# EE910: Digital Communication Systems-I

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Lecture #2A: Review of signals

## Signals: Introduction

- A signal, x(t), is defined to be a function of time  $(t \in \mathcal{R})$ .
- Signals in engineering systems are typically described with five different mathematical classifications:
  - Deterministic or random
  - Energy or power
  - Periodic or aperiodic
  - Complex or real
  - Continuous time or discrete time



# Deterministic vs. random signal

- A signal is said to be deterministic if there is no uncertainty with respect to its value at any instant of time.
- Deterministic signals can be defined exactly by a mathematical formula.
- In contrast, there is uncertainty with respect to the value of a random signal at some instant of time.
- Random signals are modeled in probabilistic terms.

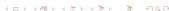


# **Energy signal**

• The energy,  $E_x$ , of a signal x(t) is given by

$$E_{x} = \lim_{T \to \infty} \int_{-T/2}^{T/2} |x(t)|^{2} dt$$
 (1)

- x(t) is called an energy signal when  $E_x < \infty$ .
- Energy signals are normally associated with finite duration waveforms.



# **Energy signal**

Example:

$$x(t) = \begin{cases} \frac{1}{\sqrt{T}} & 0 \le t \le T \\ 0 & \text{elsewhere} \end{cases} E_{x} = 1$$
 (2)

## Power signal

- A signal is called a power signal if it does not have finite energy.
- The signal power,  $P_x$ , is given by

$$P_{x} = \lim_{T \to \infty} \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^{2} dt$$
 (3)

Note that if  $E_x < \infty$ , then  $P_x = 0$  and if  $P_x > 0$ , then  $E_x = \infty$ .



# Power signal

• Example:

$$x(t) = \cos(2\pi f_c t)$$

$$P_x = \lim_{T \to \infty} \frac{1}{T} \int_{-T/2}^{T/2} \cos^2(2\pi f_c t) dt$$

$$= \lim_{T \to \infty} \frac{1}{T} \int_{-T/2}^{T/2} \left(\frac{1}{2} + \frac{1}{2}\cos(4\pi f_c t)\right) dt = \frac{1}{2}$$
(4)

# Periodic vs. Aperiodic signal

- A periodic signal is one that repeats itself in time.
- x(t) is a periodic signal when

$$x(t) = x(t + T_0) \quad \forall t \quad \text{and for some } T_0 \neq 0$$
 (5)

• The signal period is given by

$$T = \min(|T_0|) \tag{6}$$

• The fundamental frequency is given by

$$f_T = \frac{1}{T} \tag{7}$$

• Most periodic signals are power signals



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## Periodic vs. Aperiodic signal

Example:

$$x(t) = \cos(2\pi f_m t)$$
  $T_0 = \frac{n}{f_m}$   $T = \frac{1}{f_m}$  (8)

• An aperiodic signal is defined to be a signal that is not periodic.

## Complex signal vs. real signal

• We define a complex signal and a complex exponential as

$$z(t) = x(t) + jy(t) \quad e^{j\theta} = \cos(\theta) + j\sin(\theta) \tag{9}$$

where x(t) and y(t) are both real signals.

• A magnitude  $(\alpha(t))$  and phase  $(\theta(t))$  representation of a complex signal is also commonly used

$$z(t) = \alpha(t)e^{j\theta(t)} \tag{10}$$

where

$$\alpha(t) = |z(t)| = \sqrt{x^2(t) + y^2(t)} \quad \theta(t) = \arg(z(t)) = \tan^{-1}(y(t), x(t))$$
(11)

• The complex conjugate operation is defined as

$$z^*(t) = x(t) - jy(t) = \alpha(t)e^{-j\theta(t)}$$
(12)

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## Complex signal vs real signal

• Some important formulas for analyzing complex signals are

$$\begin{split} |z(t)|^2 &= \alpha(t)^2 = z(t)z^*(t) = x^2(t) + y^2(t) & \cos(\theta)^2 + \sin(\theta)^2 = 1 \\ \Re[z(t)] &= x(t) = \alpha(t)\cos(\theta(t)) = \frac{1}{2}\left[z(t) + z^*(t)\right] & \cos(\theta) = \frac{1}{2}\left[e^{i\theta} + e^{-i\theta}\right] \\ \Im[z(t)] &= y(t) = \alpha(t)\sin(\theta(t)) = \frac{1}{2j}\left[z(t) - z^*(t)\right] & \sin(\theta) = \frac{1}{2j}\left[e^{i\theta} - e^{-i\theta}\right] \end{split}$$

• Example:

$$\exp\left[j2\pi f_m t\right] = \cos\left(2\pi f_m t\right) + j\sin\left(2\pi f_m t\right) \tag{13}$$

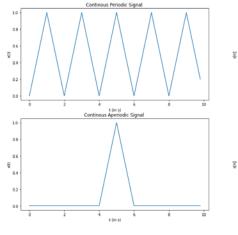
## Continuous Time Signals vs. Discrete Time Signals

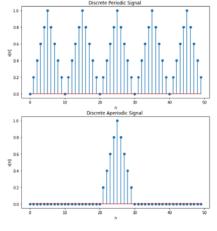
- A signal, x(t), is defined to be a continuous time signal if the domain of the function defining the signal contains intervals of the real line.
- A signal, x(t), is defined to be a discrete time signal if the domain of the signal is a countable subset of the real line.
- Often a discrete signal is denoted by x(k), where k is an integer and a discrete signal often arises from (uniform) sampling of a continuous time signal, e.g.,  $x(k) = x(kT_s)$ , where  $T_s$  is the sampling period.

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# Continuous Time Signals vs. Discrete Time Signals





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#### **Fourier Series**

- Signal analysis can be completed in either the time or frequency domains.
- If x(t) is periodic with period T, then x(t) can be represented as

$$x(t) = \sum_{n = -\infty}^{\infty} x_n \exp\left[\frac{j2\pi nt}{T}\right] = \sum_{n = -\infty}^{\infty} x_n \exp\left[j2\pi f_T nt\right]$$
 (14)

where  $f_T = 1/T$  and

$$x_n = \frac{1}{T} \int_0^T x(t) \exp\left[-j2\pi f_T nt\right] dt \tag{15}$$

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# Fourier Series

• Example:

$$x(t) = \cos(2\pi f_m t) \tag{16}$$

- For this signal  $T=1/f_m$  and the only nonzero Fourier coefficients are  $x_1=0.5, x_{-1}=0.5$ .
- Therefore

$$x(t) = \frac{1}{2} \exp[j2\pi f_T t] + \frac{1}{2} \exp[-j2\pi f_T t]$$
 (17)

#### Parseval Theorem

 Parseval's theorem states that the power of a signal can be calculated using either the time or the frequency domain representation of the signal and the two results are identical.

$$P_{x} = \frac{1}{T} \int_{0}^{T} |x(t)|^{2} dt = \sum_{n=-\infty}^{\infty} |x_{n}|^{2}$$
 (18)

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## Parseval Theorem

• Example: For  $x(t) = \cos(2\pi f_m t)$  computing the power in the frequency domain, we get

$$P_{x} = |x_{-1}|^{2} + |x_{1}|^{2} = (0.5)^{2} + (0.5)^{2} = 0.5$$
 (19)

• Similarly, computing the power in the time domain, we get

$$P_{\times} = \frac{1}{T} \int_{0}^{T} |\cos(2\pi f_{m} t)|^{2} dt = 0.5$$
 (20)

## Fourier Transform

• If x(t) is an energy signal, then the Fourier transform is defined as

$$X(f) = \int_{-\infty}^{\infty} x(t)e^{-j2\pi ft}dt = \mathcal{F}\{x(t)\}$$
 (21)

- $\bullet$  X(f) is in general complex and gives the frequency domain representation of x(t).
- The inverse Fourier transform is

$$X(t) = \int_{-\infty}^{\infty} X(f)e^{j2\pi ft}df = \mathcal{F}^{-1}\{X(f)\}$$
 (22)



# Fourier Transform

• Example: The Fourier transform of

$$x(t) = \begin{cases} 1 & 0 \le t \le T \\ 0 & \text{elsewhere} \end{cases}$$
 (23)

is given as

$$X(f) = \int_0^T e^{-j2\pi f t} dt = \frac{\exp[-j2\pi f t]}{-j2\pi f} \Big|_0^T = T \exp[j\pi f T] \operatorname{sinc}(fT)$$
(24)

## Rayleigh's Energy Theorem

· According to Rayleigh's Energy Theorem, we have

$$E_{x} = \int_{-\infty}^{\infty} |x(t)|^{2} dt = \int_{-\infty}^{\infty} |X(f)|^{2} df$$
 (25)

• Example: For the Fourier transform pair of

$$x(t) = \begin{cases} 1 & 0 \le t \le T \\ 0 & \text{elsewhere} \end{cases} X(f) = T \exp[j\pi fT] \operatorname{sinc}(fT) \quad (26)$$

the energy is most easily computed in the time domain

$$E_{x} = \int_{0}^{T} |x(t)|^{2} dt = T$$
 (27)

#### **Correlation Function**

• The correlation function of a signal x(t) is

$$V_{x}(\tau) = \int_{-\infty}^{\infty} x(t)x^{*}(t-\tau)dt$$
 (28)

- Three important characteristics of the correlation function are
  - $V_x(0) = \int_{-\infty}^{\infty} |x(t)|^2 dt = E_x$   $V_x(\tau) = V_x^*(-\tau)$   $|V_x(\tau)| < V_x(0)$

# Correlation Function

• Example: For the pulse

$$x(t) = \begin{cases} 1 & 0 \le t \le T \\ 0 & \text{elsewhere} \end{cases}$$
 (29)

the correlation function is

$$V_{\times}(\tau) = \begin{cases} T \left( 1 - \frac{|\tau|}{T} \right) & |\tau| \le T \\ 0 & \text{elsewhere} \end{cases}$$
 (30)

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## **Energy Spectrum**

• The energy spectrum of a signal x(t) is given by

$$G_{x}(f) = X(f)X^{*}(f) = |X(f)|^{2}$$
 (31)

 The energy spectral density is the Fourier transform of the correlation function, i.e.,

$$G_{x}(f) = \mathcal{F}\left\{V_{x}(\tau)\right\} \tag{32}$$

- The energy spectrum is a functional description of how the energy in the signal x(t) is distributed as a function of frequency.
- Properties of the energy spectral density:

 $G_{x}(f) \ge 0 \quad \forall f$  (Energy in a signal cannot be negative valued)

$$E_{x} = \int_{-\infty}^{\infty} |x(t)|^{2} dt = \int_{-\infty}^{\infty} G_{x}(f) df$$

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## **Energy Spectrum**

• Example: For the Fourier transform pair of

$$x(t) = \begin{cases} 1 & 0 \le t \le T \\ 0 & \text{elsewhere} \end{cases} X(f) = T \exp[-j\pi fT] \operatorname{sinc}(fT) \quad (34)$$

the energy spectrum is

$$G_{x}(f) = T^{2} \left(\operatorname{sinc}(fT)\right)^{2} \tag{35}$$

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# Bandwidth of the signal

- Bandwidth most often refers to the amount of positive frequency spectrum that a signal occupies.
- If a signal x(t) has an energy spectrum  $G_x(f)$ , then  $B_X$  is determined as

$$10\log\left(\max_{f}G_{X}(f)\right) = X + 10\log\left(G_{X}(B_{X})\right) \tag{36}$$

where  $G_x(B_X) > G_x(f)$  for  $|f| > B_X$ 

- A signal has a relative bandwidth  $B_X$ , if the energy spectrum is at least X dB down from the peak at all frequencies at or above  $B_X$  Hz.
- ullet Often used values for X in engineering practice are the 3-dB bandwidth and the 40-dB bandwidth.



## Bandwidth of the signal

• If a signal x(t) has an energy spectrum  $G_x(f)$ , then  $B_P$  is determined as

$$P = \frac{\int_{-B_P}^{B_p} G_x(f) df}{E_x} \tag{37}$$

- ullet In words, a signal has an integral bandwidth  $B_P$  if the percent of the total energy in the interval  $[-B_P, B_P]$  is equal to P%.
- $\bullet$  Often used values for P in engineering practice are 98% and 99%.



# Bandwidth of the signal

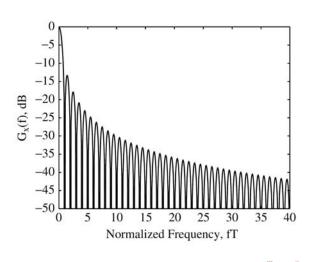
• Example: For the rectangular pulse

$$x(t) = \begin{cases} 1 & 0 \le t \le T \\ 0 & \text{elsewhere} \end{cases}$$
 (38)

The energy spectrum of this signal is given as

$$G_X(f) = |X(f)|^2 = T^2 \left( \operatorname{sinc}(fT) \right)^2$$
 (39)

# Bandwidth of the signal



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# Bandwidth of the signal

- ullet The 3-dB bandwidth is given by  $B_3=0.442/T$
- ullet The 40-dB bandwidth is given by  $B_{40}=31.54/T$
- Integrating the power spectrum gives a 98% energy bandwidth of  $B_{98} = 5.25/T$ .