \Leftrightarrow \begin{cases} h_{10}(0) = 0 \\ h'_{10}(0) = 0 \\ h_{10}(1) = 1 \end{cases}$$

and we get  $h_{10}(x) = x^2$ .

The Hermite polynomial is

$$(H_2f)(x) = -x^2 + 1 - 2x^2 + 2x - 3x^2 = -6x^2 + 2x + 1.$$

The Hermite interpolation formula is

$$f = H_n f + R_n f.$$

where  $R_n f$  denotes the remainder term (the error).

**Theorem 4** If  $f \in C^n[\alpha, \beta]$  and  $f^{(n)}$  is derivable on  $(\alpha, \beta)$ , with  $\alpha = \min\{x, x_0, ..., x_m\}$  and  $\beta = \max\{x, x_0, ..., x_m\}$ , then there exists  $\xi \in (\alpha, \beta)$  such that

$$(R_n f)(x) = \frac{u(x)}{(n+1)!} f^{(n+1)}(\xi).$$
 (3)

**Proof.** Consider

$$F(z) = \begin{vmatrix} u(z) & (R_n f)(z) \\ u(x) & (R_n f)(x) \end{vmatrix}.$$

 $F \in C^n[\alpha, \beta]$  and there exists  $F^{(n+1)}$  on  $(\alpha, \beta)$ .

We have

$$F(x) = 0$$
,  $F^{(j)}(x_k) = 0$ ,  $k = 0, ..., m$ ;  $j = 0, ..., r_k$ ;

because

$$u(x) = \prod_{k=0}^{m} (x - x_k)^{r_k + 1} \Rightarrow u^{(j)}(x_k) = 0, \ j = 0, ..., r_k$$

and

$$(R_m f)^{(j)}(x_k) = f^{(j)}(x_k) - (H_n f)^{(j)}(x_k) = f^{(j)}(x_k) - f^{(j)}(x_k) = 0.$$

So, F and its derivatives have n+2 distinct zeros in  $(\alpha,\beta)$ . Applying successively Rolle's theorem it follows that F' has at least n+1 zeros in  $(\alpha,\beta) \Rightarrow ... \Rightarrow F^{(n+1)}$  has at least one zero  $\xi \in (\alpha,\beta)$ ,  $F^{(n+1)}(\xi) = 0$ .

We have

$$F^{(n+1)}(z) = \begin{vmatrix} u^{(n+1)}(z) & (R_n f)^{(n+1)}(z) \\ u(x) & (R_n f)(x) \end{vmatrix},$$

with 
$$u(z) = \prod_{k=0}^{m} (z - z_k)^{r_k + 1} \in \mathbb{P}_{n+1} \Rightarrow u^{(n+1)}(z) = (n+1)!$$
, and  $(R_n f)^{(n+1)}(z) = f^{(n+1)}(z) - (H_n f)^{(n+1)}(z) = f^{(n+1)}(z)$  (as,  $H_n f \in \mathbb{P}_n$ )

 $\mathbb{P}_n$ ). We get

$$F^{(n+1)}(\xi) = \begin{vmatrix} (n+1)! & f^{(n+1)}(\xi) \\ u(x) & (R_n f)(x) \end{vmatrix} = 0,$$

whence it follows (3).

Corollary 5 If  $f \in C^{n+1}[a,b]$  then

$$|(R_n f)(x)| \le \frac{|u(x)|}{(n+1)!} ||f^{(n+1)}||_{\infty}, \quad x \in [a,b]$$

where  $\|\cdot\|_{\infty}$  denotes the uniform norm  $(\|f\|_{\infty} = \max_{x \in [a,b]} |f(x)|)$ .

Remark 6 In case of m=0, i.e.,  $n=r_0$ , (HIP) becomes Taylor interpolation problem. Taylor interpolation polynomial is

$$(T_n f)(x) = \sum_{j=0}^n \frac{(x - x_0)^j}{j!} f^{(j)}(x_0).$$

**Example 7** Find the Hermite interpolation formula for the function  $f(x) = xe^x$  for which we know f(-1) = -0.3679, f(0) = 0, f'(0) = 1,

f(1)=2.7183, (equivalent with  $x_0=-1$  simple,  $x_1=0$  multiple of order 2 and  $x_2=1$  simple). Which is the limit of the error for approximating  $f(\frac{1}{2})$ ?

## Hermite interpolation with double nodes

**Example 8** In the following table there are some data regarding a moving car. We may estimate the position (and the speed) of the car when the time is t = 10 using Hermite interpolation.

Consider 
$$f:[a,b] \to \mathbb{R}, x_0, x_1, ..., x_m \in [a,b]$$

and the values 
$$f(x_0), f(x_1), ..., f(x_m), f'(x_0), f'(x_1), ..., f'(x_m)$$
.

The Hermite interpolation polynomial with double nodes,  $H_{2m+1}$ , satisfies the interpolation properties:

$$H_{2m+1}(x_i) = f(x_i), i = \overline{0, m},$$
  
 $H'_{2m+1}(x_i) = f'(x_i), i = \overline{0, m}.$ 

It is a polynomial of n = 2m + 1 degree.

For computation: use Lagrange polynomial written in Newton form, with divided differences table having each node  $x_i$  written twice.

Consider 
$$z_0 = x_0$$
,  $z_1 = x_0$ ,  $z_2 = x_1$ ,  $z_3 = x_1$ , ...,  $z_{2m} = x_m$ ,  $z_{2m+1} = x_m$ .

Form divided differences table: each node appear twice, in the first column write the values of f for each node twice; in the second column, at the odd positions put the values of the derivatives of f; the other elements are computed using the rule from divided differences.

## We obtain the following table:

$z_0$	$f(z_0)$	$(\mathcal{D}^1 f)(z_0) = f'(x_0)$	$(\mathcal{D}^2 f)(z_0)$		$(\mathcal{D}^{2m}f)(z_0)$	$(\mathcal{D}^{2m+1}f)(z_0)$
$z_1$	$f(z_1)$	$(\mathcal{D}^1f)(z_1)$	:		$(\mathcal{D}^{2m}f)(z_1)$	
$z_2$	$f(z_2)$	$(\mathcal{D}^1 f)(z_2) = f'(x_1)$				
$z_3$	$f(z_3)$	•••				
:	÷	$(\mathcal{D}^1f)(z_{2m-1})$	$(\mathcal{D}^2f)(z_{2m-1})$	٠		
$z_{2m}$	$f(z_{2m})$	$(\mathcal{D}^1 f)(z_{2m}) = f'(x_m)$				
$z_{2m+1}$	$f(z_{2m+1})$					

Newton interpolation polynomial for the nodes  $x_0,...,x_n$  is

$$(N_n f)(x) = f(x_0) + \sum_{i=1}^n (x - x_0) \dots (x - x_{i-1})(\mathcal{D}^i f)(x_0),$$

and similarly, Hermite interpolation polynomial is

$$(H_{2m+1}f)(x) = f(z_0) + \sum_{i=1}^{2m+1} (x - z_0)...(x - z_{i-1})(\mathcal{D}^i f)(z_0),$$

where  $(\mathcal{D}^i f)(z_0)$ , i=1,...,2m+1 are the elements from the first line and columns 2,...,2m+1.

**Example 9** Consider the double nodes  $x_0 = -1$  and  $x_1 = 1$ , and f(-1) = -3, f'(-1) = 10, f(1) = 1, f'(1) = 2. Find the Hermite interpolation polynomial, that approximates the function f, in both forms, using the classical formula and using divided differences.

**Sol.** We present here the method with divided differences. We have  $m=1, r_0=r_1=1 \Rightarrow n=3$ 

$$z_0 = -1 \quad f(-1) = -3 \quad f'(-1) = 10 \quad \frac{\frac{f(1) - f(-1)}{2} - f'(-1)}{z_2 - z_0} = -4 \quad \frac{0 - (-4)}{z_3 - z_0} = 2$$

$$z_1 = -1 \quad f(-1) = -3 \quad \frac{f(1) - f(-1)}{z_2 - z_1} = 2 \quad \frac{f'(1) - \frac{f(1) - f(-1)}{2}}{z_3 - z_1} = 0$$

$$z_2 = 1 \quad f(1) = 1 \quad f'(1) = 2 \quad z_3 - z_1$$

$$f(1) = 1 \quad f(1) = 1 \quad f'(1) = 2$$

The Hermite interpolation polynomial is

$$(H_3f)(x) = f(z_0) + \sum_{i=1}^{3} (x - z_0)...(x - z_{i-1})(\mathcal{D}^i f)(z_0)$$
  
=  $f(z_0) + (x - z_0)(\mathcal{D}^1 f)(z_0) + (x - z_0)(x - z_1)(\mathcal{D}^2 f)(z_0)$   
+  $(x - z_0)(x - z_1)(x - z_2)(\mathcal{D}^3 f)(z_0)$ 

i.e.,

$$(H_3f)(x) = f(-1) + (x+1)f'(-1) + (x+1)^2 \frac{f(1)-f(-1)-2f'(-1)}{4} + (x+1)^2 (x-1) \frac{2f'(1)-f(1)+f(-1)}{4}$$

$$= -3 + 10(x+1) - 4(x+1)^2 + 2(x+1)^2 (x-1)$$

$$= 2x^3 - 2x^2 + 1.$$

Example 10 Considering the the following data

$$x$$
 0 2 3  $f(x)$  0 10 12  $f'(x)$  5 3 7

find the corresponding Hermite interpolation polynomial.