view_frames Result Recorded at time: 1650441136.026 base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1650441136.026 sec old) Most recent transform: 0.000 (1650441136.026 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec base_link_inertia base Broadcaster: /ur_hardware_interface Broadcaster: /robot_state_publisher Average rate: 125.001 Hz Average rate: 41.870 Hz Most recent transform: 1650441135.991 (0.035 sec old) Most recent transform: 1650441136.015 (0.011 sec old) Buffer length: 4.952 sec Buffer length: 4.920 sec shoulder_link tool0_controller Broadcaster: /robot_state_publisher Average rate: 41.870 Hz Most recent transform: 1650441135.991 (0.035 sec old) Buffer length: 4.920 sec upper_arm_link Broadcaster: /robot_state_publisher Average rate: 41.870 Hz Most recent transform: 1650441135.991 (0.035 sec old) Buffer length: 4.920 sec forearm_link Broadcaster: /robot_state_publisher Average rate: 41.870 Hz Most recent transform: 1650441135.991 (0.035 sec old) Buffer length: 4.920 sec wrist_1_link Broadcaster: /robot_state_publisher Average rate: 41.870 Hz Most recent transform: 1650441135.991 (0.035 sec old) Buffer length: 4.920 sec wrist_2_link Broadcaster: /robot_state_publisher Average rate: 41.870 Hz Most recent transform: 1650441135.991 (0.035 sec old) Buffer length: 4.920 sec wrist_3_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1650441136.026 sec old) Buffer length: 0.000 sec flange Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1650441136.026 sec old) Buffer length: 0.000 sec tool0