

*Stochastic Simulation.
(and Gillespie's algorithm)*

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QUOTE OF THE DAY

D.T. GILLESPIE *Exact Stochastic Simulation of Coupled Chemical Reactions* J. OF PHYSICAL CHEMISTRY, 81(25), 1977

There are two formalisms for mathematically describing the time behavior of a spatially homogeneous chemical system: **the deterministic approach** regards the time evolution as a continuous, wholly predictable process which is governed by a set of coupled, ordinary differential equations (the “reaction-rate equations”); **the stochastic approach** regards the time evolution as a kind of random-walk process which is governed by a single differential-difference equation (the “master equation”). Fairly simple kinetic theory arguments show that the stochastic formulation of chemical kinetics has a firmer physical basis than the deterministic formulation, but unfortunately the stochastic master equation is often mathematically intractable. There is, however, a way to make exact numerical calculations within the framework of the stochastic formulation without having to deal with the master equation directly.
[...]

OUTLINE

1 STOCHASTIC PROCESSES

2 THE GILLESPIE ALGORITHM

EXPONENTIAL DISTRIBUTION

An **exponential distribution** models the **time of occurrence** of a (simple) random event.

It is given by a random variable T , with values in $[0, \infty)$, with density

$$f(t) = \lambda e^{-\lambda t},$$

where λ is the **rate** of the exponential distribution.

The probability of the event happening within time t is

$$P(T \leq t) = 1 - e^{-\lambda t}.$$

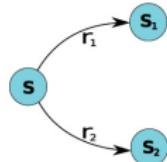
Mean: $E[T] = \frac{1}{\lambda}$

Variance: $VAR[T] = \frac{1}{\lambda^2}$

λ is the **average density of frequency of events per unit of time**.

CONTINUOUS TIME MARKOV CHAINS

What happens if we have more than one event competing?



In this case, there is a **race condition** between events: the fastest event is executed and modifies globally the state of the system.

CONTINUOUS TIME MARKOV CHAINS

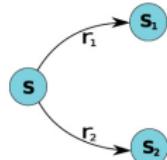
There is a discrete set of **states**, connected by **transitions** each with an associated **rate** of an exponential distribution.

In each state, transitions compete in a **race condition**: the fastest one determines the new state and the time elapsed.

In the new state, the race condition is started anew (**memoryless property**).

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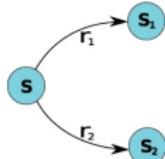
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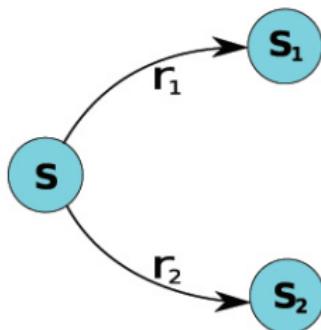
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EQUIVALENT CHARACTERIZATION

- In each state, we select the next state according to a *probability distribution* obtained **normalizing rates** (from S to S_1 with prob. $\frac{r_1}{r_1+r_2}$).
- The **time** spent in a state is given by an **exponentially distributed random variable**, with rate given by the *sum of outgoing transitions* from the actual node ($r_1 + r_2$).

STOCHASTIC MODEL OF A CHEMICAL SYSTEM

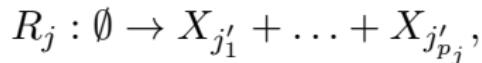
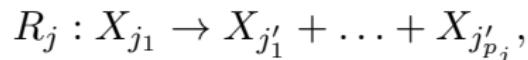
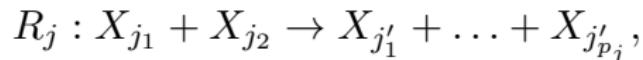
We have a set of chemical substances S_1, \dots, S_N contained in a volume V , with

$X_i =$ number of molecules of species i ,

subject to a set of chemical reactions

R_1, \dots, R_M ,

where each R_j is of the form



The system is supposed to be in **thermal equilibrium**

STOCHASTIC MODEL OF A CHEMICAL SYSTEM

KEY ASSUMPTION

Each reaction R_j has associated a specific **probability rate constant** c_j :

$c_j dt$ = probability that a randomly chosen combination of R_j reactant molecules inside V at time t will react according to R_j in the next infinitesimal time interval $[t, t + dt)$.

KEY OBSERVATION

The next reaction that will happen depends only on the current configuration of the system (number of molecules), not on past history (memoryless property).

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DERIVING KINETIC PARAMETERS

Let's focus on a bimolecular reaction...

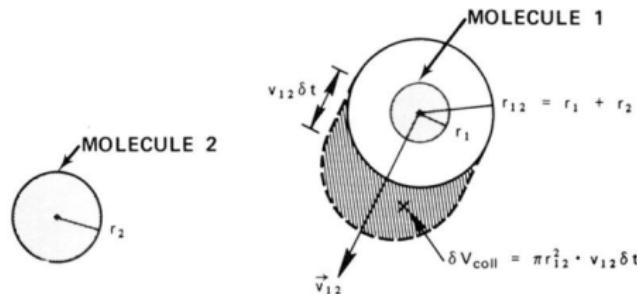


Figure 1. The “collision volume” δV_{coll} which molecule 1 will sweep out relative to molecule 2 in the next small time interval δt .

PROBLEM

“... it is *physically meaningless* to talk about “the number of molecules whose centers lie inside δV_{coll} ” in the required limit of vanishingly small δt”

THE STOCHASTIC MODEL

Under the hypothesis of **thermal equilibrium**, molecules are **uniformly distributed in space**, and velocities follow a Boltzmann distribution.

The collision volume swept *on average* is

$$\delta V = \pi r_{12}^2 \langle v_{12} \rangle \delta t.$$

The collision probability is therefore

$$\frac{\delta V}{V} = \frac{\pi r_{12}^2 \langle v_{12} \rangle \delta t}{V}.$$

THE STOCHASTIC MODEL

REACTION PROBABILITY

$p_j \stackrel{=}{\text{def}}$ probability that a *colliding* pair of R_j reactant molecules will chemically react according to R_j .

The basic rate of reaction c_j is therefore

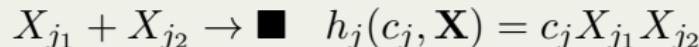
$$c_j = V^{-1} \pi r_{12}^2 \langle v_{12} \rangle p_j.$$

RATE FUNCTIONS

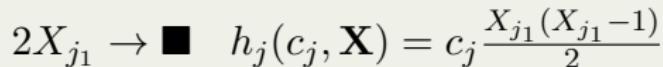
c_j gives the rate of reaction for a single pair of molecules involved in R_j .

To determine the global rate of reaction R_j , we need to count how many pairs of reacting molecules we have. We do this with the **rate function** $h_j(c_j, \mathbf{X})$.

REACTANTS OF DIFFERENT SPECIES



REACTANTS OF THE SAME SPECIES



CHEMICAL MASTER EQUATION

From rate functions, we can derive a differential equations saying how the probability of being in different states (of having different number of molecules) varies over time. It is called the **chemical master equation**:

$$\frac{dP(\mathbf{X}, t)}{dt} = \sum_{j=1}^M \left(\underbrace{h_j(c_j, \mathbf{X} - \nu_j) P(\mathbf{X} - \nu_j, t)}_{\text{A reaction } R_j \text{ happened in time } [t, t + dt]} - \underbrace{h_j(c_j, \mathbf{X}) P(\mathbf{X}, t)}_{\text{No reaction happened in } [t, t + dt]} \right)$$

PRO

This equation is *everything we need to know* about the stochastic process.

CONS

This equation is *very difficult to solve*, even numerically.

THE APPROACH OF GILLESPIE

The central notion becomes the following definition of **reaction probability density function**:

$P(\tau, j) \stackrel{=}{def}$ probability that, given the state $\mathbf{X} = (X_1, \dots, X_N)$ at time t , the *next* reaction in V will occur in the infinitesimal time interval $(t + \tau, t + \tau + dt)$, *and* will be an R_j reaction

THE APPROACH OF GILLESPIE

EXPLICIT FORM OF $P(\tau, j)$

$$P(\tau, j) = \underbrace{h_0(\mathbf{X})e^{-h_0(\mathbf{X})\tau}}_{\text{time elapsed}} \cdot \underbrace{\frac{h_j(c_j, \mathbf{X})}{h_0(\mathbf{X})}}_{\text{next reaction}}$$

INTUITIVELY...

The equation says that the next reaction is chosen with probability $\frac{h_j}{h_0}$, while the time elapsed to see this reaction happen is exponentially distributed with rate h_0 .

This stochastic process is a Continuous Time Markov Chain.

NUMERICALLY SIMULATING $P(\tau, \mu)$ NUMERICALLY SIMULATING $P(\tau, \mu)$

A random number generator can be used to draw random pairs (τ, μ) whose probability density function is $P(\tau, \mu)$.

Given r_1 and r_2 randomly generated, determine τ and μ such that:

$$\tau = (1/h_0) \log(1/r_1) \quad \sum_{\nu=1}^{j-1} h_\nu < r_2 h_0 \leq \sum_{\nu=1}^j h_\nu$$

THE METHOD

A general Monte Carlo technique called **inversion method**: x will be randomly drawn with probability density function $P(x)$ if $x = F^{-1}(r)$ with r randomly drawn with uniform probability density function in $[0, 1]$ and F is the probability distribution function ($\int_{-\infty}^x P(y)dy$).

THE ALGORITHM

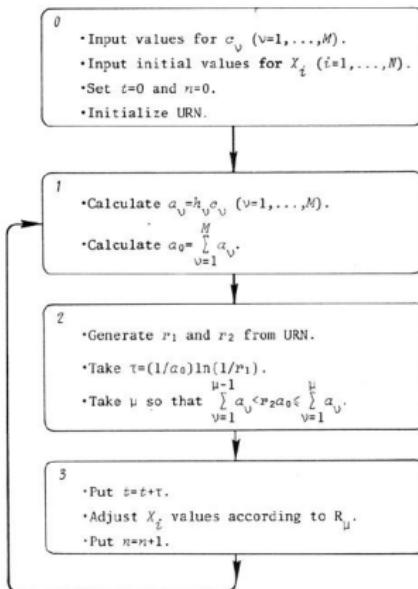
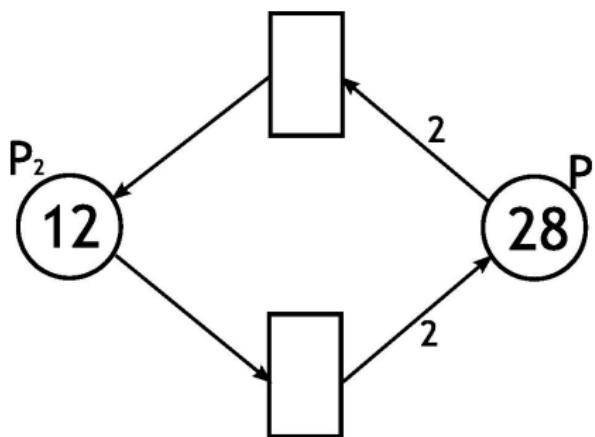


Figure 2. Schematic of the stochastic simulation algorithm.

GILLESPIE ALGORITHM AND PETRI NETS



$$2P \leftrightarrow P_2$$

$$h_1(1, \mathbf{X}) = 1 * (27 * 28) / 2 = 378$$

$$h_2(2, \mathbf{X}) = 2 * 12 = 24$$

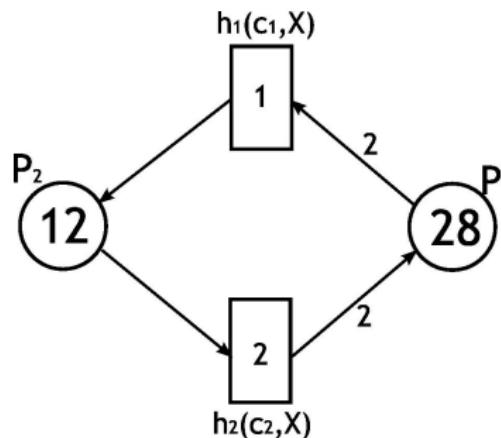
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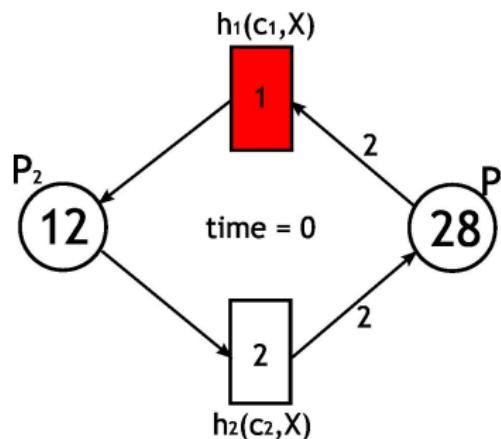
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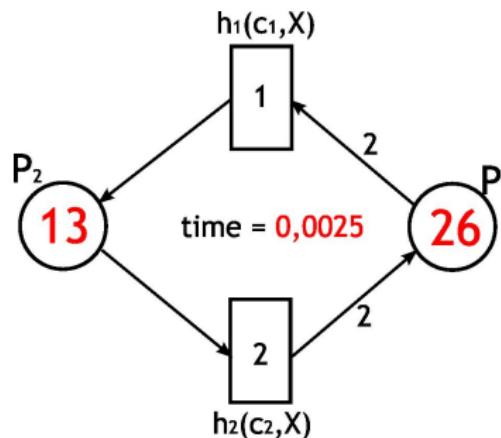
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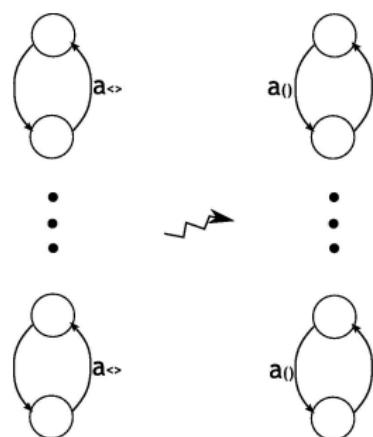
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GILLESPIE ALGORITHM AND π -CALCULUS

Each channel has a **basic rate λ** associated to it.

The global rate of a channel depends on how many agents are ready to communicate on it.

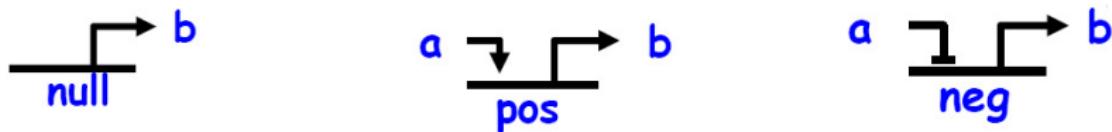
In this example:

$$\lambda MN$$

The functions h_i are determined implicitly by the semantics of the language. **Gillespie can be used to simulate stochastic π -calculus as well!!!**

AN EXAMPLE: GENETIC REGULATORY NETWORKS

Genes as logical gates



Repressilator

