EE910: Digital Communication Systems-I

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Lecture #6A: Optimal Detection and Error Probability for ASK or PAM and PSK Signalling



• The constellation for an ASK Signalling scheme is shown as



• In this constellation the minimum distance between any two points is d_{min} which is given by

$$d_{min} = \sqrt{\frac{12\log_2 M}{M^2 - 1}} \mathcal{E}_{bavg} \tag{1}$$

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Optimal Detection and Error Probability for ASK or PAM Signalling

- The constellation points are located at $\left\{\pm\frac{1}{2}d_{min},\pm\frac{3}{2}d_{min},...,\pm\frac{M-1}{2}d_{min}\right\}$
- In this ASK constellation, there are M-2 inner points and 2 outer points.

- Let us denote the error probabilities of inner points and outer points by P_{ei} and P_{eo} , respectively.
- Since n is a zero-mean Gaussian random variable with variance $\frac{1}{2}N_0$, we have

$$P_{ei} = P\left[|n| > \frac{1}{2}d_{min}\right] = 2Q\left(\frac{d_{min}}{\sqrt{2N_0}}\right) \tag{2}$$

and for outer points

$$P_{eo} = \frac{1}{2}P_{ei} = Q\left(\frac{d_{min}}{\sqrt{2N_0}}\right) \tag{3}$$

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Optimal Detection and Error Probability for ASK or PAM Signalling

• The symbol error probability is given by

$$P_{e} = \frac{1}{M} \sum_{m=1}^{M} P[error|m \ sent]$$

$$= \frac{1}{M} \left[2(M-2)Q\left(\frac{d_{min}}{\sqrt{2N_{0}}}\right) + 2Q\left(\frac{d_{min}}{\sqrt{2N_{0}}}\right) \right]$$

$$= \frac{2(M-1)}{M} Q\left(\frac{d_{min}}{\sqrt{2N_{0}}}\right)$$
(4)

Substituting for d_{min} from Equation (1) we get

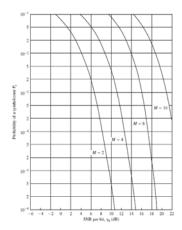
$$P_{e} = 2\left(1 - \frac{1}{M}\right)Q\left(\sqrt{\frac{6\log_{2}M}{M^{2}-1}} \frac{\mathcal{E}_{bavg}}{N_{0}}\right)$$

$$\approx 2Q\left(\sqrt{\frac{6\log_{2}M}{M^{2}-1}} \frac{\mathcal{E}_{bavg}}{N_{0}}\right) \quad \text{for large } M$$
(5)

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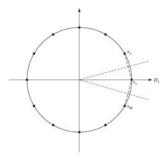
- The average SNR/bit $\frac{\mathcal{E}_{bavg}}{N_0}$ is scaled by $\frac{6\log_2 M}{M^2-1}$ To keep the error probability constant as M increases, the SNR/bit must increase.
- For increasing the transmission rate by 1 bit, one would need 6 dB more power

Plots of the error probability of baseband PAM/ASK.



• Increasing M deteriorates the performance, and for large M the distance between curves corresponding to M and 2M is roughly 6 dB.

• The constellation for an M-ary PSK Signalling is shown below



- ullet In this constellation, the decision region D_1 is also shown.
- The decision regions are based on the minimum-distance detection rule.

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Optimal Detection and Error Probability for PSK Signalling

- By symmetry of the constellation, the error probability of the system is equal to the error probability when $s_1 = (\sqrt{\mathcal{E}}, 0)$ is transmitted.
- The received vector \mathbf{r} is given by

$$\mathbf{r} = (r_1, r_2) = (\sqrt{\mathcal{E}} + n_1, n_2)$$
 (6)

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• It is seen that r_1 and r_2 are independent Gaussian random variables with variance $\sigma^2=\frac{1}{2}N_0$ and means $\sqrt{\mathcal{E}}$ and 0, respectively; hence

$$p(r_1, r_2) = \frac{1}{\pi N_0} e^{-\frac{(r_1 - \sqrt{\varepsilon})^2 + r_2^2}{N_0}}$$
 (7)

• We introduce polar coordinates transformations of (r_1, r_2) as

$$V = \sqrt{r_1^2 + r_2^2} \tag{8}$$

$$\Theta = \arctan \frac{r_2}{r_1} \tag{9}$$

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Optimal Detection and Error Probability for PSK Signalling

ullet The joint PDF of V and Θ can be derived as

$$p_{V,\Theta}(\nu,\theta) = \frac{\nu}{\pi N_0} e^{-\frac{\nu^2 + \mathcal{E} - 2\sqrt{\mathcal{E}}\nu\cos\theta}{N_0}}$$
 (10)

• Integrating over ν , we derive the marginal PDF of Θ as

$$p_{\Theta}(\theta) = \int_{0}^{\infty} p_{V,\Theta}(\nu,\theta) d\nu$$

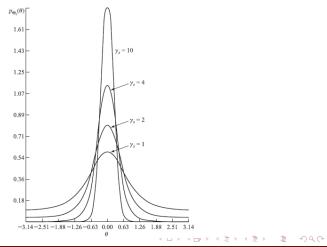
$$= \frac{1}{2\pi} e^{-\gamma_{s} \sin^{2}\theta} \int_{0}^{\infty} \nu e^{-\frac{(\nu - \sqrt{2\gamma_{s}}\cos\theta)^{2}}{2}} d\nu$$
(11)

• We have defined the symbol SNR or SNR per symbol as

$$\gamma_{s} = \frac{\mathcal{E}}{N_{0}} \tag{12}$$

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• This figure illustrates $p_{\Theta}(\theta)$ for several values of γ_s



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Optimal Detection and Error Probability for PSK Signalling

- Note that $p_{\Theta}(\theta)$ becomes narrower and more peaked about $\theta=0$ as γ_s increases.
- ullet The decision region D_1 can be described as $D_1=\{ heta: rac{-\pi}{M}< heta\leq rac{\pi}{M}\}$
- The message error probability is given by

$$P_{e} = 1 - \int_{-\pi/M}^{\pi/M} p_{\Theta}(\theta) d\theta \tag{13}$$

- In general, the integral of $p_{\Theta}(\theta)$ does not reduce to a simple form and must be evaluated numerically, except for M=2 and M=4.
- For binary phase modulation, the two signals $s_1(t)$ and $s_2(t)$ are antipodal, and hence the error probability is

$$P_b = Q\left(\sqrt{\frac{2\mathcal{E}_b}{N_0}}\right) \tag{14}$$

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Optimal Detection and Error Probability for PSK Signalling

- When M=4, we have two binary phase-modulation signals in phase quadrature. Hence, the bit error probability is identical to Binary phase modulation.
- The symbol error probability for M=4 is determined by noting that

$$P_c = (1 - P_b)^2 = \left[1 - Q\left(\sqrt{\frac{2\mathcal{E}_b}{N_0}}\right)\right]^2$$
 (15)

where P_c is the probability of a correct decision for the 2-bit symbol.

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• Therefore, the symbol error probability for M=4 is

$$P_{e} = 1 - P_{c}$$

$$= 2Q\left(\sqrt{\frac{2\mathcal{E}_{b}}{N_{0}}}\right) \left[1 - \frac{1}{2}Q\left(\sqrt{\frac{2\mathcal{E}_{b}}{N_{0}}}\right)\right]$$
(16)

• For M > 4, the symbol error probability P_e is obtained by numerically integrating the equation

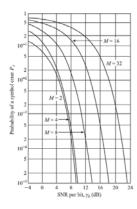
$$P_e = 1 - \int_{-\pi/M}^{\pi/M} p_{\Theta}(\theta) d\theta \tag{17}$$

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Error probability as a function of the SNR per bit for M = 2, 4, 8, 16, and 32.



• The graph clearly illustrates the penalty in SNR per bit as M increases beyond M=4.

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- For large values of M, doubling the number of phases requires an additional 6 dB/bit to achieve the same performance.
- An approximation to the error probability for large values of M and for large SNR may be obtained by first approximating $p_{\Theta}(\theta)$.
- For $\frac{\mathcal{E}}{N_0}\gg 1$ and $|\theta|\leq \frac{1}{2}\pi$, $p_{\Theta}(\theta)$ is well approximated as

$$p_{\Theta}(\theta) \approx \sqrt{\frac{\gamma_s}{\pi}} \cos \theta e^{-\gamma_s \sin^2 \theta}$$
 (18)

• By substituting for $p_{\theta}(\theta)$ in equation $P_{e}=1-\int_{-\pi/M}^{\pi/M}p_{\Theta}(\theta)d\theta$ and performing the change in variable from θ to $u=\sqrt{\gamma_{\rm s}}\sin\theta$ we find that

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Optimal Detection and Error Probability for PSK Signalling

Probability of symbol error

$$P_{e} \approx 1 - \int_{-\frac{\pi}{M}}^{\frac{\pi}{M}} \sqrt{\frac{\gamma_{s}}{\pi}} \cos \theta e^{-\gamma_{s} \sin^{2} \theta} d\theta$$

$$\approx \frac{2}{\sqrt{\pi}} \int_{\sqrt{2\gamma_{s}} \sin(\pi/M)}^{\infty} e^{-u^{2}} du$$

$$= 2Q \left(\sqrt{2\gamma_{s}} \sin(\frac{\pi}{M}) \right)$$

$$= 2Q \left(\sqrt{(2 \log_{2} M) \sin^{2}(\frac{\pi}{M})} \frac{\mathcal{E}_{b}}{N_{0}} \right)$$
(19)

where we have used the definition of the SNR per bit as

$$\frac{\mathcal{E}_b}{N_0} = \frac{\mathcal{E}}{N_0 \log_2 M} = \frac{\gamma_s}{\log_2 M} \tag{20}$$

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- Note that this approximation to the error probability is good for all values of M.
- For example, when M=2 and M=4, we have $P_e=2Q(\sqrt{2\gamma_b})$
- For the case when M is large, we can use the approximation $sin\frac{\pi}{M} \approx \frac{\pi}{M}$ to find another approximation to error probability for large M as

$$P_{\rm e} \approx 2Q \left(\sqrt{\frac{2\pi^2 \log_2 M}{M^2} \frac{\mathcal{E}_b}{N_0}} \right) \quad \text{for large } M$$
 (21)

• From this equation, it is clear that doubling M reduces the effective SNR per bit by 6 dB.

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Optimal Detection and Error Probability for PSK Signalling

- The equivalent bit error probability for M-ary PSK is rather tedious to derive due to its dependence on the mapping of k-bit symbols into the corresponding signal phases.
- Since the most probable errors due to noise result in the erroneous selection of an adjacent phase to the true phase, most k-bit symbol errors contain only a single-bit error.
- Hence, the equivalent bit error probability for M-ary PSK is well approximated as

 $P_b \approx \frac{1}{k} P_e \tag{22}$



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