Vlad Sobal

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Education

PhD in Data Science, New York University

New York, NY

NYU Center for Data Science, advised by professors Yann LeCun and Kyunghyun Cho

Sep. 2019 - present

Working on representation learning, model-based planning, joint-embedding predciting architectures (JEPA).

BSc in Computer Science, University of Warsaw

Warsaw, Poland

Faculty of Mathematics, Informatics, and Mechanics

Oct. 2015 - May 2019

Thesis topic: Feature Space Augmentations for Object Classification and Detection.

Publications

• X-Sample Contrastive Loss: Improving Contrastive Learning with Sample Similarity Graphs Vlad Sobal, Mark Ibrahim, Randall Balestriero, Vivien Cabannes, Diane Bouchacourt, Pietro Astolfi, Kyunghyun Cho, Yann LeCun (The International Conference on Learning Representations 2025) https://arxiv.org/abs/2407.18134

- Hierarchical World Models as Visual Whole-Body Humanoid Controllers Nicklas Hansen, Jyothir S V, Vlad Sobal, Yann LeCun, Xiaolong Wang, Hao Su (The International Conference on Learning Representations 2025) https://arxiv.org/abs/2405.18418
- Gradient-based Planning with World Models
 Jyothir S V, Siddhartha Jalagam, Yann LeCun, Vlad Sobal
 (Generative Models for Decision Making Workshop at ICLR 2024)
 https://arxiv.org/abs/2312.17227
- A cookbook of self-supervised learning
 Randall Balestriero, Mark Ibrahim, Vlad Sobal et. al. (contributed a chapter on RL)
 (2023, ArXiV preprint)
 https://arxiv.org/abs/2304.12210
- Light-weight probing of unsupervised representations for reinforcement learning Wancong Zhang, Anthony GX-Chen, Vlad Sobal, Yann LeCun, Nicolas Carion (2023, Reinforcement Learning Conference 2024) https://arxiv.org/abs/2208.12345
- Joint embedding predictive architectures focus on slow features Vlad Sobal, Jyothir SV, Siddhartha Jalagam, Nicolas Carion, Kyunghyun Cho, Yann LeCun (Self-Supervised Learning Theory and Practice Workshop, NeurIPS 2022) https://arxiv.org/abs/2204.07184
- Separating the World and Ego Models for Self-Driving Vlad Sobal, Alfredo Canziani, Nicolas Carion, Kyunghyun Cho, Yann LeCun (Generalizable Policy Learning in the Physical World Workshop at ICLR 2022) https://arxiv.org/abs/2204.07184

Experience

Meta AI Research

October 2022 - October 2024

Visiting Researcher with Mikael Henaff and Yann LeCun

New York, NY

• Working on learning representations and world models for robotic manipulation tasks using joint-embedding predictive architectures (JEPAs).

NVIDIA

June 2021 - December 2021

Deep Learning Research Intern

Remote

• Applying joint-embedding methods to pre-train autonomous vehicles perception models.

NVIDIA May 2019 - August 2019

Software Engineering Intern with Autonomous Vehicles Perception team

Santa Clara, CA

- Contributed to C++ pipeline for intersection bounding box processing.
- Built a model to classify digital traffic signs.

Jane Street Europe

July 2018 - September 2018

Software Engineering Intern with Trading Systems team

London, UK

• Working on Jane Street trading systems' price processing pipeline built with OCaml.

NVIDIA
Software Engineering Intern with Autonomous Vehicles SDK team

March 2018 - June 2018 Santa Clara, CA

• Built a tool to monitor pipeline throughput for autonomous vehicle's sensor data.

NVIDIA October 2017 - March 2018

Software Engineering Intern with GPU Cloud team (NGC)

Santa Clara, CA

• Contributed to the front-end and back-end of communication system for GPU cluster (Python), making dataset upload up to 10 times faster.

Google July 2017 - October 2017

Software Engineering Intern with Google Ads team

Mountain View, CA

• Built a logs analysis pipeline for dynamically generated ads using Go.

Google July 2016 - September 2016

Software Engineering Intern with Google Maps for iOS team

Zurich, Switzerland

• Worked on permission notification system for Timeline feature of iOS app for Google Maps (Objective C).

Service

Reviewer: NeurIPS Goal-Conditioned RL workshop 2023, NeurIPS 2023, ICML 2023, ICLR 2024

Teaching Assistant: NYU Deep Learning class Spring 2021, Spring 2022

Volunteer: ICML 2022