Live Interaction #6:

5th November 2023

E-masters Communication Systems

Estimation for Wireless

MMSE: Minimum Mean Square Error.

$$\min E\left\{\left\|\hat{\mathbf{h}} - \overline{\mathbf{h}}\right\|^2\right\}$$

▶ h: Random quantity.

$$\hat{\mathbf{h}} = E\{\bar{\mathbf{h}}|\bar{\mathbf{y}}\}$$

Simplest case: $\bar{\mathbf{h}}, \bar{\mathbf{y}}$ to be **jointly Gaussian** and zeromean

$$\hat{\mathbf{h}} = E\{\bar{\mathbf{h}}|\bar{\mathbf{y}}\} = \mathbf{R}_{hy}\mathbf{R}_{yy}^{-1}\bar{\mathbf{y}}$$

$$\hat{\mathbf{h}} = E\{\bar{\mathbf{h}}|\bar{\mathbf{y}}\} = \mathbf{R}_{hy}\mathbf{R}_{yy}^{-1}(\bar{\mathbf{y}} - \bar{\boldsymbol{\mu}}_{y}) + \bar{\boldsymbol{\mu}}_{h}$$

$$\mathbf{R}_{hy} = E\{(\bar{\mathbf{h}} - \bar{\boldsymbol{\mu}}_{h})(\bar{\mathbf{y}} - \bar{\boldsymbol{\mu}}_{y})^{T}\}$$

$$\frac{\text{cross-covariance}}{\mathbf{R}_{yy}} = E\{(\bar{\mathbf{y}} - \bar{\boldsymbol{\mu}}_{y})(\bar{\mathbf{y}} - \bar{\boldsymbol{\mu}}_{y})^{T}\}$$

$$\frac{\text{covariance}}{\text{covariance}}$$

▶ Linear Model:

$$\underline{\overline{y}} = X\overline{h} + \overline{v}$$
Linear model

MMSE Estimate:

$$\hat{\mathbf{h}} = \left(\mathbf{X}^{T}\mathbf{X} + \frac{1}{SNR}\mathbf{I}\right)^{-1}\mathbf{X}^{T}\bar{\mathbf{y}}$$

$$MMSE \text{ Estimate}$$

$$SNR = \frac{\sigma_{h}^{2}}{\sigma^{2}}$$

$$E\{\bar{\mathbf{h}}\bar{\mathbf{h}}^{T}\} = \sigma_{h}^{2}\mathbf{I}$$

$$E\{\bar{\mathbf{v}}\bar{\mathbf{v}}^{T}\} = \sigma^{2}\mathbf{I}$$

▶ MMSE estimate $SNR \rightarrow \infty$.

$$\hat{\mathbf{h}} = \left(\mathbf{X}^T \mathbf{X} + \frac{1}{SNR} \mathbf{I}\right)^{-1} \mathbf{X}^T \bar{\mathbf{y}}$$

$$= \underbrace{(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \bar{\mathbf{y}}}_{\text{ML Estimate}}$$

▶ Error covariance matrix:

$$E\left\{\left(\hat{\mathbf{h}} - \bar{\mathbf{h}}\right)\left(\hat{\mathbf{h}} - \bar{\mathbf{h}}\right)^{T}\right\} = \mathbf{R}_{hh} - \mathbf{R}_{hy}\mathbf{R}_{yy}^{-1}\mathbf{R}_{yh}$$

$$= \sigma^{2}\left(\mathbf{X}^{T}\mathbf{X} + \frac{1}{SNR}\mathbf{I}\right)^{-1}$$

$$= \sigma^{2}\left(\mathbf{X}^{T}\mathbf{X} + \frac{\sigma^{2}}{\sigma_{h}^{2}}\mathbf{I}\right)^{-1}$$

$$= \left(\frac{1}{\sigma^{2}}\mathbf{X}^{T}\mathbf{X} + \frac{1}{\sigma_{h}^{2}}\mathbf{I}\right)^{-1}$$

▶ Noise power $\sigma^2 \to \infty$?

$$\sigma_h^2 \mathbf{I}$$

Example:

$$\mathbf{X} = \begin{bmatrix} 1 & -1 \\ -1 & -1 \\ 1 & 1 \\ -1 & 1 \end{bmatrix}, \bar{\mathbf{y}} = \begin{bmatrix} -2 \\ 1 \\ 3 \\ 2 \end{bmatrix}$$

$$\sigma^2 = 2, \sigma_h^2 = \frac{1}{4} \Rightarrow SNR = \frac{\sigma_h^2}{\sigma^2} = \frac{\frac{1}{4}}{2} = \frac{1}{8}$$

$$\Rightarrow \frac{1}{SNR} = 8$$

▶ MMSE Estimate, Error covariance, MSE?

$$\mathbf{X}^{T}\mathbf{X} = 4\mathbf{I}$$

$$\mathbf{X}^{T}\mathbf{X} + \frac{1}{SNR}\mathbf{I} = 4\mathbf{I} + 8\mathbf{I} = 12\mathbf{I}$$

$$\left(\mathbf{X}^{T}\mathbf{X} + \frac{1}{SNR}\mathbf{I}\right)^{-1}\mathbf{X}^{T}\bar{\mathbf{y}}$$

$$= \frac{1}{12}\begin{bmatrix} 1 & -1 & 1 & -1 \\ -1 & -1 & 1 & 1 \end{bmatrix} \begin{bmatrix} -2 \\ 1 \\ 3 \\ 2 \end{bmatrix}$$

$$\hat{\mathbf{h}} = \frac{1}{12}\begin{bmatrix} -2 \\ 6 \end{bmatrix} = \begin{bmatrix} -\frac{1}{6} \\ 1 \end{bmatrix}$$

Error covariance =
$$\sigma^2 \left(\mathbf{X}^T \mathbf{X} + \frac{1}{SNR} \mathbf{I} \right)^{-1}$$

= $2 \times \frac{1}{12} \mathbf{I} = \frac{1}{6} \mathbf{I}$

$$MSE = Tr\left\{\frac{1}{6}\mathbf{I}\right\} = \frac{1}{3}$$

- ▶ Assignment 6 deadline: 16th November 11:59 PM.
- Assignment 5,6 discussion: 18th November 12:30-1:00 PM.
- Quiz 3: 19th November 11:45-12:30 PM.
- ▶ Live Interaction #7: 19th November 12:40-1:30 PM

