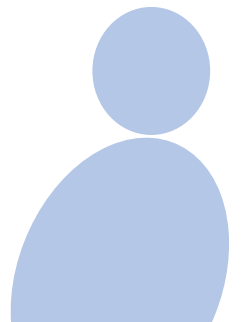


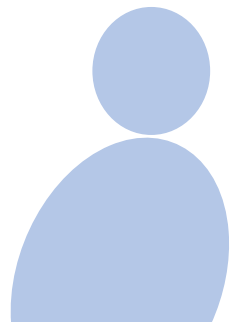
eMasters in Communication Systems

**Prof. Aditya
Jagannatham**



Elective Module:

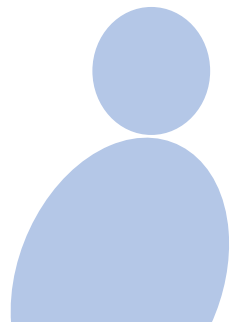
**Estimation for Wireless
Communication**



Chapter 2

Most
important!!

Channel Estimation



Wireless System Model

- The wireless system can be modeled as follows

$$y = hx + v$$

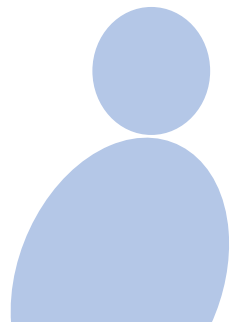
- h = Channel coefficient
- x = Transmit symbol
- y = Received symbol n = noise

output symbol.

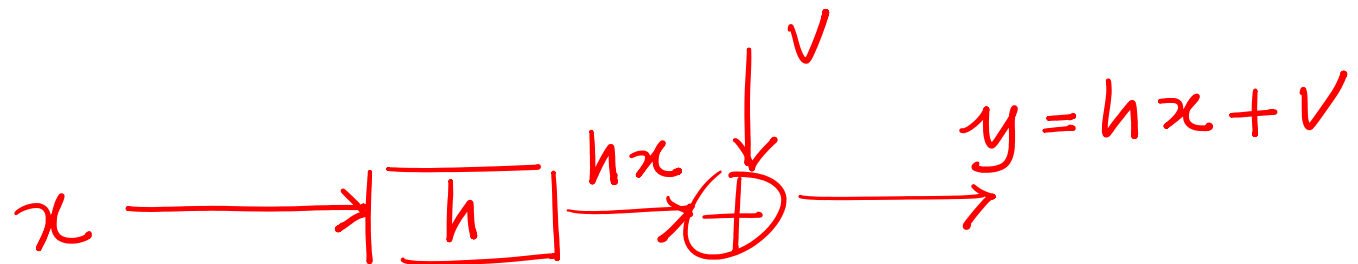
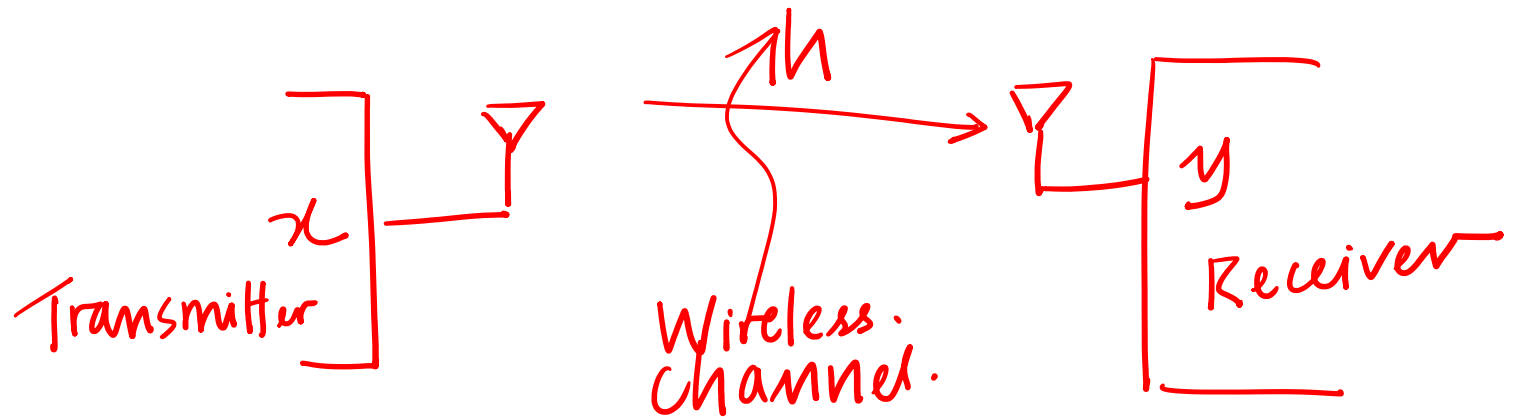
Transmit/input symbol.

Noise

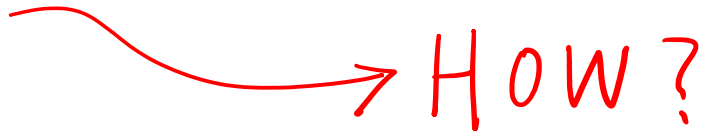
channel coefficient is Necessary for decoding at Receiver

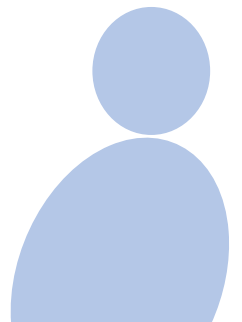


Wireless System Schematic



Wireless System Model

- The channel coefficient h is unknown
- Estimating this is termed channel estimation.  *HOW?*



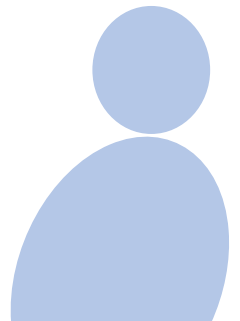
Wireless System Model

- This is achieved via transmission of training or pilot symbols

Fixed Symbols
Purely for the
purpose of
channel Est.

$$x(1), x(2), \dots, x(N)$$

Training symbols.
Pilots

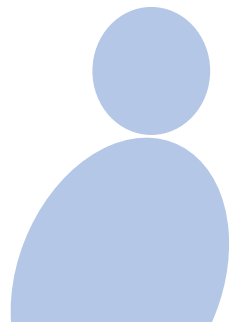


Wireless System Model

- **Pilot symbols** are transmitted purely for the purpose of **channel estimation**.

Fixed
symbols

Predetermined
known



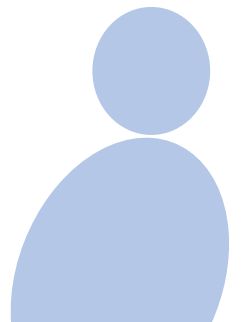
Wireless System Model

- The corresponding outputs are given as

$$y(1) = hx(1) + v(1)$$

$$y(2) = hx(2) + v(2)$$

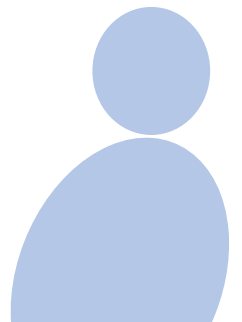
$$\vdots$$
$$y(N) = hx(N) + v(N).$$



Wireless System Model

- The corresponding outputs are given as

$$\text{Outputs} \cdot \begin{cases} y(1) = hx(1) + v(1) \\ y(2) = hx(2) + v(2) \\ \vdots \\ y(N) = hx(N) + v(N) \end{cases}$$



Wireless System Model

$$\bar{y} = \begin{bmatrix} y(1) \\ y(2) \\ \vdots \\ y(N) \end{bmatrix} \sim N \times 1$$

Output Vector

$$\bar{x} = \begin{bmatrix} x(1) \\ x(2) \\ \vdots \\ x(N) \end{bmatrix} \sim N \times 1$$

Pilot Vector

$$x(1), x(2), \dots, x(N)$$

Pilot Symbols

$$y(1), y(2), \dots, y(N)$$

Outputs.

Wireless System Model

- Consider now the k^{th} observation

$$y(k) = hx(k) + v(k)$$

$N(hx(k), \sigma^2)$
Gaussian
Mean = $hx(k)$
Var = σ^2

Gaussian
Mean = 0
Var = σ^2
 $N(0, \sigma^2)$

- PDF of $y(k)$ is given as follows

$$f_{Y(k)}(y(k)) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y(k) - hx(k))^2}{2\sigma^2}}$$

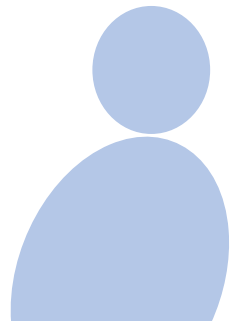
PDF of $y(k)$.

Wireless System Model

$$y(k) = hx(k) + v(k)$$

- Observe $y(k)$ is Gaussian with mean $hx(k)$ variance σ^2

- Hence, PDF is
- $$\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2} (y(k) - hx(k))^2}$$

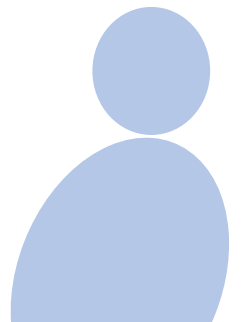


Wireless System Model

$$y(k) = hx(k) + v(k)$$

- Observe $y(k)$ is Gaussian with mean $hx(k)$ variance σ^2
- Hence, PDF is

$$\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y(k)-hx(k))^2}{2\sigma^2}}$$



Wireless System Model

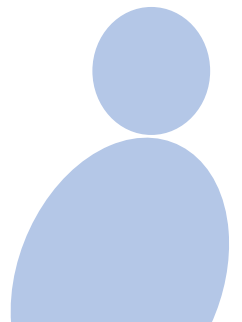
Noise samples i.i.d.

- Joint PDF of observations is

$$= f_{Y(1)}(y(1)) \times \dots \times f_{Y(N)}(y(N))$$

$$= \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(y(1)-hx(1))^2} \times \dots \times \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(y(N)-hx(N))^2}$$

Joint PDF

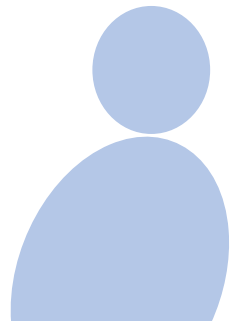


Wireless System Model

- Joint PDF of observations is

$$\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y(1)-hx(1))^2}{2\sigma^2}} \times \dots \times \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y(N)-hx(N))^2}{2\sigma^2}}$$

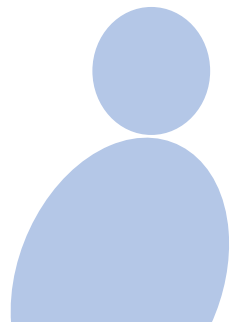
Multiplication of individual PDFs.



Wireless System Model

- Joint PDF of observations is

$$f_{\bar{Y}}(\bar{y}) = \left(\frac{1}{\sqrt{2\pi\sigma^2}} \right)^N e^{-\frac{1}{2\sigma^2} \sum_{k=1}^N (y(k) - h x(k))^2}$$



Wireless System Model

- Joint PDF of observations is

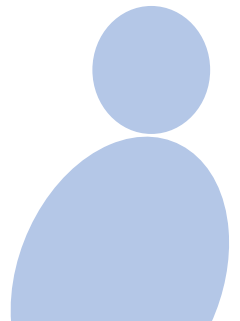
$$\left(\frac{1}{\sqrt{2\pi\sigma^2}} \right)^N e^{-\frac{1}{2\sigma^2} \sum_{k=1}^N (y(k) - hx(k))^2}$$

Likelihood as a function of h

$p(\bar{y}; h)$

To compute Estimate of h
maximize Likelihood.

This is MLE.



Wireless System Model

- This is the likelihood $p(\bar{y}; h)$

$$p(\bar{y}; h) = \left(\frac{1}{\sqrt{2\pi\sigma^2}} \right)^N e^{-\frac{1}{2\sigma^2} \sum_{k=1}^N (y(k) - hx(k))^2}$$

Handwritten notes: "constant" points to the term $\left(\frac{1}{\sqrt{2\pi\sigma^2}} \right)^N$; "-ve constant minimize" points to the term $e^{-\frac{1}{2\sigma^2} \sum_{k=1}^N (y(k) - hx(k))^2}$; "minimize" points to the sum $\sum_{k=1}^N (y(k) - hx(k))^2$.

- To maximize the likelihood, minimize

$$\equiv \sum_{k=1}^N (y(k) - hx(k))^2$$

Handwritten notes: An arrow points from the \equiv symbol to the text "Equivalent Cost Function."

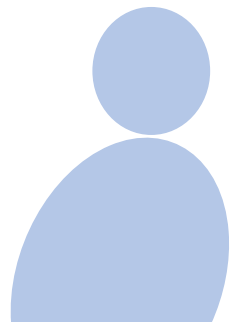
Wireless System Model

- This is the likelihood $p(\bar{\mathbf{y}}; h)$

$$p(\bar{\mathbf{y}}; h) = \left(\frac{1}{\sqrt{2\pi\sigma^2}} \right)^N e^{-\frac{1}{2\sigma^2} \sum_{k=1}^N (y(k) - hx(k))^2}$$

- To maximize the likelihood, minimize

$$\sum_{k=1}^N (y(k) - hx(k))^2$$



Wireless System Model

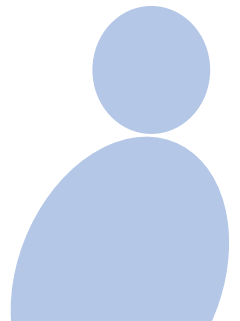
- This can be achieved as follows

Take derivative wrto h
& set equal to 0.

$$\frac{d}{dh} \sum_{k=1}^N (y(k) - h x(k))^2 = 0$$

$$\Rightarrow \sum_{k=1}^N \cancel{x(k)} (y(k) - h x(k)) (-x(k)) = 0$$

$$\Rightarrow \sum_{k=1}^N y(k) x(k) = \sum_{k=1}^N h x^2(k)$$



Wireless System Model

$$\Rightarrow \hat{h} = \frac{\sum_{k=1}^N y(k) x(k)}{\sum_{k=1}^N x^2(k)}$$

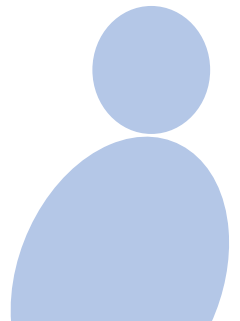
inner product $\bar{x}^T \bar{y}$

$\|\bar{x}\|^2$

MLE
Maximum Likelihood Estimate

Channel
Estimate

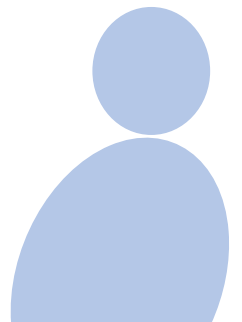
$$\hat{h} = \frac{\bar{x}^T \bar{y}}{\bar{x}^T \bar{x}} = \frac{\bar{x}^T \bar{y}}{\|\bar{x}\|^2}$$



Wireless System Model

- This can be achieved as follows

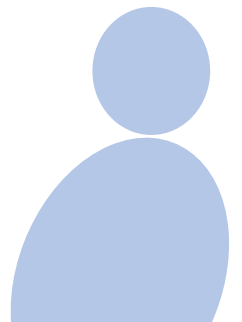
$$\begin{aligned} & \frac{d}{dh} \sum_{k=1}^N (y(k) - hx(k))^2 \\ &= \sum_{k=1}^N -2x(k)(y(k) - hx(k)) = 0 \end{aligned}$$



Wireless System Model

$$\sum_{k=1}^N -2x(k)(y(k) - hx(k)) = 0$$

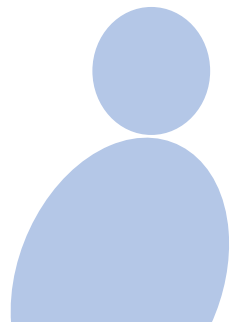
$$\Rightarrow \hat{h} = \frac{\sum_{k=1}^N x(k)y(k)}{\sum_{k=1}^N x^2(k)}$$



Wireless System Model

- This can be expressed as follows

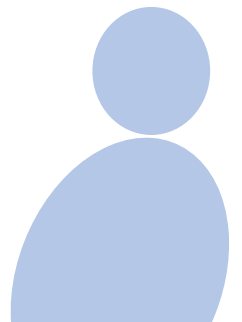
$$\hat{h} = \frac{\sum_{k=1}^N x(k)y(k)}{\sum_{k=1}^N x^2(k)} = \frac{\bar{x}^T \bar{y}}{\bar{x}^T \bar{x}} = \frac{\bar{x}^T \bar{y}}{\|\bar{x}\|^2}$$



Wireless System Model

- This can be expressed as follows

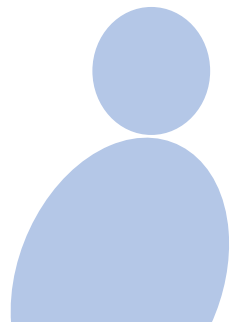
$$\hat{h} = \frac{\sum_{k=1}^N x(k)y(k)}{\sum_{k=1}^N x^2(k)} = \frac{\bar{\mathbf{x}}^T \bar{\mathbf{y}}}{\bar{\mathbf{x}}^T \bar{\mathbf{x}}}$$



Wireless System Model

- This can be expressed as follows

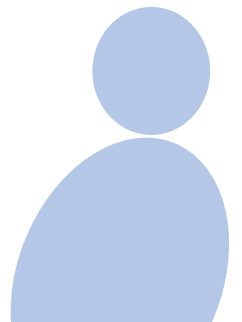
$$\bar{\mathbf{x}} = \begin{bmatrix} x(1) \\ x(2) \\ \vdots \\ x(N) \end{bmatrix} \quad \bar{\mathbf{y}} = \begin{bmatrix} y(1) \\ y(2) \\ \vdots \\ y(N) \end{bmatrix}$$



Wireless System Model

- This can be expressed as follows

$$\bar{\mathbf{x}} = \begin{bmatrix} x(1) \\ x(2) \\ \vdots \\ x(N) \end{bmatrix} \quad \bar{\mathbf{y}} = \begin{bmatrix} y(1) \\ y(2) \\ \vdots \\ y(N) \end{bmatrix}$$

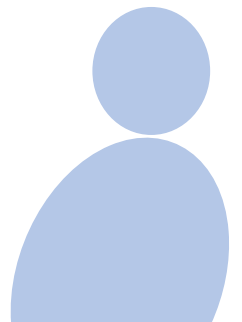


Wireless System Model

- For complex quantities, the channel estimate is given as


$$\hat{h} = \frac{\sum_{k=1}^N x^*(k)y(k)}{\sum_{k=1}^N |x(k)|^2} = \frac{\bar{x}^H \bar{y}}{\bar{x}^H \bar{x}}$$

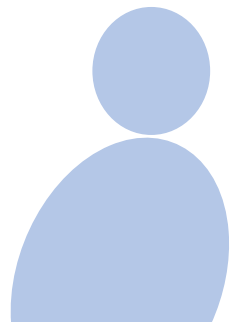
Handwritten notes in red:
 $\bar{x} = \text{complex}$
 $\bar{y} = \text{complex}$
 $= \frac{\bar{x}^H \bar{x}}{\|\bar{x}\|^2}$



Wireless System Model

- For complex quantities, the channel estimate is given as

$$\hat{h} = \frac{\sum_{k=1}^N x^*(k)y(k)}{\sum_{k=1}^N |x(k)|^2} = \frac{\bar{\mathbf{x}}^H \bar{\mathbf{y}}}{\bar{\mathbf{x}}^H \bar{\mathbf{x}}}$$


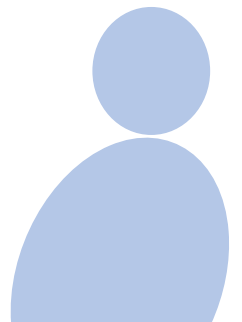


Properties of MLE

$$\hat{h} = \frac{\sum_{k=1}^N x(k)y(k)}{\sum_{k=1}^N x^2(k)} = \sum_{k=1}^N \frac{x(k)}{\|x\|^2} y(k)$$

Handwritten notes:
- An arrow points from $y(k)$ in the numerator to the word "Gaussian".
- A wavy line under the fraction $\frac{x(k)}{\|x\|^2}$ is labeled "Linear combination of".
- Below the wavy line, it says "y(k)".
- At the bottom right, it says "y(k) ~ Gaussian".

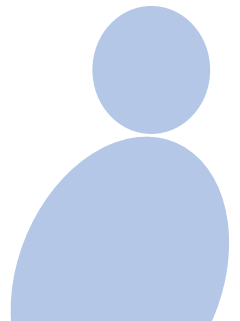
- \hat{h} is a linear combination of **Gaussian RVs**
Handwritten note: $y(k) \sim \text{Gaussian}$
- Hence, it is **Gaussian**
 $\Rightarrow \hat{h}$ is Gaussian RV



Properties of MLE

- What is mean of \hat{h}

$$\begin{aligned} E\{\hat{h}\} &= E\left\{ \frac{\sum_{k=1}^N x(k)y(k)}{\sum_{k=1}^N x^2(k)} \right\} \\ &= \frac{\sum_{k=1}^N x(k) E\{y(k)\}}{\sum_{k=1}^N x^2(k)} = \frac{\sum_{k=1}^N x(k) E\{hx(k) + v(k)\}}{\sum_{k=1}^N x^2(k)} \\ &= \frac{\sum_{k=1}^N x(k) h x(k)}{\sum_{k=1}^N x^2(k)} \end{aligned}$$



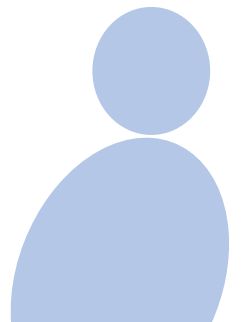
Properties of MLE

$$E\{\hat{h}\} = h \cdot \frac{\sum_{k=1}^N x^2(k)}{\sum_{k=1}^N x^2(k)} = h$$

$$E\{\hat{h}\} = h$$

\Rightarrow Estimate is
unbiased!!

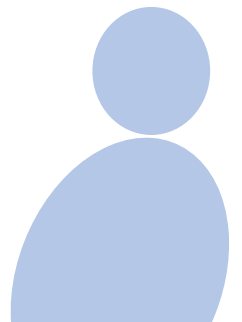
UNBIASED



Properties of MLE

- We now explore properties of the ML Estimate

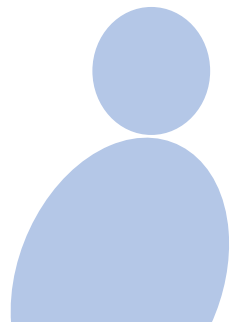
$$\begin{aligned} E\{\hat{h}\} &= E\left\{\frac{\sum_{k=1}^N x(k)y(k)}{\sum_{k=1}^N x^2(k)}\right\} = \frac{\sum_{k=1}^N x(k)E\{y(k)\}}{\sum_{k=1}^N x^2(k)} \\ &= \frac{\sum_{k=1}^N x(k)E\{hx(k) + v(k)\}}{\sum_{k=1}^N x^2(k)} \end{aligned}$$



Properties of MLE

$$E\{\hat{h}\} = \frac{\sum_{k=1}^N x(k) h x(k)}{\sum_{k=1}^N x^2(k)}$$

$$= h \frac{\sum_{k=1}^N x^2(k)}{\sum_{k=1}^N x^2(k)} = h$$

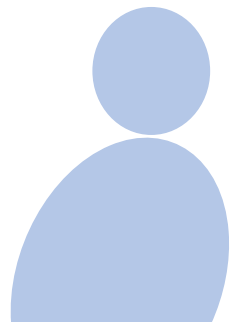


Properties of MLE

- Therefore

$$\underline{E\{\hat{h}\} = h}$$

- This is termed an unbiased estimate

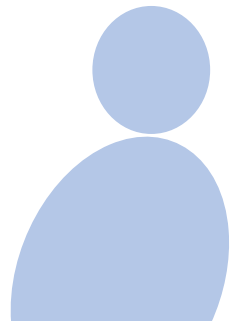


Properties of MLE

- What about MSE?

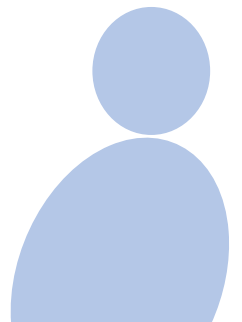
$$\underbrace{E \left\{ (\hat{h} - h)^2 \right\}}_{\text{MSE} = \text{Mean Square Error}} = ? \quad \frac{\overbrace{E \left\{ (X - \mu_X)^2 \right\}}^{\text{mean}}}{\text{Variance.}}$$

- This is also variance
- This can be found as follows



Properties of MLE

$$\begin{aligned} E \left\{ (\hat{h} - h)^2 \right\} &= E \left\{ \left(\frac{\sum_{k=1}^N x(k)y(k)}{\sum_{k=1}^N x^2(k)} - h \right)^2 \right\} \\ &= E \left\{ \left(\frac{\sum_{k=1}^N x(k)y(k) - h \sum_{k=1}^N x^2(k)}{\sum_{k=1}^N x^2(k)} \right)^2 \right\} \\ &= \frac{E \left\{ \left(\sum_{k=1}^N x(k)(y(k) - h x(k)) \right)^2 \right\}}{\| \bar{x} \|^4} \end{aligned}$$



Properties of MLE

$V(i)$ iid
independent
identically distributed
Gaussian
 $N(0, \sigma^2)$

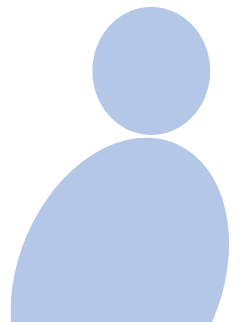
$$\begin{aligned}
 & E \left\{ \left(\sum_{k=1}^N x(k) v(k) \right)^2 \right\} \\
 = & \frac{\| \bar{x} \|^4}{E \left\{ \left(\sum_{k=1}^N x(k) v(k) \right) \left(\sum_{l=1}^N x(l) v(l) \right) \right\}} \\
 = & \frac{\| \bar{x} \|^4}{\sum_{k=1}^N \sum_{l=1}^N x(k) x(l) E \left\{ v(k) v(l) \right\}} \quad \sigma^2 \delta(k-l)
 \end{aligned}$$

Properties of MLE

$$MSE = E\left\{\left(\hat{h} - h\right)^2\right\} = \frac{\sum_{k=1}^N \sum_{l=1}^N \sigma^2 x(k) x(l) \delta(k-l)}{\|\bar{x}\|^4}$$

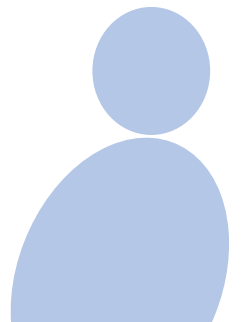
$$= \frac{\sigma^2 \sum_{k=1}^N x^2(k)}{\|\bar{x}\|^4} = \frac{\sigma^2 \|\bar{x}\|^2}{\|\bar{x}\|^4}$$

$$= \frac{\sigma^2}{\|\bar{x}\|^2} \left. \vphantom{\frac{\sigma^2}{\|\bar{x}\|^2}} \right\} \begin{array}{l} \text{Variance} \\ \text{MSE} \end{array}$$



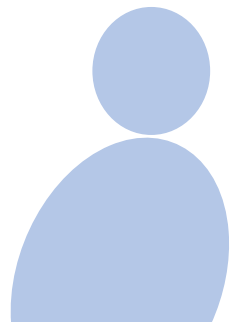
Properties of MLE

$$\begin{aligned} E \left\{ (\hat{h} - h)^2 \right\} &= E \left\{ \left(\frac{\sum_{k=1}^N x(k)y(k)}{\sum_{k=1}^N x^2(k)} - h \right)^2 \right\} \\ &= E \left\{ \left(\sum_{k=1}^N \frac{x(k)(y(k) - hx(k))}{x^2(k)} \right)^2 \right\} \\ &= \frac{E \left\{ \left(\sum_{k=1}^N x(k)v(k) \right)^2 \right\}}{\left(\sum_{k=1}^N x^2(k) \right)^2} \end{aligned}$$



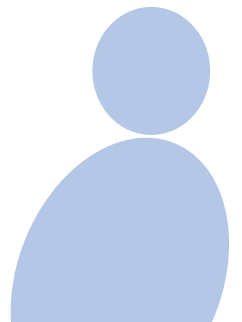
Properties of MLE

$$\begin{aligned} & \frac{E \left\{ \left(\sum_{k=1}^N x(k) v(k) \right)^2 \right\}}{\left(\sum_{k=1}^N x^2(k) \right)^2} \\ &= \frac{1}{\left(\sum_{k=1}^N x^2(k) \right)^2} E \left\{ \left(\sum_{k=1}^N x(k) v(k) \right) \left(\sum_{l=1}^N x(l) v(l) \right) \right\} \\ &= \frac{1}{\left(\sum_{k=1}^N x^2(k) \right)^2} \sum_{k=1}^N \sum_{l=1}^N x(k) x(l) E \{ v(l) v(k) \} \end{aligned}$$



Properties of MLE

$$\begin{aligned} & \frac{1}{(\sum_{k=1}^N x^2(k))^2} \sum_{k=1}^N \sum_{l=1}^N x(k)x(l)\sigma^2\delta(k-l) \\ &= \frac{\sigma^2}{(\sum_{k=1}^N x^2(k))^2} \sum_{k=1}^N x^2(k) \\ &= \frac{\sigma^2}{\sum_{k=1}^N x^2(k)} = \frac{\sigma^2}{\|\bar{\mathbf{x}}\|^2} \end{aligned}$$



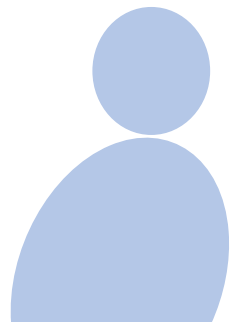
Properties of MLE

Mean Square Error

- Therefore, MSE decreases as

$$MSE = \frac{\sigma^2}{\|\bar{\mathbf{x}}\|^2} \propto \frac{1}{\|\bar{\mathbf{x}}\|^2}$$

decreases as $\frac{1}{\|\bar{\mathbf{x}}\|^2}$
 $\|\bar{\mathbf{x}}\|^2 = \text{Energy of pilot}$

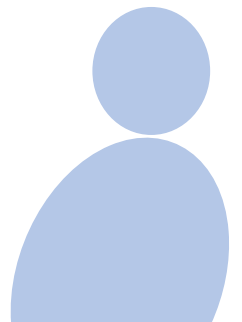


Properties of MLE

- Therefore, \hat{h} is Gaussian with mean h and variance $\frac{\sigma^2}{\|\bar{\mathbf{x}}\|^2}$ *unbiased.*

$$\hat{h} \sim \mathcal{N}\left(h, \frac{\sigma^2}{\|\bar{\mathbf{x}}\|^2}\right)$$

channel Estimate



Example

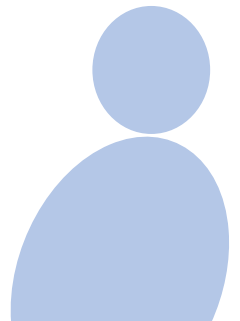
Pilots

input/pilot vector

- $\bar{\mathbf{x}} = [1 \quad -1 \quad 1 \quad -1]^T$
- $\bar{\mathbf{y}} = [2 \quad -3 \quad -2 \quad 1]^T$
- What is the MLE of the channel coefficient h ?

$N=4$ pilots.

$$\hat{h} = \frac{\bar{\mathbf{x}}^T \bar{\mathbf{y}}}{\|\bar{\mathbf{x}}\|^2} = \frac{[1 \quad -1 \quad 1 \quad -1] \begin{bmatrix} 2 \\ -3 \\ -2 \\ 1 \end{bmatrix}}{1+1+1+1}$$

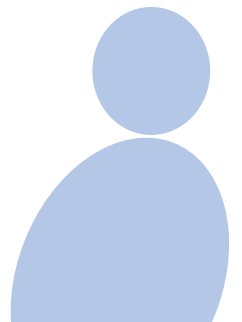


Example

- The channel estimate is,

$$\hat{h} = \frac{2+3-2-1}{4} = \frac{2}{4} = \frac{1}{2}$$

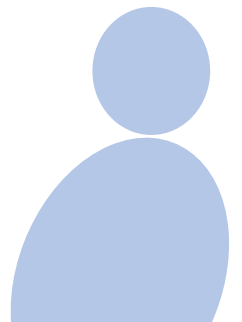
$\hat{h} = \frac{1}{2}$ → Maximum Likelihood Estimate
MLE.



Example

- The channel estimate is,

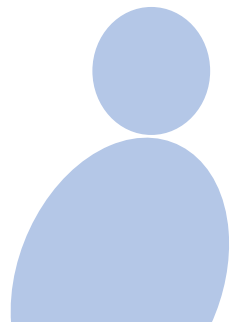
$$\hat{h} = \frac{\bar{\mathbf{x}}^T \bar{\mathbf{y}}}{\bar{\mathbf{x}}^T \bar{\mathbf{x}}} = \frac{2}{4} = \frac{1}{2}$$



Example

- Given i.i.d. Gaussian noise with zero-mean and variance $\sigma^2 = 2$
- Variance of the maximum likelihood \hat{h} is,

$$\frac{\sigma^2}{\|\bar{x}\|^2} = \frac{2}{4} = \frac{1}{2}$$



Example

MSE = Mean Squared Error

- Given i.i.d. Gaussian noise with zero-mean and variance $\sigma^2 = 2$
- Variance of the maximum likelihood \hat{h} is,

$$\frac{\sigma^2}{\|\bar{\mathbf{x}}\|^2} = \frac{2}{4} = \frac{1}{2}$$

Estimate of channel.

$$y = h x + v$$
$$\hat{x} = \frac{y}{\hat{h}}$$

EQUALIZATION

Equalization

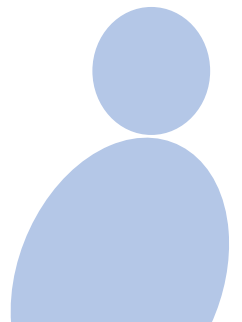
$$y = hx + n$$

information symbol

$$\hat{x} = \frac{y}{h} \left\{ \begin{array}{l} \text{ideal.} \\ h \text{ is unknown} \end{array} \right.$$

- Estimate h

$$- \hat{x} = \frac{y}{\hat{h}} \left\{ \begin{array}{l} \text{Practical} \\ \text{Equalization with } \hat{h} \end{array} \right.$$



Instructors may use this white area (14.5 cm / 25.4 cm) for the text.
Three options provided below for the font size.

Font: Avenir (Book), Size: 32, Colour: Dark Grey

Font: Avenir (Book), Size: 28, Colour: Dark Grey

Font: Avenir (Book), Size: 24, Colour: Dark Grey

Do not use the space below.

