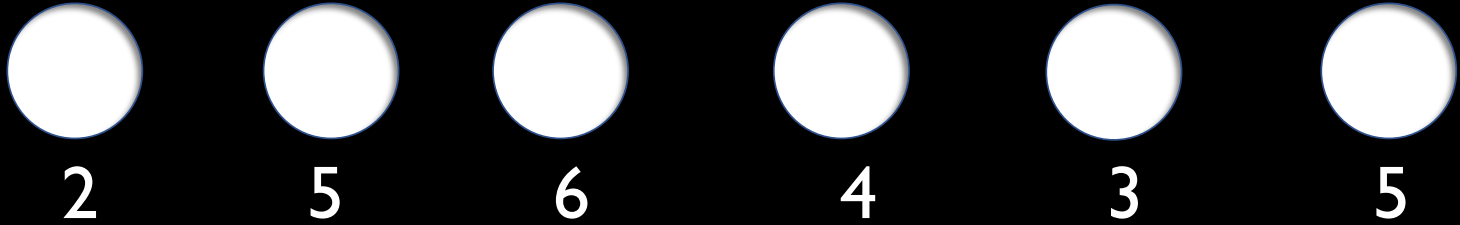


Algorithm Design and Analysis

Dynamic Programming I

8/2/2022

The First Example



Input : A set of balls arranged in a row ; each ball has a weight

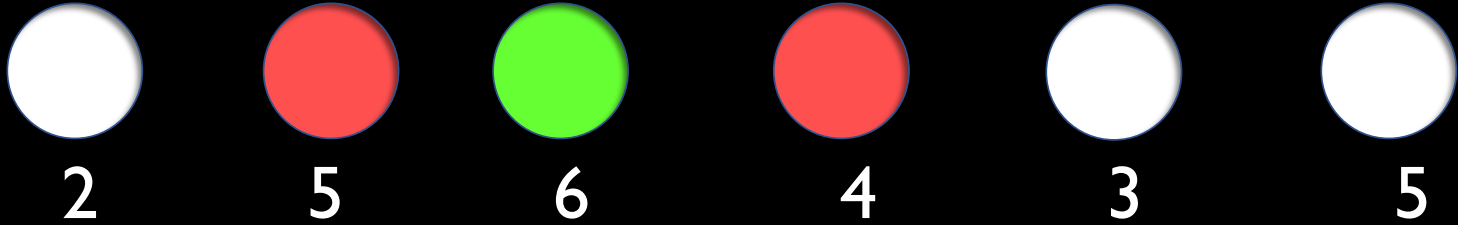
Output : Pick balls of maximum possible total weight ; No two adjacent balls can be picked

The First Example :An Intuitive ‘Greedy’ Approach



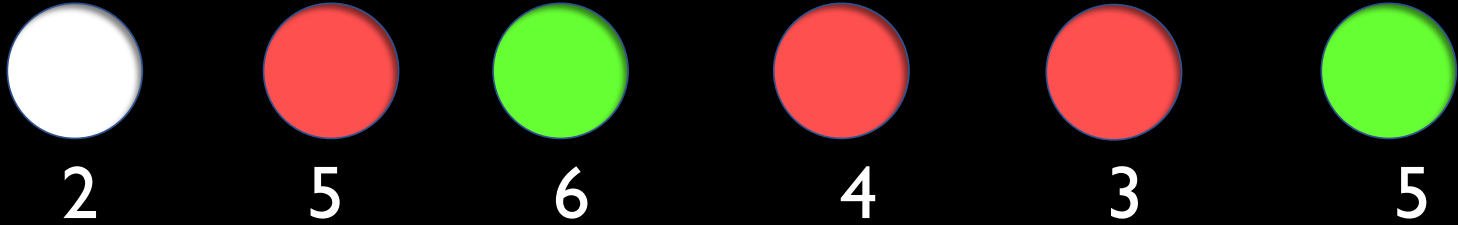
Attempt 1 : Pick the ball of maximum weight unless you have picked its neighbors and continue...

The First Example :An Intuitive ‘Greedy’ Approach



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The First Example :An Intuitive ‘Greedy’ Approach

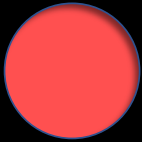


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The First Example :An Intuitive 'Greedy' Approach



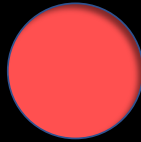
2



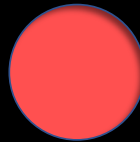
5



6



4



3

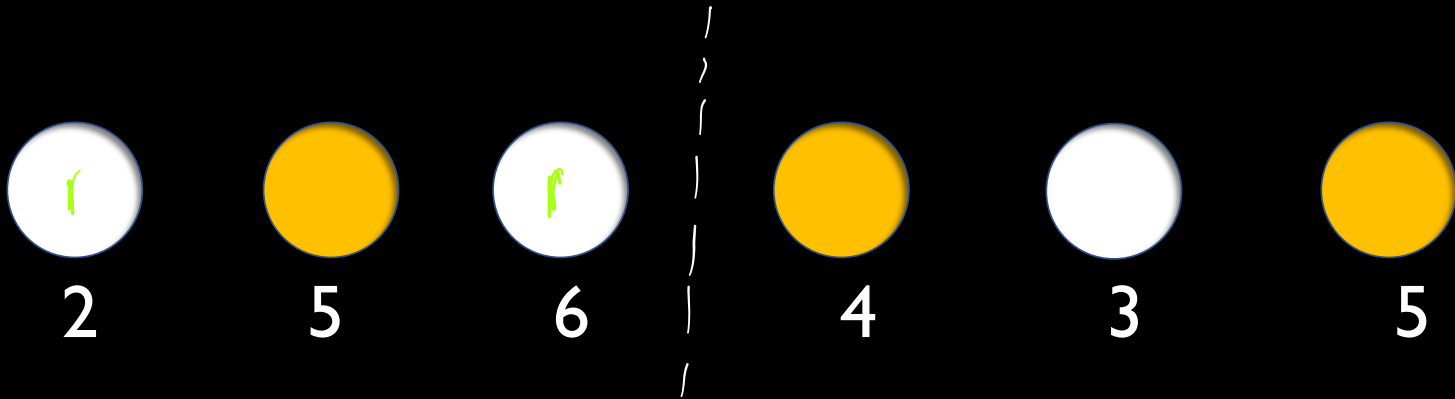


5

Attempt 1 : Pick the ball of maximum weight unless you have picked its neighbors and continue

Total weight of greedy solution = $11 + 2 = 13$.

The First Example :An Intuitive 'Greedy' Approach



Attempt 1 : Pick the ball of maximum weight unless you have picked its neighbors and continue

Total weight of greedy solution = ~~14~~ 13

But optimal solution is = 14

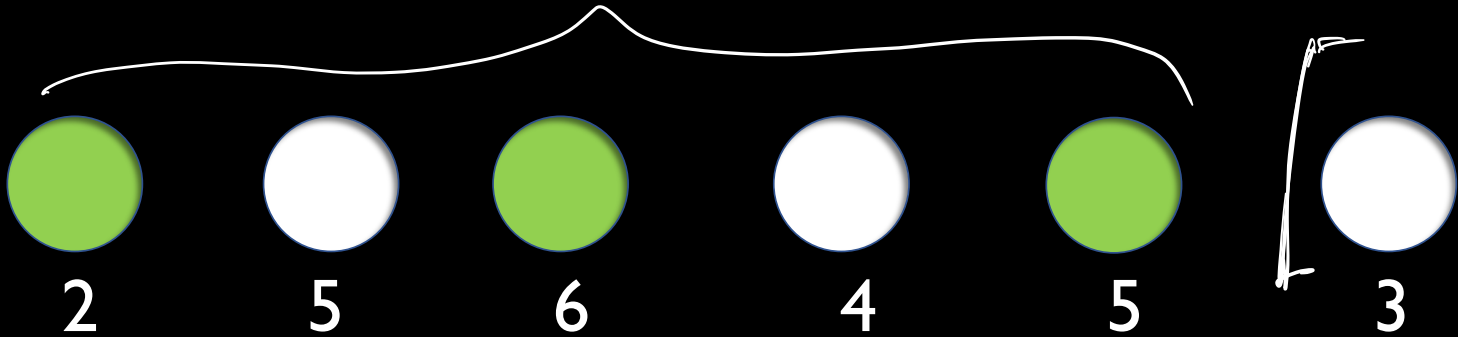
$$T(n) = 4 T(n/2) \\ O(n^2)$$

A Recursive approach

Recap:

A **recursive algorithm** is one which solves a problem by invoking itself repeatedly on inputs of strictly smaller sizes until the size is so small that one can solve it trivially

Understanding the Optimal Solution

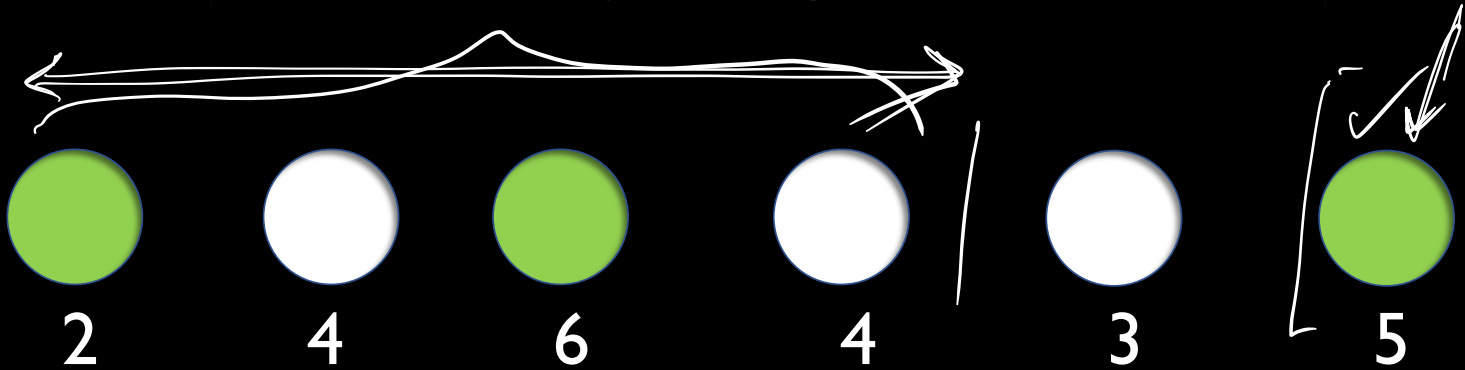


Observation 1:

If Last ball is not part of the optimal solution, then

Optimal solution = Optimal solution with the last ball removed from input
(a strictly smaller input !!)

Understanding the Optimal Solution



Observation 2:

If Last ball is part of the optimal solution
So, second last ball cannot be !

If not true $\Rightarrow \exists$ another
optimal solution with
value $> \text{opt}[i] - \text{weight}(i)$

Optimal solution to the original problem = Optimal solution to the problem
without last two balls (a strictly smaller solution) + weight of last ball

Formal Recurrence

$\text{opt}[i]$: The optimal solution with balls $\{b_1, b_2, \dots, b_i\}$ [Subproblem defn]
 $\forall i = 0, 1, 2, \dots, n$

$\text{opt}[0] = 0$; $\text{opt}[1] = \text{weight}(1)$.

$$\text{opt}[i] = \max \begin{cases} \text{opt}[i-1] & \text{Case I} \\ \text{opt}[i-2] + \text{weight}(i) & \text{Case II} \end{cases}$$

Claim (Case II):

Proof: Optimal solution for b_1, b_2, \dots, b_i with b_i removed IS an optimal solⁿ for b_1, b_2, \dots, b_{i-2}

Suppose this is not true. $\text{opt}[i-2] = \text{opt}[i] - \text{weight}(i)$

Towards an Algorithm

Upshot : The optimal solution for balls b_1, b_2, \dots, b_n can look **only two different ways** –

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Trouble : We do not know the optimal solution So, we do not know which option to take !

Way out : Try both and take the best

A Recursive Algorithm

SelectBalls (b_1, b_2, \dots, b_n, n)

If $n == 1$, return b_1 Else If $n == 0$,
return 0 Else

$$w_1 = \text{SelectBalls}(\underline{b_1, b_2, \dots, b_{n-1}}, n - 1)$$

$$w_2 = \text{SelectBalls}(\underline{b_1, b_2, \dots, b_{n-2}}, n - 2) \\ + \text{weight of } b_n$$

Return $\max\{w_1, w_2\}$

Runtime:

$$\left. \begin{aligned} T(n) &= T(n-1) \\ &\quad + T(n-2) + c. \end{aligned} \right\}$$

$$T(0) = 1; T(1) = 1.$$

A Recursive Algorithm : Runtime

SelectBalls (b_1, b_2, \dots, b_n, n)

If $n == 1$, return b_1 Else

$w_1 = \text{SelectBalls}(b_1, b_2, \dots, b_{n-1}, n - 1)$

$w_2 = \text{SelectBalls}(b_1, b_2, \dots, b_{n-2}, n - 2)$
+ weight of b_n

Return $\max\{w_1, w_2\}$

$$T(n) = T(n - 1) + T(n - 2) + c$$

A Recursive Algorithm : Runtime

SelectBalls (b_1, b_2, \dots, b_n, n)

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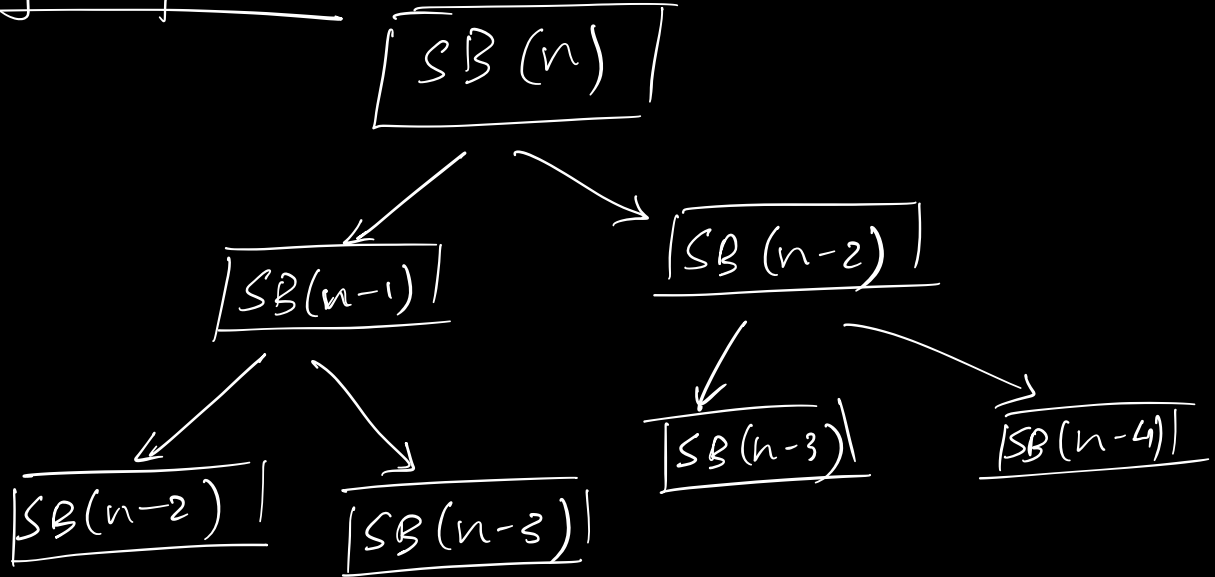
Return $\max\{w_1, w_2\}$

$$T(n) = T(n - 1) + T(n - 2) + c$$

$$T(n) = \frac{1}{\sqrt{5}} \left(\frac{1 + \sqrt{5}}{2} \right)^n - \frac{1}{\sqrt{5}} \left(\frac{1 - \sqrt{5}}{2} \right)^n$$

Why is the Runtime So Horrible ?

Overlapping Subproblems



The MOST important insight

Question : How many distinct recursive subproblems is this algorithm really solving ?

Answer : n

The MOST important insight

Question : How many distinct recursive subproblems is this algorithm really solving ?

Answer : n

Obvious Fix : Cache already computed subproblem values in an array and look them up in $O(1)$ time if available ; otherwise recurse [memo(r?!)ization]

Eliminating Redundancy

Tab : Array of size $n \rightarrow$ Memoization Table

SelectBalls ($b_1, b_2, \dots b_n$)

If Tab[n] is valid return Tab[n] else

Tab[i]

If $n==0$, Tab[n]= 0 Else If

If $n==1$, Tab[n]= weight of b_1 Else

$w_1 = \text{SelectBalls}(b_1, b_2, \dots b_{n-1})$

$w_2 = \text{SelectBalls}(b_1, b_2, \dots b_{n-2}) + \text{weight of } b_n$

Tab[n] = $\max\{w_1, w_2\}$

A Linear Time Iterative Solution

Tab : Array of size $n + 1$

SelectBalls (b_1, b_2, \dots, b_n)

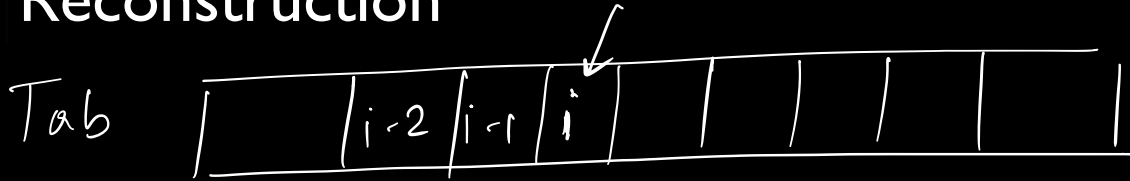
$$\text{Tab}[0] = 0; \text{Tab}[1] = b_1$$

for $i = 2, 3, \dots, n$

$$\text{Tab}[i] = \max \begin{cases} \text{Tab}[i-1] \\ \text{Tab}[i-2] + \text{weight}(b_i) \end{cases}$$

Return $\text{Tab}[n]$

Reconstruction



Obvious:- Maintain the 'solution' for each entry.

Better:- Use the already computed Tab.

Key Point:-

Ball i
is selected



$$\text{Tab}[i] = \text{Tab}[i-2] + \text{weight}(i)$$

Reconstruction

Reconstruct(Tab)

$S : \emptyset$ [store the balls]

$i = n$

while $i \geq 1$

if $\text{Tab}[i] = \text{Tab}[i-2] + \text{weight}(b_i)$ ✓

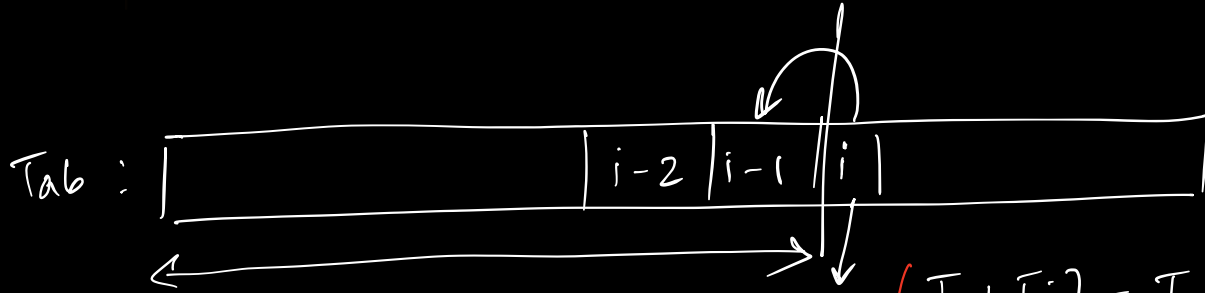
add i to S

decrement i by 2.

else dec. i by 1.

Return S .

Reconstruction



✓ ~~✓~~ $\text{Tab}[i] = \text{Tab}[i-2] + \text{weight}(b_i)$

✓ $\text{Tab}[i] = ? \text{Tab}[i-1]$

