Assignment 5

Digital Communication System-I

May 2023

Please answer the following questions:

Consider a cascaded binary symmetric channel (BSC) in Figure 1 to answer Q1-Q2.

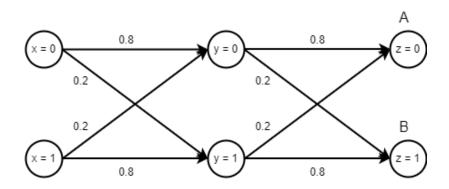


Figure 1: Cascaded BSC

Q 1: Find out the probability Pr(z=1) and Pr(z=0) at node A and B, respectively, if a priori probability is given as Pr(x=0)=0.3 and Pr(x=1)=0.7.

- (a) 0.572,0.428
- (b) 0.428,0.572
- (c) 0.56, 0.44
- (d) 0.44,0.56

Q 2: MAP decision rule is same as the ML decision rule if Pr(y=0|x=1) = Pr(y=1|x=0) = 0.5.

- (a) True
- (b) False

Q 3: Why do we need optimum detection rule in communication system?

- (a) Minimize the energy consumption
- (b) Effective use of channel bandwidth
- (c) Minimize the probability of error
- (d) To detect and correct the error

Q 4: If the bit error probability for BPSK modulated signal with coherent detection over an AWGN channel with the power spectral density of the channel noise is $N_0/2$ is 0.1587 then find out the SNR (in dB) in the AWGN channel. The two signals $s_1(t)$ and $s_2(t)$ are assumed to be equi-probable with bit energy E_b ?

(a) 10 dB

- (b) 5
- (c) -3 dB
- (d) 2 dB

Q 5: The vector representations of the binary equiprobable orthogonal signal set is given as $S_1 = (\sqrt{2E_b}, 0)$ and $S_1 = (0, \sqrt{2E_b})$. What is their error probability over the AWGN channel?

- (a) $Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$
- (b) $Q\left(\sqrt{\frac{4E_b}{N_0}}\right)$
- (c) $Q\left(\sqrt{\frac{E_b}{N_0}}\right)$
- (d) $Q\left(\sqrt{\frac{E_b}{2N_0}}\right)$

Q 6: Probability of error depends on which of the following factor(s)?

- (a) Euclidean distances among signal vectors in signal space diagram
- (b) Positions of signal vectors in signal space diagram
- (c) Both (a) and (b)
- (d) None of these

Q 7: Assume a binary antipodal signalling scheme $s_1(t) = \sqrt{E_b}$ and $s_2(t) = -\sqrt{E_b}$, with a priori probability of $s_1(t) = 0.2$ and of $s_2(t) = 0.8$ over an AWGN channel with the power spectral density of the channel noise is $N_0/2$. Find out the threshold (r_{th}) for the decision region

- (a) $r_{th} = \frac{0.1 N_0}{\sqrt{E_b}}$
- (b) $r_{th} = \frac{0.4N_0}{\sqrt{E_b}}$
- (c) $r_{th} = \frac{0.69N_0}{\sqrt{E_b}}$
- (d) $r_{th} = \frac{0.38N_0}{\sqrt{E_h}}$

Q 8: Which of the following statement about the Q function is correct?

- (a) Q function is an even function
- (b) Q(x) is a decreasing function for x > 0
- (c) Both (a) and (b)
- (d) None of the above

Q 9: Which of the following expressions represent(s) the ML decision rule for AWGN vector channel?

- (a) $\hat{m} = \arg\min_{1 \le m \le M} \|r s_m\|^2$
- (b) $\hat{m} = \arg \max_{1 \le m \le M} \left(\int_0^T r(t) s_m(t) dt + \frac{1}{2} \int_0^T |s_m(t)|^2 dt \right)$
- (c) $\hat{m} = \arg\max_{1 \le m \le M} \|r s_m\|^2$
- (d) None of the above

Q 10: Consider the following signal

$$s(t) = \begin{cases} \frac{A}{T} \sin(2\pi f_c t), & \text{if } 0 \le t \le T \\ 0, & \text{otherwise} \end{cases}$$

What is the output of the matched filter at t = T?

- (a) $\frac{A^2}{2T^2}\sin(4\pi f_c T)$
- (b) $\frac{A^2}{2T}\cos(2\pi f_c T)$
- (c) $\frac{A^2}{2T} \frac{A^2}{2T}\sin(4\pi f_c T)$
- (d) $\frac{A^2}{2T} \frac{A^2}{8\pi f_c T^2} \sin(4\pi f_c T)$