

# **eMasters in Communication Systems**

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Jagannatham**



**Elective Module:**

**Estimation for Wireless  
Communication**



# Chapter 1

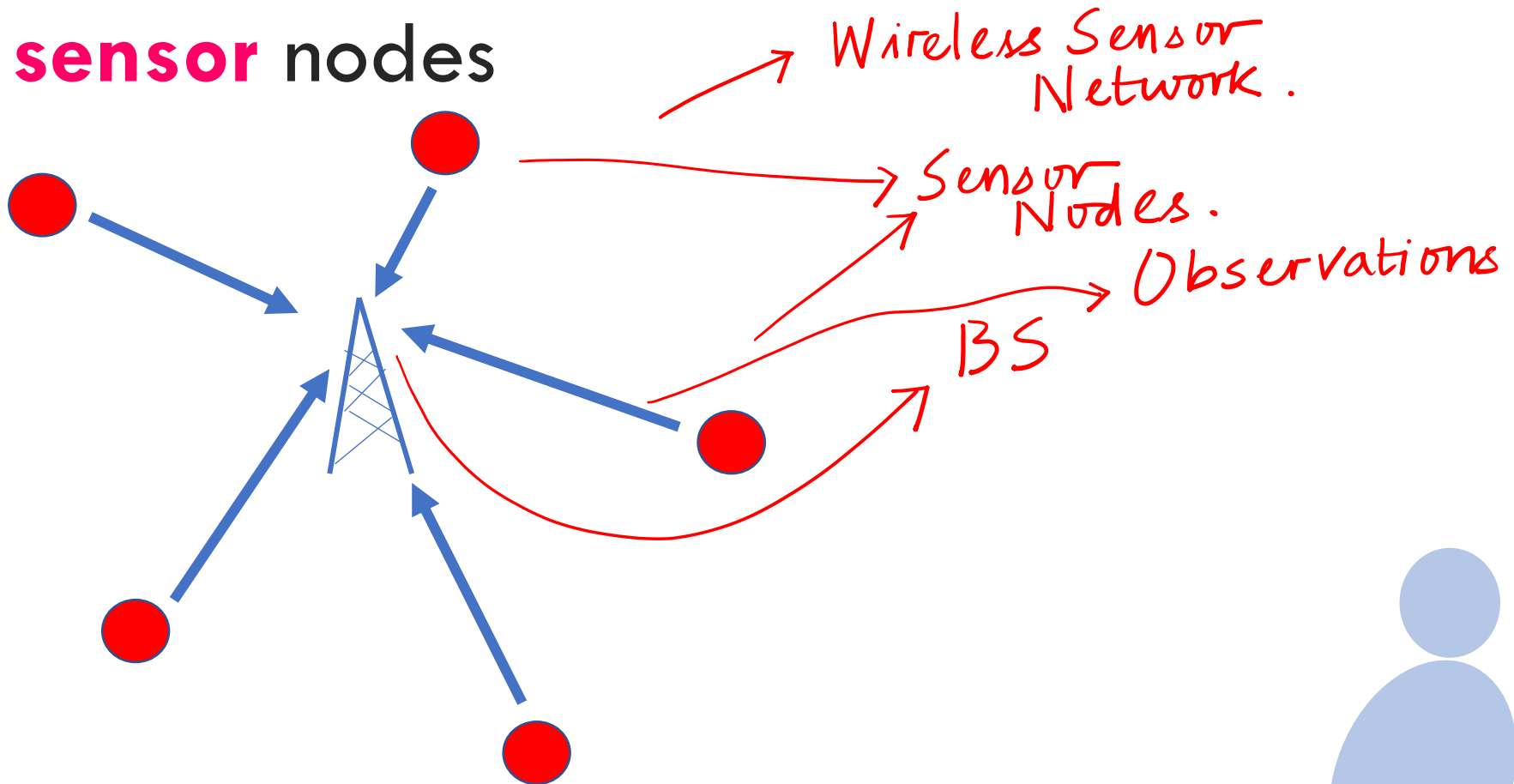
# Maximum Likelihood Estimation

(ML)



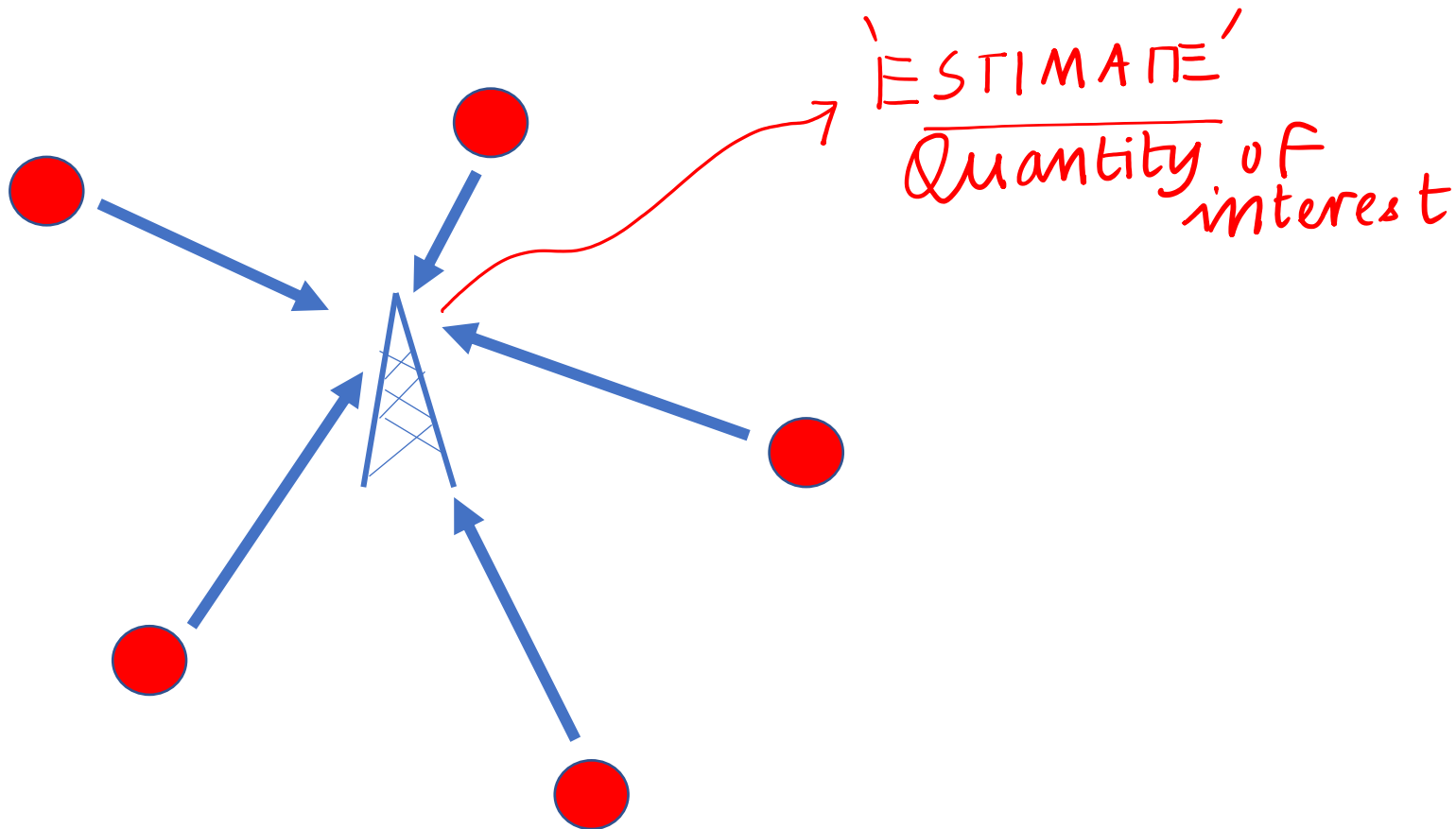
# Introduction to Estimation

- Where do we use estimation?
- Consider large number of **wireless sensor** nodes



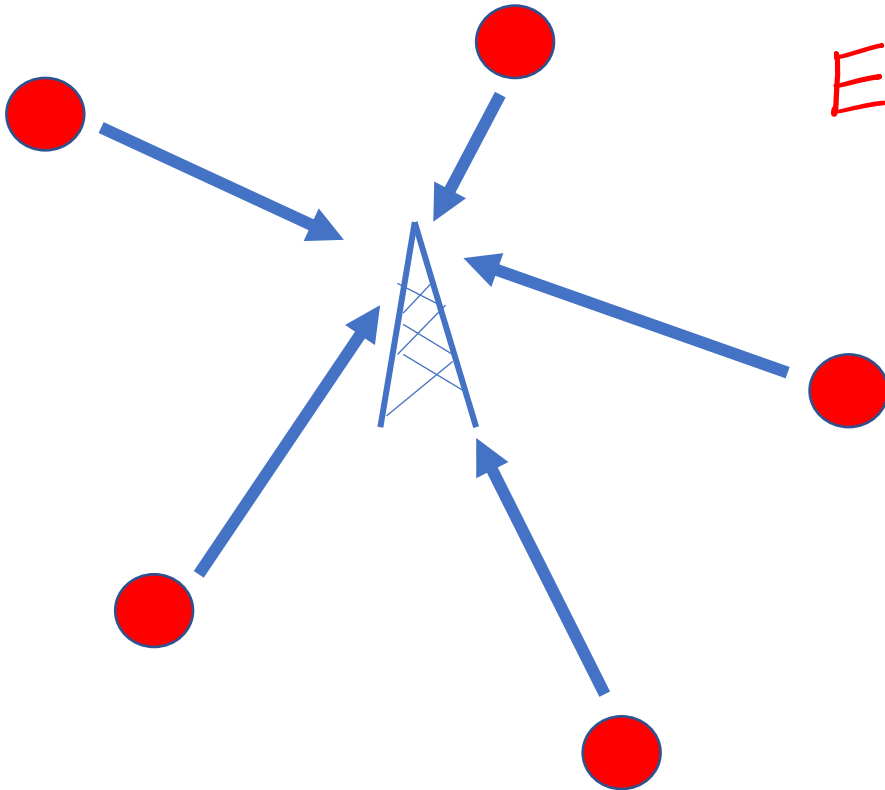
# Introduction to Estimation

- Each sensor node transmits an **observation**
  - Ex: Temperature, pressure, moisture level etc

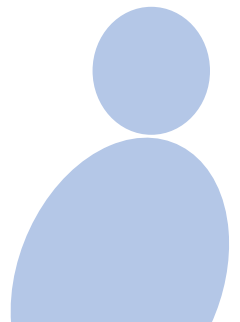


# Introduction to Estimation

- How to estimate the unknown quantity at the BS?
  - This is termed as a PARAMETER.

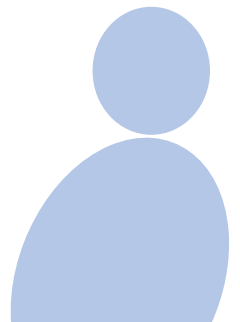
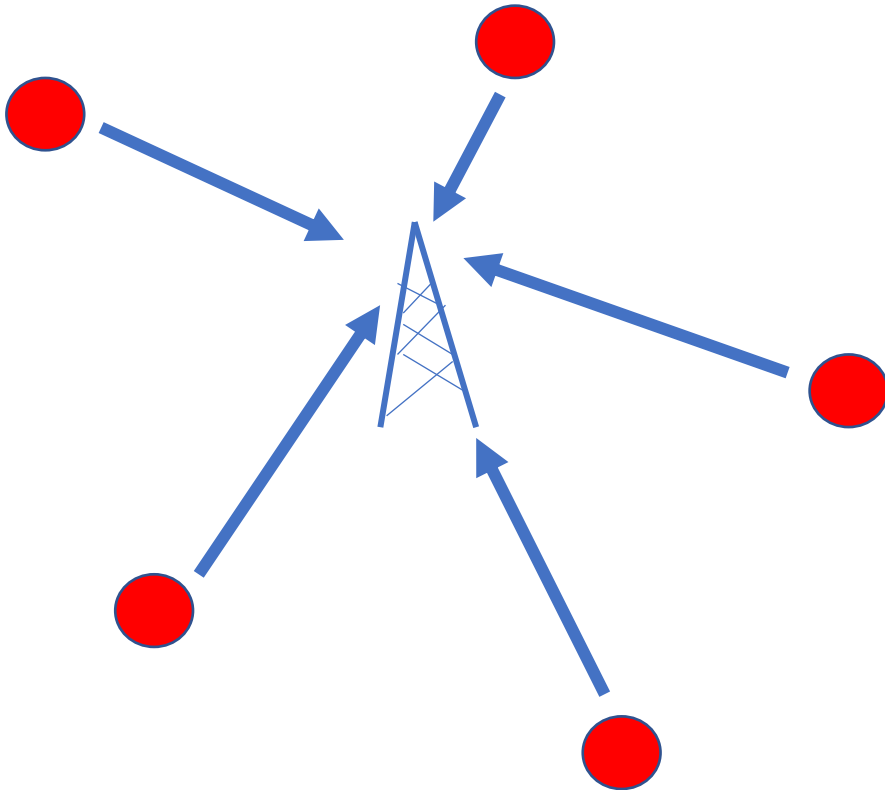


Estimate  
Parameter of interest



# Introduction to Estimation

- How to estimate the *unknown quantity* at the BS?
  - This is termed as a **parameter**.



# Estimation Model

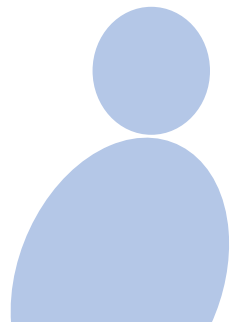
- This can be modeled as follows

$$y = h + v$$

Diagram illustrating the Estimation Model equation  $y = h + v$  with handwritten annotations:

- $y$ : Measurement/Observation
- $h$ : Parameter
- $v$ : Noise
- The entire equation  $y = h + v$  is labeled as Noisy Observation.

- **Observation = Parameter + Noise**





# Estimation Model

- Let noise  $v$  be **Gaussian**

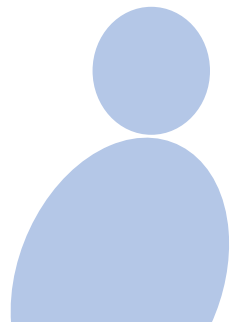
- Mean  $\overset{\mu=0}{=} 0$  and variance  $= \sigma^2$

$$y = h + v$$

Handwritten notes for the equation  $y = h + v$ :

- Arrow from  $y$  to "Gaussian Mean =  $h$  Var =  $\sigma^2$ "
- Arrow from  $v$  to "Gaussian Noise" (above the first bullet)
- Arrow from  $v$  to "unknown constant Fixed."
- Formula for PDF of  $v$ :  $f_v(v) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{v^2}{2\sigma^2}}$

- What is PDF of  $y$ ?

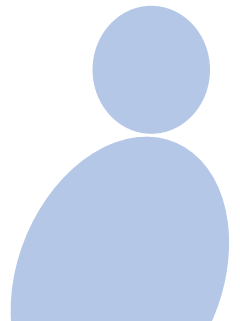


# Estimation Model

- PDF of  $y$  is given as

$$y \sim \mathcal{N}(h, \sigma^2)$$
$$f_Y(y) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y-h)^2}{2\sigma^2}}$$

Gaussian PDF  
mean =  $h$   
var =  $\sigma^2$



# Estimation Model

- PDF of  $y$  is given as
- $y$  is **Gaussian** with mean  $h$  and variance  $\sigma^2$

$$f_Y(y) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y-h)^2}{2\sigma^2}}$$



# Estimation Model

$\rightarrow$   $N$  observations/measurements.

- Consider now  $N$  measurements

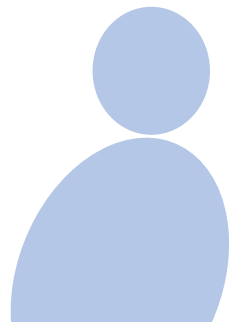
$$y(1) = h + v(1)$$

$$y(2) = h + v(2)$$

$$\vdots$$

$$y(N) = h + v(N)$$

$N = \#$   
measurements.



# Estimation Model $\bar{y} = h \cdot \bar{1} + \bar{v}$

vector model.

- Consider now  $N$  measurements

$$\begin{bmatrix} y(1) \\ y(2) \\ \vdots \\ y(N) \end{bmatrix} = h + \begin{bmatrix} v(1) \\ v(2) \\ \vdots \\ v(N) \end{bmatrix}$$

$\underbrace{\begin{bmatrix} y(1) \\ y(2) \\ \vdots \\ y(N) \end{bmatrix}}_{\bar{y}} = h \cdot \underbrace{\begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}}_{\bar{1}} + \underbrace{\begin{bmatrix} v(1) \\ v(2) \\ \vdots \\ v(N) \end{bmatrix}}_{\bar{v}}$

# Estimation Model

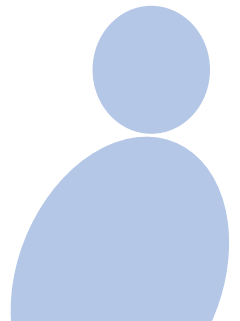
- PDF of each  $y(k)$  is given as

*Gaussian*  
*mean =  $h$*   
*var =  $\sigma^2$*

*mean = 0*  
*var =  $\sigma^2$*

$$y(k) = h + v(k) \sim \mathcal{N}(0, \sigma^2)$$
$$\frac{1}{\sqrt{2\pi\sigma^2}} \cdot e^{-\frac{(y(k)-h)^2}{2\sigma^2}} = f_{Y(k)}(y(k))$$

PDF of  $y(k)$ .



# Estimation Model

- PDF of each  $y(k)$  is given as

$$f_{Y(k)}(y(k)) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y(k)-h)^2}{2\sigma^2}}$$

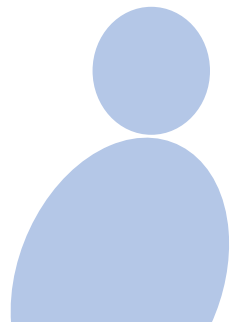


# Estimation Model

- Considering IID noise samples *Joint PDF of observations  $y(1) \dots y(N)$ .*

$$f_{\bar{Y}}(\bar{y}) = \underbrace{\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y(1)-h)^2}{2\sigma^2}}}_{\text{PDF } y(1)} \times \dots \times \underbrace{\frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(y(N)-h)^2}{2\sigma^2}}}_{\text{PDF } y(N)}.$$

$$= \underbrace{\left( \frac{1}{2\pi\sigma^2} \right)^{\frac{N}{2}} e^{-\frac{1}{2\sigma^2} \sum_{k=1}^N (y(k)-h)^2}}_{\text{Joint PDF.}}$$





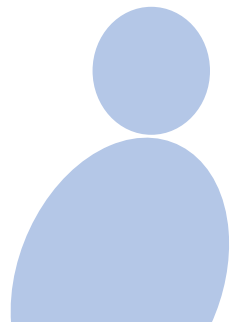
# Likelihood Function

- This is termed as a **likelihood function** wrto  $h$

$$p(\bar{y}; h) = \left( \frac{1}{2\pi\sigma^2} \right)^{\frac{N}{2}} \cdot e^{-\frac{1}{2\sigma^2} \sum_{k=1}^N (y(k) - h)^2}$$

Function of  $h$   
Termed Likelihood of  $h$

How well does  $h$   
Explain observations.



# Likelihood Function

- This is termed as a **likelihood function** wrto  $h$

$$p(\bar{y}; h) = \left( \frac{1}{2\pi\sigma^2} \right)^{\frac{N}{2}} e^{-\frac{1}{2\sigma^2} \sum_{k=1}^N (y(k) - h)^2}$$

semi-colon

parameter is deterministic unknown

Function of  $h$ .

# Likelihood Function

- The estimate of  $h$  is obtained by maximizing the likelihood

Value of  $h$  that best explains observations.

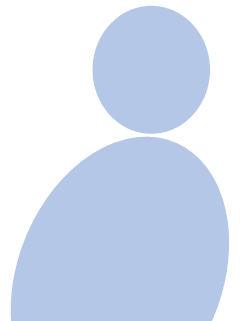
$$\hat{h} = \max p(\bar{y}; h)$$

max. likelihood function

$$= \max \left( \frac{1}{2\pi\sigma^2} \right)^{\frac{N}{2}} e^{-\frac{1}{2\sigma^2} \sum_{k=1}^N (y(k) - h)^2}$$

ML Estimate  
MLE

Maximum Likelihood Estimate.



# Likelihood Function

- The likelihood can be maximized as

$$\max \left( \frac{1}{2\pi\sigma^2} \right)^{\frac{N}{2}} e^{-\frac{1}{2\sigma^2} \sum_{k=1}^N (y(k) - h)^2}$$

*constant*

*-ve sign*  
*maximize*

*minimize*  
*constant*

$$\equiv \min \sum_{k=1}^N (y(k) - h)^2$$

*EQUIVALENT*

*minimization of above Qty.*

# Likelihood Function

- This can be minimized by differentiating wrto  $h$  and set to 0

$$\frac{d}{dh} \sum_{k=1}^N (y(k) - h)^2 = 0$$

minimization


$$\sum_{k=1}^N 2(y(k) - h) = 0$$



$$\sum_{k=1}^N (y(k) - h) = 0$$

$$\Rightarrow Nh = \sum_{k=1}^N y(k)$$

Sample Mean



$$\Rightarrow \hat{h} = \frac{1}{N} \sum_{k=1}^N y(k).$$

---

ML Estimate



# Likelihood Function

- This can be **minimized** by differentiating wrto  $h$  and set to 0

$$\frac{d}{dh} \sum_{k=1}^N (y(k) - h)^2 = 0$$

$$\Rightarrow \sum_{k=1}^N -2(y(k) - h) = 0$$



# Likelihood Function

$$\Rightarrow \hat{h} = \frac{1}{N} \sum_{k=1}^N y(k)$$

ML ESTIMATE  
- Sample Mean  
- Average of  
observations.





# Maximum Likelihood

- This is termed the Maximum Likelihood (ML) Estimate MLE
- It is also the sample mean of the observations



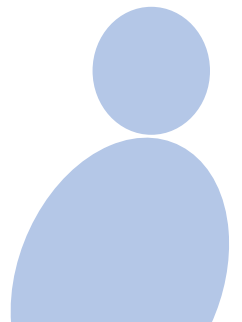
# Properties of MLE

ESTIMATE

- We now explore properties of the ML Estimate
- What is the distribution of  $\hat{h}$

Random Qty.

$$\hat{h} = \frac{1}{N} \sum_{k=1}^N y(k)$$



# Properties of MLE

$$\hat{h} = \frac{1}{N} \sum_{k=1}^N y(k) = \frac{1}{N} (y(1) + \dots + y(N))$$

*Annotations:*  
-  $\hat{h}$  is circled in red.  
-  $N$  is labeled "Gaussian" with a red arrow.  
-  $y(k)$  is labeled "Gaussian" with a red arrow.  
- The sum  $y(1) + \dots + y(N)$  is labeled "Linear Transform" with a red bracket.

- $\hat{h}$  is a linear combination of **Gaussian RVs**  
*Annotation:* "Average of Observations." with a red arrow pointing to the fraction  $\frac{1}{N}$ .
- Hence, it is **Gaussian**

$\hat{h} \sim \text{Gaussian}$



# Properties of MLE

- What is mean of  $\hat{h}$

$$\frac{1}{N} \sum_{k=1}^N y(k)$$

$$\begin{aligned} E\{\hat{h}\} &= \\ E\{\hat{h}\} &= ? \quad E\{\hat{h}\} = E\left\{\frac{1}{N} \sum_{k=1}^N y(k)\right\} \\ &= \frac{1}{N} \sum_{k=1}^N E\{y(k)\} = \frac{1}{N} \sum_{k=1}^N E\{h + v(k)\} \\ &= \frac{1}{N} \sum_{k=1}^N (h + E\{v(k)\}) \quad \text{Zero mean Gaussian} \end{aligned}$$

# Properties of MLE

Mean of  
Estimate = True Parameter

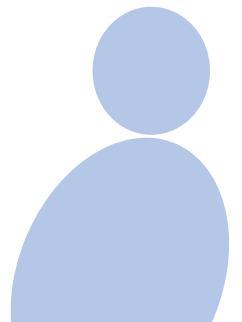
$$E\{\hat{\eta}\} = \frac{1}{N} \sum_{k=1}^N \eta = \frac{1}{N} \times N\eta = \eta$$

$$E\{\hat{\eta}\} = \eta$$

True  
Parameter

'UNBIASED'  
Estimator

Very interesting!!!  
Property.



# Properties of MLE

- We now explore properties of the ML Estimate

$$\begin{aligned} E\{\hat{h}\} &= E\left\{\frac{1}{N} \sum_{k=1}^N y(k)\right\} = \frac{1}{N} \sum_{k=1}^N E\{y(k)\} \\ &= \frac{1}{N} \sum_{k=1}^N E\{h + v(k)\} = \frac{1}{N} \sum_{k=1}^N h = h \end{aligned}$$



# Properties of MLE

- Therefore

$$E\{\hat{h}\} = h$$

- This is termed an unbiased estimate.



# Properties of MLE

- What about MSE?

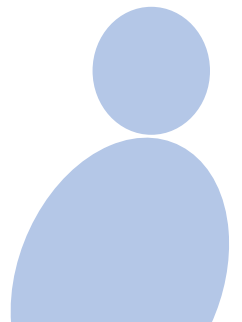
$$E\{(\hat{h} - h)^2\}$$

Mean Square Error

$$E\{(\hat{h} - h)^2\} = ?$$

Mean.

- This is also variance
- This can be found as follows





# Properties of MLE

$$E\{\|\hat{h} - h\|^2\}.$$

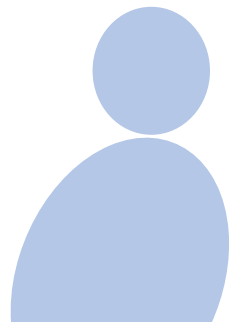
$$E\left\{\left(\hat{h} - h\right)^2\right\}$$

$$= E\left\{\left(\frac{1}{N} \sum_{k=1}^N y(k) - h\right)^2\right\}$$

$$= E\left\{\left(\frac{1}{N} \sum_{k=1}^N (y(k) - h)\right)^2\right\}$$

$$= \frac{1}{N^2} E\left\{\left(\sum_{k=1}^N v(k)\right)^2\right\}.$$

$$y(k) = h + v(k) \\ \Rightarrow y(k) - h = v(k).$$



# Properties of MLE

$$\begin{aligned} \text{MSE} &= \frac{1}{N^2} \cdot E \left\{ \left( \sum_{k=1}^N V(k) \right)^2 \right\} \\ &= \frac{1}{N^2} \cdot E \left\{ \left( \sum_{k=1}^N V(k) \right) \left( \sum_{l=1}^N V(l) \right) \right\} \\ &= \frac{1}{N^2} \cdot E \left\{ \sum_{k=1}^N \sum_{l=1}^N V(k) V(l) \right\} \\ &= \frac{1}{N^2} \cdot \sum_{k=1}^N \sum_{l=1}^N E \{ V(k) V(l) \} \end{aligned}$$



# Properties of MLE

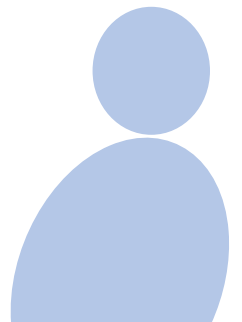
$V(k) - \text{i.i.d.}$

independent identically distributed.

$$E\{V(k)V(l)\} = \sigma^2 \delta(k-l)$$

if  $k \neq l$   $\rightarrow E\{V(k)\}E\{V(l)\} = 0 \times 0 = 0$

if  $k = l$   $\rightarrow E\{V^2(k)\} = \sigma^2$



# Properties of MLE

$$E \{ \sum_{k=1}^N (\hat{h} - h)^2 \} = \frac{\sigma^2}{N}$$

$$MSE = \frac{1}{N^2} \cdot \sum_{k=1}^N \sum_{l=1}^N E \{ v(k) v(l) \}$$

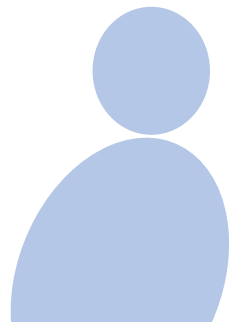
$$= \frac{1}{N^2} \cdot \sum_{k=1}^N \sum_{l=1}^N \sigma^2 \delta(k-l)$$

Mean Square  
Error

$$= \frac{1}{N^2} \cdot \sum_{k=1}^N \sigma^2 = \frac{1}{N^2} \cdot N \sigma^2$$

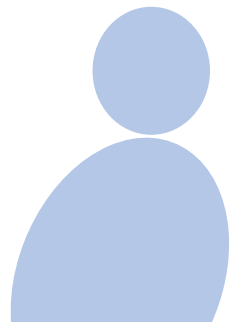
$$= \frac{\sigma^2}{N} = \underline{MSE} = \underline{\text{Variance.}}$$

$$\hat{h} \sim \mathcal{N}\left(h, \frac{\sigma^2}{N}\right)$$



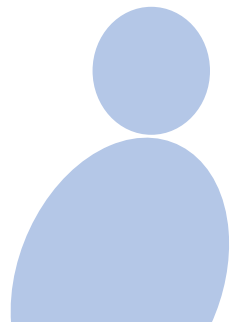
# Properties of MLE

$$\begin{aligned} E \left\{ (\hat{h} - h)^2 \right\} &= E \left\{ \left( \frac{1}{N} \sum_{k=1}^N y(k) - h \right)^2 \right\} \\ &= E \left\{ \left( \frac{1}{N} \sum_{k=1}^N (y(k) - h) \right)^2 \right\} = E \left\{ \left( \frac{1}{N} \sum_{k=1}^N v(k) \right)^2 \right\} \end{aligned}$$



# Properties of MLE

$$\begin{aligned} & E \left\{ \left( \frac{1}{N} \sum_{k=1}^N v(k) \right)^2 \right\} \\ &= \frac{1}{N^2} E \left\{ \left( \sum_{k=1}^N v(k) \right) \left( \sum_{l=1}^N v(l) \right) \right\} \\ &= \frac{1}{N^2} \sum_{k=1}^N \sum_{l=1}^N E \{ v(l) v(k) \} \end{aligned}$$



# Properties of MLE

$$\frac{1}{N^2} \sum_{k=1}^N \sum_{l=1}^N E\{v(l)v(k)\} = \frac{1}{N^2} \sum_{k=1}^N \sum_{l=1}^N \sigma^2 \delta(k-l)$$

$$= \frac{1}{N^2} \sum_{k=1}^N \sigma^2 = \frac{\sigma^2}{N}$$

MSE decreases  
as  $\frac{1}{N}$ .

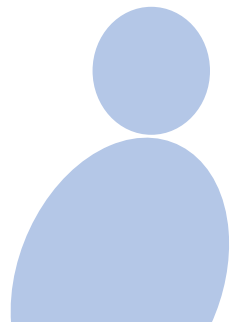


# Properties of MLE

- Therefore, MSE decreases as

$$MSE = \frac{\sigma^2}{N} \propto \frac{1}{N}$$

$$\underline{MSE \rightarrow 0 \text{ as } N \rightarrow \infty.}$$





# Properties of MLE

- Therefore,  $\hat{h}$  is Gaussian with mean 0 and variance  $\frac{\sigma^2}{N}$

$$\hat{h} \sim \mathcal{N}\left(h, \frac{\sigma^2}{N}\right)$$

*Mean*

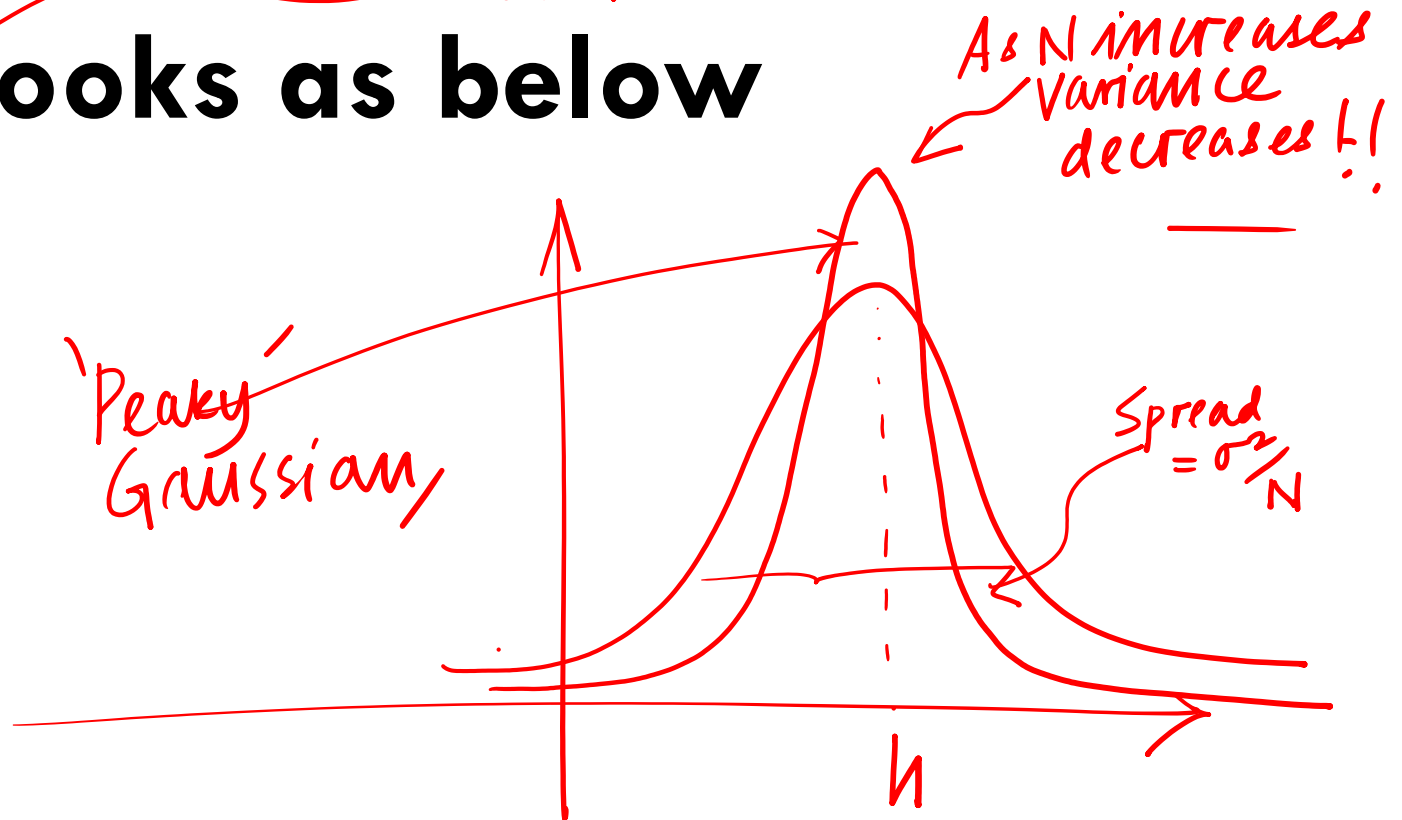
*Variance*

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# Properties of MLE

- PDF looks as below



# MLE Example

$$N = 4.$$

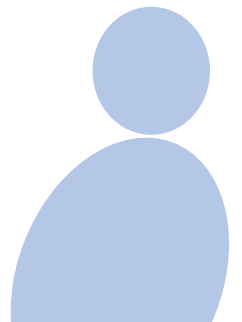
- Consider the observations be  $y(1) = 1$ ,  $y(2) = -3$ ,  $y(3) = 2$ ,  $y(4) = -1$ .
- What is the **maximum likelihood** estimate  $\hat{h}$  of the unknown parameter  $h$  ?

$$\begin{aligned} & \frac{1}{4} \{ y(1) + y(2) + y(3) + y(4) \} \\ &= \frac{1}{4} \{ 1 + (-3) + 2 + (-1) \} = \underline{-\frac{1}{4}}. \end{aligned}$$



# MLE Example

- The ML estimate is given by the sample mean



# MLE Example

- The ML estimate is given by the sample mean

$$\hat{h} = \frac{1}{N} \sum_{k=1}^N y(k) = \frac{1 - 3 + 2 - 1}{4} = -\frac{1}{4}$$

$\hat{h} = -\frac{1}{4}$



# MLE Example

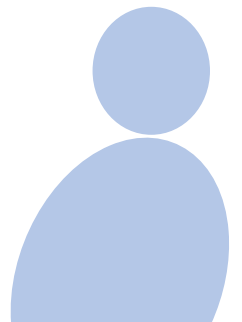
- Consider the observations be  $y(1) = 1$ ,  $y(2) = -3$ ,  $y(3) = 2$ ,  $y(4) = -1$ .
- IID Gaussian noise samples of variance  $\underline{\sigma^2} = \frac{1}{4}$ . What is the variance of the ML estimate ?

$$\begin{aligned} \text{MSE} = \text{Variance} &= \frac{\sigma^2}{4} = \frac{\sigma^2}{N} \\ &= \frac{1/4}{4} = \underline{\underline{1/16}}. \end{aligned}$$



# MLE Example

- Given  $\sigma^2 = \frac{1}{4}$ . The variance of the sample mean is  $\frac{\sigma^2}{N}$ .
- Given  $N = 4$ , the variance of the sample mean is



# MLE Example

- Given  $\sigma^2 = \frac{1}{4}$ . The variance of the sample mean is  $\frac{\sigma^2}{N}$ .
- Given  $N = 4$ , the variance of the sample mean is

$$\frac{\sigma^2}{N} = \frac{\frac{1}{4}}{4} = \frac{1}{16}$$

MSE/  
Variance

