

Unmanned Aerial Vehicle Imaging System Creation For Water Quality Analysis



Victoria Scholl

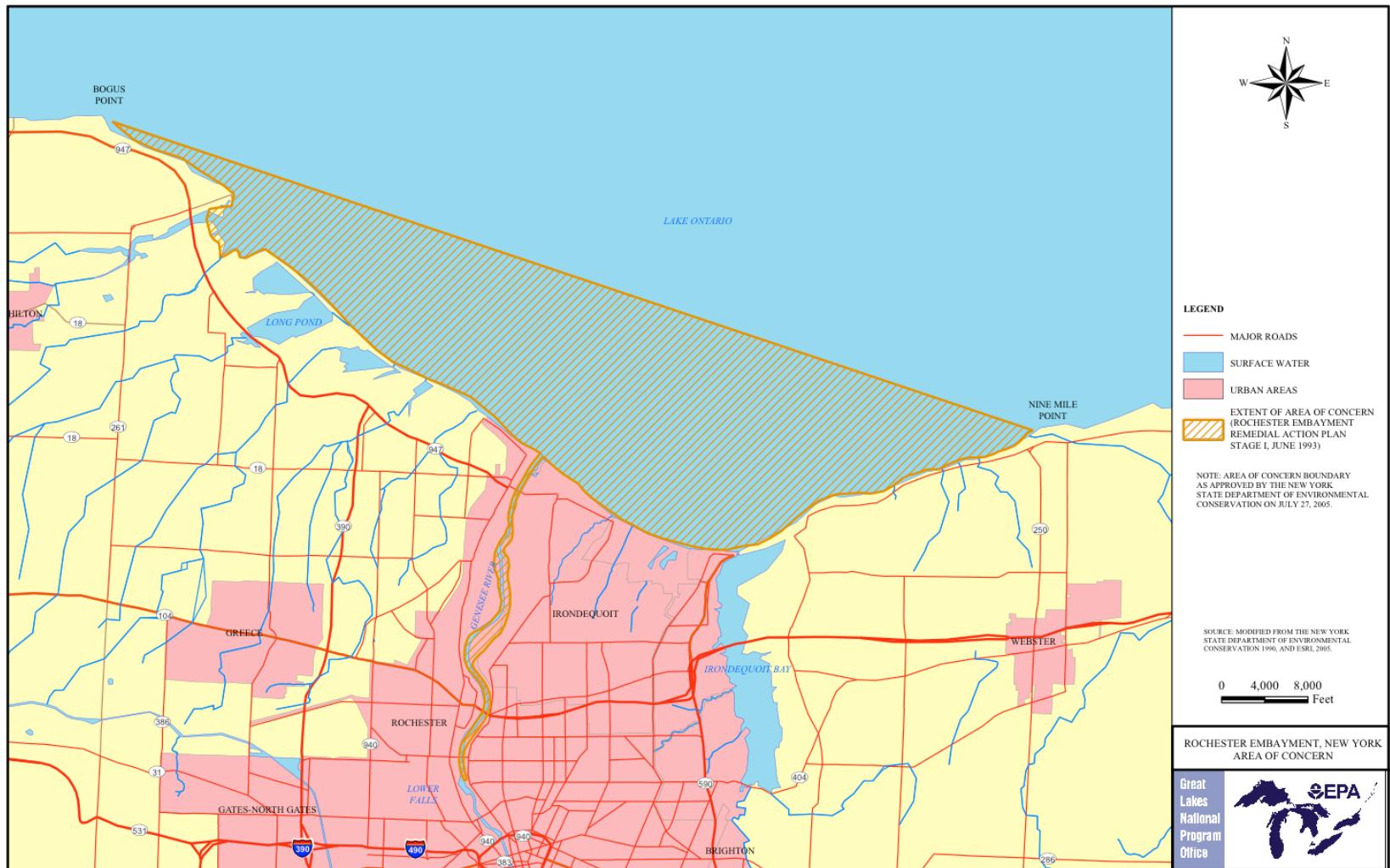
Advisor: Aaron Gerace

Committee: David Long, Carl Salvaggio

Outline

1. The Purpose
2. The Dream
3. The Team
4. The Progress
5. The Future

The Purpose



The Purpose

- NASA Jet Propulsion Lab Airborne Visible InfraRed Imaging Spectrometer
 - + spectral resolution (224 bands, 400-2500nm)
 - temporal resolution (once in 1999)

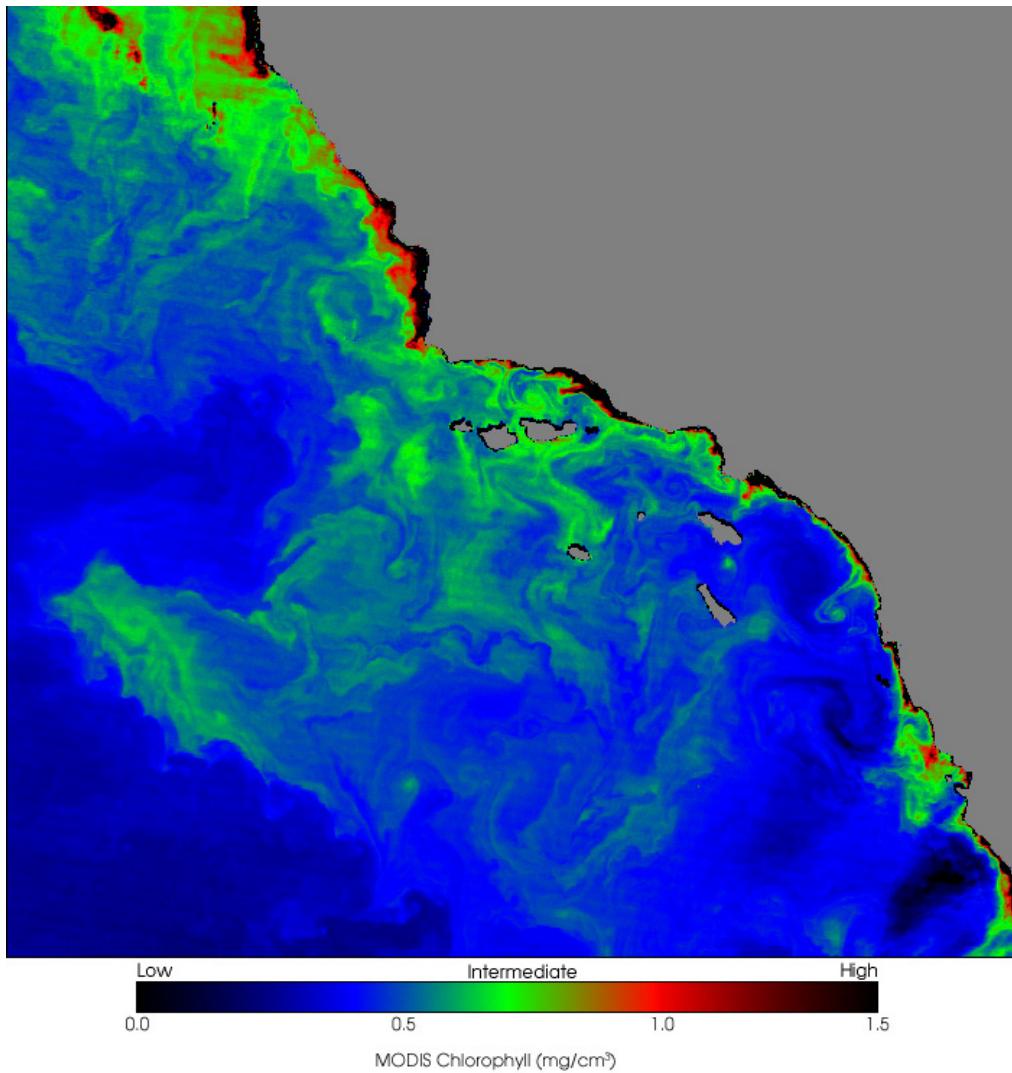
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- NASA Landsat 8 satellite
 - + temporal resolution (every 16 days)
 - spectral/spatial resolution (30m pixels)
 - limited by presence of atmosphere & clouds

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 - spectral/spatial resolution (30m pixels)
 - limited by presence of atmosphere & clouds
- Multispectral UAV Imaging System
 - + temporal resolution (whenever we want)
 - spectral (any filters we want) /spatial resolution (1 inch pixels)
 - + minimal atmosphere at low altitudes

The Dream



- Fully functioning system and capture workflow
- Develop calibration protocol
- Image transfer, conversion, stitching
- Near real-time, in-water constituent mapping

The Team

- Students
 - Liz Bondi (Land) & myself (Water)



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- Research Experience
 - Aaron Gerace, CIS
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- Drone ownership & operation
 - Zeke Hurd and Mickey
 - PJ (Papa Jeff Ring)



The Team



Jeffrey Ring

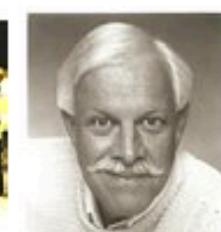
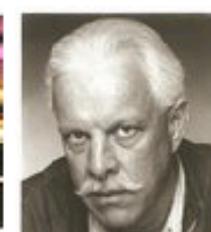
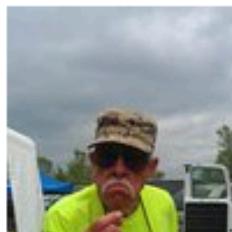


Actor | Camera Department | Transportation Department

[View Resume](#) | [Official Photos »](#)

Jeffrey Ring was born as Jeffrey Alan Ring. He is known for his work on [3.14...](#) (2014), [Troop Beverly Hills](#) (1989) and [Hide in Plain Sight](#) (1980). He has been married to Judith Ring since December 18, 1965. [See full bio »](#)

Born: [Jeffrey Alan Ring](#)



The Progress

Over the summer:

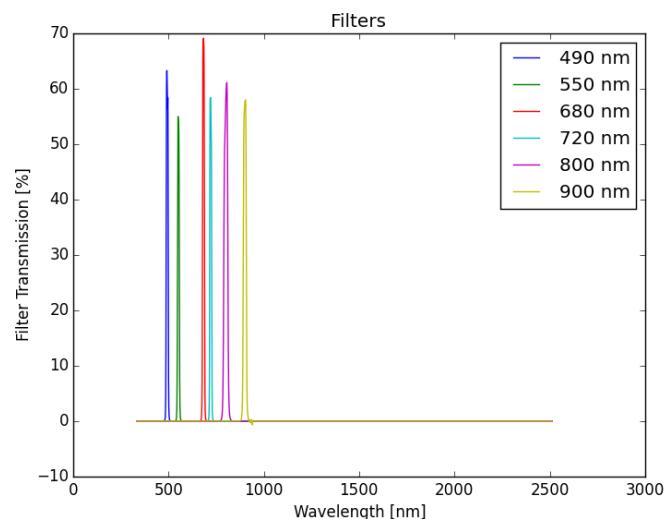
- Wrote funding proposal. CIS MicroGrant awarded (\$5000)
- Band selection analysis started over the summer
- Camera acquired, complications with initial testing



The Progress

Tetracam Micro Multi-Camera Array Snap (\$20,000)

- 6 compact, synchronized digital cameras
- 16GB memory card per camera
- 1.3 megapixel CMOS sensors (1280x1024), 10-bit DC
- Each bandpass filter (\$1,300)
- 1 master (set exposure time and geo-referencing), 5 slaves (set relative to master)
- PixelWrench2 software for image transfer and processing requires Windows 8
- Focal Length: 9.6mm
- Global shutter



The Progress

Documenting how to use the Tetracam:

- Gain, exposure time, format, capture mode

The Tetracam Checklist

I. Turn on and Capture

1. Connect camera to monitor
2. Plug in power cord to monitor
3. Plug in power cord to camera
4. Watch monitor screen. In diagnostic mode, should see all READY and OK statuses.
Status light should turn green. Live Preview should start, with date/time/gps/image info displayed along the lower portion of the screen
5. Set capture settings
 - a. Press ↲ to enter Menu
 - b. Use ↑ ↓ to toggle through selections, press ↲ to select, press [camera] to return to live preview
6. Press [camera] button to start capture
7. To turn off, unplug power cord to camera (from wall/outlet)

II. Transferring Images to Computer

1. Turn on camera and monitor (Section I, Steps 1-4)
2. Plug in small end of USB cord to camera body. Plug in other end of USB to port on PC.
6 new devices/drives should appear on computer (each of the SD cards)
3. Open PixelWrench2 software
 - a. If this is the first time you're using the software after installing it on a PC,
 - i. Navigate to the program folder
(C:/ProgramFiles/Tratracam/PixelWrench2/)
 - ii. Right click on the 3 .exe files → Properties → Compatibility → Check the "Run this program as administrator" box.



The Progress

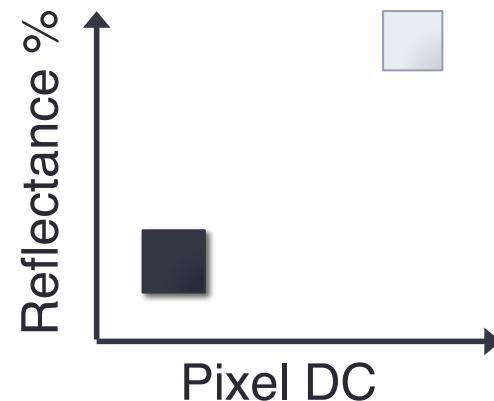
Calibration

- To use the imagery for scientific purposes, we have to equate digital count to a quantity of interest: reflectance

The Progress

Calibration

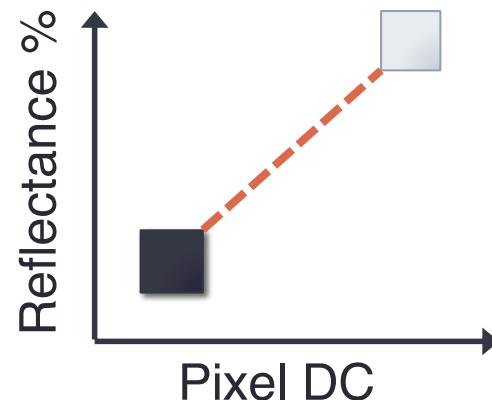
- To use the imagery for scientific purposes, we have to equate digital count to a quantity of interest: reflectance
- ELM (Empirical Line Method)
- Interpolate between dark and light targets of **known reflectance**



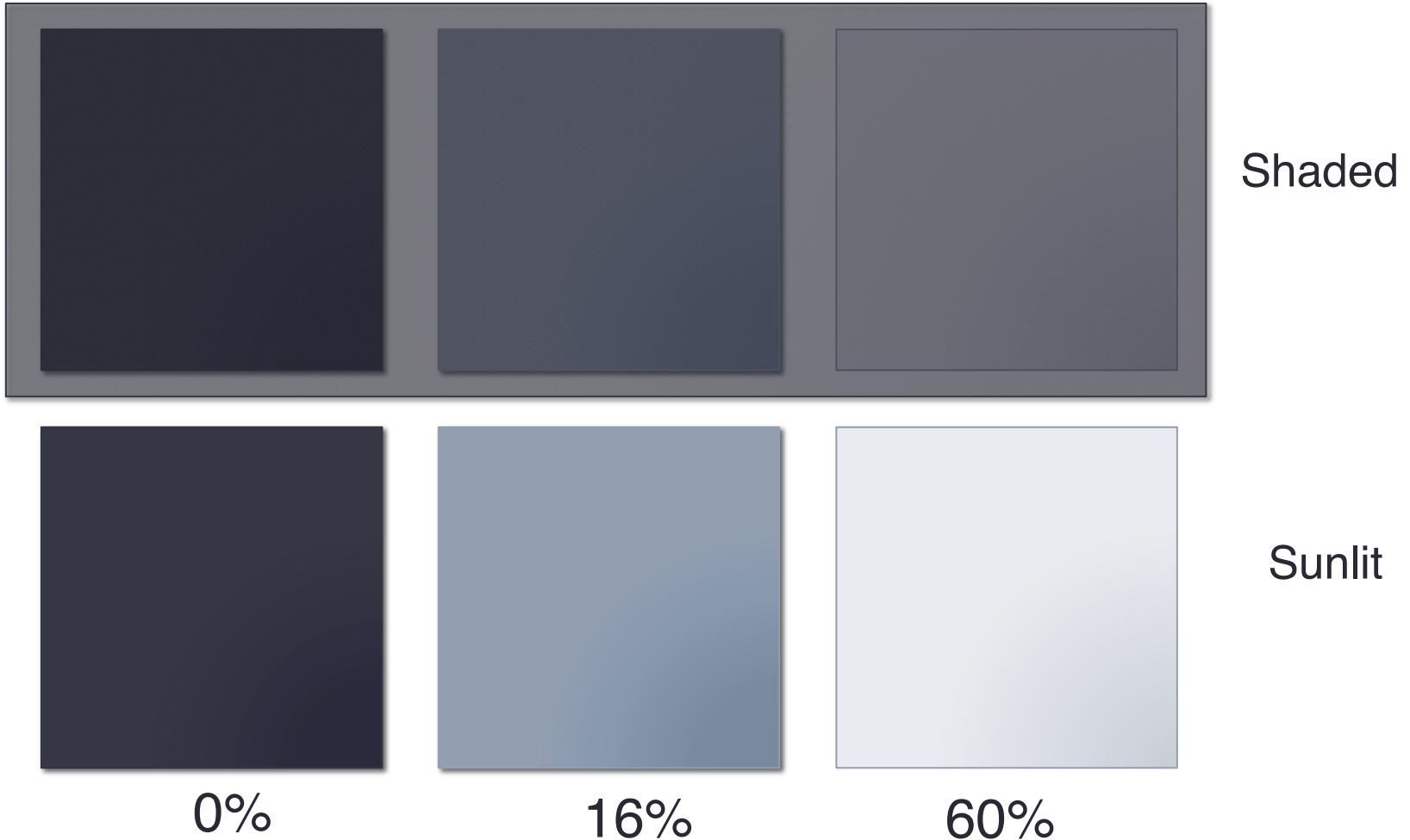
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The Progress



The Progress

Calibration Target Paint Reflectance

- Light, Land: 60%
- Light, Water: 16%
- Dark: 0%



The Progress

Calibration Target Paint Reflectance

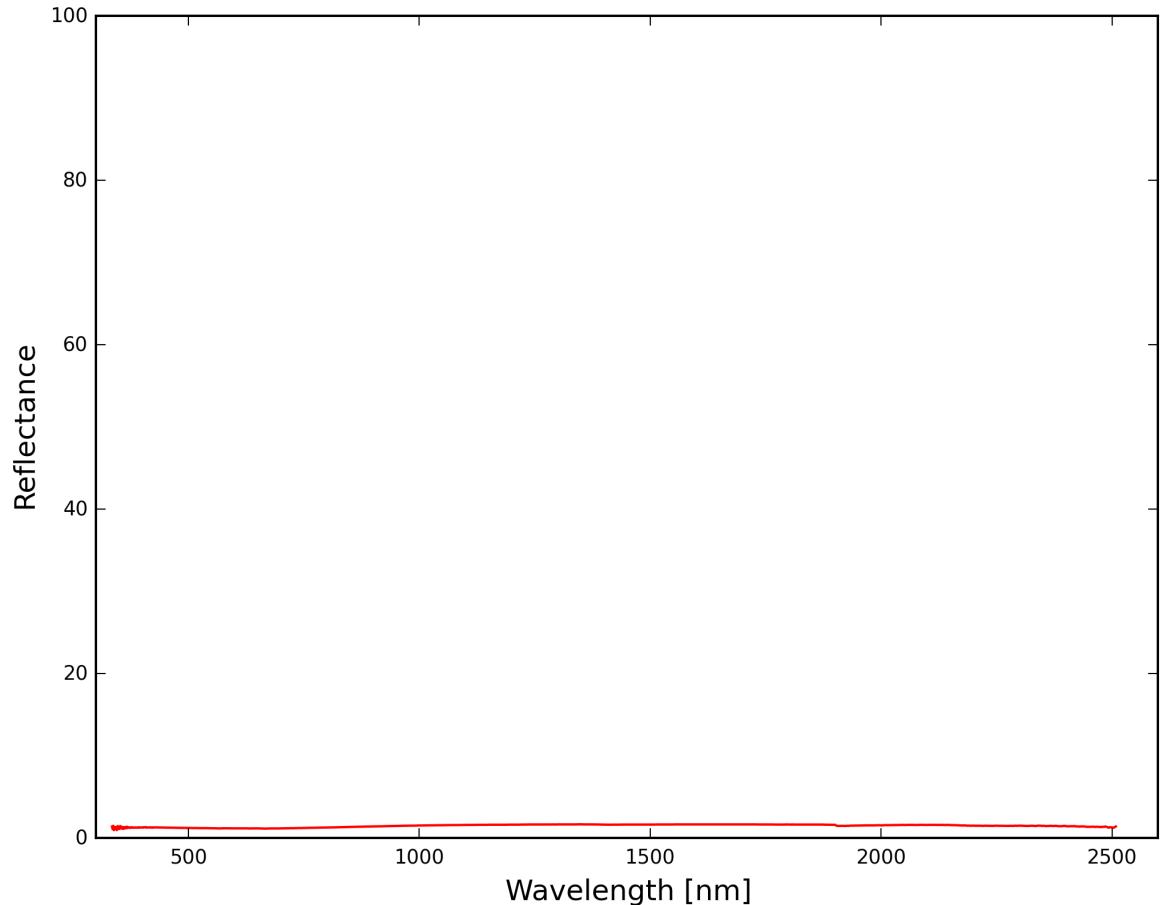
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The Progress

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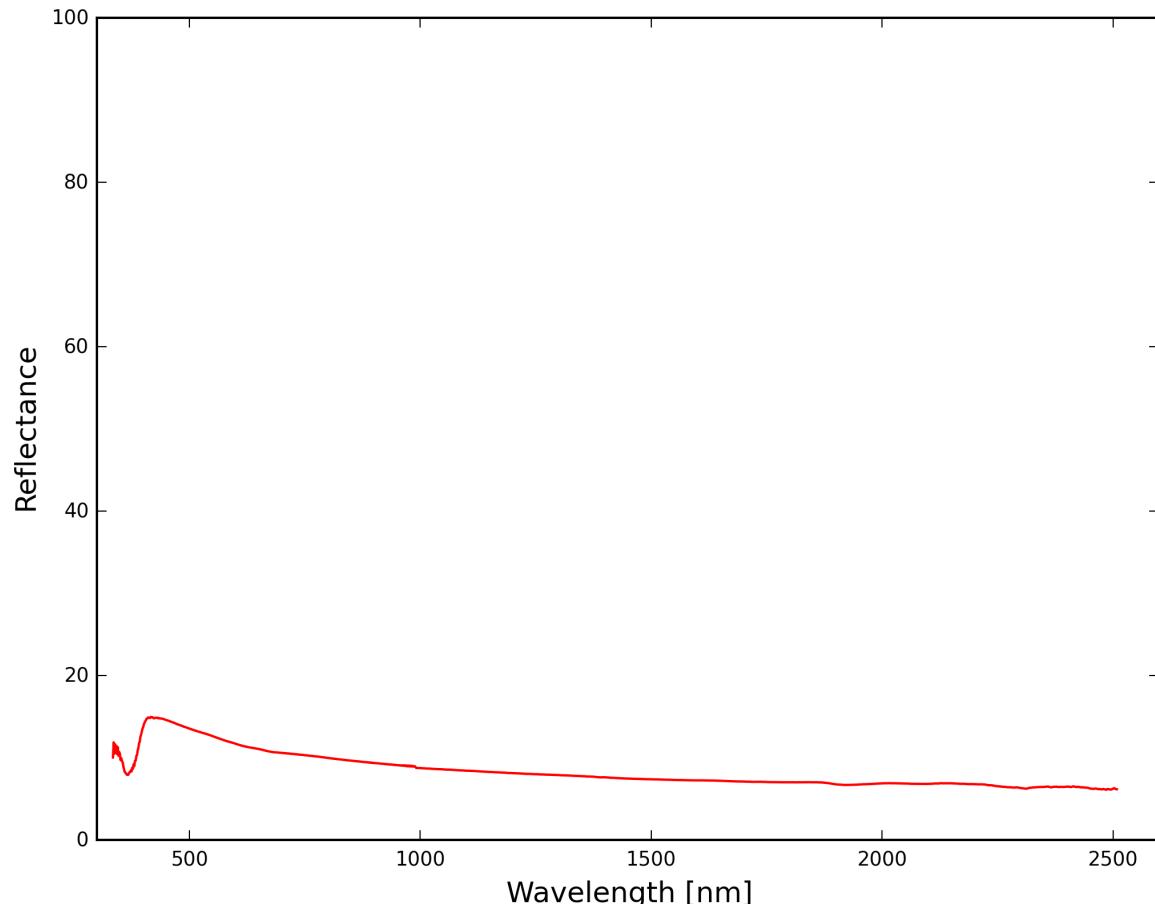
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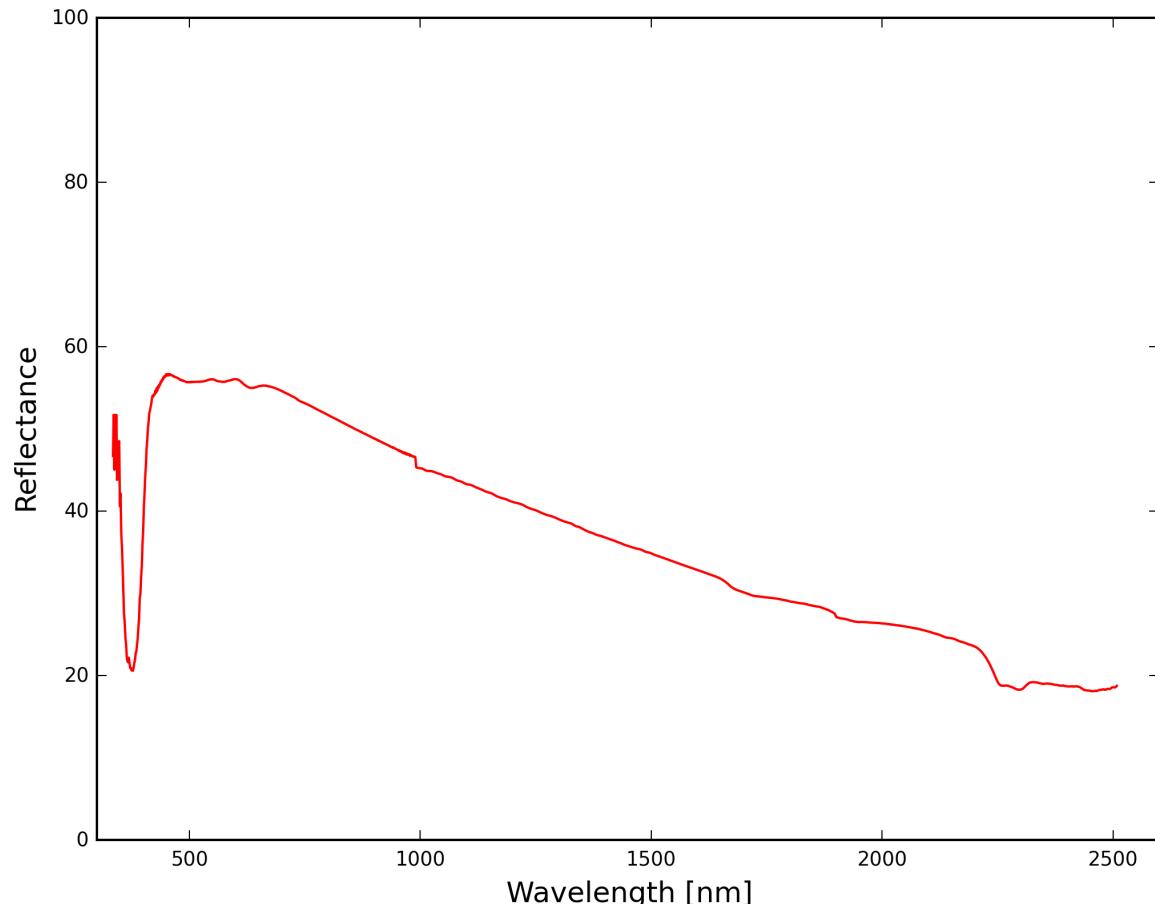
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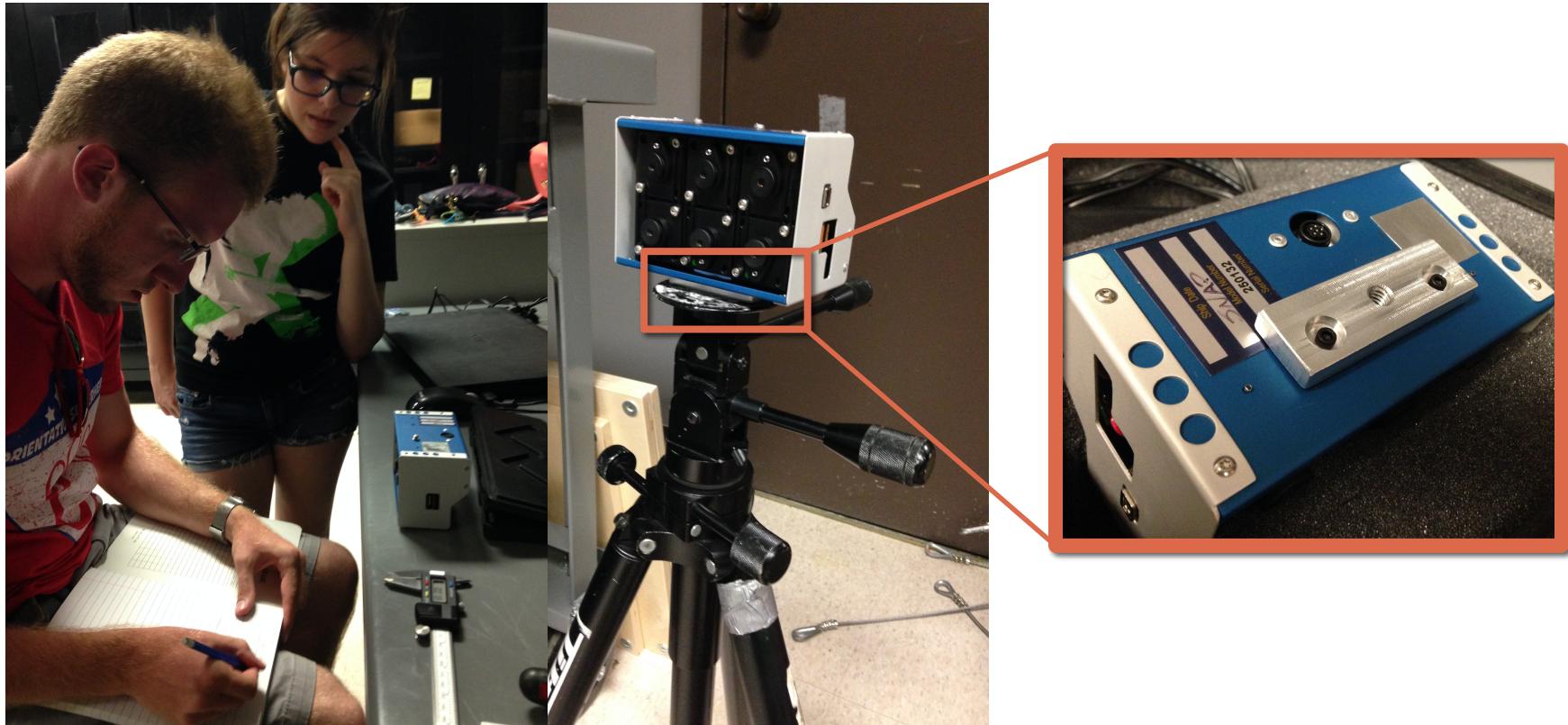
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The Progress

Hardware prep

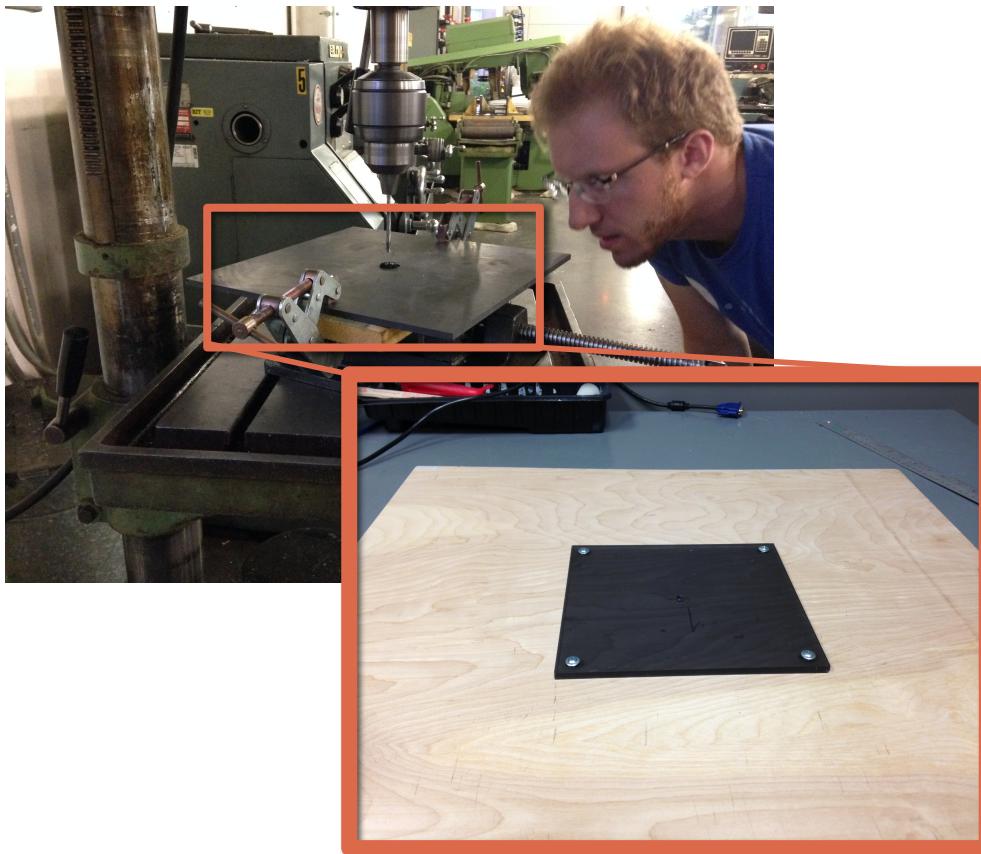
- Tetracam tripod mount



The Progress

Hardware prep

- 6 wooden calibration targets, painted, with tripod mounts
- Exposure target



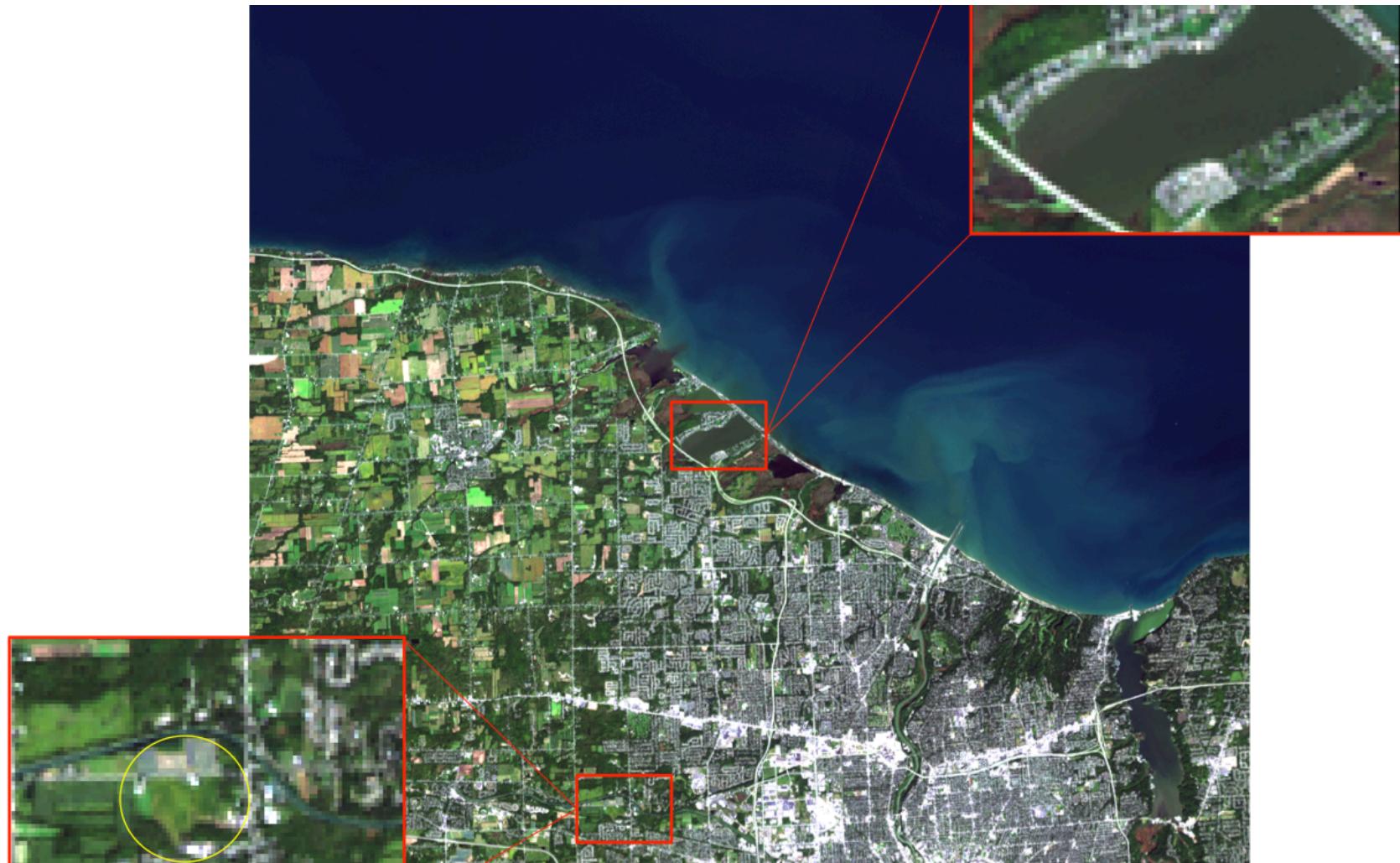
The Progress

- Protocol for setting exposure
 - Need to manually set exposure time (microseconds)
 - Auto-exposure means imagery is not scientifically meaningful



The Progress

Test Sites





The Progress

Spreading Wings S900 drone

- Max flight time: 22 minutes



The Progress

Test Flight and Initial Aerial Capture



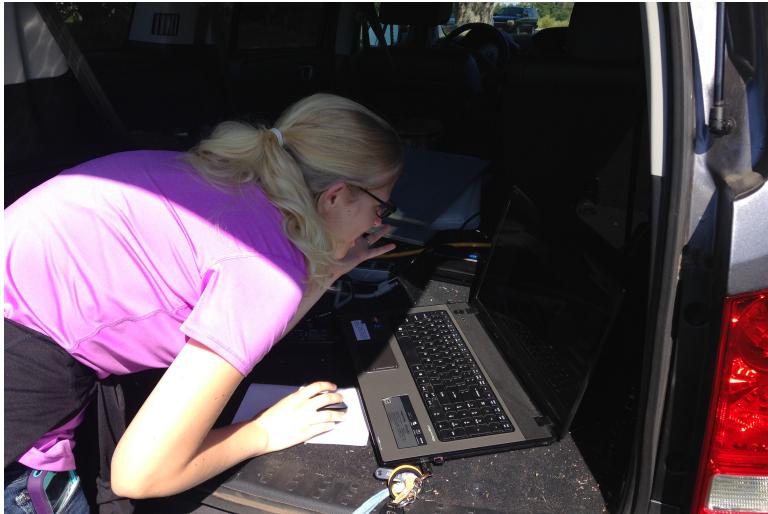
The Progress

Setting up Calibration Targets



The Progress

Setting Exposure



The Progress

Flight over Maier's Farm Soybean Field



EMERGENCY
STOPPING
ONLY



The Progress

Imaging Long Pond



The Progress

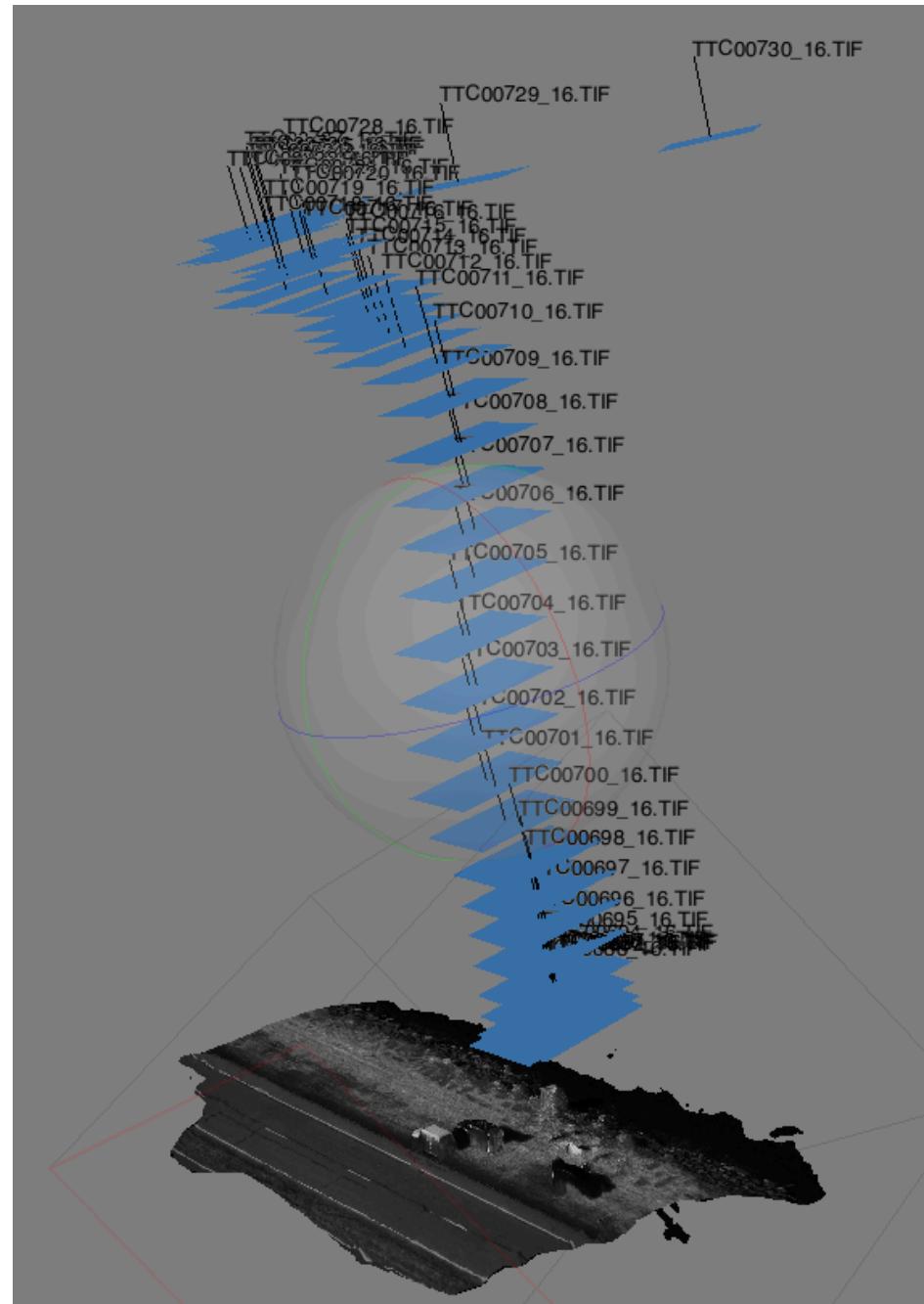
Same-day Landsat collection, water samples taken



The Progress

- Challenges in the field
 - Windows Updates
 - Efficient exposure method determined for vegetation
 - Inefficient exposure method determined for water
 - Manual flight renders imagery useless
 - No GPS information

The Progress



The Future

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 - Test runs
- Water quality analysis
 - Mosaic over water
 - Multispectral analysis

The Future

Anticipated to be involved in the following:

- ~~Writing grant proposal for funding~~
- **Modeling to determine spectral bands most pertinent to water quality analysis**
- ~~Acquisition and integration of hardware components~~
- ~~Learning to operate UAS & program flight collection paths~~
- ~~Ground truth data collection~~
- **ELM Calibration to account for atmospheric effects**
- ~~Collaboration with other academic institutions for measurements~~
- **Stitching together collected imagery**
- **Programming algorithms to extract water quality information from imagery**
- **Producing RGB and in-water constituent map for scene**

KEY

~~Completed~~

In progress

Not yet attempted

~~Likely not going to be involved~~

Questions / Comments?

