

## Question 1:

### 1.1 A

The worst-case runtime of a single *MULTIPOP* operation is  $O(n)$  since in a single operation, the most you can pop is the size of the stack.

### 1.2 B

A sequence of  $n$  operations in any combination of *PUSH*, *POP*, and *MULTIPOP* should take  $O(n)$  time since for an element *PUSH*'ed to the stack it can be popped at most once. And so, the number of times that a *POP* operation can be executed is at most the number of times that an element has been *PUSH*'ed, which is at most  $n$ , so  $O(n)$ .

### 1.3 C

**What virtual cost would you give to each operation?**

$PUSH \rightarrow 2$

$POP \rightarrow 0$

$MULTIPOP \rightarrow 0$

**What is the real cost of each operation?**

$PUSH \rightarrow O(1)$

$POP \rightarrow O(1)$

$MULTIPOP \rightarrow O(\min(k, n))$

$k$  is the number of elements to be *POP*'ed

$n$  is the number of elements in the stack.

### 1.4 D

When we push to the stack we pre-pay a cost of 1 coin, thus each element in the stack has been half paid for. So when we pop an element, we also remove the pre-paid cost and use it to pay the *POP* cost, so we charge the operation nothing but use the pre-paid cost for payment. This is the same for a *MULTIPOP* operation, since that is just a series of *POP* operations. Therefore we always have enough stored up in pre-paid amounts to pay for

the *POP* and *MULTIPOP* operations. And since the stack is always non-negative we also ensure that the amount stored up in credit is always non-negative as well so we will never run out of coins.

## 1.5 E

Since we know:

- That for any sequence of  $n$  *PUSH*, *POP*, and *MULTIPOP* operations, amortized cost upper bounds the total cost by definition.
- And the total credit stored in the stack is the difference between the amortized cost and the total cost.
- Therefore the total credit is always nonnegative.
- We also know that for any *POP* operation, there must have been a previous *PUSH* operation.
- Therefore we know that since the amortized cost is  $O(n)$  then the total cost must also be  $O(n)$

## 1.6 F

Since a *MULTIPUSH* operation is simply a series of *PUSH* operations executed  $k$  times on an object. The amortized cost of the *MULTIPUSH* operation would be  $2k$ . This is not different, however, from individually pushing an object  $k$  times and so the total cost would be dependent on the number of elements in the stack and not the method of pushing. So *POP* and *MULTIPOP* have unchanged amortized costs and the total amortized cost would still be  $O(n)$  and so too the total actual cost.

## Question 2:

### 2.1 A

I would use an ArrayList.

### 2.2 B

To insert, I would simply insert at the end of the array if there is space left. Therefore insertion would take  $O(1)$  time. If there is no space left, create a new array of size  $2n$  and copy over the  $n$  elements,  $O(n)$  time. So for the first  $n$  elements insertion is constant time.

### 2.3 C

To delete the largest  $\lceil \frac{n}{2} \rceil$  elements, since to achieve constant insertion the array would need to be unsorted, I would use the median method to split the array into elements larger than the median and smaller than the median. That way we are left with a half of the array that is strictly larger than the other half. Deleting that half would be done in constant  $O(1)$  time and partitioning by relation to the median would be done in  $O(n)$  time.

### 2.4 D

Since we probably don't want to measure exact runtime, an individual operation can take at the worst case  $O(n)$  time, I'm going to assess runtime in the average case where there are a sequence of operations being performed.

### 2.5 E

The potential function  $\Phi$  would be defined as the number of elements present in the Array. The potential of the empty Array,  $D_0$  would be set to 0. So  $\Phi(D_0) = 0$ .

## 2.6 F

From the TextBook we know  $\hat{c}_i = c_i + \Phi(D_i) - \Phi(D_{i-1})$ .

For the *INSERT* operation, we know that for an Array containing  $n$  elements, after the operation it would contain  $n + 1$  elements. Therefore we know  $\Phi(D_i) - \Phi(D_{i-1}) = (n + 1) - n = 1$ . So  $\hat{c}_i = c_i + 1$ . Since  $c_i$  is the actual cost of the insert operation. Assuming the insertion is in an array containing  $n - 1$  elements,  $c_i = 1$ . Therefore for the *INSERT* operation we have  $\hat{c}_i = 2$ , so  $\hat{c}_i$  for *INSERT* is constant.

For the *DELETE-HALF* operation, we know that for an Array containing  $n$  elements, after the operation it would contain  $\lfloor \frac{n}{2} \rfloor$  elements. Therefore we know  $\Phi(D_i) - \Phi(D_{i-1}) = \frac{n}{2} - n = -\frac{n}{2}$ . So  $\hat{c}_i = c_i - \frac{n}{2}$ . Since  $c_i$  is the actual cost of the *DELETE-HALF* operation,  $c_i = \frac{n}{2}$  and so we have  $\hat{c}_i = 0$ .

## 2.7 G

- Since we know by our definition of  $\Phi$  that  $\Phi(D_i) \geq \Phi(D_0)$  (because the number of elements in the array will never be negative)
- This means that the total amortized cost is an upper bound on the total cost.
- So for a sequence of  $m$  operations, we have  $O(m)$