

Hazard ID	Operational Mode	Operational Scenario	Situational Analysis			Situation Description	Function	Deviation Details	Hazard Identification		Hazardous Event Description	Exposure (if situation)	Rationale (for exposure)	Hazardous Event Classification			Rationale (for controllability)	Determination of ASLR and Safety Goals		
			Environmental Details	Situational Context	Other Details (optional)				Non Usage Function	Hazardous Event Description				Hazardous Event Description	Severity	Controllability		Rationale	ASLR	Safety Goals
HA-001	CM003 Normal Driving	CM004 Highway	EN001 Normal Conditions	SC002 High Speed	LU01-Correctly used	Normal driving on a highway during rain (steering road) with high speed and correctly used system.	Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver with haptic feedback.	DEV04 Actor effect is too much	The Lane Departure Warning applies a very strong oscillating torque to the wheel (above limits).	EV003-Collision with other vehicle	High haptic feedback can affect driver's ability to steer as intended. The driver could lose control of the vehicle and collide with another vehicle or with road infrastructure.	The LDW function applies too high an oscillating torque to the steering wheel (above limits).	E2 - Low probability	The risk probability of occurrence depends on each Earth zone, time around the year. In the worst cases, it rains around 50% of the year.	CS1-Life threatening or fatal injuries	CS3-Life threatening or fatal injuries	The driver is travelling at high speed	Vehicle control when there is a strong vibration is hard and surprising.	C	The oscillating steering torque from the Lane Departure Warning function shall be limited.
HA-002	CM003 Normal Driving	CM003 Country Road	EN001 Normal Conditions	SC002 High Speed	LU01-Incorrectly used	Normal driving on country roads during normal conditions at high speed. The driver is misusing the lane keeping assistance function as an autonomous function.	Lane Keeping Assistance (LKA) function shall apply the steering torque when active in order to stay in ego lane	DEV03 - Function is always activated	Lane Keeping is always activated.	EV003-Collision with other vehicle	The driver misuses the Lane Keeping function and the LKA is always ON.	E2-Low probability	The driver is on a country road and misusing the system.	CS3-Life threatening or fatal injuries	CS3-Life threatening or fatal injuries	The driver is travelling at high speed	CS3-Difficult to control or uncontrollable	Because hands aren't on the wheel at high speed, a vehicle accident would not be controllable.	B	The Lane Keeping Assistance function shall be limited, and additional steering torque shall end after a given time interval so the driver cannot misuse the system for autonomous driving.
HA-003	CM003 Normal Driving	CM002 City Road	EN001 Normal Conditions	SC001 Low Speed	LU01-Correctly used	Normal driving on a city road during rain (steering road) with low speed and correctly used system.	Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver with haptic feedback.	DEV04 Actor effect is too much	The Lane Departure Warning applies a very strong oscillating torque to the wheel (above limits).	EV003-Collision with other vehicle	High haptic feedback can affect driver's ability to steer as intended. The driver could lose control of the vehicle and collide with another vehicle or with road infrastructure.	The LDW function applies too high an oscillating torque to the steering wheel (above limits).	E3 - Medium probability	The risk probability of occurrence depends on each Earth zone, time around the year. In the worst cases, it rains around 50% of the year.	CS2-Severe and life threatening injuries	CS3-Life threatening or fatal injuries	The driver is travelling at low speed. A collision may occur but since speed is slow, the effects are reduced.	Vehicle control when there is a strong vibration is hard and surprising.	B	The oscillating steering torque from the Lane Departure Warning function shall be limited.
HA-004	CM003 Normal Driving	CM004 Highway	EN001 Normal conditions	SC002 High Speed	LU01-Correctly used	Normal driving on a city road during normal conditions with high speed and correctly used system.	Lane Departure Warning (LDW) function shall apply an oscillating steering torque to provide the driver with haptic feedback.	DEV04 Actor effect is too much	The Lane Departure Warning applies a very strong oscillating torque to the wheel (above limits).	EV003-Collision with other vehicle	High haptic feedback can affect driver's ability to steer as intended. The driver could lose control of the vehicle and collide with another vehicle or with road infrastructure.	The LDW function applies too high an oscillating torque to the steering wheel (above limits).	E4-High probability	Normal conditions are expected. Almost anytime the car is driving.	CS3-Life threatening or fatal injuries	CS3-Life threatening or fatal injuries	The driver is travelling at high speed	Vehicle control when there is a strong vibration is hard and surprising.	D	The oscillating steering torque from the Lane Departure Warning function shall be limited.