

# Eigenvalues and Eigenvectors of Symmetric Matrices

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# Recap and agenda for today's class

- Discussed eigenvalues and eigenvectors for a generic matrix  $A$
- Discuss these concepts for symmetric matrices
  - Chapter 6.4 of the book

# Eigenvalues, Eigenvectors, Diagonalization (recap)

- Almost all vectors change direction when they are multiple by  $A$  i.e.,  $A\mathbf{x} = \mathbf{y}$
- Certain exceptional vectors  $\mathbf{x}$  are in the same direction as  $A\mathbf{x}$

$$A\mathbf{x} = \lambda\mathbf{x}$$

- $\mathbf{x}$  is an eigenvector and  $\lambda$  is eigenvalue
  - $\lambda$  tell us whether the eigenvector is shrunk or stretched or left unchanged
  - $\lambda$  can be complex also
- Suppose  $n \times n$  matrix  $A$  has  $n$  linearly independent eigenvectors  $\mathbf{x}_1, \dots, \mathbf{x}_n$ 
  - We have  $AX = X\Lambda \Rightarrow A = X\Lambda X^{-1}$

# Eigenvalues, Eigenvectors of Symmetric Matrix

- What is special about  $S\mathbf{x} = \lambda\mathbf{x}$  when  $S$  is real and symmetric i.e.,  $S = S^T$ 
  - Symmetric matrix has real eigenvalues
  - Eigenvectors are chosen orthonormal when they correspond to different eigenvalues
- Why do we use the word "choose"?
  - Because eigenvectors need not be unit vectors, we can decide their lengths
  - We will choose eigenvectors of length one, which are orthonormal
- Suppose  $S\mathbf{x} = \lambda\mathbf{x}$ ,  $\lambda = a + ib$  might be complex, with conjugate  $\bar{\lambda} = a - ib$
- Components of  $\mathbf{x}$  may be complex
  - We change signs of their imaginary parts and denote it as  $\bar{\mathbf{x}}$
- Note that  $\bar{\lambda}\bar{\mathbf{x}} = \overline{\lambda\mathbf{x}}$  and  $\overline{S\mathbf{x}} = \bar{S}\bar{\mathbf{x}} = S\bar{\mathbf{x}}$

# Eigenvalues of symmetric matrix are real

- We can take conjugate of  $S\mathbf{x} = \lambda\mathbf{x}$ , with  $S$  being real

$$\overline{S\mathbf{x}} = \overline{\lambda\mathbf{x}} \text{ leads to } S\bar{\mathbf{x}} = \bar{\lambda}\bar{\mathbf{x}}. \text{ Transposes to } \bar{\mathbf{x}}^T S = \bar{\mathbf{x}}^T \bar{\lambda}$$

- Take inner product of the first equation with  $\bar{\mathbf{x}}$  and last equation with  $\mathbf{x}$

$$\bar{\mathbf{x}}^T S \bar{\mathbf{x}} = \bar{\mathbf{x}}^T \lambda \bar{\mathbf{x}} = \lambda \|\bar{\mathbf{x}}\|^2$$

$$\bar{\mathbf{x}}^T S \bar{\mathbf{x}} = \bar{\mathbf{x}}^T \bar{\lambda} \bar{\mathbf{x}} = \bar{\lambda} \|\bar{\mathbf{x}}\|^2$$

- This implies that  $\lambda = \bar{\lambda}$ , which implies that  $\lambda$  is real
- Eigenvector come from solving  $(S - \lambda I)\mathbf{x} = \mathbf{0}$ , they are also real
- Important fact is that they are also perpendicular which we prove now

# Eigenvectors are chosen orthogonal

- Suppose  $S\mathbf{x} = \lambda_1\mathbf{x}$  and  $S\mathbf{y} = \lambda_2\mathbf{y}$ , and we have

$$(\lambda_1\mathbf{x})^T\mathbf{y} = (S\mathbf{x})^T\mathbf{y} = \mathbf{x}^TS^T\mathbf{y} = \mathbf{x}^TS\mathbf{y} = \mathbf{x}^T\lambda_2\mathbf{y} = \lambda_2\mathbf{x}^T\mathbf{y} \quad (1)$$

- We also have

$$(\lambda_1\mathbf{x})^T\mathbf{y} = \mathbf{x}^T\lambda_1\mathbf{y} = \lambda_1\mathbf{x}^T\mathbf{y} \quad (2)$$

- LHS of Eq. (1) = LHS of Eq. (2). RHS of Eq. (1) = RHS of Eq. (2):

$$\lambda_2\mathbf{x}^T\mathbf{y} = \lambda_1\mathbf{x}^T\mathbf{y} \Rightarrow (\lambda_2 - \lambda_1)\mathbf{x}^T\mathbf{y} = 0$$

- Since  $\lambda_1 \neq \lambda_2$ , we have  $\mathbf{x}^T\mathbf{y} = 0$
- $\mathbf{x}$  and  $\mathbf{y}$  may not have unit length but we can choose them to have so

$$S\mathbf{x} = \lambda_1\mathbf{x} \Rightarrow S\frac{\mathbf{x}}{\|\mathbf{x}\|} = \lambda_1\frac{\mathbf{x}}{\|\mathbf{x}\|}$$

# Eigenvectors are chosen orthogonal

- Symmetric matrix  $S$  has orthogonal eigenvector matrices  $Q$
- Every 2 by 2 symmetric matrix  $S$  can be decomposed as

$$\begin{aligned} S &= Q\Lambda Q^{-1} = Q\Lambda Q^T = \begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_2 \end{bmatrix} \begin{bmatrix} \lambda_1 & \\ & \lambda_2 \end{bmatrix} \begin{bmatrix} \mathbf{x}_1^T \\ \mathbf{x}_2^T \end{bmatrix} \\ &= \lambda_1 \mathbf{x}_1 \mathbf{x}_1^T + \lambda_2 \mathbf{x}_2 \mathbf{x}_2^T \end{aligned}$$

- Every  $n$  by  $n$  symmetric matrix  $S$  can be similarly decomposed as

$$S = \lambda_1 \mathbf{x}_1 \mathbf{x}_1^T + \lambda_2 \mathbf{x}_2 \mathbf{x}_2^T + \cdots + \lambda_n \mathbf{x}_n \mathbf{x}_n^T$$

- Spectral Theorem: Every symmetric matrix can be factorized as  $S = Q\Lambda Q^T$  with real eigenvalues in  $\Lambda$  and orthonormal eigenvectors in the columns of  $Q$

# Complex Eigenvalues of Real Matrices

- For a real non-symmetric matrix, complex eigenvalues and eigenvectors occur in pair

$$\text{If } A\mathbf{x} = \lambda\mathbf{x} \text{ then } A\bar{\mathbf{x}} = \bar{\lambda}\bar{\mathbf{x}}$$

- For  $A = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ ,  $\lambda_1 = \cos \theta + i \sin \theta$  and  $\lambda_2 = \cos \theta - i \sin \theta$
- Eigenvectors must be  $\mathbf{x}$  and  $\bar{\mathbf{x}}$  as  $A$  is real

$$A\mathbf{x} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} 1 \\ -i \end{bmatrix} = (\cos \theta + i \sin \theta) \begin{bmatrix} 1 \\ -i \end{bmatrix}$$

$$A\bar{\mathbf{x}} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} 1 \\ i \end{bmatrix} = (\cos \theta - i \sin \theta) \begin{bmatrix} 1 \\ i \end{bmatrix}$$



# All Symmetric Matrices are Diagonalizable

- When no eigenvalues of  $A$  are repeated, eigenvectors are independent
  - $A$  can be diagonalized
- But a repeated eigenvalue can produce a shortage of eigenvectors
  - This sometimes happens for nonsymmetric matrices
- It never happens for symmetric matrices
  - There are always enough eigenvectors to diagonalize