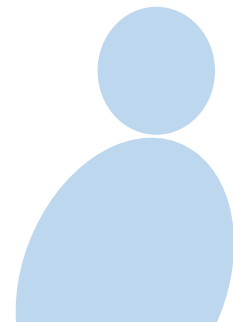


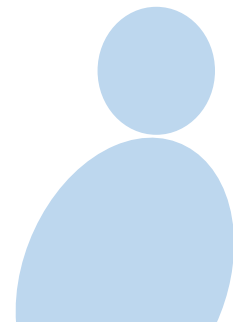
# **eMasters in Communication Systems**

**Prof. Aditya  
Jagannatham**



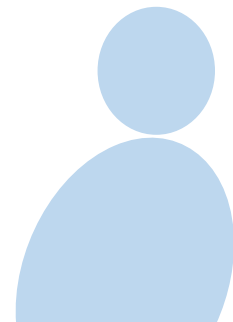
**Elective Module:**

**Detection for Wireless  
Communication**



# Chapter 3

## Generalized ML Detection



# Detection

- **Mathematical Model**

$\mathcal{H}_0$ :

$$y(1) = s_0(1) + v(1)$$

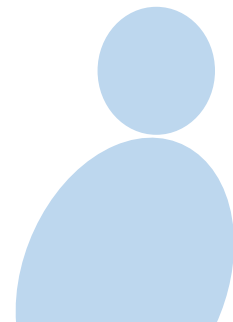
$$y(2) = s_0(2) + v(2)$$

$\vdots$

$$y(N) = s_0(N) + v(N)$$

$s_d(i)$  ← Signal corresponding to  $\mathcal{H}_0$ .

iid Gaussian  
noise samples  
mean = 0  
var =  $\sigma^2$



# Detection

- **Mathematical Model**

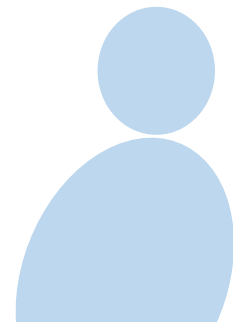
$\mathcal{H}_0$ :

$$y(1) = s_0(1) + v(1)$$

$$y(2) = s_0(2) + v(2)$$

$\vdots$

$$y(N) = s_0(N) + v(N)$$



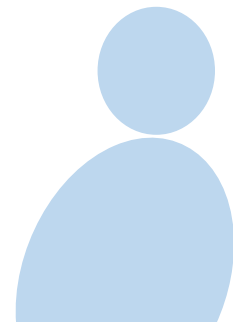
# Detection

$\bar{s}_0 = \text{Signal for } \mathcal{H}_0$

- **Mathematical Model**

$$\mathcal{H}_0: \begin{bmatrix} y(1) \\ y(2) \\ \vdots \\ y(N) \end{bmatrix} = \begin{bmatrix} s_0(1) \\ s_0(2) \\ \vdots \\ s_0(N) \end{bmatrix} + \begin{bmatrix} v(1) \\ v(2) \\ \vdots \\ v(N) \end{bmatrix}$$

$$\bar{y} = \bar{s}_0 + \bar{v}; \mathcal{H}_0$$

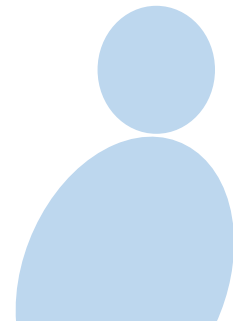


# Detection

- **Mathematical Model**

$$\mathcal{H}_0: \begin{bmatrix} y(1) \\ y(2) \\ \vdots \\ y(N) \end{bmatrix} = \begin{bmatrix} s_0(1) \\ s_0(2) \\ \vdots \\ s_0(N) \end{bmatrix} + \begin{bmatrix} v(1) \\ v(2) \\ \vdots \\ v(N) \end{bmatrix}$$

$$\bar{y} = \bar{s}_0 + \bar{v}$$



# Detection

- **Mathematical Model**

$\mathcal{H}_1$ :

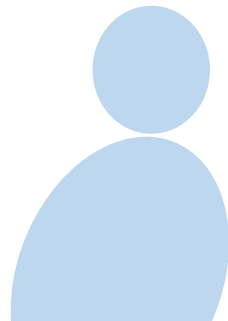
$$y(1) = s_1(1) + v(1)$$

$$y(2) = s_1(2) + v(2)$$

$\vdots$

$$y(N) = s_1(N) + v(N)$$

Signal for  $\mathcal{H}_1$ .





# Detection

- **Mathematical Model**

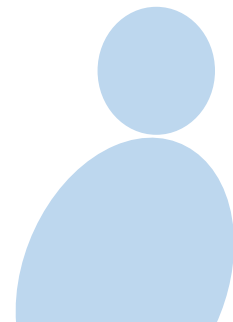
$\mathcal{H}_1$ :

$$y(1) = s_1(1) + v(1)$$

$$y(2) = s_1(2) + v(2)$$

$\vdots$

$$y(N) = s_1(N) + v(N)$$

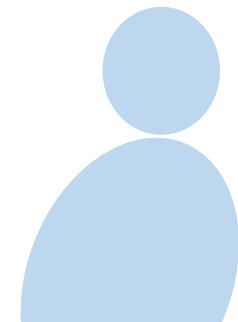


# Detection

- **Mathematical Model**

$$\mathcal{H}_1: \begin{bmatrix} y(1) \\ y(2) \\ \vdots \\ y(N) \end{bmatrix} = \begin{bmatrix} \bar{s}_1 \\ s_1(1) \\ s_1(2) \\ \vdots \\ s_1(N) \end{bmatrix} + \begin{bmatrix} \bar{v} \\ v(1) \\ v(2) \\ \vdots \\ v(N) \end{bmatrix}$$

$$\bar{y} = \bar{s}_1 + \bar{v} ; \mathcal{H}_1$$

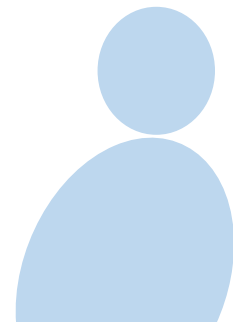


# Detection

- **Mathematical Model**

$$\mathcal{H}_1: \begin{bmatrix} y(1) \\ y(2) \\ \vdots \\ y(N) \end{bmatrix} = \begin{bmatrix} s_1(1) \\ s_1(2) \\ \vdots \\ s_1(N) \end{bmatrix} + \begin{bmatrix} v(1) \\ v(2) \\ \vdots \\ v(N) \end{bmatrix}$$

$\bar{y} = \bar{s}_1 + \bar{v}$



# Detection

i.i.d.  $\leftarrow$  independent  
identically distributed.  
 $V(1), V(2), \dots, V(N)$

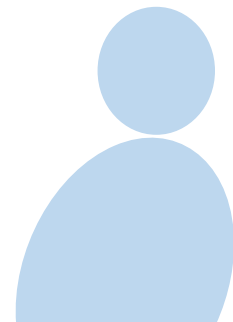
- Noise samples in  $\bar{V}$  are i.i.d.

Gaussian, mean 0 variance is  $\sigma^2$ .

- $\bar{s}_0, \bar{s}_1$  are **known signals**

$H_0$  NULL Hypothesis

$H_1$  ALTERNATIVE  
Hypothesis.

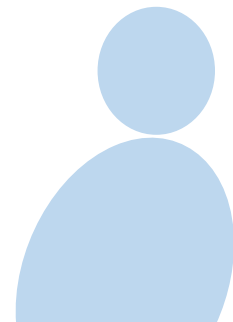


# Detection

- Write it in the compact form

$$\mathcal{H}_0: \quad \bar{y} = \bar{s}_0 + \bar{v}$$

$$\mathcal{H}_1: \quad \bar{y} = \bar{s}_1 + \bar{v}$$



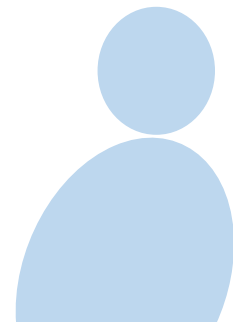
# Detection

Binary hypothesis Testing  
What is the LRT?

- Write it in the compact form

$$\mathcal{H}_0: \bar{y} = \bar{s}_0 + \bar{v}$$

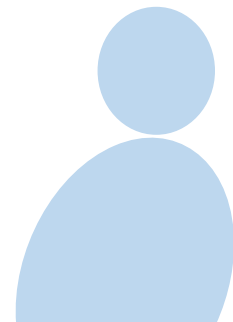
$$\mathcal{H}_1: \bar{y} = \bar{s}_1 + \bar{v}$$



# Detection

- Define

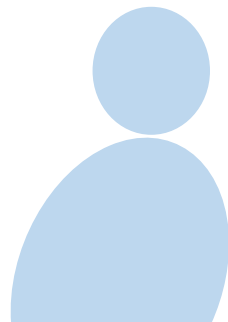
$$\tilde{\mathbf{y}} = \bar{\mathbf{y}} - \bar{\mathbf{S}}_0$$



# Detection

- Define

$$\bar{y} - \bar{s}_0 = \tilde{y}$$





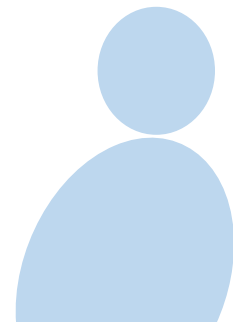
# Detection

- Write it in the compact form

$$\mathcal{H}_0: \bar{y} = \bar{s}_0 + \bar{v}$$

$$\Rightarrow \bar{y} - \bar{s}_0 = \bar{v}$$

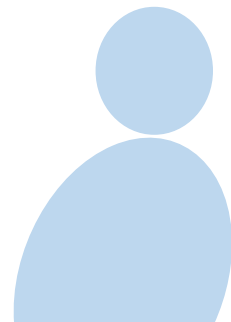
$$\Rightarrow \tilde{y} = \bar{v}$$



# Detection

- Write it in the compact form

$$\begin{aligned}\mathcal{H}_0: \bar{y} &= \bar{s}_0 + \bar{v} \\ \Rightarrow \bar{y} - \bar{s}_0 &= \bar{v} \\ \Rightarrow \tilde{y} &= \bar{v} \text{ ; } \mathcal{H}_0\end{aligned}$$



# Detection

$$\bar{s} = \bar{s}_1 - \bar{s}_0$$

- Write it in the compact form

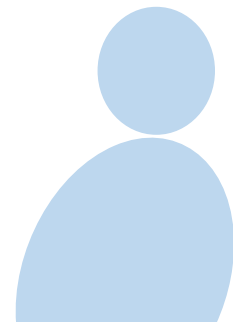
$$\mathcal{H}_1: \bar{y} = \bar{s}_1 + \bar{v}$$

$\Rightarrow$

$$\bar{y} - \bar{s}_0 = \bar{s}_1 - \bar{s}_0 + \bar{v}$$

$\Rightarrow$

$$\tilde{y} = \bar{s} + \bar{v}$$



# Detection

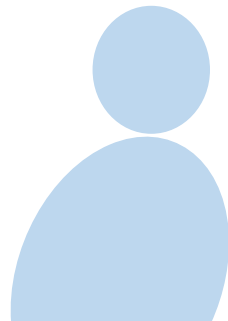
- Write it in the compact form

$$\mathcal{H}_1: \bar{y} = \bar{s}_1 + \bar{v}$$

$$\Rightarrow \bar{y} - \bar{s}_0 = \bar{s}_1 - \bar{s}_0 + \bar{v}$$

$$\Rightarrow \tilde{y} = \bar{s} + \bar{v}$$

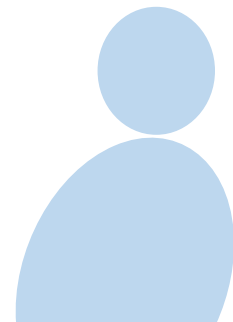
$$\bar{s} = \bar{s}_1 - \bar{s}_0$$



# Detection

- Write it in the compact form

$$\begin{array}{ll} \mathcal{H}_0: & \tilde{y} = \bar{v} \\ \mathcal{H}_1: & \tilde{y} = \bar{s} + \bar{v} \end{array} \quad \left. \vphantom{\begin{array}{l} \mathcal{H}_0 \\ \mathcal{H}_1 \end{array}} \right\} \begin{array}{l} \text{original signal.} \\ \text{Detection problem.} \end{array}$$
$$\begin{array}{l} \bar{y} \rightarrow \tilde{y} \\ \bar{s} \rightarrow \bar{s}_1 - \bar{s}_0 \end{array}$$

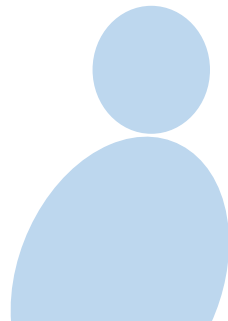


# Detection

- Write it in the compact form

$$\mathcal{H}_0: \tilde{\mathbf{y}} = \bar{\mathbf{v}}$$

$$\mathcal{H}_1: \tilde{\mathbf{y}} = \bar{\mathbf{s}} + \bar{\mathbf{v}}$$



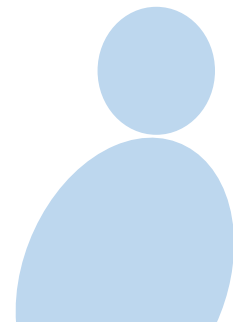
# Likelihood

- Choose  $\mathcal{H}_0$  if

$$\bar{z}^T \tilde{y} \leq \tau$$

$$(\bar{z}_1 - \bar{z}_0)^T \tilde{y} \leq \tau$$

$$(\bar{z}_1 - \bar{z}_0)^T (\bar{y} - \bar{z}_0) \leq \tau$$



# Likelihood

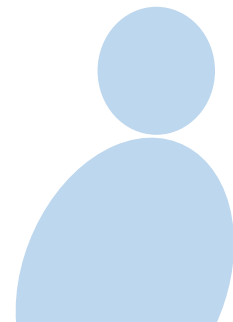
- Choose  $\mathcal{H}_0$  if

$$\bar{\mathbf{s}}^T \tilde{\mathbf{y}} \leq \gamma$$

$$(\bar{\mathbf{s}}_1 - \bar{\mathbf{s}}_0)^T \tilde{\mathbf{y}} \leq \gamma$$

TEST STATISTIC -

LRT

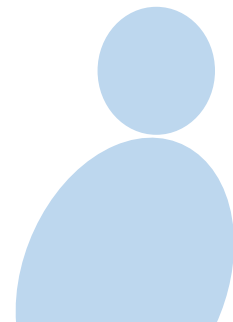




# Likelihood

- Choose  $\mathcal{H}_1$  if

$$\begin{aligned}\bar{z}^T \tilde{y} &> \gamma \\ (\bar{z}_1 - \bar{z}_0)^T (\bar{y} - \bar{z}_0) &> \gamma\end{aligned}$$



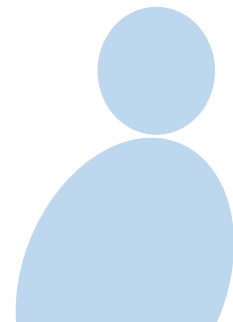
# Likelihood

- Choose  $\mathcal{H}_1$  if

$$\bar{\mathbf{s}}^T \tilde{\mathbf{y}} > \gamma$$

$$(\bar{\mathbf{s}}_1 - \bar{\mathbf{s}}_0)^T \tilde{\mathbf{y}} > \gamma$$

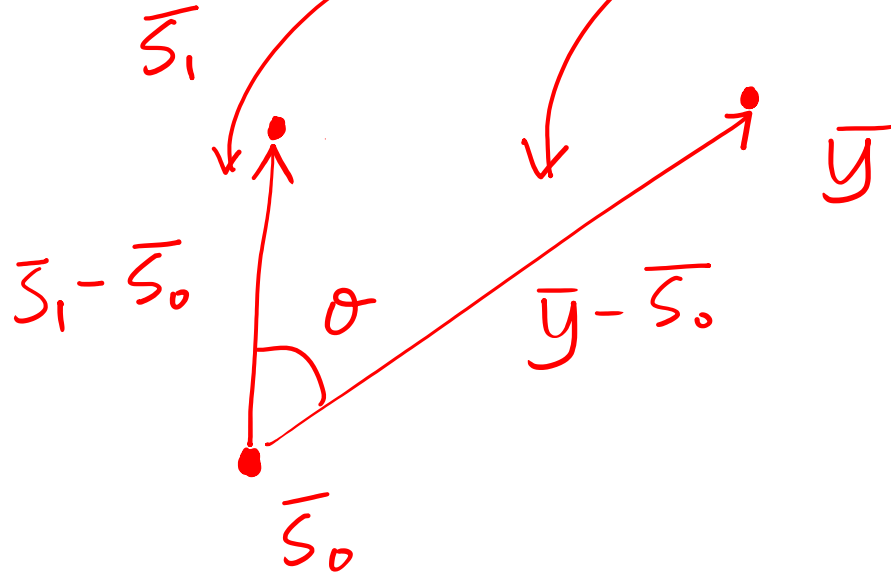
Generalized Signal-Detection  
problem.



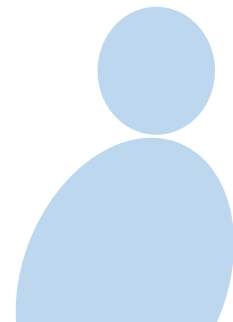
# Figure: Intuition

$$(\bar{z}_1 - \bar{z}_0)^T (\bar{y} - \bar{z}_0)$$

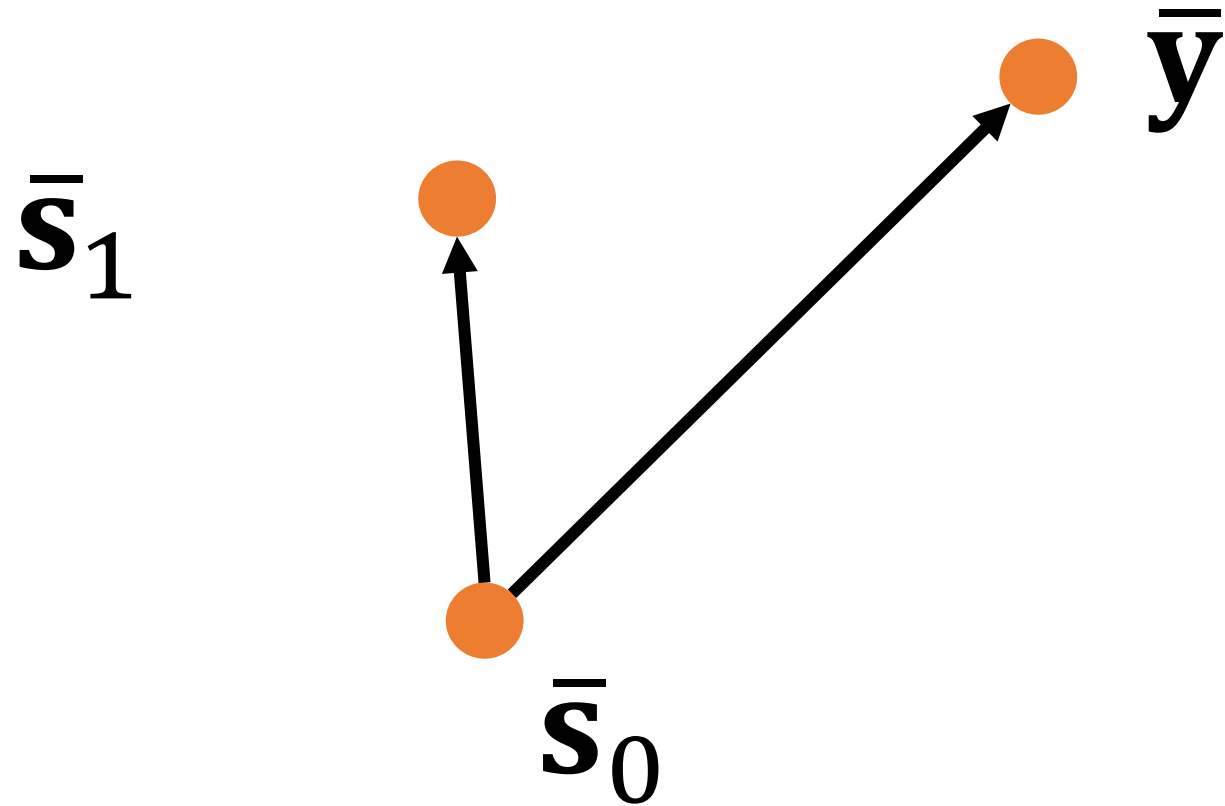
$$= |\bar{z}_1 - \bar{z}_0| |\bar{y} - \bar{z}_0| \cos \theta$$



Test statistic = Dot product  
or inner product  
between these  
2 vectors.



# Figure: Intuition

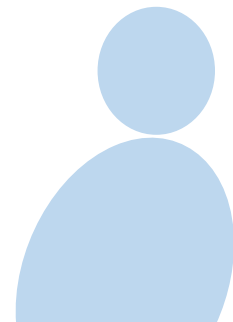


# Performance

- Therefore,  $P_{FA}$ ,  $P_D$  are given as

$$P_{FA} = Q\left(\frac{\gamma}{\sigma \|\bar{\mathbf{s}}\|}\right) = Q\left(\frac{\gamma}{\sigma \|\bar{\mathbf{z}}_1 - \bar{\mathbf{z}}_0\|}\right)$$

$$P_D = Q\left(\frac{\gamma - \|\bar{\mathbf{s}}\|^2}{\sigma \|\bar{\mathbf{s}}\|}\right) = Q\left(\frac{\gamma - \|\bar{\mathbf{z}}_1 - \bar{\mathbf{z}}_0\|^2}{\sigma \|\bar{\mathbf{z}}_1 - \bar{\mathbf{z}}_0\|}\right).$$

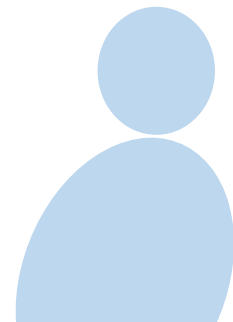


# Performance

- Therefore,  $P_{FA}$ ,  $P_D$  are given as

$$P_{FA} = Q\left(\frac{\gamma}{\sigma\|\bar{\mathbf{s}}\|}\right) = Q\left(\frac{\gamma}{\sigma\|\bar{\mathbf{s}}_1 - \bar{\mathbf{s}}_0\|}\right)$$

$$P_D = Q\left(\frac{\gamma - \|\bar{\mathbf{s}}\|^2}{\sigma\|\bar{\mathbf{s}}\|}\right) = Q\left(\frac{\gamma - \|\bar{\mathbf{s}}_1 - \bar{\mathbf{s}}_0\|^2}{\sigma\|\bar{\mathbf{s}}_1 - \bar{\mathbf{s}}_0\|}\right)$$



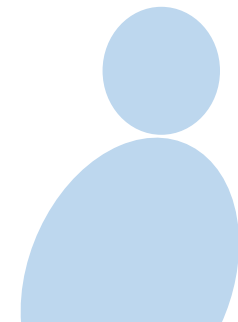
# Performance ML

- For ML set

$$\tilde{y} = \bar{y} - \bar{s}_0$$

$$\gamma = \frac{\|\bar{s}\|^2}{2} = \frac{\|\bar{s}_1 - \bar{s}_0\|^2}{2}$$

$$\begin{aligned} H_0 & \text{ if } (\bar{s}_1 - \bar{s}_0)^T \tilde{y} \leq \frac{\|\bar{s}_1 - \bar{s}_0\|^2}{2} \\ H_1 & \text{ if } (\bar{s}_1 - \bar{s}_0)^T \tilde{y} > \frac{\|\bar{s}_1 - \bar{s}_0\|^2}{2} \end{aligned}$$



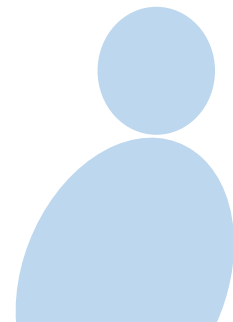
# Performance ML

- Therefore,  $P_{FA}$ ,  $P_D$  are given as

$$P_{FA} = Q\left(\frac{\|\bar{\mathbf{s}}\|}{2\sigma}\right) = Q\left(\frac{\|\bar{\mathbf{s}}_1 - \bar{\mathbf{s}}_0\|}{2\sigma}\right)$$

$$P_{MD} = Q\left(\frac{\|\bar{\mathbf{s}}\|}{2\sigma}\right) = Q\left(\frac{\|\bar{\mathbf{s}}_1 - \bar{\mathbf{s}}_0\|}{2\sigma}\right)$$

Probability of  
Miss Detection  
 $= 1 - P_D$ .





# Performance ML

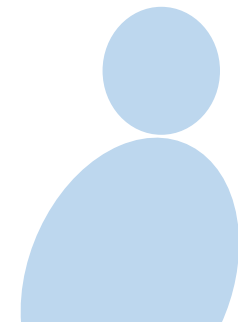
- Therefore,  $P_e$  is

$$Q\left(\frac{\|\bar{s}\|}{2\sigma}\right) = Q\left(\frac{\|\bar{s}_1 - \bar{s}_0\|}{2\sigma}\right) = Q\left(\frac{d}{2\sigma}\right)$$

To minimize  $P_e$   
maximize distance  
between signals.

$\|\bar{s}_1 - \bar{s}_0\| =$  Distance between  $\bar{s}_1, \bar{s}_0$

distance between two signals.  $\bar{s}_0$



# Performance ML

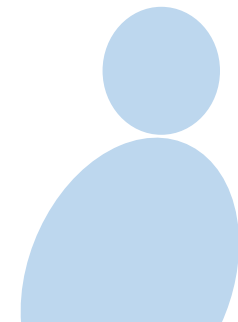
- Therefore,  $P_e$  is

$$\Pr(\mathcal{H}_0) \Pr(\mathcal{H}_1|\mathcal{H}_0) + \Pr(\mathcal{H}_1) \Pr(\mathcal{H}_0|\mathcal{H}_1)$$

$$\frac{1}{2}P_{FA} + \frac{1}{2}P_{MD} = Q\left(\frac{\|\bar{\mathbf{s}}\|}{2\sigma}\right) = Q\left(\frac{\|\bar{\mathbf{s}}_1 - \bar{\mathbf{s}}_0\|}{2\sigma}\right)$$

$$= Q\left(\frac{d}{2\sigma}\right)$$

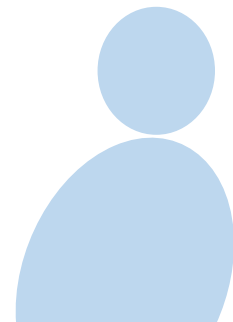
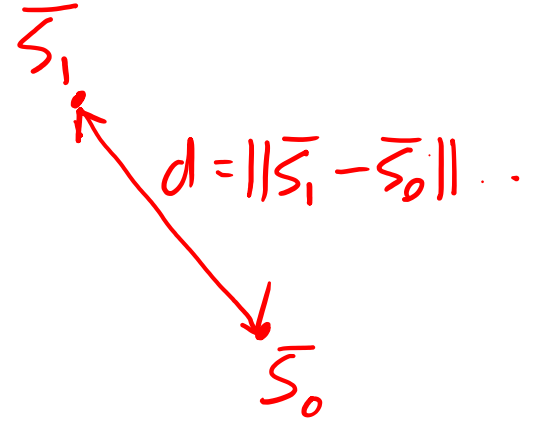
$d = \|\bar{\mathbf{s}}_1 - \bar{\mathbf{s}}_0\|$ .



# Performance ML

- Note that  $d$  is the distance between the points  $\bar{s}_1, \bar{s}_0$

$$d = \|\bar{s}_1 - \bar{s}_0\|$$



# Example

ASK:  $\{0, A\}$

- Consider **Binary Phase Shift Keying (BPSK)**

- $s = A$

$N=1$

$$\mathcal{H}_0: y = -\overset{s_0}{A} + v$$

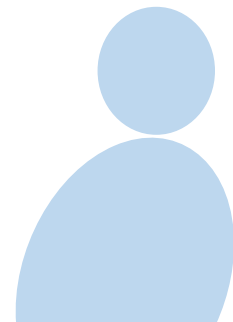
$$\mathcal{H}_1: y = \underset{\bar{s}_1}{A} + v$$

$\{-A, A\}$

$180^\circ$   
 $0^\circ$

Binary constellation  
1 bit/symbol.

$$\begin{aligned} s_0 &= -A \\ s_1 &= A \end{aligned}$$

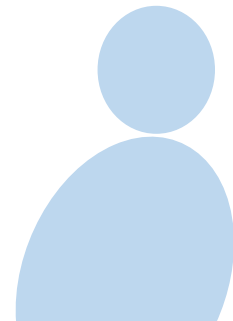


# Example

- Therefore,  $P_e$  is

$$\sigma^2 = \frac{N_0}{2}$$

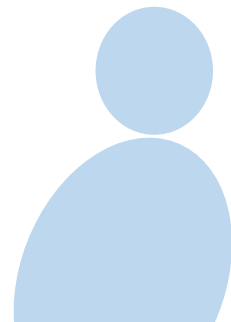
$$\begin{aligned} Q\left(\frac{\|\bar{s}_1 - \bar{s}_0\|}{2\sigma}\right) &= Q\left(\frac{\|A - (-A)\|}{2\sqrt{\frac{N_0}{2}}}\right) \\ &= Q\left(\frac{2A}{\sqrt{2N_0}}\right) = Q\left(\sqrt{\frac{2A^2}{N_0}}\right) \end{aligned}$$



# Example

- Therefore,  $P_e$  is

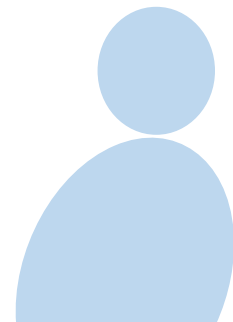
$$Q\left(\frac{\|\bar{s}_1 - \bar{s}_0\|}{2\sigma}\right) = Q\left(\frac{2A}{2\sqrt{N_0/2}}\right) = \underbrace{Q\left(\sqrt{\frac{2A^2}{N_0}}\right)}_{\text{Probability of error of BPSK.}}$$



# Example

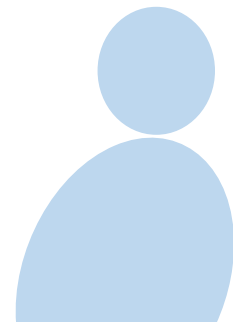
- Each symbol carries one bit
- Let  $E_b$  be the *energy per bit*
- Let each symbol be **equiprobable**

$$\Pr(-A) = \Pr(A) = \frac{1}{2}$$



# Example

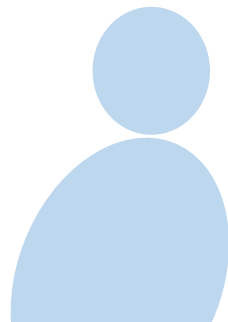
$$E_b = \frac{1}{2} A^2 + \frac{1}{2} (-A)^2 = \frac{1}{2} A^2 + \frac{1}{2} A^2 = A^2$$
$$\Rightarrow A = \sqrt{E_b}$$
$$\Rightarrow A^2 = E_b.$$





## Example

$$E_b = \frac{1}{2} \times (-A)^2 + \frac{1}{2} \times A^2$$
$$\Rightarrow A^2 = E_b$$



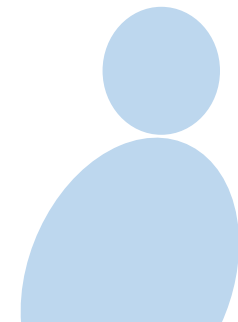
# Example

- Therefore,  $P_e$  is

$$Q\left(\sqrt{\frac{2A^2}{N_0}}\right) = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

Bit Error Rate (BER)  
of BPSK.

- This is termed as **bit error rate**

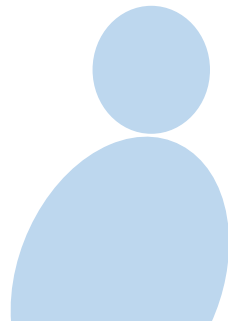


# Example

- Therefore,  $P_e$  is

$$Q\left(\sqrt{\frac{2A^2}{N_0}}\right) = Q\left(\sqrt{\frac{2E_b}{N_0}}\right) = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

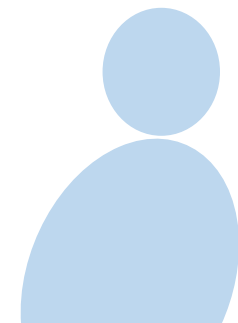
- This is termed as bit error rate (BER)



# ASK vs BPSK

For same  $E_b$ .  
BER of BPSK is lower!

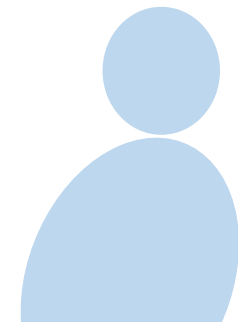
BER of ASK	BER of BPSK
$Q\left(\sqrt{\frac{E_b}{N_0}}\right)$	$Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$



# ASK vs BPSK

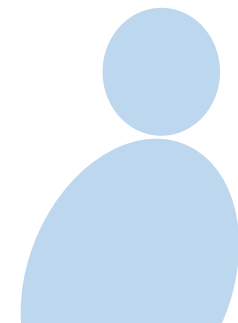
BER of ASK	BER of BPSK
$Q\left(\sqrt{\frac{E_b}{N_0}}\right)$	$Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$

TO achieve same BER  
with BPSK, we need  
half the  $E_b$  as  
that of ASK!



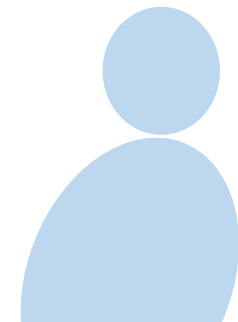
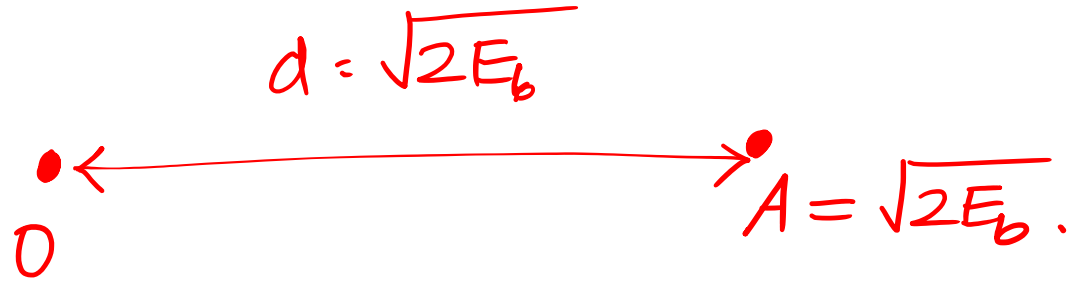
# Example

- For same  $E_b$  BPSK has lower BER!
- In fact, BPSK is 3 dB **more efficient** than ASK
  - BPSK Needs half the  $E_b$  for same BER i.e. 3 dB less!

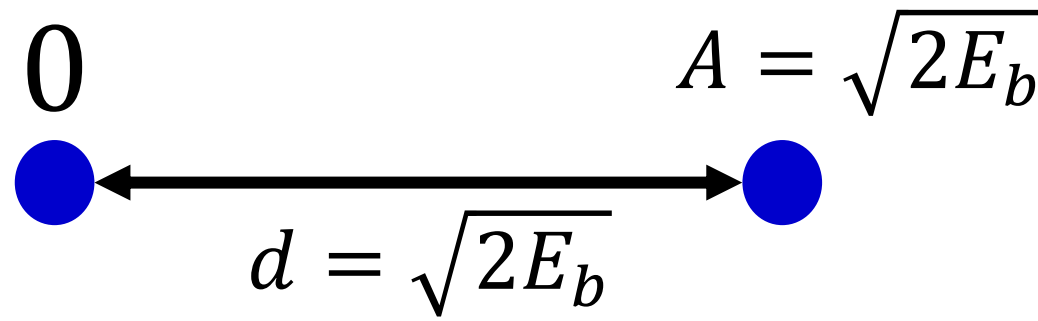


# ASK Distance Properties

*intuition?*

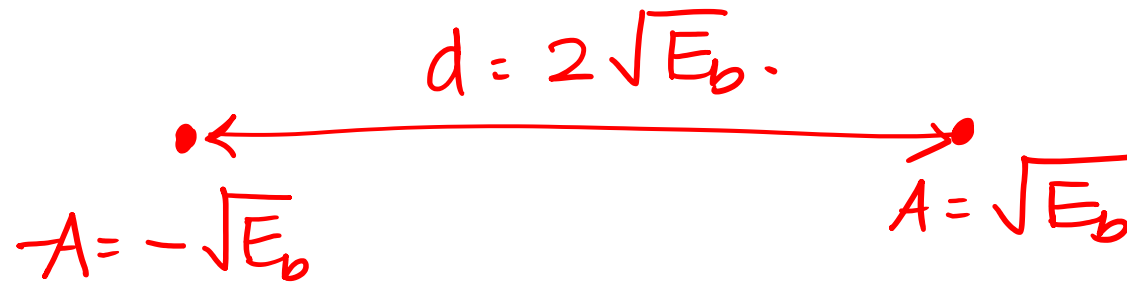


# ASK Distance Properties





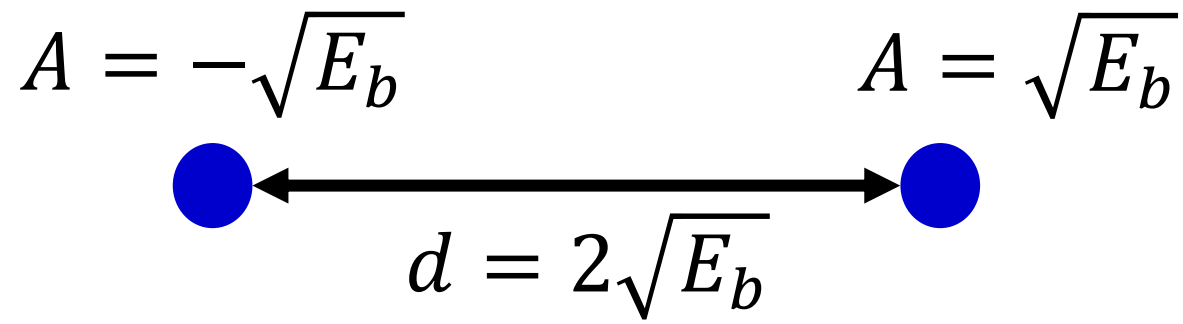
# BPSK Distance Properties



A diagram illustrating the distance between two BPSK signal points. Two red dots represent the signal points on a horizontal axis. The left dot is labeled  $A = -\sqrt{E_b}$  and the right dot is labeled  $A = \sqrt{E_b}$ . A red double-headed arrow connects the two dots, with the label  $d = 2\sqrt{E_b}$  written above it.

$$d = 2\sqrt{E_b}$$
$$A = -\sqrt{E_b}$$
$$A = \sqrt{E_b}$$

# BPSK Distance Properties

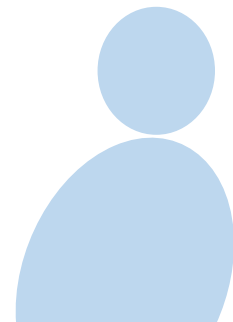


# BPSK vs ASK Distance

- For same  $E_b$  distance of BPSK is

$$2\sqrt{E_b} > \sqrt{2E_b} = \text{distance of ASK!}$$

- While that of ASK is only  $\sqrt{2E_b}$



# BPSK vs ASK Distance

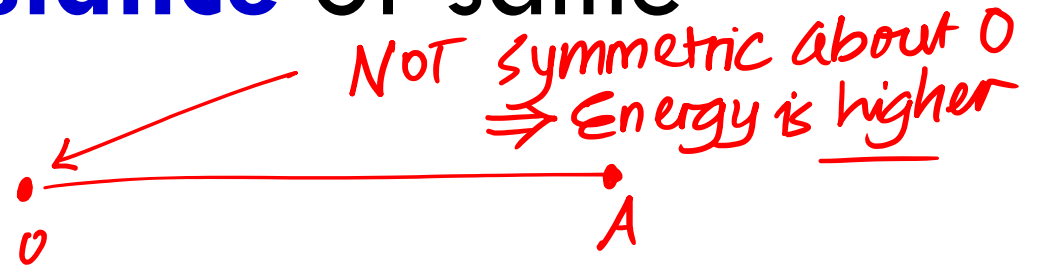
- BPSK is **ANTIPODAL**, i.e., centered around zero



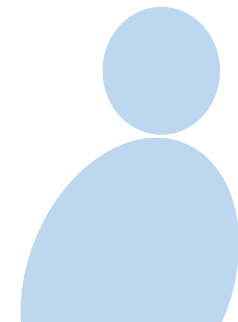
Symmetric about 0  
 $\Rightarrow$  Energy = min!

- This **maximizes distance** of same average power

constellation has to be symmetric about 0 to minimize  $P_e$ .



NOT symmetric about 0  
 $\Rightarrow$  Energy is higher



Instructors may use this white area (14.5 cm / 25.4 cm) for the text.  
Three options provided below for the font size.

Font: Avenir (Book), Size: 32, Colour: Dark Grey

Font: Avenir (Book), Size: 28, Colour: Dark Grey

Font: Avenir (Book), Size: 24, Colour: Dark Grey

Do not use the space below.

