(1)
$$P(-2,-2,3)$$
 repeate $P'(-3,1,4)$ \overline{U} en diverción PP' . Cosenos clirectores.

$$P'P = P - P' = (-2,-2,3) - (-3,1,4) = (1,-3,-1) \quad |\overline{U}| = \sqrt{1^2 + (-3)^2 + (1)^2} = \sqrt{|\overline{U}|} \quad |\overline{U}| = \sqrt{|$$

3. Sean dos sistemas de reterencia R, y Rz, que tienen el mismo origen O y ejes de coordenadas X1, X2, X3 y X1, X3 respectivamente. Sabiendo que el ángulo que forman los ejes X, y X1 es de 30°, encontrar la matriz de transformación para el cambio de un sistema de acordenadas al otro. Sea un vector, ruyas componentes respecto al sistema R, son Ā= (1,2,-21. Encontrar las componentes del vector en Rz. Determinar su módulo y sus cosenos directores respecto R, y Rz.

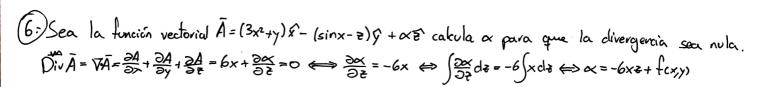
$$\begin{array}{l} |R_{1}| \cos \alpha = \frac{Ax}{|A|} = \frac{1}{3} \cos \beta = \frac{Ay}{|A|} = \frac{2}{3} \cos \phi = \frac{A^{2}}{|A|} = \frac{2}{3} \left(|A| = \sqrt{1^{2} + 2^{2} + (z^{2})} = 3 \right) \\ |Q_{x_{1},x_{1}}| = 30^{\circ} \implies \cos \phi = \frac{\sqrt{3}}{2} \sin \phi = \frac{1}{2}. \text{ Rotumos sobre Of 602, elijo 02:} \\ |Q_{x_{1},x_{1}}| = 30^{\circ} \implies \cos \phi = \frac{\sqrt{3}}{2} \sin \phi = \frac{1}{2}. \text{ Rotumos sobre Of 602, elijo 02:} \\ |Q_{x_{1},x_{1}}| = 30^{\circ} \implies \cos \phi = \frac{\sqrt{3}}{2} \sin \phi = \frac{1}{2}. \text{ Rotumos sobre Of 602, elijo 02:} \\ |Q_{x_{1},x_{1}}| = \frac{1}{2} \circ \left(\sqrt{13} + \frac{1}{2} - \frac{1}{2} - \frac{1}{2} \right) \\ |Q_{x_{1},x_{1}}| = \frac{1}{2} \circ \left(\sqrt{13} + \frac{1}{2} - \frac{1}{2} -$$

(4-) P(-1,3,2) contexiones de Dirección de maximo accimiento de $\phi(x,y,z) = (x+y)^2 + z^2 - xy + 2z^2$.

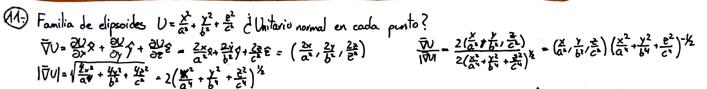
Hence de evaluar el gradiente en dicho punto y hacer la dirección unitaria. $\nabla \phi = \left(\frac{\partial \mathcal{O}}{\partial x}, \frac{\partial \mathcal{O}}{\partial y}, \frac{\partial \mathcal{O}}{\partial z}\right) = (2x+y, x+2y, 2(z+1))$ $\nabla \phi(-1,3,2) = (1,5,6)$ $\sqrt{1-1,5} = (1,5,6)$ $\sqrt{1-1} = (1,5,6)$ $\sqrt{1-1} = (1,5,6)$

(5:) Sea
$$\phi(xy) = x^2 - y^2$$
 un campo, dibuja las líneas de nivel de campo y de gradiente.

 $\nabla \phi = (z_x, -z_y)$ (uvas de nivel: $x^2m - y^2 = C \Rightarrow |y| = 4x^2 + C$) líneas de gradiente: $\frac{dx}{\frac{\partial \phi}{\partial x}} = \frac{dy}{\frac{\partial \phi}{\partial y}} \Rightarrow \frac{dx}{2x} = \frac{dy}{-z_y} \Rightarrow |y| = \frac{K}{|x|}$



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7 roy
             A=(1,1,1) est ->(A=+)?
             $ = ( = sin 0 cosy + cos 0 cosp + sin D siny + cosp + sin D siny + cosp =
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 1=1
             9=5 = sin 0 sin 4 + cos 0 sin 4 6 + cos 4 9 ; 6 = cos 0 cosp$ + cos 0 sin 4 - sin 0 2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               O=1 rod
           ê i k = cos07-sin0ô
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               y=1rad
                                                                                                                                                                                                                                                                                                                                                                               j φ=-sinφx+cosφŷ
                 A\hat{r} + A\hat{\theta} + A\hat{\phi} = \sin\theta\cos\psi\hat{x} + \sin\theta\sin\psi\hat{y} + \cos\theta\hat{z} + \cos\theta\cos\psi\hat{x} + \cos\theta\sin\psi\hat{y} - \sin\theta\hat{z} - \sin\psi\hat{x} + \cos\psi\hat{y} =
               = (\sin\theta\cos\varphi + \cos\theta\cos\varphi - \sin\varphi)\hat{x} + (\sin\theta\sin\varphi + \cos\theta\sin\varphi + \cos\varphi)\hat{y} + (\cos\theta - \sin\theta)\hat{z} = -0.095\hat{x} + 1.7\hat{y} - 0.3\hat{z}
           B=(-1,3,2) cil. -> ¿Bant?
               P = cosyx + siny ?
                                                                                                                                                                                                                                                                                                                                            -1\hat{\rho} + 3\hat{\phi} + 2\hat{z} = -\cos\phi\hat{x} - \sin\psi\hat{y} - 3\sin\psi\hat{x} + 3\cos\psi\hat{y} + 2\hat{z} = (-\cos\phi - 3\sin\psi)\hat{x} + (\sin\psi + 3\cos\phi)\hat{y} + 2\hat{z} = (-\cos\phi - 3\sin\psi)\hat{x} + (-\cos\phi - 3\sin\psi)\hat{x} + (-\cos\phi - 3\sin\psi)\hat{y} + 2\hat{z} = (-\cos\phi - 3\sin\psi)\hat{x} + (-\cos\phi - 3\sin\psi)\hat{
               $ = - sin $ + cosys
                                                                                                                                                                                                                                                                                                                                          = 05672 -31117 +27
     \textcircled{\$} \Phi(r, q, \Theta) = r^3 \sin \Theta + \cos q \rightarrow \dot{\Phi}(q, q, e), \Phi(x, y, e)
           f = (x^2 + y^2 + z^2)^{\frac{1}{2}}
f = \int_{-\infty}^{\infty} (x^2 + y^2 + z^2)^{\frac{1}{2}} = \int_{-\infty}^{\infty} (x^2 + y^2 + z^2)^{\frac{1}{2}}
                                                                                                                                                                                                                                                                                                                                                                                 \overline{\mathcal{D}}(x,y,3) = (x^2 + y^2 + \overline{e}^2)^{\frac{3}{2}} \cdot \frac{\overline{\mathcal{E}}}{(x^2 + y^2 + \overline{e}^2)^{\frac{1}{2}}} \cdot \frac{\overline{\mathcal{E}}}{(x^2 + y^2 + \overline{e}^2)^{\frac{1}{2}}} \cdot \frac{\overline{\mathcal{E}}}{X} = \frac{X}{X} (x^2 + y^2 + \overline{e}^2)^{\frac{1}{2}} \cdot (x^2 + y^2)^{\frac{1}{2}}
                                                                                                                                                                                    (:y=psin4
                                                                                                                                                                                                                                                                                                                                                                                 tany= Y
             2=rcosθ => cosθ= = +
                                                                                                                                                                     sin\theta = cos\theta \cdot \frac{sin\theta}{cos\theta} = cos\theta tan\theta
         (1,40) = ( sin Ocos 4 , i PA, V. ( D) = DA)?
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           z = r\cos\theta \iff \cos\theta = \frac{z}{r} \iff \sin\theta = \cos\theta \tan\theta = \frac{z + \tan\theta}{r} = \frac{(x^2 + y^2)^2}{r}
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             / for 0 = f(x3+ h2)/2
) L= (x3+ h2+51)/2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           \sin \varphi = \frac{y}{(\sin \varphi)} \iff \sin \varphi = \frac{y}{(\cos \varphi \tan \varphi)} = \frac{y}{z \tan \varphi} = \frac{y}{(x^2 + y^2)^2}
                   Primero, pasamos de estéricas a cartesianas: Itany . Y
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        \cos \psi = \frac{1}{\sin \psi} \cdot \frac{\sin \psi}{\cos \psi} = \frac{1}{(x^2 y^2)^2} \cdot \frac{(x^2 y^2)^2}{2} = \frac{1}{x^2 + y^2} = \frac{y^2}{x^2 + y^2}
                                                                                                                                                                                                                                                                                                                                                                               \overline{\Phi}(x,y,z) = r^2 \frac{x^2 + y^2}{r^2} \frac{y^3 z^3}{(x^2 + y^2)^3} =
                                                                                                                                                                                                                                                                                                                                                   = \frac{y^3 z^3}{(x^2 + y^2)^2}
                                                                                                                                                                                                                                                                                                                                                                                    \nabla \overline{\phi} = \left( \frac{\partial \overline{\phi}}{\partial x}, \frac{\partial \overline{\phi}}{\partial y}, \frac{\partial \overline{\phi}}{\partial z} \right) = \left( -\frac{4 \times y^3 z^3}{(x^2 y^2)^3}, \frac{z^3 (3x^2 y^2 - y^4)}{(x^2 + y^3)^3}, \frac{y^3 z^3}{(x^2 + y^4)^3} \right) \frac{y^3 z^3}{(x^2 + y^4)^2}
                                  \Delta \overline{\Phi} = \overline{\Phi} \cdot (\nabla \overline{\Phi}) = \overline{\Phi} \cdot (-\frac{1}{14} \times y^3 e^3) + \frac{e^3 (3x^4y^3)^3}{(x^24y^3)^3}, \frac{(x^24y^3)^3}{y^2}, \frac{(x^24y^3)^3}{y^2}) = \frac{\partial \overline{\Phi}}{\partial \overline{\Phi}} (x,y) \overline{E} + \frac{\partial^2 \overline{\Phi}}{\partial y^2} (x,y) \overline{E} + \frac{\partial^2 \overline{\Phi}}{\partial z^2} (x,
                     (10) Ā = (ePcosφ, ≥sinφ, p²) ¿divergencia y rotacional (∇·Ā, ▽xĀ)?
                                 \overline{\nabla \cdot A} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho A_{\rho}) + \frac{1}{\rho} \frac{\partial A_{\rho}}{\partial \phi} + \frac{\partial A_{\rho}}{\partial z} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho e^{\rho} \cos \phi) + \frac{1}{\rho} \frac{\partial}{\partial \phi} (e^{\rho} \sin \phi) + \frac{\partial}{\partial z} (\rho e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{\cos \phi}{\rho} (e^{\rho} (\rho e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho} (\rho e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} \cos \phi = \frac{1}{\rho} e^{\rho} (e^{\rho}) + \frac{1}{\rho} e^{\rho} (e^{\rho
                               VXA- (124- 2AV) P+ (2Ar - 2Az) P+ (12 (PAV) - 1 24) =-siny P=-siny + (1 2 siny + esiny) =
                                                                                                                                                                                                                                                        \overline{\nabla} \cdot \overline{A} = \frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} = \frac{1}{(x^2 + y^2)^{3/2}} \left( e^{(x^2 + y^2)^{3/2}} \left( y^2 + x^2 (x^2 + y^2)^{3/2} \right) \right) + \frac{x^2 z}{(x^2 + y^2)^{3/2}} = \frac{1}{p^3} \left( e^{p} \left( p^2 \sin^2 \varphi + p^2 \cos^2 \varphi \right) \right) + \frac{p^2 \cos^2 \varphi}{p^3} = \frac{1}{p^2} e^{p} ((1+p) + \frac{1}{2} \cos^2 \varphi) = \frac{1}{p^2} e^{p} ((1+p) + \frac{1
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12. Dade el campo vectorial A=xyx+y=y+zxx, evaluar el flujo del vector a través de la superficie de un pavalelepípedo rectangular de bados a b.c con uno de los vértices coincidente con el origen de coordenadas y las oristas paralelas a las direcciones c positivas de los ejes rectangulares. Evaluar la integral de volumen de la divergencia del vector. Discute los resultados.

The Divergencia
$$\int_{S} \bar{A} da = \phi = \sum_{i=1}^{5} \phi_{i} = \frac{a^{2}bc}{2} + \frac{ab^{2}c}{2} + \frac{abc^{2}}{2} = \frac{1}{2}abc (a+b+c)$$

$$D_{iv}(\bar{A}) = \bar{\nabla} \cdot \bar{A} = \frac{\bar{A}\bar{x}}{\bar{x}} + \frac{\partial \bar{A}\bar{y}}{\partial z} + \frac{\partial \bar{A}\bar{z}}{\partial z} = y+\bar{z}+x$$

$$\int_{V} D_{iv}(\bar{A}) dV = \int_{V} \bar{\nabla} \cdot \bar{A} dV - \int_{0}^{a} \int_{0}^{c} (x+y+\bar{z}) d\bar{z} dy dx = \frac{1}{2}abc (a+b+c)$$

$$\oint_{2} = \int_{0}^{a} \bar{A} da = \int_{0}^{a} \bar{A} \hat{z} da = \int_{0}^{a} \bar{A} \hat{z} dxdy = \int_{0}^{b} \int_{0}^{a} x dxdy = \int_{0}^{b} \int_{0}^{a} x dxdy = \int_{0}^{b} \int_{0}^{a} x dxdy = \int_{0}^{b} \frac{a^{2}}{2} dy = \frac{\hat{a}bc}{2} dxdy = \frac{\hat{a}bc}{2} dx$$

$$\phi_{y} = \int_{0}^{\infty} \overline{A} da = \int_{0}^{\infty} \overline{A} \hat{y} dx dz = -\int_{0}^{\infty} y e dx dz = -\int_{0}^{\infty} \int_{0}^{\infty} y e dx dx dz = -\int_{0}^{\infty} \int_{0}^{\infty} y e dx dz = -\int_{0}^{\infty} \int_{0$$

$$\int_{S}^{\infty} \int_{E} \overline{A} dx = \int_{C}^{\infty} \overline{A} \hat{\epsilon} dx dy = \int_{O}^{\infty} \int_{O}^{\infty} x \hat{\epsilon} dx dy = -\hat{\epsilon} \int_{O}^{\infty} \frac{a^{2}}{2} dy = 0$$

$$\lim_{h \to \infty} \frac{1}{2} dx dy = \int_{O}^{\infty} x \hat{\epsilon} dx dy = -\hat{\epsilon} \int_{O}^{\infty} \frac{a^{2}}{2} dy = 0$$

$$\phi_{6} = \int_{F} \bar{A} da = \int_{F} \bar{A} x dy dz = -\int_{F} xy dy dz = -\int_{0}^{c} \int_{0}^{b} xy dy dz$$

$$\int_{0}^{a} \int_{0}^{b} \int_{0}^{c} (x+y+z) dz dy dx = \int_{c}^{a} \int_{0}^{b} \frac{e^{2}}{2} + (x+y) = dy dx = \int_{0}^{a} \frac{bc^{2}}{2} + xbc + \frac{b^{2}c}{2} dx = \frac{abc^{2}}{2} + \frac{a^{2}bc}{2} + \frac{abc^{2}}{2} = \frac{1}{2} abc (a+b+c)$$

The Stokes of
$$\overline{A}$$
 to \overline{b} \overline{b}

$$\frac{\partial_{1}}{\partial x} = \int_{C_{1}} \overline{A} ds_{1} = \int_{C_{2}} xy^{3} dy = \int_{C_{2}} x^{2}y dy = 0$$

$$\frac{\partial_{2}}{\partial x} = \int_{C_{2}} \overline{A} ds_{2} = \int_{C_{2}} x^{2}y dx =$$

$$\frac{\partial}{\partial s} = \int_{C_3} x^2 y dx + xy^2 dy = \int_{C_3} (x^2 y + xy^2 k \frac{1}{2\sqrt{kx}}) dx = \int_{C_3} (x^2 \sqrt{kx} + \frac{kx}{2} \sqrt{kx}) dx = \int_{C_3} (x^2 \sqrt{kx} + \frac{kx}{$$

$$\frac{2\sqrt{K} \times \frac{3}{4}}{7} \Big|_{2}^{0} + \frac{K\sqrt{K}}{2} \times \frac{5}{5} \Big|_{2}^{0} = -\left(\frac{2\sqrt{K} \times \frac{3}{4}}{7} + \frac{K\sqrt{K}}{5} \times \frac{5}{5} \right]_{0}^{2} = \frac{-16\sqrt{2K}}{7} - \frac{4K\sqrt{2K}}{5}$$

$$\nabla \times \vec{A} = \begin{vmatrix} \vec{x} & \vec{y} & \vec{z} \\ \frac{\partial}{\partial x} & \vec{x} & \vec{y} \\ Ax & Ay & Az \end{vmatrix} = \left(\frac{\partial Az}{\partial y} - \frac{\partial Ay}{\partial z} \right) \hat{X} + \left(\frac{\partial Ax}{\partial z} - \frac{\partial Az}{\partial x} \right) \hat{Y} + \left(\frac{\partial Ay}{\partial x} - \frac{\partial Ay}{\partial y} \right) \hat{z} = \alpha^{2} \alpha e^{-\beta y} (\kappa x) \hat{Y} + \left(\frac{y^{2} - x^{2}}{2} \right) \hat{Z}$$

$$\int_{S} \sqrt{x} \vec{A} d\vec{a} = -\int_{S} (y^{2} - x^{2}) dx dy = -\int_{0}^{\sqrt{2}K} \left(x^{2} - x^{2} \right) dx dy dx dy = -\int_{0}^{\sqrt{2}K} \left(x^{2} - x^{2} \right) dx dy dx dy dx dy = -\int_{0}^{\sqrt{2}K} \left(x^{2} - x^{2} \right) dx dx$$

$$\int_{S} \sqrt{x} A dx = -\int_{S} (y^{2} - x^{2}) dx dy = \int_{S} (x^{2} - y^{2}) dx dy = \int_{O}^{2} \int_{\sqrt{kx}}^{\sqrt{kx}} (x^{2} - y^{2}) dy dx = \int_{O}^{2} \left[x^{2} y - \frac{y^{3}}{3} \right]_{\sqrt{kx}}^{\sqrt{kx}} dx = \int_{O}^{2} \left(x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right) dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dy \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dx \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dx \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dx \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dx \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dx \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dx \right] dx = \int_{O}^{2} \left[x^{2} \sqrt{x^{2}} (x^{2} - y^{2}) dx dx \right] dx$$

$$= \frac{8\sqrt{2K}}{3} - \frac{16\sqrt{2K}}{7} - \frac{4}{3}\sqrt{2} k^{\frac{3}{2}} + \frac{8}{15}\sqrt{2} k^{\frac{3}{2}} = \frac{8\sqrt{2K}}{3} - \frac{16\sqrt{2K}}{7} - \frac{4\sqrt{2}}{5} k^{\frac{3}{2}} = \frac{8\sqrt{2K}}{3} - \frac{16\sqrt{2K}}{7} - \frac{4K\sqrt{2K}}{5}$$

(4-) Dado el vector $\vec{A} = 4\hat{r} + 3\hat{\theta} - 2\hat{q}$ encontrar su integral de línea sobre la trayectoria cerrada de la figura. El tramo curvo es un arco de circunterencia de radio 10 centrada en el origen. Encontrar también la integral de superficie del rotocional del vector sobre el área encerrada dentro de la trayectoria. Discutir los resultados. Sol. 8 = -1017

The Stokes of
$$\overline{A}ds = \int_{S} \overline{\nabla} \times \overline{A}ds$$

$$= \int_{S}$$

$$\lambda_1 = \int_{c}^{R} dr \hat{r} = \int_{0}^{6} 4 dr = 4v_0 \qquad \lambda_2 = \int_{c}^{R} (\sin \theta) d\theta = -\int_{0}^{R} 2v \sin \theta d\theta = -v_0 \Pi \qquad \lambda_3 = \int_{c}^{R} A dr \hat{r} = \int_{v_0}^{v_0} 4 dr = -4v_0$$

$$\theta de, \text{ Cote. } \Rightarrow ds = dr \hat{r} \qquad \theta de, \text{ rote. } \Rightarrow ds = r \sin \theta d\theta \qquad \theta \text{ ote. } \text{ Gote. } \Rightarrow ds = \hat{r} dr$$

$$\left(\overline{\nabla} \times \widehat{A}\right)_{\theta} = \frac{1}{r} \left(\frac{1}{\sin \theta} \frac{\partial Ar}{\partial \varphi} - \frac{\partial}{\partial r} (rA\varphi)\right) \widehat{\delta} = \frac{1}{r} \left(\frac{1}{\sin \theta} O - (t2) + r \cdot O\right) \widehat{\delta} = \frac{2}{r} \widehat{\delta}.$$

$$\int \overline{\nabla} x \overline{A} dx = -\int 2\sin\theta dr d\phi = -\int 2dr d\phi = -\int \int \frac{\Pi/L}{2} d\phi dr = -\int \frac{10}{2} \Pi dr =$$