Introduction to Reinforcement Learning

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Paradigms of Machine Learning

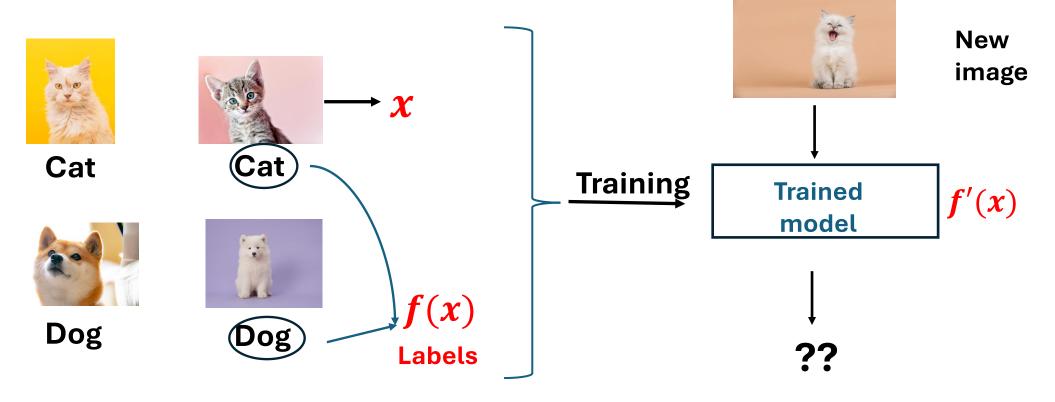
Supervised Learning

Unsupervised Learning

Reinforcement Learning

Supervised Learning

Labeled Training Data



Unsupervised Learning

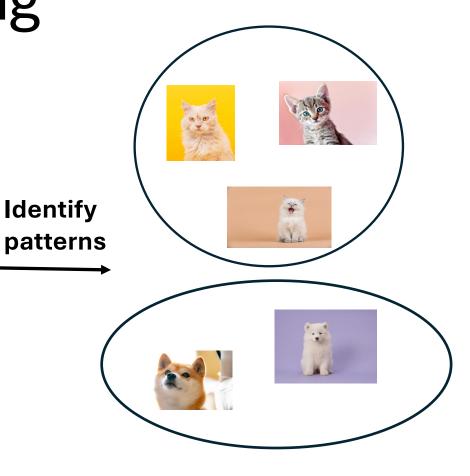
Unlabeled Data





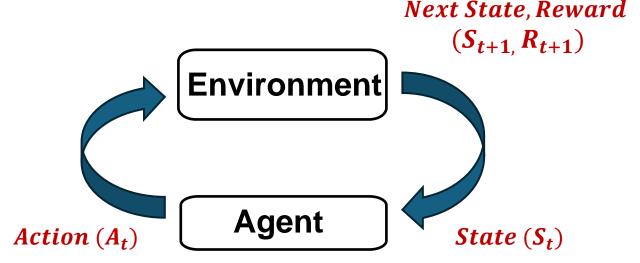






Reinforcement Learning





- 1. Agent observes the state and takes action
- 2. Environment puts the agent in a new state &
- 3. Gives a reward based on the action taken

GOAL: Learn policy to maximize the cumulative reward $\sum_{r} R_{r}$

Paradigms of Machine Learning

- Supervised Learning
 - Fitting a function for the given labeled data (x, y)
 - $y \approx f(x)$
- Unsupervised Learning
 - Identifying patterns in unlabeled data
 - E.g. Clustering

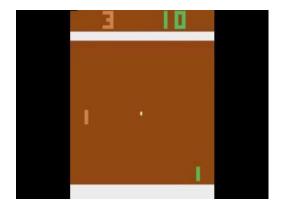
- Reinforcement Learning
 - Learning sequential tasks through trial and error
 - Feedback through reward/penalty

RL Demonstrations

Autonomous Helicopter



Pong game



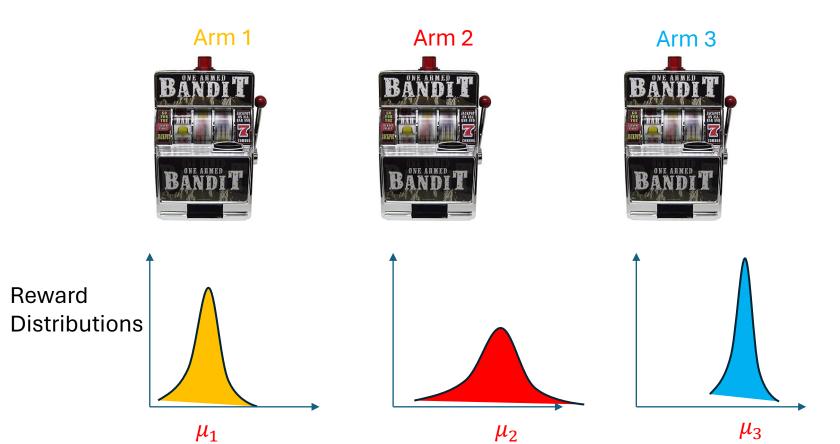
AlphaGo by DeepMind



One State RL: Multi-arm Bandits

- Simplified version of RL problem: "Multi-arm Bandit" problem.
 - Only one state
 - Multiple actions (a.k.a. arms)
 - \mathcal{A} Action set
- A reward distribution corresponding to each arm
 - \mathcal{R}_a Reward distrution for action a
 - $\mu_a = \mathbb{E}[\mathcal{R}_a]$ Expected reward for action a
- Applications: Recommendation systems, Ad placement, ...

Multi-arm Bandits



Problem:

- Reward distributions are unknown
- Given **T chances** to pull the arms
- Which arms should be pulled to maximize the total reward in those T rounds

Exploration
Vs
Exploitation dilemma

ETC (Explore-Then-Commit)

- **1. Explore:** Play each arm *N* times
- 2. Compute the sample average rewards $\bar{\mu}(a) = \frac{1}{N} \sum_{t=1}^{KN} R_t \ 1\{a_t = a\}$ for each arm $a \in \mathcal{A}$
- 3. Commit: Play the arm with the highest sample average for the remaining T KN rounds

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u^* - Optimal arm's expected reward R_t - Sample reward obtained in round t
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 a_t - Arm played in round t - Total number of rounds

K - Number of arms

Performance (ETC Vs Best possible reward): $T\mu^* - \sum_{t=1}^T \mathbb{E}[R_t]$ How much to Explore? $N \approx (\frac{T}{K})^{\frac{2}{3}}$

ϵ -Greedy (Explore uniformly)

- 1. Play each arm once
- 2. In each round t:
 - Toss a coin with bias ϵ .
 - If it lands in head: Explore Play any arm randomly
 - Else: Exploit Play the arm with the highest sample average so far

What
$$\epsilon$$
 to choose? $\epsilon \approx (\frac{K}{T})^{\frac{1}{3}}$

UCB (Upper Confidence Bound)

Optimism under UnCertainty

- 1. Play each arm once in the first K rounds
- 2. For t > K:
 - Play the arm with the highest $UCB_t(a) = \overline{\mu_{t-1}}(a) + \sqrt{\frac{2 \log T}{n_{t-1}(a)}}$
 - Based on the observed sample reward R_t , update $n_t(a_t)$ and $\overline{\mu_t}(a_t)$
 - $n_t(a_t) = n_{t-1}(a_t) + 1$
 - $\overline{\mu_t}(a_t) = \frac{1}{n_t(a_t)} [(n_t(a_t) 1) \overline{\mu_{t-1}}(a_t) + R_t]$

Exploit: High sample reward arms are favoured

Explore: Least played arms are favoured

Explore

Exploit

Contextual Bandits – Multiple states

News article Recommendation systems



- Articles arms
- Like / Dislike Reward
- User State

Different users have different preferences to articles