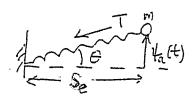
A. Tran	asverse Oscillati	ons of coupled masses	i-springs system:	
8,2024 8,2024	Now let us a	onsider the transverse	escultations of the mass	-sprinc
51-10 15 Feb,	system. Are the	re normal modes of to	ansverse oscillation?	
equilibrium	4-mil	e→1←~~ Se~~	moment for	
		, , ,	~e	·
			1/4)	
general	*	~	14(t)	٠
	Due to the sy		to guess the two modes.	They are
		middle Spring Boeps 99 vil s tvet in now	ch mode 1. 4=4b	~.
mode 1	\$	- 	1-1	and
!				
mode 2	form	mon in	4=-4a 1	
		middle spring active in normal mode 2.	Next we find the Grequencies of these mode	ر د د دا

To find the mode frequencies, here well use the "quick method" of assuming our guesses on the last page are correct and then using w2= return force/mass. desp. (Since the motion of either mass in either pure mode is s.h.m, that method ("method of physical meaning of w2") must work to provide the mode frequencies: [For homework, you will use the "method of normal Coordinates" for the transverse oscillations of this system. In guessed mode # 1, 4a(t) = 4b(t) at all times and the middle spring always remains at equilibrium shetch (no excess shetch). for Mode!

That _____ Hode!

#= 4a

Thus, for this method, all of the excess force on, say, the left mass comes from the spring that couples it to the wall (and the same is true for the right-hand mass. Thus, in mode 1,



Using sin 0 = 0 = tan 0 in the small oscillations approximation

Mode 1 $F = T_{SUL}\theta \approx T_{0} + \frac{1}{4}$ In small osc. approx., $T \approx T_{0}$ and, in small osc. does not change (hardly) in mag. approx., $Sin \theta \approx tam \theta$. (4) = $V_{0}(t) = V_{0}(t)$... $w^{2} = \frac{rehvn frice}{mass disp} = \frac{T_{0} + a}{S_{e} M \cdot V_{0}} \Rightarrow w^{2} = \frac{T_{0}}{MS_{e}}$

Normal Mode # 2

Now consider mode 2: <u>m left mass</u>: F_{x} from left spring $\approx -T_{c} \frac{4a}{s_{e}}$ F_{x} from ctr. spring $\approx -2T_{o} \frac{4a}{s_{e}}$

Thus, in general, for abbitrary internal transverse motions of the masses within their system, as long as the displacements are "small",

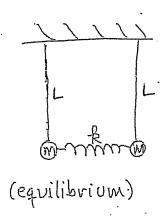
$$Y_{a}(t) = A_{1} \cos(\sqrt{\frac{T_{0}}{m_{S_{e}}}}t + \phi_{1}) + A_{2} \cos(\sqrt{\frac{3T_{0}}{m_{S_{e}}}}t + \phi_{2})$$

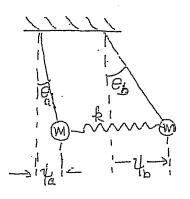
$$Y_{b}(t) = A_{1} \cos(\sqrt{\frac{T_{0}}{m_{S_{e}}}}t + \phi_{1}) - A_{2} \cos(\sqrt{\frac{3T_{0}}{m_{S_{e}}}}t + \phi_{2})$$

The most general transverse motion (in the "plane of the page") is, then, an arbitrary superposition of both modes going at once with arbitrary amplifiedes A, and Az.

B. Further Examples of Normal Modes

1. Coupled Pendula, Equal Masses (Text, sect.





What are the equations of motion?

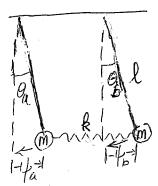
Can work either in E's or in y's. Will arbitrarily choose 4.

We have you think this through, find, in the small oscillations approx,

(16)
$$m \dot{\psi}_{b} = - m \frac{g}{l} \psi_{b} - R(\psi_{b} - \psi_{a})$$

(If we decide to "work in the O's," we get equations of the same form). To solve these we can use either the "method of searching for normal coordinates, or we can "guess" by using the "method of physical meaning of w?" We will do the latter here:

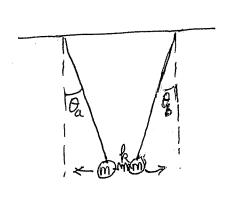
In the pure first normal mode, both masses swing together in phase at the same frequency; i.e., in this mode $Q_a(t) = Q_b(t)$



and $\psi_a(t) = \psi_b(t)$, the frequency is given by

(2a) $W_r^2 = \frac{9}{l}$.

In the pure second normal mode, both masses swing 180° out of phase with each other (i.e, "against each other"); i.e, in this



mode $\theta_b(t) = -\theta_a(t)$ and $\psi_b(t) = -\psi_a(t)$ at all times t; as you can show, the frequency of this mode is given by (2b) $W_2^2 = \frac{9}{\ell} + \frac{2k}{m}$.

The most general motion is a general superposition of both modes (each excited with arbitrary amplitude) going at once, i.e.,

 $Y_a(t) = A_1 \cos(\sqrt{2}t + \phi_1) + A_2 \cos(\sqrt{2} + \frac{2k}{m}t + \phi_2)$ $V_a(t) = A_1 \cos(\sqrt{2}t + \phi_1) - A_2 \cos(\sqrt{2} + \frac{2k}{m}t + \phi_2)$

2. Coupled Pendula, Unequal Masses [Text, Norked Exl. 6.3] The system is shown (un arbitrary configuration) in the figure:

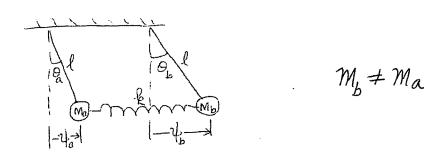


Fig. 6.10 Coupled pendula of unequal mass

As you can verify, the governing differential egns. are:

We will try the method of normal coordinates here.

Adding eqns. (3a) and (3b) we obtain

is a normal coordinate. Good.

Now we try to find the second normal coordinate. Suppose we try subtracting eqn. (26) from eqn. (2a). Then we get

 $(M_a \mathcal{H}_a - M_b \mathcal{H}_b) = -\frac{g}{L} (M_a \mathcal{H}_a - M_b \mathcal{H}_b) - 2 \mathcal{R} (\mathcal{H}_a - \mathcal{H}_b),$ which wrot a normal equation!

So, we will have to be a little clever. Suppose we divide eqn. (3u) by ma, divide eqn. (3b) by mb, and then subtract. We then get

(5)
$$(4a-4b)^{\circ} = -\frac{9}{2}(4a-4b) - k(\frac{1}{m_a} + \frac{1}{m_b})(4a-4b)$$

Recalling that the reduced mass M is defined by

(6)
$$\frac{1}{\mu} = \frac{1}{m_a} + \frac{1}{m_b},$$

(6) is

Eqn. (7) is of normal form, ... we can choose our second normal coordinate as $g_2(t) = V_a(t) - V_b(t)$.

From egns. (4) and (7) we see that the mode frequencies are

(ga)
$$W_1 = \sqrt{\frac{9}{\ell}}$$

(8b)
$$\omega_2 = \sqrt{\frac{9}{l} + \frac{k}{\mu}}$$

Question: Suppose that $m_a = 70_b$. Then eqn. (\$b) should reduce to eqn. (2b). Does it? Justify your answer.

Physical Meanings of The Normal Coordinates

Can we attach a physical meaning to each of the normal coordinates we found in this example? That of $q_2(t) \equiv V_a(t) - V_b(t)$ is clear; it is just the of the two masses ("relative coordinate"). That makes sense in mode 2, the two masses oscillate "against" each other, so the separation distance between them oscillates in s.h.m. So far, so good.

Now, what is the physical meaning of $q_i(t) = m_a \mathcal{H}_a + m_b \mathcal{H}_b$? To answer this question we need to make use of a little theorem:

Theorem: Let $q_{\times}(t)$ be a normal coordinate associated with frequency W_{\times} (x=1,2.). Then, for any constant C, the quantity $Cq_{\times}(t)$ is also a normal coordinate associated with frequency W_{\times} .

Proof: By definition, if qx(t) is a normal coordinate, it obeys

(9)
$$\dot{q}_{\infty}(t) = -W_{\infty}^2 q_{\infty}(t)$$

Multiplying both sides of eqn. (9) by any constant C, (10) $\left[Cq_{\kappa}(t)\right]^{\circ} = -w_{\kappa}^{2}\left[Cq_{\kappa}(t)\right]$.

Thus, Cq_{x} is also a normal coordinate associated with frequency W_{x} .

Suce quand cquare not independent, colloquially

We say that they are both "the same normal coordinate".

Returning, then to $q_1(t)$, we see that we can choose it as any constant times ($M_a Y_a + M_b Y_b$). Let us choose that constant to be $\frac{1}{M}$ where $M = M_a + M_b$. Then

(11)
$$q_1(t) = \frac{M_a Y_a + M_b Y_b}{M_a + M_b}$$

From egn. (11) we see that q,(+) represents the position of the center of mass! (We assume that the spring is massless.) This makes sense - in normal mode #1 the two masses are swinging in lock-step with equal amplitude, with the spring maintaining its equilibrium Stretch-the amplitudes are equal in this mode. Therefore, For motion in this mode (only) we can replace the Coupling spring with massless rigid rod. Thus, in this mode, the position of the CM indeed oscillates in S.h.m. with frequency $\omega_1 = \sqrt{\frac{9}{2}}$.

Thus, we see that, in this situation, the transformation from the (4,46) coordinate system to the (9,92) normal coordunate system is the transformation to center of mass/relative Coordinates!

We must now invert to find if and it. Doing that, I find

(12)
$$4a = 91 + \frac{m_b}{M} 92$$
 and $5with 91 = \frac{m_a 4a + m_b 4b}{M}$

$$92 = 4a - 4b$$

(13)
$$4b = 91 - \frac{Ma}{M} 92$$

So that, in general, (with M = Ma+Mb)

(14)
$$Y_a(t) = C_1 \cos(\omega_1 t + \phi_1) + \frac{M_b}{M} C_2 \cos(\omega_2 t + \phi_2)$$

(15)
$$Y_b(t) = C_1 \cos(w_1 t + \phi_1) - \frac{M_a}{M} C_2 \cos(w_2 t + \phi_2)$$

where C, and C2 are arbitrary constants. (You should verify or negate) this claim. Defining a new constant $G \equiv C_2 \frac{m_p}{M}$, we have

(14')
$$4a(t) = C_1 \cos(\omega_1 t + \phi_1) + G \cos(\omega_2 t + \phi_2)$$

(14')
$$f_a(t) = C_1 \cos(\omega_1 t + \phi_1) - \frac{Ma}{Mb} G \cos(\omega_2 t + \phi_2)$$

(15') $f_b(t) = C_1 \cos(\omega_1 t + \phi_1) - \frac{Ma}{Mb} G \cos(\omega_2 t + \phi_2)$

We must now check that these results make sense:

- 1. From eqns. (14) and (15), we mode 1 the masses move up phase with equal amplitudes. That makes sense because, in this mode, the coupling spring should maintain its equilibrium length and therefore, the entire assemblage oscillates like one big sample har monic oscillator at frequency $w_i = \sqrt{\frac{9}{2}}^7$.
- 2. However, in mode 2, the amplitudes of ma and mo are not equal and opposite. Instead, note from eqns. (14) and (15) that, in mode 2,

$$\frac{\left|\Omega_{mp_{b}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion of each is}$$

$$\frac{\left|\Omega_{mp_{a}^{(2)}}\right|}{\left|\Omega_{mp_{a}^{(2)}}\right|} = \frac{m_{a}}{m_{b}} - ie, \text{ the motion$$

That is required to keep the C.M. stationary; hence it "makes sense." That the motions of Ma and Mb are not equal and opposite in mode # 2 is also a reflection of the fact that the system is not left-right symmetric about its "mid-line". (Recalled iscussion in section 6.9 of the text.)

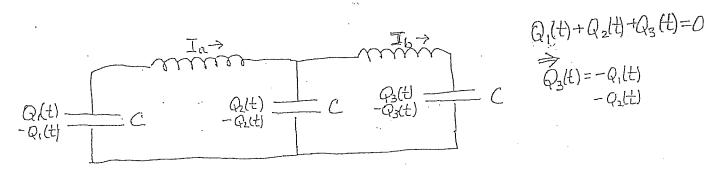
C. Normal Modes In an Electrical Circuit

We have considered the normal modes of internal longitudinal (all oscillation of the coupled mass-spring system

4-rry 1000 minon rry (equil. con figuration).

We now consider the electrical circuit analog of the above system.*

It is (since ma>L, ka> = (so L's in series, C's in parallel)]:



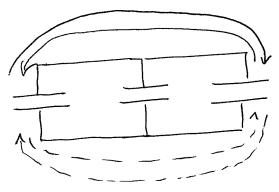
One of the spring-mass systems we considered. We work this out on two ways:

1. Reasoning By Analogy. (Serves to tell us what to expect:)

Normal Mode # 1: In the mechanical system, in this mode the middle spring always maintains equilibrium length, the two endsprings stratch and compress, and the mode frequency is $W = \sqrt{R/m}$. Since $C \Longleftrightarrow \frac{1}{R}$, $L \leadsto m$,

+ Probably the way most Physicists would reason on first considering the situation. * A slight generalization of the electrical analog system we consider here is taken up in Chap. 6 Worked Exls 6.4 and 6.5. You should read that right after our present discinction in mode # 1 in the electrical system we expect no current into or out of the middle capacitor; thus, the charge should oscillate only between the two end capacitors:

MODEL

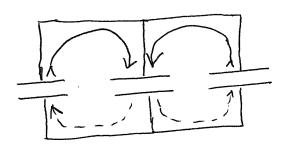


NO CURRENT IN CENTRAL LINE.

Suce the mechanical analog system hequency is $W_1^2 = \sqrt{\frac{R}{m}}$, the electrical system mode 1 frequency should be $W_1^2 = \sqrt{\frac{LC}{LC}}$.

Normal Mode #2: In this mode, in the mechanical system, while the end springs both stretch at the same time and compress at the same time, the length of the middle spring also oscillates. Thus, for the electrical system we expect the mode to look like

MODE 2:



with the arrows reversed half a period later.

Suce the mechanical system mode #2 frequency is $W_2 = \sqrt{\frac{3k}{m}}$, for the electrical system we expect that $W_2 = \sqrt{\frac{3}{LC}}$.

Thus, the general solution to the governing d.e.'s (eqns. (1) and (2) above) is

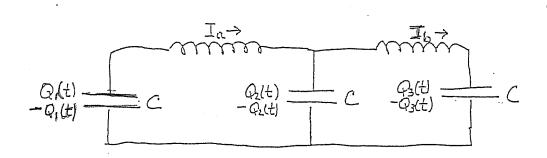
(3)
$$I_a = C_1 \cos(\sqrt{Lc} t + \phi_1) + C_2 \cos(\sqrt{Lc} t + \phi_2)$$

(4)
$$I_b(t) = C_1 \cos\left(\frac{1}{\sqrt{Lc}} t + \phi_1\right) - C_2 \cos\left(\sqrt{\frac{3}{Lc}} t + \phi_2\right)$$

for arbitrary numbers C, and Cz.

2. Analysis By Method of Searching for Normal Coordinates

[cf W.E. 6.5, sect. 6.11]



Assuming system is neutral, $Q_1(t) + Q_2(t) + Q_3(t) = 0$ $Q_3(t) = -Q_1(t)$

We need the equations of motion. Applying the loop theorem

to the left loop,
$$\frac{Q_1(t)}{dt} - L \frac{dI_0(t)}{dt} - \frac{Q_2(t)}{C} = 0 \quad \text{or} \quad L \frac{dI_0}{dt} = \frac{1}{C}(Q_1 - Q_2)$$

We can express things either in terms of the Q's or the I's. Let's say we

use the I language: Recalling $I = \frac{dQ}{dt}$ and taking another derivative, $L \frac{d^2 I_a}{dt^2} = \frac{1}{C} \left(\frac{dQ_1}{dt} - \frac{dQ_2}{dt} \right)$

But:
$$-\frac{dQ_1}{dt} = I_a$$
, $\frac{dQ_2}{dt} = I_a - I_b$, ...

(5)
$$\frac{d^2 \overline{I}_a}{dt^2} = \frac{1}{C} \overline{I}_a + \frac{1}{C} (\overline{I}_b - \overline{I}_a) , \text{ and similarly}$$

$$\frac{d^2 \overline{I}_b}{dt^2} = -\frac{1}{C} (\overline{I}_b - \overline{I}_a) - \frac{1}{C} \overline{I}_b$$

$$(6)$$

Egns. (5) and (6) are the governing differential equations for this system. Note that they are in exact analogy in form to the governing does's for the mass-sping mechanical system!

Since the physical system is exactly "left-right" symmetric, we should be able to find the normal coords in a straight-forward way. However, first-what do we expect? Since we are working in "I-language" we expect them to be $q_1^{(*)} = I_a + I_b$, $q_2^{(*)} = I_a - I_b$. To confirm this, adding and subtracting eqns. (5) and (6) we find

$$\frac{d^2(I_a+I_b)}{dt^2} = \frac{1}{LC}(I_a+I_b)$$
, and

(8)
$$\frac{d^2(I_a-I_b)}{dt^2} = -\frac{3}{LC}(I_a-I_b)$$
.

Thus, clearly the normal coordinates are

$$q_{1,2} = C_{1,2} (I_a \pm I_b)$$

Where C,, C2 are any constants.

And again the most general thing that can happen (un terms of currents internal to the system) is a general superposition of two normal modes—this follows from equs (7) and (8) above.

^{(*) 9,(}t) and 9,(t) here are normal coordinates, not charges on capa

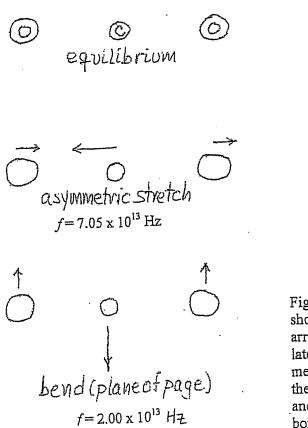
D. Normal Modes and Radiation From Triatomic Molecules; Relation To Planetary Green house Effect.

Reading! Text, sect. 6.13

In the homework, you will treat the case of diatomic molecules with both ions of arbitrary mass by multiple methods.

Here we consider a triatomic case:

Consider the COz molecule. It is a triatomic line-molecule; some of its normal modes are shown below."



 $\begin{array}{c}
\text{Symmetric stretch} \\
f = 4.01 \times 10^{13} \text{ Hz}
\end{array}$

bend (in Lout of pq.) $f = 2.00 \times 10^{13} \text{ Hz}$ + = into page $\bullet = \text{out of page}$

Fig. 6.15 Normal modes of the CO₂ molecule. Not shown is the "normal mode" of frequency zero. All arrows shown are reversed in direction one-half cycle later. The frequencies of electromagnetic radiation measured from these modes are indicated. From these, one can extract the effective spring constant, and from this, information about the C-O chemical bond. By symmetry, the frequencies of the two bend modes shown are equal.

Figure is from your text.

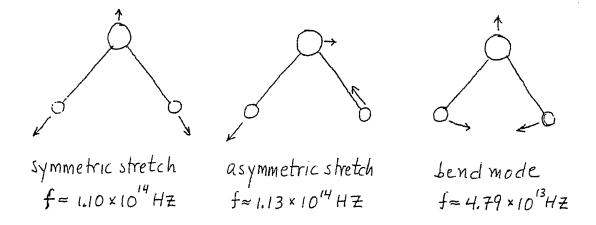


Fig. 6.16 Some of the normal modes of the H_2O molecule and their frequencies. The directions of the arrows are reversed every half cycle.

Let us return to CO_2 ; we are particularly interested in the longitudinal modes. Based on our previous work, we use a spring model for the chemical bonds:

$$(m_1)$$
 $-m_2$ $-m_2$ $-m_1$ $m_1 = m_{oxygen}$ $m_1 = m_{oxygen}$ $m_2 = m_{carbon}$

Within the context of the "spring model," it is not difficult to guess expressions for the frequencies of two of these modes; the symmetric stretch and the asymmetric stretch, both of which occur "in the plane of the page." In each of these modes, the center of mass of the molecule remains stationary². In the symmetric stretch mode (Fig. b), the Carbon in the center remains stationary with the two Oxygen atoms moving toward and away from it with equal amplitudes and 180° out of phase with each other. If each spring modeling the C-O bond has spring constant k, the mode frequency is $\omega_{ss} = \sqrt{k/m_O}$, since the Carbon acts like a "rigid Wall" (in this wo de

$$\left(\begin{array}{ccc} 0 & 0 & 0 \\ 0 & c & 0 \end{array}\right)$$

In the asymmetric stretch mode, if at any instant t the Oxygens are displaced from equilibrium by amount 40 = 4a = 4c, then to keep the CM stationary the Carbon must be displaced in the other

derection by amount $f_c(t) = -2 \frac{m_o}{m_c} f_o(t)$. From this, the total stretch (from equilibrium) of the right-hand spring is

so the force it exerts on the right-hand Oxygen is

Fretum on
$$0 = R(1 + \frac{2M_0}{M_c}) \psi_0$$

So
$$W^{2} = \frac{F_{\text{neturn on 0}}}{M_{0} + \sigma} = \frac{k}{M_{0}} \left(1 + \frac{2M_{0}}{M_{c}}\right) = \frac{k}{M_{0}} + \frac{2k}{M_{c}}$$

So we really can easily know the mode frequencies in terms of k without having to call on a more general systematic method that we will learn next.

Reading for -> Tuesday! Text, sect. 6.14.