

stream function
 the potential flow vs laminar
 & potential function

Potential flow

Frictionless irrotational flows

/ /

FLUID MECHANICS

Continuum: fluid is a continuous medium

↳ Invalid if smallest dimension is comparable less than the mean free path

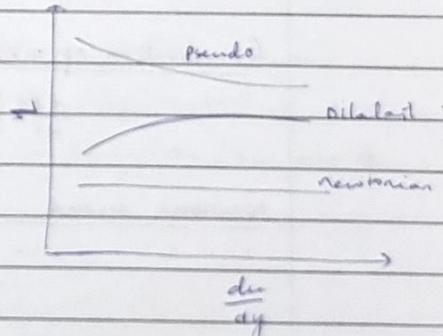
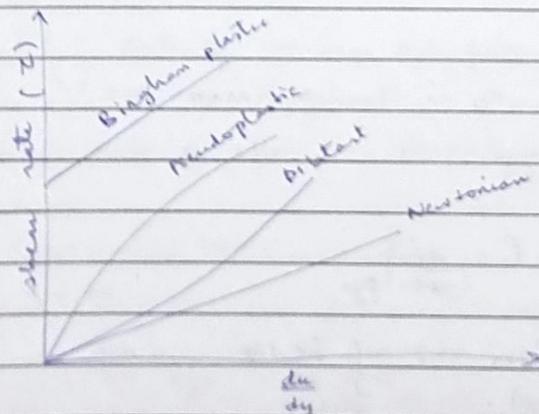
- Pathline: Path or trajectory traced out by a moving fluid particles.
- Streakline: lines drawn to the flow field so that at a given instant they are tangent to the direction of flow at every point in the flow field
- streamline: The line joining all the fluid particles which are passed through a fixed point at some time
- Viscosity: measure of a fluid's resistance to flow.
- shear stress arises due to viscous flow

$$\begin{aligned}
 \text{Newtonian fluids: } \tau_{xy} &\propto \frac{du}{dy} & \tau_{xy} = \mu \frac{du}{dy} \\
 &\text{↳ shear stress} \propto \text{rate of deformation}
 \end{aligned}$$

Non-newtonian fluids

$$\tau_{xy} = k \left(\frac{du}{dy} \right)^n \quad k = \text{consistency index}$$

$$\eta = k \left(\frac{du}{dy} \right)^{n-1} \rightarrow \text{apparent viscosity.}$$



$n < 1 \rightarrow$ pseudoplastic \rightarrow shear thinning fluids.

↳ apparent viscosity decreases with T in \propto deformation rate
polymer soln., colloids, ketchup, Paint

$n > 1 \rightarrow$ dilatant (shear thickening)

↳ apparent viscosity \uparrow with deformation rate
suspension of starch and sand.

\rightarrow Bingham plastic: fluid \neq behaves like solid until min yield stress is exceeded.

$$\tau_y = \tau_y + \mu \frac{dy}{dx}$$

force in x -direction
area of distortion \propto
 $(x$ momentum \propto being transmitted to x direction)

Surface tension: energy required for creating unit surface area

\rightarrow Inviscid $\rightarrow \mu = 0$

\rightarrow compressible \rightarrow varying density

Conservation of mass

$$\frac{dM}{dt} \Big|_{sys} = 0 \quad M = \text{mass.}$$

Newton's second law

$$\vec{F} = \frac{d\vec{p}}{dt} \Big|_{sys}$$

$$\vec{P}_{sys} = \int \vec{V} dm - \int \vec{V} cd\tau$$

Energy

$$\delta Q - \delta W = dE \quad \begin{matrix} \rightarrow \text{change in} \\ \text{heat} \quad \text{work} \\ \text{added} \quad \text{done} \end{matrix} \quad \text{internal} \\ \text{energy.}$$

$$Q - W = \frac{dE}{dt} \Big|_{sys}$$

$$E_{sys} = \int_M c dm = \int c \tau d\tau$$

$$c = u + \frac{v^2}{2} + gz$$

$$N_{sys} = \int_M \eta dm \quad \begin{matrix} \eta = \text{intensive property} \\ N = \text{extensive} \end{matrix}$$

$$\frac{dN}{dt} \Big|_{sys} = \frac{\partial}{\partial t} \int_M \eta d\tau + \int_M \eta \frac{\partial c}{\partial t} d\tau \quad \begin{matrix} \rightarrow \text{integral form} \\ \text{relation of system derivatives} \\ (\text{Reynolds transport theorem}) \end{matrix}$$

$$\frac{dN}{dt} = \text{rate of change in extensive property}$$

(2) = rate of change of property N in control volume
↳ amt of N present in the CV at any instant t

(3) = rate of efflux \rightarrow property N leaving the surface ∂V

CONTINUITY EQN (conservation of mass)

$$N = M$$

$$\frac{dm}{dt} \Big|_{sys} = \frac{\partial}{\partial t} \int_M \rho d\tau + \int_{\partial V} \rho v \cdot d\vec{A}$$

$$\frac{dm}{dt} \Big|_{sys} =$$

$$\int_{\partial V} \rho v \cdot d\vec{A} + \int_{\partial V} \rho \vec{v} \cdot d\vec{A} = 0$$

Momentum equation for control volume

$$N = P$$

$$\frac{y}{m} = \bar{v}$$

$$\frac{d\vec{F}}{dt} = \frac{\partial}{\partial t} \int_{cv} \bar{v} d\vec{A} + \int_{cs} \bar{v} (\bar{v} \cdot d\vec{A}) \rightarrow \text{total force acting on the CV leads to rate of change of momentum with CV}$$

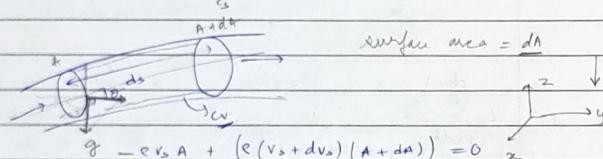
non-accelerating

$$\frac{d\vec{F}}{dt} = \bar{F} = \bar{F}_x + \bar{F}_B$$

net force acting of the CV

Bernoulli's eqn (conservation of energy)

$$\text{steady flow} \rightarrow \int \bar{v} \cdot d\vec{A} = 0$$



(cannot be used across propellers, turbines, windmills when friction neglected)

$$F_x = PA - (p+dp)(A+da) + (p+dp)da$$

at the ends

on the surface

avg pressure

$$F_B = -g(A+da)dz \rightarrow da \text{ about } \frac{dA}{dx}$$

(direction) $\frac{dA}{dx}$

$$\int \bar{v} \cdot d\vec{A} = -v_x (PA) + (A+da)(e(v_x+dv_x)(A+da))$$

$$= e v_x A dv_x$$

$$-A dp - \frac{1}{2} dv_x da - gA dz - \frac{1}{2} gA da dz = ev_x A dv_x$$

$$-\frac{dp}{c} - g dz = ev_x dv_x$$

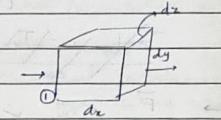
$$\frac{P}{c} + \frac{V^2}{2} + gz = \text{const}$$

restrictions

- ① steady flow
- ② no friction losses
- ③ incompressible
- ④ flow along a streamline
- ⑤ inviscid flow

Rectangular coordinate

$$e|_{x+dx, z} = p + \left(\frac{\partial p}{\partial x}\right) \frac{dx}{2}$$



$$u|_{x+dx, z} = u + \left(\frac{\partial u}{\partial x}\right) \frac{dx}{2}$$

$$\text{①} \rightarrow \int \bar{v} \cdot d\vec{A} = \left(e \cdot \left(\frac{\partial p}{\partial x}\right) dz\right) \left(u - \left(\frac{\partial u}{\partial x}\right) dz\right) dy dz - eu dy dz + \frac{1}{2} \left[u \left(\frac{\partial p}{\partial x}\right) + e \frac{\partial u}{\partial x}\right] dy dz$$

Wait for all the surfaces

$$\frac{\partial (eu)}{\partial x} + \frac{\partial ev}{\partial y} + \frac{\partial ew}{\partial z} + \frac{\partial e}{\partial t} = 0$$

~~→ 0~~

→ acceleration :- total derivative $\rightarrow \frac{\partial \bar{v}}{\partial t} - u \frac{\partial \bar{v}}{\partial x} + v \frac{\partial \bar{v}}{\partial y} + w \frac{\partial \bar{v}}{\partial z} + \frac{\partial \bar{v}}{\partial t}$

Substantial derivative

→ free vortex

→ Euler equation :- $e \frac{\partial \bar{v}}{\partial t} = e \bar{g} - \nabla p$ / without viscosity

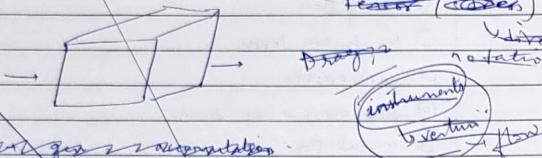
→ Inertial force resists the change in velocity

Pumps
Navier
scattering
Bernoulli + restrictions

Navier Stokes equation

Turbulent flow \vec{v} (δy , T_B)

Tensor (stress)



$$\nabla \cdot \vec{v} = 2\partial_x v_x + 2\partial_y v_y + 2\partial_z v_z$$

[force balance] \rightarrow Reynolds transport

$$\frac{\partial}{\partial t} \int_{cv} \vec{v} dV + \int_{cv} \vec{v} \cdot \nabla \vec{v} dV = -\int_{cv} \nabla P dV + \int_{cv} \tau_{ij} \frac{\partial v_i}{\partial x_j} dV$$

$$\vec{F} = m \frac{D\vec{v}}{Dt} \quad \vec{s} = \rho \frac{D\vec{v}}{Dt} \rightarrow \text{force per unit volume.}$$

Net force acting on the control volume =

$$[\tau_{xx}|_{x+\Delta x} - \tau_{xx}|_x] \Delta y \Delta z + [\tau_{yy}|_{y+\Delta y} - \tau_{yy}|_y] \Delta x \Delta z + [\tau_{zz}|_{z+\Delta z} - \tau_{zz}|_z] \Delta x \Delta y$$

$$\rightarrow T_{xx} - p = \tau_{xx}$$

$$\tau_{xy} = \tau_{yx}$$

$$\tau_{yy} - p = \tau_{yy}$$

$$\tau_{yx} = \tau_{xy}$$

$$T_{zz} - p = \tau_{zz}$$

$$\rho \frac{Dv_x}{Dt} = \rho g_{zx} + \frac{\partial T_{xx}}{\partial x} + \frac{\partial T_{yz}}{\partial y} + \frac{\partial T_{zx}}{\partial z}$$

$$\rho \frac{Dv_y}{Dt} = \rho g_{yz} + \frac{\partial T_{xy}}{\partial x} + \frac{\partial T_{yy}}{\partial y} + \frac{\partial T_{zy}}{\partial z}$$

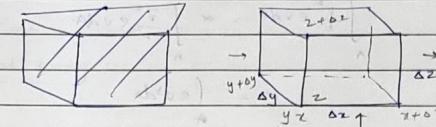
$$\rho \frac{Dv_z}{Dt} = \rho g_{zx} + \frac{\partial T_{xz}}{\partial x} + \frac{\partial T_{yz}}{\partial y} + \frac{\partial T_{zz}}{\partial z}$$

slids
sin

BL separation
(Turbulent flow)

Navier Stokes equation

momentum \rightarrow quantity of motion



rate of accumulation = IN - OUT + net force acting on the system

$m \cdot \vec{v}$ - flow rate

$$\text{x component: } \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} + \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} + \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x}$$

↓ momentum
mass entering
through face
at $x = \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x}$
↓ no momentum enters and leaves
the face y and $y + \Delta y$

$$\frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x}$$

$$\text{conduction: } \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} + \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x}$$

$$\text{due to } \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} + \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x}$$

$$\frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x}$$

↓ shear stress in
the z -direction
due to transport of
 z -momentum in z

$$\text{accumulation: } \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x}$$

$$\frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x}$$

BL: No shear at liquid-vapour interface

No slip at liquid-solid interface

$$\frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} + \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} + \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} - \frac{\partial}{\partial z} (\rho v_x)_{x+\Delta x} = -\frac{\partial p}{\partial z}$$

$$\mu \left[\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2} \right]$$

$$+ \rho g_x$$

$$W = \frac{\rho}{F} \times \frac{ds}{dt} \quad V = \frac{m}{c}$$

Kinetic energy coefficient

$$\int \frac{V^2}{2} \rho v dA = \alpha \int \frac{V^2}{2} \rho v dA$$

point velocity is
replaced by avg
velocity $\rightarrow \alpha = \text{constant}$
 $\alpha = \frac{\int v^3 dA}{\int v^2 dA}$

Ideal Bernoulli

$$x=1, h_{LT}=0$$

frictionless flow.

Bernoulli Work done = 0

$\rightarrow \text{Head loss} = h_{LT} = h_2 - h_1$

major losses \rightarrow due to entrance, fittings, area change etc
(due to friction) (in const area).

$$\left(\frac{P_1}{\rho} + \frac{\alpha_1 V_1^2}{2} + g z_1 \right) - \left(\frac{P_2}{\rho} + \frac{\alpha_2 V_2^2}{2} + g z_2 \right) = h_{LT}$$

$h_L = f \frac{L}{D} \frac{V^2}{2}$ \rightarrow $f = \text{friction factor}$
 $f = f(R_e, c)$ \rightarrow Moody chart
 roughness.

$$h_m = \frac{k \frac{V^2}{2}}{2} \quad h_m = f \frac{L}{D} \frac{V^2}{2}$$

sudden change in area. \rightarrow $L = \text{corr length}$ (bends)

$e = \frac{\epsilon}{D} \rightarrow \text{roughness}$

Pump

$$W_{\text{pump}} = \dot{m} \left[\left(\frac{P}{\rho} + \frac{V^2}{2} + g z \right)_{\text{discharge}} - \left(\frac{P}{\rho} + \frac{V^2}{2} + g z \right)_{\text{suction}} \right]$$

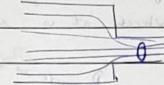
$$W_{\text{pump}} = \dot{m} \left(\frac{\Delta P}{\rho} \right)$$

pump adds energy in the form of gain in pressure to the fluid

\rightarrow Pump, fan, blowers.

Centrifugal pumps

Vena contracta \rightarrow fluid streamline cannot change its direction abruptly (sharp edges) (max velocity)



\rightarrow When the fluid passes through the nozzle, gradual contraction takes place

\rightarrow Priming is done by filling with water \rightarrow removal of air from pump and suction line

Pump \rightarrow impeller \rightarrow is a rotor used to increase the pressure and flow of a fluid.

Types of pump

① +ve displacement

Boundary layers?

pump / turbine

\rightarrow extracts energy and reduces pressure from fluid and does work

\rightarrow Pump head is the capacity. (to what height it will raise the fluid)

\downarrow pump capacity \times head \rightarrow flow rate through the pump \times head allowed \rightarrow flow rate of fluid \rightarrow $m \text{ kg/s} \times \text{m} \rightarrow \text{m}^3/\text{min}$

\Rightarrow head \rightarrow energy imparted to the medium

Dynamic P = kinetic energy per unit volume

Tensor → magnitude, direction and plane

9 components
Tensors are simply mathematical objects
that can be used to describe physical properties just like scalar and vectors.

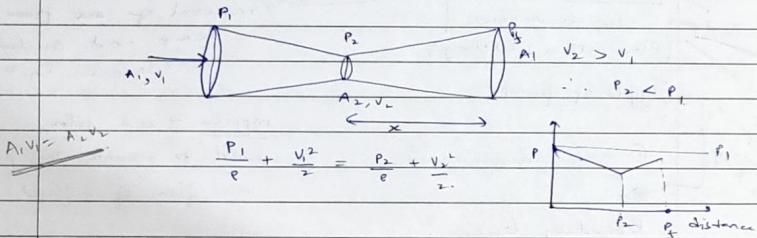
→ Manometer → to measure pressure

→ Buoyancy: Net vertical force acting on the body due to the liquid in which it is immersed.

Flow measuring instruments

① Venturi meter

$$Q = A_1 V_1 = A_2 V_2$$



large eddies → turbulent $P_f < P_1$ → loss of eddies.

length x must be large to avoid eddies

pressure coeff (c_p)

$$c_p = \frac{P_s - P_\infty}{\frac{1}{2} \rho u_\infty^2}$$

u_∞ = velocity at the surface

$$P_s - P_\infty = \frac{1}{2} \rho u_\infty^2 - \frac{1}{2} \rho u_s^2$$

relative pressure measured in head field

$$c_p = \frac{P_s - P_\infty}{\frac{1}{2} \rho u_\infty^2} \rightarrow \frac{\text{pressure forces}}{\text{inertial forces}}$$

$$C_V = \text{coeff of venturi meter} = \frac{\text{actual flow}}{\text{theoretical flow}}$$

↳ velocity ratio is getting converted to pressure ratio

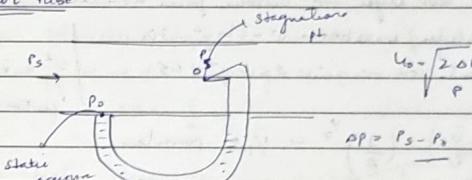
stagnation
and
decaying
flow
(if flow is ideal)

Orifice meter

$$V = \frac{C_o}{\sqrt{1 - f_h}} \sqrt{\frac{2(gf)}{e}}$$

→ venturi meter and orifice meter both will measure avg flow rate (not local)

Pilot tube

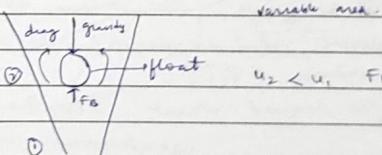


(local velocity)

→ Bourdon tube → pressure measurement → static P

↳ mercury column

Rotameter ($\Omega \times h$) → ($\Omega \times A$)



variable area

$u_2 < u_1$ $F_D = 6\pi\gamma ru$
for as float moves up,
 u_2 → hence float attains equilibrium

NPSHR → required min pressure
NPSHA → available → calculated

$$C_D = \frac{\text{drag force}}{\text{projected area} \times \frac{1}{2} \rho u^2}$$

$$\text{drag force} = C_D \times A \times \frac{1}{2} \rho u^2$$

drag coeff = used to quantify & resistance to of an object in fluid environment

→ Turbimeters → hot wire anemometers

→ Fluidization → notes

Turbulent flow

$$V = \bar{V} + V_t$$

→ viscous sub layer → viscous forces dominate $\rightarrow u^+ = \frac{\bar{u}}{u^+} = y^+$

→ buffer layer / transition $\rightarrow u^+ = 5 \ln y^+ - 3.05$

→ turbulent core $\rightarrow u^+ = 2.5 \ln y^+ + 5.5$

$$u^+ = \bar{V} \sqrt{\frac{f}{\rho}} \quad y^+ = y \frac{u^+}{\nu}$$

$$\left(\frac{\bar{u}}{V} \right) = \left(\frac{y}{e} \right)^{1/2} \rightarrow 1/2 \text{ in power law}$$

at the boundaries, stress cannot be calculated.

(undeterminate)

actual head available \rightarrow min req to avoid cavitation

NPSH-A → system property | NPSH-R → pump property

Cavitation: Bubble forms. These bubbles collapse in the form of implosion (violent explosion). It causes shock waves to travel through liquid

the liquid which hit the impeller and cause damage

shock wave
strong pressure
waves produced
by object moving
fast or at
speed of
sound
by body plan

Surface forces: - created on a surface of the body

Body forces: - acts throughout the volume of the body

Non-Dimensionalize: - to convert PDE to ODE

No. of variables can be reduced

h v/s laminar vs turbulence \rightarrow HT

Concave flow

→ flow between parallel plates - one plate is stationary and $\Delta P = 0 \rightarrow$ linear other is moving.
 $\Delta P \neq 0 \rightarrow$ parabolic

Creeping flow

convection $\rightarrow 0$

→ Hagen Poiseuille eqn → used to find ΔP .

→ friction factor $\rightarrow f \rightarrow$ Moody diagram.

$$\Delta P = \frac{f}{2} \frac{L}{D} \frac{V^2}{2}$$

→ Cone-plate viscometer.

from no longer follows the profile of the body around which it flows state forcing adhesion and detachment of boundary layer from a surface into a wake (drag reduces)

Boundary layer separation (why??)

detachment of boundary layer from a surface into a wake (drag reduces)

high pressure gradient
drag force will increase.
high pressure \rightarrow pt of separation
high Re
drag direction (not preferable)
so shape of the object is elongated to avoid separation
make low pressure

→ static pressure = pressure when there is no movement of fluid

→ dynamic → movement of fluid

→ to avoid BL separation, golf ball has dimples.

→ Drag force = opposite to the relative motion of any object moving w.r.t surrounding fluid.



mechanical force generated by solid object moving through a fluid.

→ acts opposite to the motion of the solid body.

→ source of drag depends on shape of solid

$$\text{Drag force} \rightarrow \text{Pressure drag} = \frac{1}{2} C_d A \rho v^2$$

→ lift force due to the motion

↳ component of pressure force due to

→ flowing fluid around the surface of an object exerts force on it. in direction → lift

opp to motion → drag

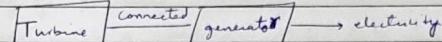
$$\text{Drag} = \text{avg. force} = \frac{1}{2} C_d \rho v^2 A$$

drag coeff

C_d = friction coeff → local.

→ friction drag → shear stress

Turbine (gas turbine)



produce
magnetic field

chemical energy to mechanical

→ Fuel must be burnt in a combustion chamber.

The energy produced during combustion is used to rotate the shaft fixed to the generator → and then it is used to produce electricity.

Water turbine : uses energy from the fluid to do work.

→ Re → characterizes the type of flow

how to derive reynolds no.?

height of BL becomes const after travelling certain distance

See few problems with Pressure gradient (continuum)

→ Industrial applications of fluid mechanics? - Dimples on ball

(airfoil or ball) (fluid mechanics)

(dimples in golf ball)

airplane

wing, tail

jet

turbine

water

dimensions

members

→ Lagrangian / Eulerian approach