eMasters in Communication Systems Prof. Aditya Jagannatham

Elective Module: Estimation for Wireless Communication

Chapter 11 MMSE/LMMSE MIMO Estimation and Receivers

/tx1

r = # Receive auteuras. t = # Transmit auteuras.

MIMO system model is given as

$$\begin{bmatrix} y_1(k) \\ y_2(k) \\ \vdots \\ y_r(k) \end{bmatrix} = \begin{bmatrix} h_{11} & h_{12} & \dots & h_{1t} \\ h_{21} & h_{22} & \dots & h_{2t} \\ \vdots & \vdots & \ddots & \vdots \\ h_{r1} & h_{r2} & \dots & h_{rt} \end{bmatrix} \begin{bmatrix} x_1(k) \\ x_2(k) \\ \vdots \\ x_t(k) \end{bmatrix} + \begin{bmatrix} v_1(k) \\ v_2(k) \\ \vdots \\ v_r(k) \end{bmatrix}$$

$$\bar{y}(k)$$
What the theory where the properties of the properties

• MIMO imput output model.

• MIMO system model can be represented in the compact fashion

$$\overline{J}(k) = \overline{H} \overline{\chi}(k) + \overline{V}(k) -$$

 MIMO system model can be represented in the compact fashion

$$\bar{\mathbf{y}}(k) = \mathbf{H}\bar{\mathbf{x}}(k) + \bar{\mathbf{v}}(k)$$

ullet Consider the transmission of N pilot vectors

$$\overline{y}(1) = H\overline{x}(1) + \overline{v}(1)$$

$$\overline{y}(z) = H\overline{x}(z) + \overline{v}(z)$$

$$\vdots$$

$$\overline{y}(N) \stackrel{!}{=} H\overline{x}(N) + \overline{v}(N).$$

ullet Consider the transmission of N pilot vectors

$$\bar{\mathbf{y}}(1) = \mathbf{H}\bar{\mathbf{x}}(1) + \bar{\mathbf{v}}(1)
\bar{\mathbf{y}}(2) = \mathbf{H}\bar{\mathbf{x}}(2) + \bar{\mathbf{v}}(2)
\vdots
\bar{\mathbf{y}}(N) = \mathbf{H}\bar{\mathbf{x}}(N) + \bar{\mathbf{v}}(N)$$

We can concatenate them as

$$[\bar{\mathbf{y}}(1) \quad \bar{\mathbf{y}}(2) \quad \dots \quad \bar{\mathbf{y}}(N)]$$

$$= \mathbf{H} [\bar{\mathbf{x}}(1) \quad \bar{\mathbf{x}}(2) \quad \dots \quad \bar{\mathbf{x}}(N)]$$

$$+ [\bar{\mathbf{v}}(1) \quad \bar{\mathbf{v}}(2) \quad \dots \quad \bar{\mathbf{v}}(N)]$$

$$\check{\mathbf{v}}$$

MIMO Estimation Model

 This can be represented in the compact fashion

$$Y = HX + N.$$

MIMO Estimation Model

• This can be represented in the compact fashion

$$Y = HX + V$$

MIMO channel Estimation model.

Pinv of
$$X = X^{T}(XX^{T})^{-1}$$

$$X^{H}(XX^{H})^{-1}$$

ML MIMO Estimate

The ML MIMO channel estimate is

$$\widehat{\mathbf{H}} = \mathbf{Y}\mathbf{X}^T(\mathbf{X}\mathbf{X}^T)^{-1}$$

ML Channel estimate
min.
$$\|Y - HX\|_F^{robenius}$$

LMMSE MIMO Estimate

• The LMMSE MIMO channel estimate is

$$\widehat{\mathbf{H}} = \mathbf{Y}\mathbf{X}^{T} \left(\mathbf{X}\mathbf{X}^{T} + \frac{1}{SNR} \mathbf{I} \right)^{-1}$$

$$SNR = \frac{\sigma_{h}^{2}}{\sigma^{2}} \quad \stackrel{\text{SNR} \to \infty}{\text{LAMSE} \to ML}$$

 Consider the MIMO channel estimation problem with pilot vectors

$$\bar{\mathbf{x}}(1) = [3 \quad -2]^T, \bar{\mathbf{x}}(2) = [-2 \quad 3]^T$$
 $\bar{\mathbf{x}}(3) = [4 \quad 2]^T, \bar{\mathbf{x}}(4) = [2 \quad 2]^T$
 $N=4$
 $N=4 \quad k=2$

What is the pilot matrix?, 2x4

$$X = \begin{bmatrix} 3 & -2 & 4 & 2 \\ -2 & 3 & 2 & 2 \end{bmatrix}$$

The pilot matrix is

$$\mathbf{X} = \begin{bmatrix} \overline{\mathbf{x}}(1) & \overline{\mathbf{x}}(2) & \overline{\mathbf{x}}(3) & \overline{\mathbf{x}}(4) \end{bmatrix}$$
$$= \begin{bmatrix} 3 & -2 & 4 & 2 \\ -2 & 3 & 2 & 2 \end{bmatrix}$$

The output vectors are

$$\bar{\mathbf{y}}(1) = [-2, 1, -3]^T,
\bar{\mathbf{y}}(2) = [-1, 3, 3]^T,
\bar{\mathbf{y}}(3) = [-1, -2, 2]^T,
\bar{\mathbf{y}}(4) = [-3, -1, 1]^T$$

TXL = 3 x 2 MIMD System 3 x 4

• What is the output matrix?

$$Y = \begin{bmatrix} -2 & -1 & -1 & -3 \\ 1 & 3 & -2 & -1 \\ -3 & 3 & 2 & 1 \end{bmatrix}$$

The output matrix is

$$\mathbf{Y} = \begin{bmatrix} \bar{\mathbf{y}}(1) & \bar{\mathbf{y}}(2) & \bar{\mathbf{y}}(3) & \bar{\mathbf{y}}(4) \end{bmatrix}$$

$$= \begin{bmatrix} -2 & -1 & -1 & -3 \\ 1 & 3 & -2 & -1 \\ -3 & 3 & 2 & 1 \end{bmatrix}$$

The LMMSE channel estimate is given as follows

$$\widehat{\mathbf{H}} = \mathbf{Y}\mathbf{X}^T \left(\mathbf{X}\mathbf{X}^T + \frac{1}{SNR}\mathbf{I}\right)^{-1}$$

Let us first evaluate

$$= \begin{bmatrix} 3 & -2 & 4 & 2 \\ -2 & 3 & 2 & 2 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ -2 & 3 \\ 4 & 2 \\ 2 & 2 \end{bmatrix} = \begin{bmatrix} 33 & 0 \\ 0 & 21 \end{bmatrix}$$

$$\times \begin{bmatrix} 3 & -2 \\ 2 & 2 \end{bmatrix} = \begin{bmatrix} 33 & 0 \\ 0 & 21 \end{bmatrix}$$

Let
$$SNR = -6 dB = \frac{1}{4}$$

$$\begin{pmatrix} \mathbf{X}\mathbf{X}^T + \frac{1}{SNR}\mathbf{I} \end{pmatrix}^{-1} = \begin{pmatrix} \begin{bmatrix} 33 & 0 \\ 0 & 21 \end{bmatrix} + 4\mathbf{I} \end{pmatrix}^{-1}$$

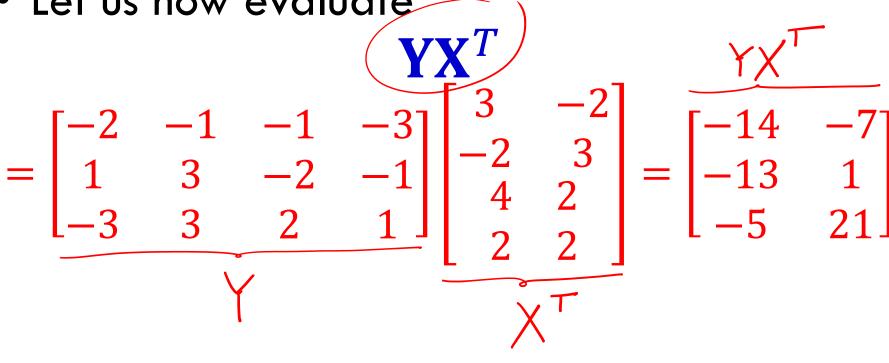
$$= \begin{bmatrix} 33 & 0 \\ 0 & 21 \end{bmatrix} + 4\begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 37 & 0 \\ 0 & 25 \end{bmatrix}$$

Let
$$SNR = -6 dB$$

$$\left(\mathbf{X}\mathbf{X}^{T} + \frac{1}{SNR}\mathbf{I}\right)^{-1} = \left(\begin{bmatrix}33 & 0\\0 & 21\end{bmatrix} + 4\mathbf{I}\right)^{-1}$$

$$= \begin{bmatrix} \frac{1}{37} & 0\\ 37 & 1\\ 0 & \frac{1}{25} \end{bmatrix}$$

Let us now evaluate



Finally, the MIMO channel estimate is

$$\hat{\mathbf{H}} = \mathbf{Y}\mathbf{X}^{T} \left(\mathbf{X}\mathbf{X}^{T} + \frac{1}{SNR} \mathbf{I} \right)^{-1}$$

$$= \begin{bmatrix} -14 & -7 \\ -13 & 1 \\ -5 & 21 \end{bmatrix} \begin{bmatrix} \frac{1}{37} & 0 \\ 0 & \frac{1}{25} \end{bmatrix} = \begin{bmatrix} -\frac{14}{37} & -\frac{7}{25} \\ -\frac{13}{37} & \frac{1}{25} \end{bmatrix}$$

• Finally, the MIMO channel estimate is

$$\widehat{\mathbf{H}} = \mathbf{Y}\mathbf{X}^{T} \begin{pmatrix} \mathbf{X}\mathbf{X}^{T} + \frac{1}{SNR} \mathbf{I} \\ -14 & -7 \\ -13 & 1 \\ -5 & 21 \end{pmatrix} \begin{bmatrix} \frac{1}{37} & 0 \\ 0 & \frac{1}{25} \end{bmatrix} = \begin{bmatrix} \frac{1}{37} & \frac{1}{25} \\ -\frac{13}{37} & \frac{1}{25} \\ -\frac{5}{37} & \frac{21}{25} \end{bmatrix}$$

$$LMMSE MIMD Chaund Estimate -$$

MIMO Receivers

MIMO Receivers

John Halk + Volume

• Consider the MIMO model

$$\bar{\mathbf{y}} = \mathbf{H}\bar{\mathbf{x}} + \bar{\mathbf{v}}$$

ullet Time index k dropped for simplicity

MIMO Receivers $\overline{y} = H\overline{x} + \overline{v}$

• How to determine \bar{x} given \bar{y} ?

What is estimate of Transmit vector?

MIMO ZF Receiver

Least squares Receiver
$$\min \| \overline{\mathbf{y}} - \mathbf{H} \overline{\mathbf{x}} \|^2$$

This is termed the least-squares problem.

$$\hat{\chi} = (H^{H}H)^{T}H^{H}J^{T}$$
Zero Forcing (ZF) Receiver

MIMO Receiver

$$\hat{\mathbf{x}} = (\mathbf{H}^H \mathbf{H})^{-1} \mathbf{H}^H \bar{\mathbf{y}}$$

This is termed as the zero-forcing (ZF)
 Receiver.

Example:

Consider

$$\bar{\mathbf{y}} = \begin{bmatrix} -1 \\ 3 \\ 1 \\ -2 \end{bmatrix}, \mathbf{H} = \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{bmatrix}$$

What is $\hat{\mathbf{x}}$?

The **ZF** estimate can be calculated as follows

$$\mathbf{H}^{T}\mathbf{H} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \\ 1 & 4 \end{bmatrix}$$
$$= \begin{bmatrix} 4 & 10 \\ 10 & 30 \end{bmatrix}$$

$$\mathbf{H}^T \mathbf{H} = \begin{bmatrix} 4 & 10 \\ 10 & 30 \end{bmatrix}$$

$$(\mathbf{H}^T\mathbf{H})^{-1} = \frac{1}{20} \begin{bmatrix} 30 & -10 \\ -10 & 4 \end{bmatrix}$$

$$\mathbf{H}^T \mathbf{H} = \begin{bmatrix} 4 & 10 \\ 10 & 30 \end{bmatrix}$$

$$(\mathbf{H}^T \mathbf{H})^{-1} = \frac{1}{20} \begin{bmatrix} 30 & -10 \\ -10 & 4 \end{bmatrix}$$

$$(\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T = \frac{1}{20} \begin{bmatrix} 30 & -10 \\ -10 & 4 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & \frac{1}{2} & 0 & -\frac{1}{2} \\ -\frac{3}{10} & -\frac{1}{10} & \frac{1}{10} & \frac{3}{10} \end{bmatrix}$$
$$(H^{T}H)^{H}H^{T}$$

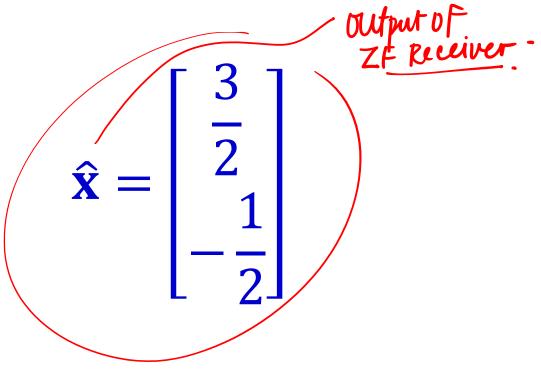
$$\hat{\mathbf{x}} = (\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T \mathbf{\bar{y}}$$

$$= \begin{bmatrix} 1 & \frac{1}{2} & 0 & -\frac{1}{2} \\ -\frac{3}{10} & -\frac{1}{10} & \frac{1}{10} & \frac{3}{10} \end{bmatrix} \begin{bmatrix} -1 \\ 3 \\ 1 \\ -2 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{3}{2} \\ -\frac{1}{2} \end{bmatrix} = \hat{\lambda} = \text{Zero Foreing}_{\text{Estimals}}$$

MIMO ZF Receiver Example

• Therefore, the **ZF** estimate is



LMMSE Receiver

 Another popular MIMO receiver is the LMMSE Receiver

ML: Deterministic

MMSE/LMMSE: Random -

LMMSE

$$\min E\{\|\mathbf{C}^H\mathbf{\bar{y}}-\mathbf{\bar{x}}\|^2\}$$

LMMSE Receiver

$$[= \{ x(i) \} = 0$$

 $[= \{ |x(i)|^2 \} = P$

power P.

$$E\{\bar{\mathbf{x}}\bar{\mathbf{x}}^H\} = P\mathbf{I}$$

LMMSE Receiver

• The LMMSE Receiver is

$$\hat{\mathbf{x}} = \left(\mathbf{H}^H \mathbf{H} + \frac{1}{SNR} \mathbf{I}\right)^{-1} \mathbf{H}^H \bar{\mathbf{y}}$$

$$SNR = \frac{P}{N_0}$$

Example:

Consider

$$\bar{\mathbf{y}} = \begin{bmatrix} -1\\3\\1\\-2 \end{bmatrix}, \mathbf{H} = \begin{bmatrix} 1\\1\\1\\1\\-1 \end{bmatrix}$$

What is
$$\hat{\mathbf{x}}$$
 when $SNR = -3dB = \frac{1}{2}$

The LMMSE estimate can be calculated as follows

$$\mathbf{H}^{T}\mathbf{H} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \\ 1 & 1 \end{bmatrix}$$
$$= \begin{bmatrix} 4 & 0 \\ 0 & 4 \end{bmatrix} = 4\mathbf{I}$$

•
$$SNR = -3 dB \approx \frac{1}{2}$$

$$\mathbf{H}^{T}\mathbf{H} + \frac{1}{SNR}\mathbf{I} = 4\mathbf{I} + 2\mathbf{I} = 6\mathbf{I}$$

$$= \begin{bmatrix} 6 & 0 \\ 0 & 6 \end{bmatrix}$$

•
$$SNR = -3 dB \approx \frac{1}{2}$$

$$\mathbf{H}^T \mathbf{H} + \frac{1}{SNR} \mathbf{I} = \begin{bmatrix} 6 & 0 \\ 0 & 6 \end{bmatrix}$$

$$\mathbf{H}^T \mathbf{H} + \frac{1}{SNR} \mathbf{I} = \begin{bmatrix} 6 & 0 \\ 0 & 6 \end{bmatrix}$$

$$\left(\mathbf{H}^T\mathbf{H} + \frac{1}{SNR}\mathbf{I}\right)^{-1} = \frac{1}{6}\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\mathbf{H}^T \mathbf{H} + \frac{1}{SNR} \mathbf{I} = \begin{bmatrix} 6 & 0 \\ 0 & 6 \end{bmatrix}$$

$$\left(\mathbf{H}^T\mathbf{H} + \frac{1}{SNR}\mathbf{I}\right)^{-1} = \frac{1}{6}\begin{bmatrix}1 & 0\\ 0 & 1\end{bmatrix}$$

$$\left(\mathbf{H}^{T}\mathbf{H} + \frac{1}{\text{SNR}}\mathbf{I}\right)^{-1}\mathbf{H}^{T} = \frac{1}{6}\begin{bmatrix}1 & 0\\ 0 & 1\end{bmatrix}\begin{bmatrix}1 & 1 & 1 & 1\\ 1 & -1 & 1 & -1\end{bmatrix}$$

$$= \frac{1}{6} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \end{bmatrix}$$

$$= \frac{1}{6} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \end{bmatrix}$$

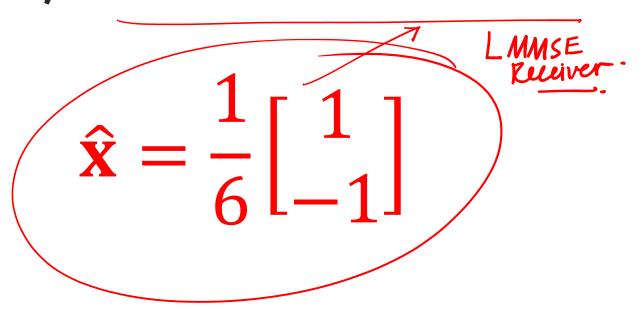
$$\hat{\mathbf{x}} = (\mathbf{H}^T \mathbf{H})^{-1} \mathbf{H}^T \bar{\mathbf{y}}$$

$$= \frac{1}{6} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -1 & 1 & -1 \end{bmatrix} \begin{bmatrix} -1 \\ 3 \\ 1 \\ -2 \end{bmatrix}$$

$$= \frac{1}{6} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 2 \text{ LMMSE}$$

$$= \frac{1}{6} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 2 \text{ LMMSE}$$

• Therefore, the LMMSE estimate is



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