### Parallel Algorithms

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- Introduction to parallel algorithms development
- □ Reduction algorithms
- □ Broadcast algorithms
- □ Prefix sums algorithms

# Introduction to Parallel Algorithm Development

- Parallel algorithms mostly depend on destination parallel platforms and architectures
- MIMD algorithm classification
  - Pre-scheduled data-parallel algorithms
  - Self-scheduled data-parallel algorithms
  - Control-parallel algorithms
- □ According to M.J.Quinn (1994), there are 7 design strategies for parallel algorithms



- □ 3 elementary problems to be considered
  - Reduction
  - Broadcast
  - Prefix sums
- □ Target Architectures
  - Hypercube SIMD model
  - 2D-mesh SIMD model
  - UMA multiprocessor model
  - Hypercube Multicomputer



□ Description: Given n values  $a_0$ ,  $a_1$ ,  $a_2$ ... $a_{n-1}$  associative operation  $\oplus$ , let's use p processors to compute the *sum*:

$$S = a_0 \oplus a_1 \oplus a_2 \oplus \dots \oplus a_{n-1}$$

### □ Design strategy 1

 "If a cost optimal CREW PRAM algorithms exists and the way the PRAM processors interact through shared variables maps onto the target architecture, a PRAM algorithm is a reasonable starting point"

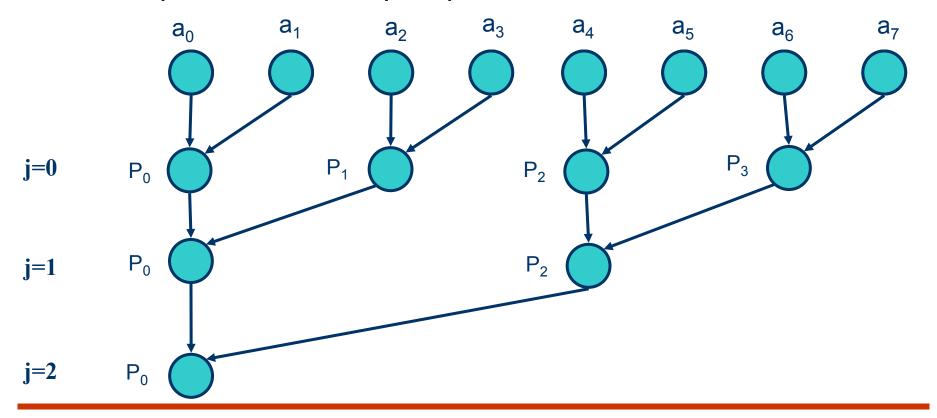


# Cost Optimal PRAM Algorithm for the Reduction Problem

Cost optimal PRAM algorithm complexity:

O(logn) (using n div 2 processors)

□ Example for n=8 and p=4 processors





## Cost Optimal PRAM Algorithm for the Reduction Problem(cont'd)

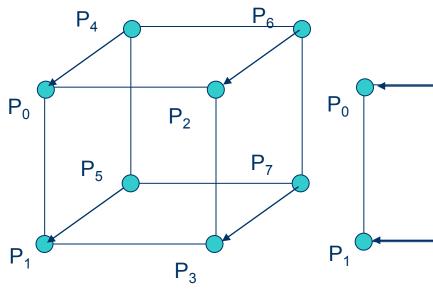
#### **Using p= n div 2 processors to add n numbers:**

```
Global a[0..n-1], n, i, j, p;
Begin
  spawn(P_0, P_1, \dots, P_{p-1});
  for all P_i where 0 \le i \le p-1 do
        for j=0 to ceiling(logp)-1 do
                 if i mod 2^{j} = 0 and 2^{j} + 2^{j} < n then
                     a[2i] := a[2i] \oplus a[2i + 2^{j}]:
                 endif;
         endfor j;
  endforall;
End.
```

Notes: the processors communicate in a biominal-tree pattern



### Solving Reducing Problem on Hypercube SIMD Computer



 $P_0$   $P_2$   $P_1$   $P_3$ 



Step 1:

Reduce by dimension j=2

Step 2:

Reduce by dimension j=1

Step 3:

Reduce by dimension j=0

The total sum will be at P<sub>0</sub>



### Solving Reducing Problem on Hypercube SIMD Computer (cond't)

#### Using p processors to add n numbers (p << n)

```
Global j;
```

Local local.set.size, local.value[1..n div p +1], sum, tmp;

Begin

```
spawn(P_0, P_1, \dots, P_{p-1});
```

for all  $P_i$  where  $0 \le i \le p-1$  do

if (i < n mod p) then local.set.size:= n div p + 1

else local.set.size := n div p;

endif;

sum[i]:=0;

endforall;

Allocate workload for each processors



### Solving Reducing Problem on Hypercube SIMD Computer (cond't)

Calculate the partial sum for each processor

```
for j:=1 to (n div p +1) do

for all P_i where 0 \le i \le p-1 do

if local.set.size \ge j then

sum[i]:= sum \bigoplus local.value [j];

endforall;

endfor j;
```



### Solving Reducing Problem on Hypercube SIMD Computer (cond't)

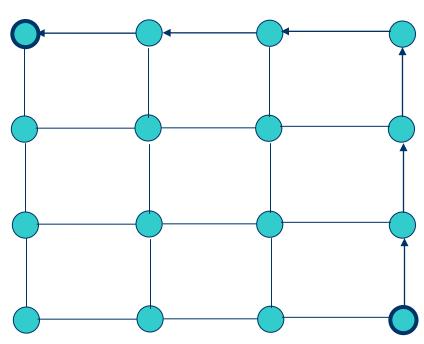
Calculate the total sum by reducing for each dimension of the hypercube

```
for j:=ceiling(logp)-1 downto 0 do
     for all P_i where 0 \le i \le p-1 do
    if i < 2^{j} then
          tmp := [i + 2^j]sum;
       sum := sum \bigoplus tmp;
         endif;
  endforall;
endfor j;
```



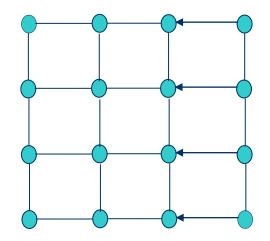
- □ A 2D-mesh with p\*p processors need at least 2(p-1) steps to send data between two farthest nodes
- → The lower bound of the complexity of any reduction sum algorithm is  $O(n/p^2 + p)$

**Example:** a 4\*4 mesh need 2\*3 steps to get the subtotals from the corner processors



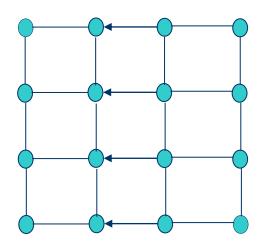


□ Example: compute the total sum on a 4\*4 mesh



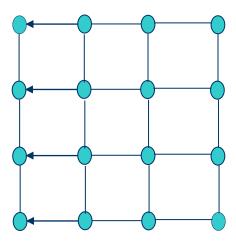
Stage 1

Step i = 3



Stage 1

Step i = 2

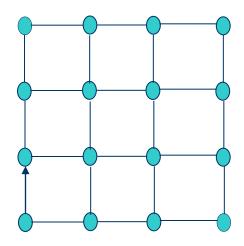


Stage 1

Step i = 1

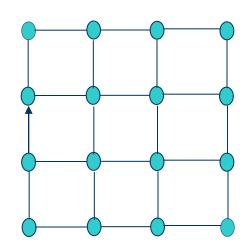


□ Example: compute the total sum on a 4\*4 mesh



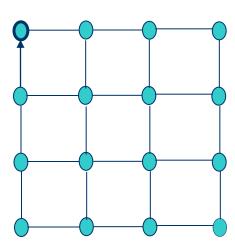
Stage 2

Step i = 3



Stage 2

Step i = 2



Stage 2

Step i = 1

(the sum is at  $P_{1,1}$ )



#### Summation (2D-mesh SIMD with I\*I processors

```
Global i;
Local tmp, sum;
Begin
 {Each processor finds sum of its local value →
   code not shown}
 for i:=I-1 downto 1 do
  for all P_{i,i} where 1 \le i \le I do
        {Processing elements in colum i active}
        tmp := right(sum);
        sum:= sum ⊕ tmp;
     end forall;
 endfor;
```

Stage 1:

P<sub>i,1</sub> computes the sum of all processors in row i-th



#### Stage2:

Compute the total sum and store it at P<sub>1.1</sub>

```
for i:= I-1 downto 1 do
    for all Pi,1 do
        {Only a single processing element active}
        tmp:=down(sum);
        sum:=sum  tmp;
        end forall;
    endfor;
    End.
```



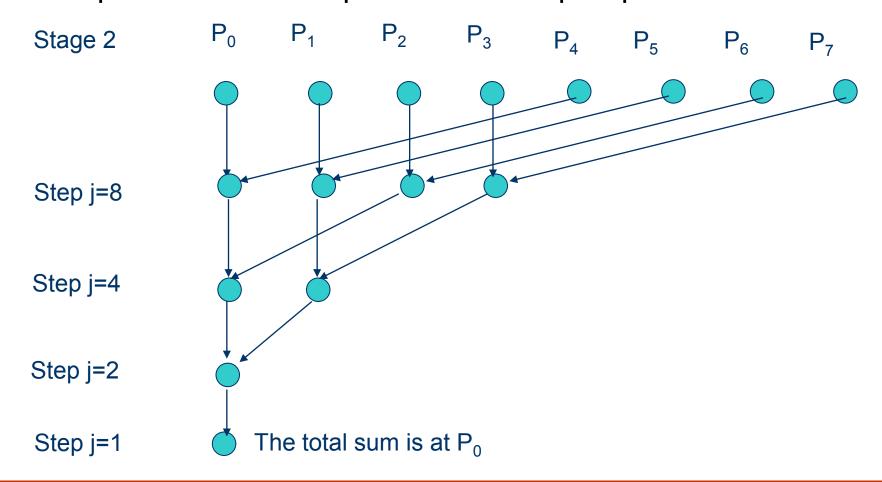
- □ Easily to access data like PRAM
- □ Processors execute asynchronously, so we must ensure that no processor access an "unstable" variable
- □ Variables used:

```
Global a[0..n-1], {values to be added}
p, {number of processor, a power of 2}
flags[0..p-1], {Set to 1 when partial sum available}
partial[0..p-1], {Contains partial sum}
global_sum; {Result stored here}

Local local sum;
```



□ Example for UMA multiprocessor with p=8 processors





#### **Summation (UMA multiprocessor model)**

Stage 1:

Each processor computes the partial sum of n/p values

```
Begin
for k:=0 to p-1 do flags[k]:=0;
for all P<sub>i</sub> where 0 ≤ i < p do
local_sum :=0;
for j:=i to n-1 step p do
local_sum:=local_sum ⊕ a[j];
```



Stage 2:

Compute the total sum

Each processor waits for the partial sum of its partner available

```
j:=p;
    while j>0 do begin
      if i \ge j/2 then
         partial[i]:=local sum;
         flags[i]:=1;
         break;
      else
        ⊶while (flags[i+j/2]=0) do;
         local sum:=local sum \oplus partial[i+j/2];
      endif;
      j=j/2;
    end while;
    if i=0 then global_sum:=local_sum;
end forall;
End.
```



- □ Algorithm complexity 0(n/p+p)
- What is the advantage of this algorithm compared with another one using critical-section style to compute the total sum?
- □ Design strategy 2:
  - Look for a data-parallel algorithm before considering a control-parallel algorithm
  - → On MIMD computer, we should exploit both data parallelism and control parallelism (try to develop SPMD program if possible)

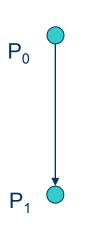


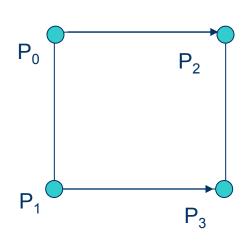
- □ Description:
  - Given a message of length M stored at one processor, let's send this message to all other processors
- □ Things to be considered:
  - Length of the message
  - Message passing overhead and data-transfer time

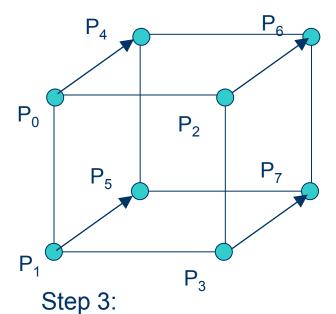


### **Broadcast Algorithm on Hypercube SIMD**

- □ If the amount of data is small, the best algorithm takes **logp** communication steps on a **p-node** hypercube
- □ Examples: broadcasting a number on a **8-node** hypercube







Step 1:

Send the number via the 1<sup>st</sup> dimension of the hypercube

Step 2:

Send the number via the 2<sup>nd</sup> dimension of the hypercube

Send the number via the 3<sup>rd</sup> dimension of the hypercube



# Broadcast Algorithm on Hypercube SIMD(cont'd)

#### Broadcasting a number from P<sub>0</sub> to all other processors

```
Local
                   {Loop iteration}
                   {Partner processor}
         position; {Position in broadcast tree}
         value; {Value to be broadcast}
Begin
 spawn(P_0, P_1, \dots, P_{p-1});
 for j:=0 to logp-1 do
   for all P_i where 0 \le i \le p-1 do
     if i < 2^{j} then
          partner := i+2<sup>j</sup>;
        [partner]value:=value;
           endif;
   endforall:
end forj;
End.
```

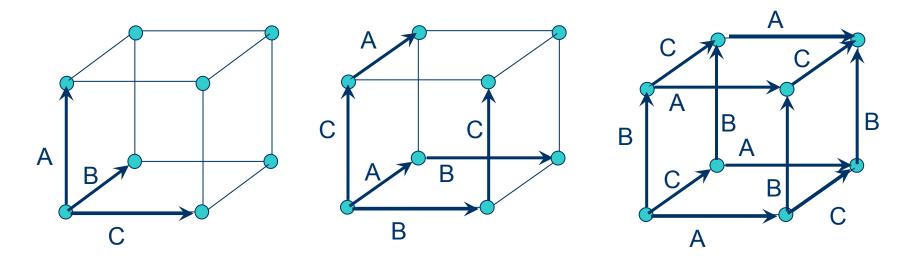


### **Broadcast Algorithm on Hypercube SIMD(cont'd)**

- □ The previous algorithm
  - Uses at most p/2 out of plogp links of the hypercube
  - Requires time Mlogp to broadcast a length M msg
  - → not efficient to broadcast long messages
- □ Johhsson and Ho (1989) have designed an algorithm that executes logp times faster by:
  - Breaking the message into logp parts
  - Broadcasting each parts to all other nodes through a different biominal spanning tree



# Johnsson and Ho's Broadcast Algorithm on Hypercube SIMD



- □ Time to broadcast a msg of length M is Mlogp/logp = M
- □ The maximum number of links used simultaneously is plogp, much greater than that of the previous algorithm



### Johnsson and Ho's Broadcast Algorithm on Hypercube SIMD(cont'd)

- □ Design strategy 3
  - As problem size grow, use the algorithm that makes best use of the available resources



### **Prefix SUMS Problem**

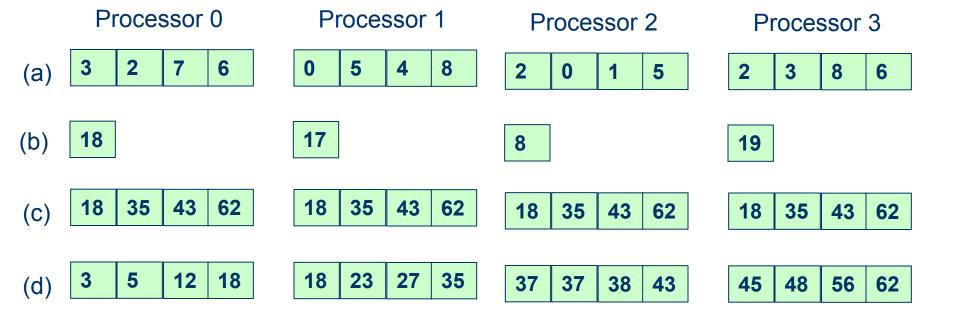
#### □ Description:

- Given an associative operation ⊕ and an array A containing n elements, let's compute the n quantities
  - A[0]
  - A[0] ⊕ A[1]
  - A[0] ⊕ A[1] ⊕ A[2]
  - ...
  - A[0] ⊕ A[1] ⊕ A[2] ⊕ ... ⊕ A[n-1]
- □ Cost-optimal PRAM algorithm:
  - "Parallel Computing: Theory and Practice", section 2.3.2, p. 32



# Prefix SUMS Problem on Multicomputers

#### □ Finding the prefix sums of 16 values





# Prefix SUMS Problem on Multicomputers(cont'd)

- □ Step (a)
  - Each processor is allocated with its share of values
- □ Step (b)
  - Each processor computes the sum of its local elements
- □ Step (c)
  - The prefix sums of the local sums are computed and distributed to all processor
- □ Step (d)
  - Each processor computes the prefix sum of its own elements and adds to each result the sum of the values held in lower-numbered processors