Discretize mean-field limit using JKO, see if it is similar to GD.

**Mean-field limit**(Chizat & Bach): For a sufficiently large width, the training dynamics of a NN can be coupled with the evolution of a probability distribution described by a PDE.

### 1 Classic setup

Data  $x_i \in \mathbb{R}^d$  and labels  $y_i \in \mathbb{R}$ , j = 1,...,n

First layer  $w_i \in \mathbb{R}^d$ , second layer  $\alpha_i \in \mathbb{R}$ , i = 1,...,m

 $\gamma > 0$  step-size,  $\beta$  regularization

$$\mathcal{L}(W,\alpha) = \sum_{j=1}^{n} \left( \underbrace{\sum_{i=1}^{m} \max(0, w_i^{\top} x_j) \alpha_i - y_j}^{2} + \lambda \underbrace{\sum_{i=1}^{m} \|w_i\|_{2}^{2} + \alpha_i^{2}}_{\text{Weight Decay}} \right)$$

#### Discret time.

Full-batch gradient descent

$$(W,\alpha)_{t+1} = (W,\alpha)_t - \gamma \nabla \mathcal{L}((W,\alpha)_t)$$

**Implicit** 

$$\theta_{t+1} = \underset{\theta}{\operatorname{arg\,min}} \mathcal{L}(\theta) + \frac{1}{2\gamma} \|\theta - \theta_t\|$$

### Continuous time.

Taking  $\gamma \to 0$ , we get the gradient flow:  $\frac{d\theta_t}{dt} = -\nabla \mathcal{L}(\theta_t)$ . We make ReLU differentiable with  $\sigma'(0) = 0$  as justified in (Boursier et al.).

# 2 Using a measure

$$\int_{\Theta} m(\theta; x) d\mu(\theta) = \frac{1}{m} \sum_{i=1}^{m} \langle w_i, x_j \rangle_{+} \alpha_i$$

Different ways to use a measure:

- $\Theta = \mathbb{R}^d \times \mathbb{R}$ , measure  $\mu = \frac{1}{m} \sum_{i=1}^m \delta_{\theta_i = (w_i, \alpha_i)}$ , output of one neuron  $m(\theta = (w, \alpha); x) = \langle x, w \rangle_+ \alpha$ : (works, output matches discrete)
- $\Theta = \mathbb{R}^d$ , measure  $\mu = \frac{1}{m} \sum_{i=1}^m \alpha_i \delta_{\theta_i = w_i}$  output of one neuron  $m(\theta = w; x) = \langle x, w \rangle_+$  (works)
- $\Theta = \mathbb{R}^{d} \times \mathbb{R}^{d}$ , output of one neuron  $m(\tilde{w}_{+}, \tilde{w}_{-}, x) = \langle \tilde{w}_{+}, x \rangle \langle \tilde{w}_{-}, x \rangle$  (works, separate neg and positive)
- $\Theta = (S^{d-1} \times \mathbb{R})$ , output of one neuron  $m((d, \tilde{\alpha}); x) = \tilde{\alpha} \langle d, x \rangle = \tilde{\alpha} \mathbb{1}_{\langle d, x \rangle > 0}$  (works), mapping:  $d = \frac{w}{\|w\|}$  and  $\tilde{\alpha} = \|w\|\alpha$ . Gradient are not equal to discrete.

#### 2.1 Algorithm, discretize the measure's space

Take a grid of N points in  $\Theta$ , we can match the notation above by taking a neuron for each point of the grid m = N.

$$\mu(t+1) = \operatorname*{arg\,min}_{\mu \in \mathcal{M}(\Theta)} F(\mu) + \frac{1}{2\gamma} W_2(\mu; \mu(t))$$

A essayer: KL à la place de distance wasserstein.

Remark: le 1/m c'est principalement pour être ok à l'infini. Dans le papier JKO (Carlier et al.) ils utilisent un vecteur de proba

### 2.2 Infinity and beyond

Take  $\gamma \to 0$ , get gradient flow. Take  $m \to \infty$ , get wasserstein gradient flow (Bach & Chizat), and if it converges, it goes to the global optimal.

#### 2.3 JKO

What we compute by using the entropic JKO flow iterations.

$$\begin{split} \forall t > 0, p_{t+1} := & \operatorname{Prox}_{\tau f}^{W_{\gamma}}(p_t) \\ &= \underset{p \in \operatorname{simplex}}{\operatorname{arg\,min}} \ W_{\gamma}(p,q) + \tau f(p) \\ &= \underset{p \in \operatorname{simplex}}{\operatorname{arg\,min}} \left( \underset{\pi \in \Pi(p,q)}{\min} \langle c, \pi \rangle + \gamma E(\pi) \right) + \tau f(p) \end{split}$$

f "should" be convex and with a closed form proximal

- Meta Optimal Transport (paper) and (code git): InputConvexNN to predict solution of OT problem
- JKOnet (paper) and (code git):
  - /models -> sinkhorn loss defined in loss.py, differentiable loop in fixed point.py
  - next step: trying to create the right Geometry object from OTT library, which is what's used for sinkhorn

## 2.4 Papers

The algo we try to implement

Paper with a specific case that doesn't match ours:

In the future, large-scale waserstein gradient flows

### 2.4.1 Grid Problems

The grid currently dictate the neuron's scale, giving multiple choices. One solution: duplicate each neuron, make one with a small scale and one with a very big scale.

## References

Francis Bach and Lenaïc Chizat. Gradient descent on infinitely wide neural networks: Global convergence and generalization. URL http://arxiv.org/abs/2110.08084.

Etienne Boursier, Loucas Pillaud-Vivien, and Nicolas Flammarion. Gradient flow dynamics of shallow relu networks for square loss and orthogonal inputs. URL http://arxiv.org/abs/2206.00939.

Guillaume Carlier, Vincent Duval, Gabriel Peyré, and Bernhard Schmitzer. Convergence of entropic schemes for optimal transport and gradient flows. URL http://arxiv.org/abs/1512.02783.

Lénaïc Chizat and Francis R. Bach. On the global convergence of gradient descent for overparameterized models using optimal transport. In Samy Bengio, Hanna M. Wallach, Hugo Larochelle, Kristen Grauman, Nicolò Cesa-Bianchi, and Roman Garnett (eds.), Adv. Neural Inf. Process. Syst. 31 Annu. Conf. Neural Inf. Process. Syst. 2018 NeurIPS 2018 Dec. 3-8 2018 Montr. Can., pp. 3040–3050. URL https://proceedings.neurips.cc/paper/2018/hash/a1afc58c6ca9540d057299ec3016d726-Abstract.html.