# 8.3 Modbus Protocol Communication

#### 8.3.1 Introduction

MASTER-K120S built-in communication supports Modbus, the Modicon product's communication protocol. It supports ASCII mode, using ASCII data and RTU mode using Hex data. Function code used in Modbus is supported by instruction and especially function code 01, 02, 03, 04, 05, 06, 15 and 16. Refer to "Modicon Modbus Protocol Reference Guide"

#### 8.3.2 Basic Specification

- 1) ASCII mode
  - (1) It communicates, using ASCII data.
  - (2) Each frame uses ': (colon: H3A)', for header, CRLF (Carriage Return-Line Feed: H0D H0A), for tail.
  - (3) It allows Max. 1 second interval between characters.
  - (4) It checks errors, using LRC.
  - (5) Frame structure (ASCII data)

| Item | Header | Address | Function code | Data    | LRC     | Tail(CR/LF) |
|------|--------|---------|---------------|---------|---------|-------------|
| Size | 1 byte | 2 bytes | 2 bytes       | n bytes | 2 bytes | 2 bytes     |

#### 2) RTU mode

- (1) It communicates, using hex data.
- (2) There's no header and tail. It starts with address and finishes frame with CRC.
- (3) It has at least 3.5 character times between two frames.
- (4) It ignores the current frame when 1.5 character times elapse between characters.
- (5) It checks errors, using 16 bit CRC.
- (6) Frame structure (hex data).

| Item | Address | Function code | Data    | CRC     |
|------|---------|---------------|---------|---------|
| Size | 1 byte  | 1 bytes       | n bytes | 2 bytes |

#### REMARK

- 1) The size constituting 1 letter is 1 character. So 1 character is 8 bits that is 1 byte.
- 2) 1 character time means the time lapsed for sending 1 character.
  - Ex) Calculation of 1 character time at 1200 bps.
  - 1200 bps means that it takes 1 second to send 1200 bits. To send 1 bit,  $1 \sec/1200$  bits = 0.83 ms.

Therefore 1 character time is 0.83ms \* 8 bits = 6.64ms.

3) 584, 984 A/B/X executes frame division, using intervals of more than 1 sec without LRC in processing internally.

#### 3) Address area

- (1) Setting range is available from 1 to 247, but MASTER-K120S supports from 0 to 31.
- (2) Address 0 is used for broadcast address. Broadcast address is all slave device recognize and respond to like the self-address, which can't be supported by MASTER-K120S.

#### 4) Function code area

- (1) MASTER-K120S supports only 01, 02, 03, 04, 05, 06, 15, and 16 among Modicon products' function codes.
- (2) If the response format is confirm+(ACK), it uses the same function code.
- (3) If the response format is confirm-(NCK), it returns as it sets the 8th bit of function code as 1.

Ex) If function code is 03, (we write here only function code part. Because only function codes are different.)

[Request] 0000 0011 (H03)

[Confirm+] 0000 0011 (H03)

[Confirm-] 1000 0011 (H83)

It returns as it sets the 8th bit of function code of request frame.

#### 5) Data area

- (1) It sends data, using ASCII data(ASCII mode) or hex (RTU mode).
- (2) Data is changed according to each function code.
- (3) Response frame uses data area as response data or error code.

#### 6) LRC Check/CRC Check area

- (1) LRC (Longitudinal Redundancy Check): It works in ASCII mode. It takes 2' complement from sum of frame except header or tail to change into ASCII code,
- (2) CRC (Cyclical Redundancy Check): It works in RTU mode. It uses 2-byte CRC check rules.

#### REMARK

 $1) \quad \hbox{All numerical data can use hexadecimal, decimal, and binary type. If we convert decimal 7 and 10 into each type:} \\$ 

 $Hexa decimal: H07, H0A \ or \ 16\#07, 16\#0A$ 

Decimal: 7, 10

Binary: 2#0111, 2#1010

#### 7) Function code types and memory mapping

| Code | Function code name        | Modicon PLC<br>Data address | R emark     |
|------|---------------------------|-----------------------------|-------------|
| 01   | Read Coil Status          | 0XXXX(bit-output)           | Read bits   |
| 02   | Read Input Status         | 1XXXX(bit-input)            | Read bits   |
| 03   | Read Holding Registers    | 4XXXX(word-output)          | Read words  |
| 04   | Read Input Registers      | 3XXXX(word-input)           | Read words  |
| 05   | Force Single Coil         | 0XXXX(bit-output)           | Write bit   |
| 06   | Preset Single Register    | 4XXXX(word-output)          | Write word  |
| 15   | Force Multiple Coils      | 0XXXX(bit-output)           | Write bits  |
| 16   | Preset Multiple Registers | 4XXXX(word-output)          | Write words |

#### • MASTER-K120S Mapping

|         | Bit area  | Word area |                            |  |  |  |
|---------|-----------|-----------|----------------------------|--|--|--|
| Address | Data area | Address   | Data area                  |  |  |  |
| h0000   | P area    | h0000     | P area                     |  |  |  |
| h1000   | M area    | h1000     | M area                     |  |  |  |
| h2000   | L area    | h2000     | L area                     |  |  |  |
| h3000   | K area    | h3000     | K area                     |  |  |  |
| h4000   | F area    | h4000     | F area                     |  |  |  |
| h5000   | T area    | h5000     | T area(current value area) |  |  |  |
| h6000   | C area    | h6000     | C area(current value area) |  |  |  |
|         |           | h7000     | S area                     |  |  |  |
|         |           | h8000     | D area                     |  |  |  |

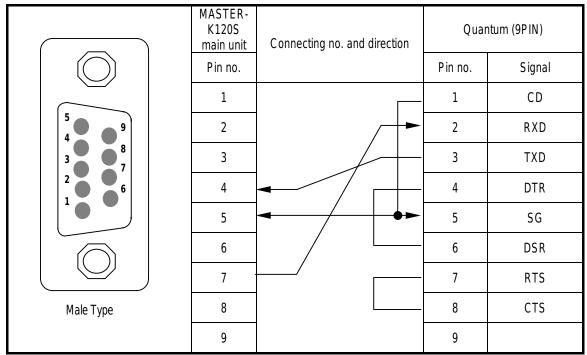
### 8) Modbus addressing rules

MASTER-K120S main unit starts its address from 0 and matches with 1 of Modicon products' data address. So MASTER-K120S's address n matches n+1 of Modicon products' address. This means that the output contact point 1 (0001) of Modicon products is marked as communication address 0 and the input contact point 1 (0001) of Modicon products is marked as communication address 0 in MASTER-K120S.

### 9) The size of using data

As for data size, MASTER-K120S main unit supports 128 bytes in ASCII mode and 256 bytes in RTU mode. The maximum size of the Modicon products is different from each other kind. So refer to "Modicon Modbus Protocol Reference Guide."

#### 10) Map of wiring

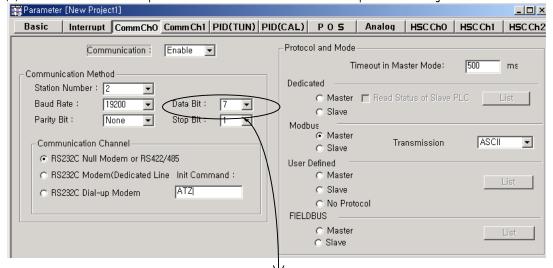


• Use RS-485 connector when using channel 2.

# 8.3.3 Parameters Setting

- 1) Setting communication parameter
  - (1) Open a new project file at KGLWIN.
    - K120S should be selected in PLC types.
    - Open a new project file for each of the master and the slave.

(2) Select a communication parameter at KGLWIN and double click to open the following window.



If communication mode & ASCII, Be sure to set 7bit

# (3) Set the contents as follows.

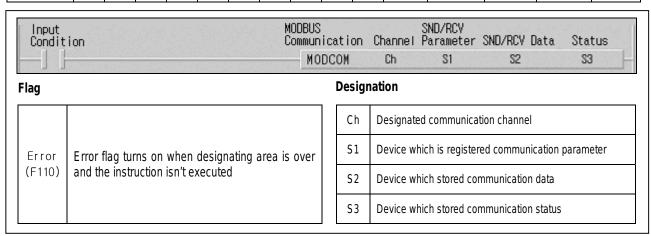
| Item                       | Setting contents   |
|----------------------------|--|
| Station No.                | Set a number between 0 to 31 (Don't assign no. 0 as broadcasting station lest it may be a cause for mistaken operation)  |
| Baud Rate                  | Set one from 1200, 2400, 4800, 9600, 19200, 38400, or 57600 bps.   |
| Data Bit                   | Set 7 or 8. ASCII mode: Set as 7 bits. RTU mode: Set as 8 bits.  |
| Parity Bit                 | Set as one of None, Even, or Odd.  |
| Stop Bit                   | Set 1 or 2 bit(s). When parity bit is set: Set as 1 bit. When parity bit isn't set: Set as 2 bits.   |
| Communication<br>Channel   | <ul> <li>RS232C Null Modem or RS422/485: It's a communication channel for the communication, using MASTER-K120S main unit's built-in communication and Cnet I/F module (G7L-CUEC).</li> <li>RS232C Modem (Dedicated Line): It's to be selected for the communication, using an dedicated modem with Cnet I/F module (G7L-CUEB).</li> <li>S232C Dial Up Modem: It's to be selected for the general communication connecting through the telephone line by dial up modem and Cnet I/F module (G7L-CUEB).</li> <li>Note: Using Cnet I/F module (G7L-CUEB) supporting RS232C, RS232C dedicated or dial-up modem communication can be done, but not through Cnet I/F module (G7L-CUEC) supporting RS422/485.</li> </ul> |
| Time out in Master<br>Mode | • It's the time waiting a responding frame since the master MK80S main unit sends a request frame.   |
| Modbus Master/<br>Slave    | If it is set as the master, it's the subject in the communication system. If it's set as the slave, it only responds to the request frame of the master.   |
| Transmission<br>Mode       | Select ASCII mode or RTU mode.   |

# 8.3.4 Instruction and example

1) MODBUS communication instruction(MODCOM)

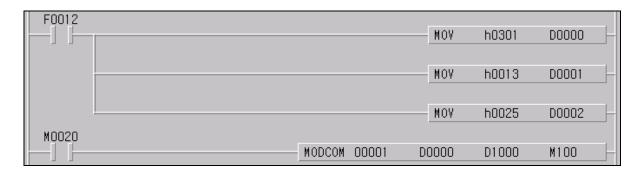


|             | Available device No. of Flag |   |   |   |   |   |   |   |   |    |         |       |                 |                 |                 |
|-------------|------------------------------|---|---|---|---|---|---|---|---|----|---------|-------|-----------------|-----------------|-----------------|
| Instruction | М                            | Р | K | L | F | T | С | S | D | #D | integer | steps | Error<br>(F110) | Zero<br>(F 111) | Carry<br>(F112) |
| Ch          |                              |   |   |   |   |   |   |   |   |    | 0       |       |                 |                 |                 |
| S1          | 0                            | 0 | 0 | 0 | 0 | 0 | 0 |   | 0 | 0  |         | 7     |                 |                 |                 |
| S2          | 0                            | 0 | 0 | 0 |   | 0 | 0 |   | 0 | 0  |         | ,     |                 |                 |                 |
| \$3         | 0                            | 0 | 0 | 0 |   | 0 | 0 |   | 0 | 0  |         |       |                 |                 |                 |



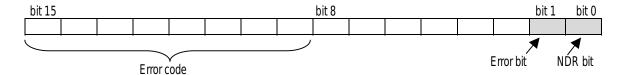
#### ■ MODCOM Ch S1 S2 S3

- (1) Example program
  - Designate slave station No. , function code, address, No. of reading
  - When input condition(M0020) turns on, MODBUS communication starts.
  - Receiving data are stored D1000, and communication status is stored to M100



When operates as slave, MASTER-K120S responses to master station without commands. And When operates as master,
 MASTER-K120S sends data in S1 with MODBUS protocol at rising edges of execution condition.

• S3 format is as below.



- NDR: when the communication ends normally, this bit turns on during 1 scan.
- Error bit: when communication error occurs, this bit turns on during 1 scan. At that time error code stores bit 8 ~ bit 15.
- Error code is as follow

| Code | Error type           | Meaning   |
|------|----------------------|---|
| 01   | Illegal Function     | Error in inputting function code in instruction.  |
| 02   | Illegal Address      | Error of exceeding the area limit of reading/writing on the slave station.  |
| 03   | Illegal Data Value   | Error when the data value to be read from or write on the slave station isn't allowed.  |
| 04   | Slave Device Failure | Error status of the slave station.  |
| 05   | Acknowledge          | It's a responding code of the slave station for the master station to prevent the master station time-out error, when request command processing takes time. The master station marks an error code and waits for a certain time without making any second request. |
| 06   | Slave Device Busy    | Error when request command processing takes too much time. The master should request again.   |
| 07   | Time Out             | Error when exceeds the time limit of the communication parameter as it communicates.  |
| 08   | Number Error         | Errors when data is 0 or more than 256 bytes  |
| 09   | Parameter Error      | Error of setting parameters (mode, master/ slave)   |
| 10   | Station Error        | Error when the station number of itself and the station number set by the S1 of instruction are the same.   |

#### Remark

-. In MASTER-K120S series, the 'MODBUS' command which has been used in MK80S series can be used. In this case, communication channel is fixed to channel 0.

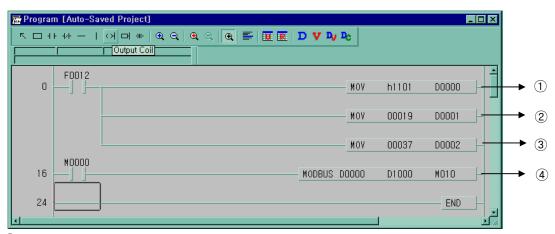
#### 2) Example program 1

It's supposed that MASTER-K120S main unit is the master and it reads Coil Status of the station no. 17, a Modicon product. The master reads status of the Coil  $00020 \sim 00056$  of the slave station no. 17. The Coil of the slave station is supposed to be as follows and the data that are read is saved in D1000

| Coil   | 59 | 58 | 57 | 56 | 55 | 54 | 53 | 52 | 51 | 50 | 49 | 48 | 47 | 46 | 45 | 44 | 43 | 42 | 41 | 40 |
|--------|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|----|
| Status | Χ  | Χ  | Χ  | 1  | 1  | 0  | 1  | 1  | 0  | 0  | 0  | 0  | 1  | 1  | 1  | 0  | 1  | 0  | 1  | 1  |
| Hex    |    |    | l  |    |    | E  | 3  |    |    | (  | )  |    |    | Е  | •  |    |    | Е  | 3  |    |
| Coil   | 39 | 38 | 37 | 36 | 35 | 34 | 33 | 32 | 31 | 30 | 29 | 28 | 27 | 26 | 25 | 24 | 23 | 22 | 21 | 20 |
| Status | 0  | 0  | 1  | 0  | 0  | 1  | 1  | 0  | 1  | 0  | 1  | 1  | 1  | 1  | 0  | 0  | 1  | 1  | 0  | 1  |
| Hex    |    | 2  | 2  |    |    | (  | ĵ  |    |    | Е  | 3  |    |    | (  |    |    |    |    | )  |    |

- The status of Coil 57, 58, 59 are redundancy.
- Data is sent starting from the low bit by byte unit. If the deficient bit of a byte is filled with 0. An example of sending the above data is as Following example 1.

Example 1) CD B2 0E 1B



- ① It designates slave station and function code (No. of station: h11(17), function code: h01)
- 2 Address setting
  - Address '0' at MODBUS protocol means address '1' actually .So if you want to designate address '20' , write address '19'
- ③ Reading number setting (Reading number is 37 from 20 to 56.)
- 4 This is MODBUS Communication instruction.
  - Data is sent starting from the low bit by byte unit. If the deficient bit of a byte is filled with 0. An example of sending the above data is as follows.
  - The data transmission starts lower byte. The remnant part of byte is filled with '0'
- ⑤ Stored data at D1000,D1001,D1002 are:

| Device | Stored data |
|--------|-------------|
| D1000  | h CD 6B     |
| D1001  | h B2 CE     |
| D1002  | h 00 1B     |

# 3) Example program 2

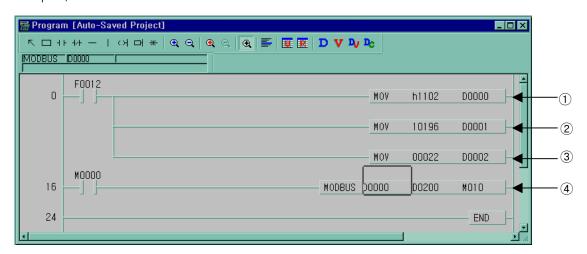
It's supposed that MASTER-K120S main unit is the master and it reads Coil Status of the station no. 17, a Modicon product. The master reads status of the input contact  $10197 \sim 10218$  of the slave station no. 17.

The input contact of the slave station is supposed to be as follows and the data that are read is saved in M015.

| Input  | 10220 | 10219 | 10218 | 10217 | 10216 | 10215 | 10214 | 10213 | 10212 | 10211 | 10210 | 10209 |
|--------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| Status | Χ     | Χ     | 1     | 1     | 0     | 1     | 0     | 1     | 1     | 1     | 0     | 1     |
| Hex    |       | 3     | 3     |       |       | ļ     | 5     |       | D     |       |       |       |
| Input  | 10208 | 10207 | 10206 | 10205 | 10204 | 10203 | 10202 | 10201 | 10200 | 10199 | 10198 | 10197 |
| Status | 1     | 0     | 1     | 1     | 1     | 0     | 1     | 0     | 1     | 1     | 0     | 0     |
| Hex    | В     |       |       |       | I     | 4     |       | C     |       |       |       |       |

- The status of input contact 10219,10220 are redundancy.
- Data is sent starting from the low bit by byte unit. If the deficient bit of a byte is filled with 0. An example of sending the
  above data is as follows.

Example 2) AC DB 35

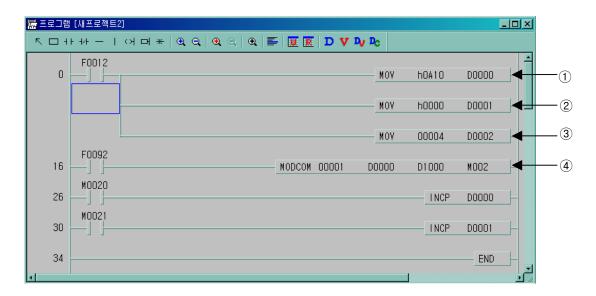


- ① : It designates slave station and function code (No. of station: h11(17), function code: h02)
- ② : Address setting Address '0' at MODBUS protocol means address '1' actually .So if you want to designate address '10197', write address '10196'
- ③ : Reading number setting ( Reading number is 22 from 10197 to 10220.)
- This is MODBUS Communication instruction.
   The data transmission starts lower byte. The remnant part of byte is filled with '0'
- ⑤ Stored data at D200,D201 are:

| Device | Stored data |
|--------|-------------|
| D200   | h AC DB     |
| D201   | h 00 35     |

#### 4) Example program 3

The master writes data D1000 ~ D1003 to contact 40000 of the slave station no. 10.

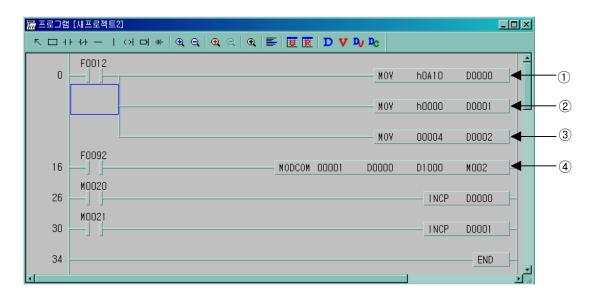


- ① : It designates slave station and function code (No. of station: h0A(10), function code: h10)
- ② : Address setting

  Address '0' of function code '16' at MODBUS protocol means address '40000' actually.
- ③ : Writing number setting (Writing number is 4)
- 4 : This is MODBUS Communication instruction.

#### 5) Example program 4

The master writes data in D1000 to contact 40000 of the slave station no. 10.



- ① : It designates slave station and function code ( No. of station : h0A(10) , function code : h06 )
- ②: Address setting

  Address '0' of function code '16' at MODBUS protocol means address '40000' actually.
- ③ : Writing number setting (Writing number is 1)
- (4): This is MODBUS Communication instruction.

#### 8.4 No Protocol Communication

#### 8.4.1 Introduction

No protocol communication is useful when communication between MASTER-K120S main unit and other kind of devices with user defined protocol is impossible. User defined protocol is very convenient when there are enough interval between frames or a kind of frame is less than 16. But, When the kind of frame is greater than 16 or frames are continued without interval, user defined protocol is not available.

When the kinds of frame are more than 16, they can't be registered in parameter area, therefore MASTER-K120s can't transfer these frames. Also, if there are no interval between frame, MASTER-K120S can't find end of frame.

To overcome these defects of user defined protocol, MASTER-K120S provide 'No Protocol Communication'.

In the No Protocol Communication, frames are designated by commands, not by parameter setting. So Max. 128 frames can be designated when using this communication mode. This section explains No protocol Communication setting & usage.

Sending Data



- Command: DSND
- Sends stored data in designated device at the rising edge of input condition.
- Data and the number of character must be stored in designated device before they are sent.
- Operands
  - (a) First operand Designates communication channel
  - (b) Second operand Number of data to sending (Unit of byte)
  - (c) Third operand Starting address of devices which stores sending data
  - (d) Fourth operand Device address which indicates communication status.

Receiving Data



- Command: DRCV
- Saves received data to pre-defined receiving devices when designated ending condition is occurs.
- The ending condition can be designated by following two kinds.
  - By number of character which is received.
  - By designated last byte. It is useful when there is no interval between received frames.
- Supports hexdecimal type.
- Operands
  - (a) First operand Designates communication channel
  - (b) Second operand Designates receiving format
  - (c) Third operand Starting address of devices which stores receiving data
  - (d) Fourth operand Device which indicates end of receiving

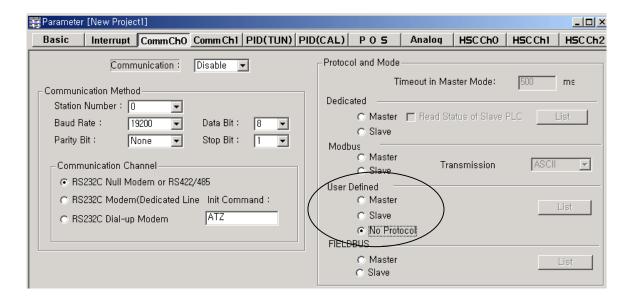
• Receiving format can be designated as below.

| Upper byte(hex)                   | Lower byte(hex)                                |
|-----------------------------------|--|
| H00(Receiving by Length of frame) | H03 (Receives when length of frame data is 3)  |
| H01(Receiving by last byte)       | H03 (Receives when last frame data is 03(ETX)) |

- When designated as length of frame : Stores received data to devices when number of received byte is equal to designated lower byte value of receiving format (setting range : 1~255)
- When designated last byte: Stores received data to devices when receives designated ending byte.

#### 8.4.2 Parameter setting

- 1) Setting Communications Parameter
  - (1) Open a new project file from KGLWIN and select MK120S as PLC type
  - (2) After selecting communication parameter at KGLWIN. Double click it to activate this window



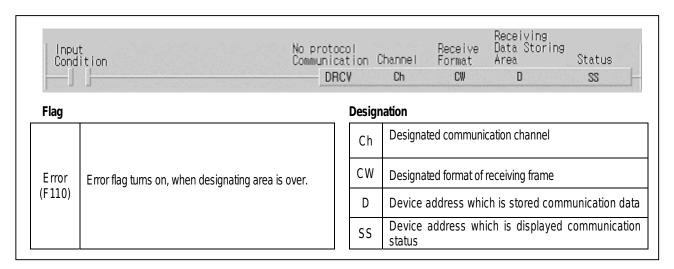
- (3) Set the communication methods and channel (Refer to Chapter 8.1.7 for details.)
- (4) Click 'No protocol', then parameter setting is finished

#### 8.4.3 Instructions

### 1) No protocol receive(DRCV)

| DRCV | No protocol receive |
|------|---------------------|
|------|---------------------|

|             | Available Device No. o |   |   |   |   |   |   |   |   | No. of | Flag    |      |                 |                 |                 |
|-------------|------------------------|---|---|---|---|---|---|---|---|--------|---------|------|-----------------|-----------------|-----------------|
| Instruction | М                      | Р | K | L | F | T | С | S | D | #D     | Integer | step | Error<br>(F110) | Zero<br>(F 111) | Carry<br>(F112) |
| Ch          |                        |   |   |   |   |   |   |   |   |        | 0       |      |                 |                 |                 |
| Cw          | 0                      | 0 | 0 | 0 | 0 | 0 | 0 |   | 0 | 0      | 0       | 9    |                 |                 |                 |
| D           | 0                      | 0 | 0 | 0 |   | 0 | 0 |   | 0 | 0      |         | 9    | 0               |                 |                 |
| SS          | 0                      | 0 | 0 | 0 |   | 0 | 0 |   | 0 | 0      |         |      |                 |                 |                 |



#### DRCV Ch Cw D SS

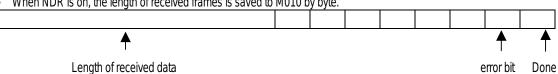
#### (1) Function

- When the execution condition is on, the communication starts with No protocol.
- Received data is stored in device 'D'
- If received data is not match to the designated format by 'Cw', data is not saved to 'D'
- The communication status is saved in 'SS'.

#### (2) Example program



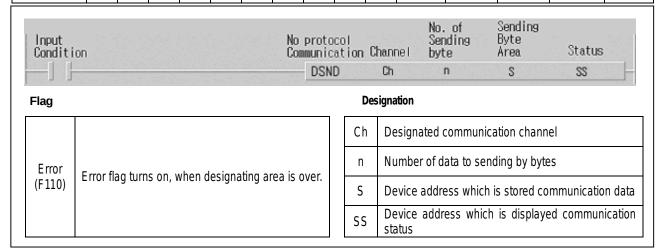
- When the execution condition M0000 is on, the communication starts with channel 1
- When 'EXT(h'03)' is received, Received frames are saved to D0100
- When NDR is on, the length of received frames is saved to M010 by byte.



#### 1) No protocol send(DSND)

| DSND | No protocol send |
|------|------------------|
|------|------------------|

|             | Available Device No. o |         |         |         |         |         |         |   |         | No. of  | Flag    |      |                 |                 |                 |
|-------------|------------------------|---------|---------|---------|---------|---------|---------|---|---------|---------|---------|------|-----------------|-----------------|-----------------|
| Instruction | M                      | Р       | K       | L       | F       | Т       | С       | S | D       | #D      | Integer | step | Error<br>(F110) | Zero<br>(F 111) | Carry<br>(F112) |
| Ch          |                        |         |         |         |         |         |         |   |         |         | 0       |      |                 |                 |                 |
| n           | $\circ$                | $\circ$ | $\circ$ | $\circ$ | $\circ$ | $\circ$ | $\circ$ |   | $\circ$ | $\circ$ | 0       | 9    |                 |                 |                 |
| S           | $\circ$                | 0       | $\circ$ | $\circ$ |         | $\circ$ | $\circ$ |   | 0       | $\circ$ |         | 9    |                 |                 |                 |
| SS          | 0                      | 0       | 0       | 0       |         | 0       | 0       |   | 0       | 0       |         |      |                 |                 |                 |



#### ■ DSND Ch n S SS

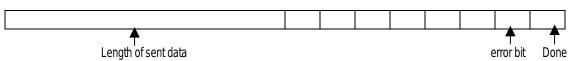
#### (1) Function

- When the execution condition is on, the No protocol communication starts
- 'n' represents the number of data to send (unit of byte) and Sending data is stored in device 'D'
- 'Ch' is designated communication channel and Communication status is saved in 'SS'.

#### (2) Example program



- When the execution condition P0040 is on, the communication starts with channel 1
- Length of sending data which is stored in D0100 is 10 byte and the communication status is stored in M000.

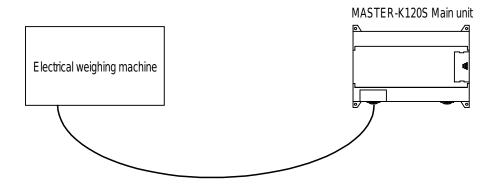


(3) Error code

| Code | Error             | Description                           |
|------|-------------------|---------------------------------------|
| 06   | Parameter Error   | Communication parameter setting error |
| 08   | Slave Device Busy | Slave device is busy                  |
| 09   | Frame Type Error  | Size of sending byte is out of range  |

# 8.4.4 Examples

Assume that a electrical weighing machine sends data which has unfixed size continuously. MASTER-K120S can communicates with it using no protocol.



For no protocol communication, one of following ending condition is designated. One is size of received data and the other is whether it has some pre-defined data.

In this example, assume that received data is as following.

"ENQ(1Byte) + Station No.(1Byte') + Data(1~10 Words) + EOT(1Byte)"

When above frame is received, Received framed is saved to designated device If designated 'Receiving Format(Cw)' is h0104. and decides if use these data or not. After that, sends data which is in sending device if required.

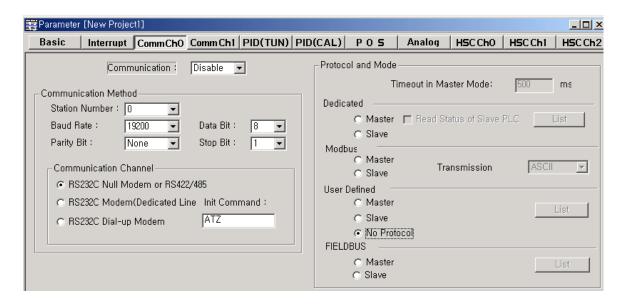
Assume that the sending data format is as following.

"ACK(1Byte) + Station No.(1Byte') + OK(2Bytes) + EOT(1Byte)"

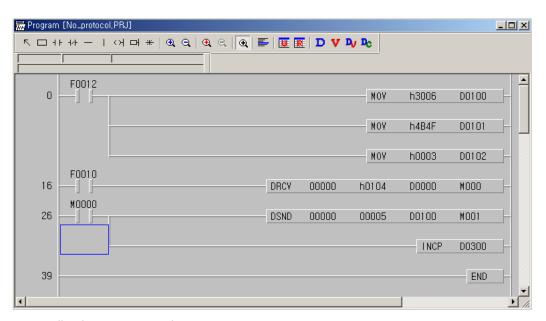
In this example the size of received data is 1 word.

### 1) Communication Parameter Setting

- Open a new project file from KGLWIN
  - K120S must be selected as PLC type.
- After selecting communication parameter from KGLWIN and clicking twice, this window comes up.
- Designate baud rate, data bit, parity bit, stop bit, and protocol.



#### 2) Program



- Save sending data to D0100 : "ack + 0 + OK + ETX"
  - If h'04(EOT) is received, h3004 is saved to D0000, and Weight data to D0111(1 Word)
  - Sending 5bytes in D0100 using DSND instruction

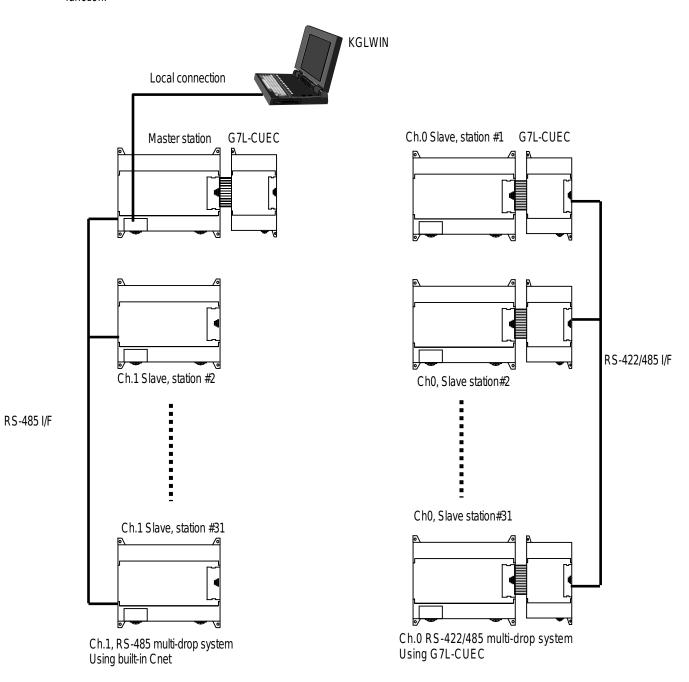
# 8.5 Remote connection and communication I/F module

#### 8.5.1 Remote connection

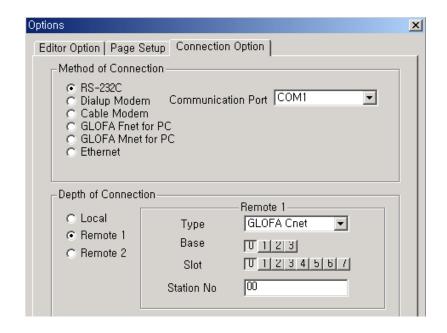
MASTER-K120S series can connect to other PLC by built-in Cnet interface or communication I/F modules.

#### 1) Remote connection by built-in Cnet I/F

Remote connection by built-in Cnet I/F is available by dedicated communication protocol only. If KGLWIN and Master station is connected physically, it can connect to each slave station using remote connection function.



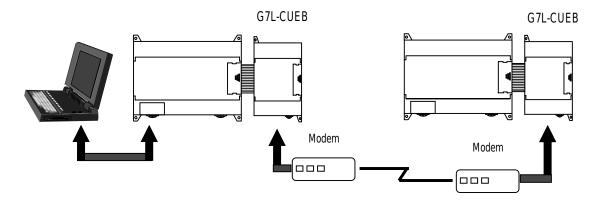
- Open a new project file from KGLWIN
- After selecting menu-project-option, click 'connection option'



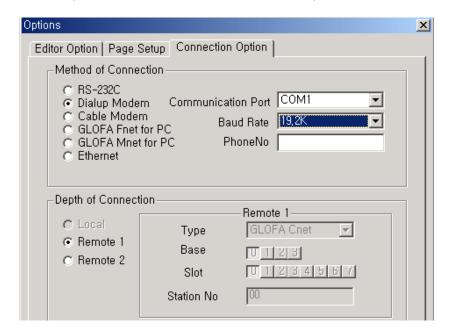
- Click 'Remote 1' in depth of connection
  - -. Type: Select GLOFA Cnet.
  - -. Base: Select '0'.
  - -. Clot: set to 0 when uses channel 0, and '1' when uses channel 1
  - -. Station No. : Input slave station number to connect
- Click 'OK'
- Remote connection is available by dedicated protocol only

### 2) Remote connection by modem

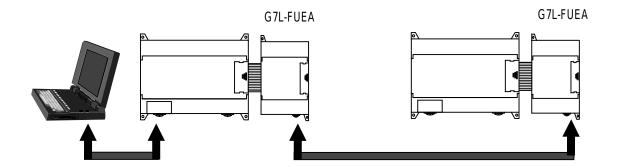
Remote connection by modem is available by G7L-CUEB I/F module. In this time, TM/TC switch of G7L-CUEB module must be set to 'On'.



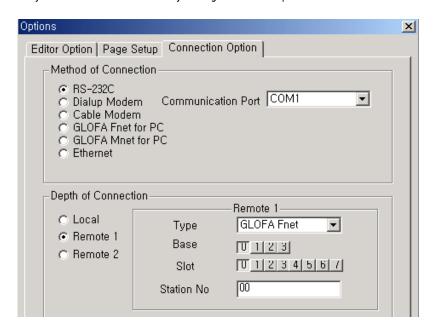
• Dedicated modem and dial-up modem are both available and Set connection option of KGLWIN as below.



3) Remote connection by Fnet I/F module



• Remote connection by Fnet interface is available by setting connection option of KGLWIN as below



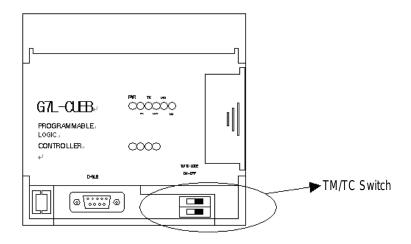
# 8.5.2 Communication I/F module

MASTER-K120S series supports various kinds of communication I/F module. In this time, Built-In Cnet in main unit must be set to 'Off' as below and only one communication module can be extended



# 1) Usage of G7L-CUEB

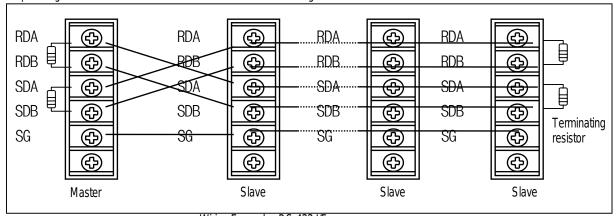
Using G7L-CUEB, MASTER-K120S can connect to other PLC by dedicated modem or dial-up modem



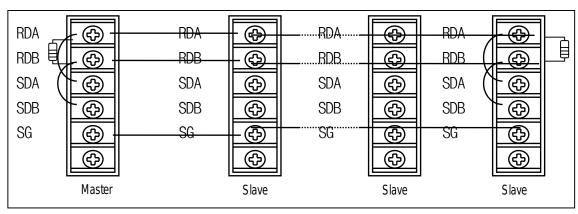
- Set TM/TC switch to 'On' when uses remote connection function
- Set TM/TC switch to 'Off' when uses data communication function
- Data communication and remote connection function are not allowed simultaneously
- Data communication mode supports every communication protocol but In remote connection function supports dedicated protocol only.

### 2) Usage of G7L-CUEC

Channel 0 can be used as RS-422/485 I/F by using G7L-CUEC I/F module Operating method is same as built-in Cnet interface and wiring is as below



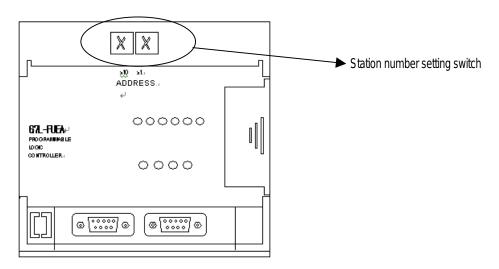
Wiring Example: RS-422 I/F



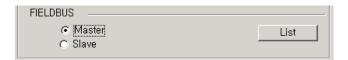
Wiring Example: RS-485 I/F

### 3) Usage of G7L-FUEA/RUEA

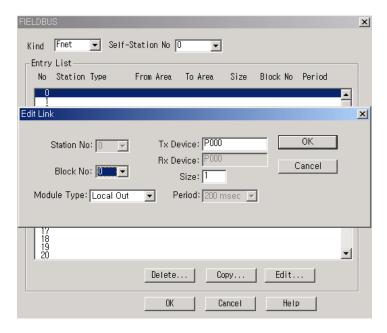
G7L-FUEA and G7L-RUEA are Field Bus Interface module of LGIS and they support High speed link communication service by parameter setting. But communication by command(Read, Write) are not available



• After selecting communication parameter from KGLWIN and select FIELDBUS MASTER as below



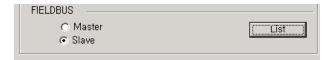
- Clicking List button then this window comes up.
- Designate self-station No. and set link items after double clicking entry list
- For the details, refer to User's manual of Fnet I/F module



### 4) Usage of G7L-PBEA/DBEA

G7L-PBEA support profibus slave function only and G7L-DBEAsupports DeviceNet slave interface function only.

• After selecting communication parameter from KGLWIN and select FIELDBUS slave as below



- Clicking List button then this window comes up.
- After double clicking entry list 0, designate from/to area
- Pnet For maximum Sending/Receiving data size is 244 byte and that of DeviceNet are 30/32 byte.
- For the details, refer to corresponding User's manual

