### Intermediate Code Generation - Part 4

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NPTEL Course on Principles of Compiler Design

#### Outline of the Lecture

- Introduction (covered in part 1)
- Different types of intermediate code (covered in part 1)
- Intermediate code generation for various constructs

#### break and continue Statements

- break statements can occur only within while, for, do-while and switch statements
- continue statements can occur only within while, for, and do-while statements (i.e., only loops)
- All other occurrences are flagged as errors by the compiler
- Examples (incorrect programs)

```
main() {
    int a=5;
    if (a<5) {break; printf("hello-1");};
    printf("hello-2");}
}</pre>
```

 Replacing break with continue in the above program is also erroneous



### break and continue Statements (correct programs)

The program below prints 6

```
main(){int a,b=10; for(a=1;a<5;a++) b--;
    printf("%d",b);}</pre>
```

The program below prints 8

```
main(){int a,b=10; for(a=1;a<5;a++)
      { if (a==3) break; b--;} printf("%d",b);}</pre>
```

The program below prints 7

```
main(){int a,b=10; for(a=1;a<5;a++)
      { if (a==3) continue; b--;} printf("%d",b);}</pre>
```

This program also prints 8

### Handling break and continue Statements

- We need extra attributes for the non-terminal STMT
  - STMT.break and STMT.continue, along with STMT.next(existing one), all of which are lists of quadruples with unfilled branch targets
- STMT → break

```
{ STMT.break := makelist(nextquad); gen('goto __'); 
 STMT.next := makelist(NULL); 
 STMT.continue := makelist(NULL); }
```

STMT → continue

```
{ STMT.continue := makelist(nextquad); gen('goto __'); 
 STMT.next := makelist(NULL); 
 STMT.break := makelist(NULL); }
```

### SATG for While-do Statement with break and continue

```
WHILEXEP → while M E
  { WHILEEXP.falselist := makelist(nextquad);
   gen('if E.result < 0 goto '):
   WHILEEXP.begin := M.quad; }

    STMT → WHILEXEP do STMT<sub>1</sub>

  { gen('goto WHILEEXP.begin');
    backpatch(STMT<sub>1</sub>.next, WHILEEXP.begin);
    backpatch(STMT<sub>1</sub>.continue, WHILEEXP.begin);
    STMT.continue := makelist(NULL);
    STMT.break := makelist(NULL);
   STMT.next := merge(WHILEEXP.falselist, STMT<sub>1</sub>.break); }
\bullet M \rightarrow \epsilon
  { M.quad := nextquad; }
```

### Code Generation Template for *C For-Loop* with *break* and *continue*

```
for (E_1; E_2; E_3) S
         code for E<sub>1</sub>
L1:
         code for E_2 (result in T)
         goto L4
L2:
         code for E_3
         aoto L1
L3:
         code for S /* all breaks out of S goto L5 */
/* all continues and other jumps out of S goto L2 */
         goto L2
L4:
         if T == 0 goto L5 /* if T is zero, jump to exit */
         goto L3
         /* exit */
15:
```

### Code Generation for C For-Loop with *break* and *continue*

```
• STMT \rightarrow for ( E_1; M E_2; N E_3 ) P STMT_1
  { gen('goto N.quad+1'); Q1 := nextquad;
   gen(if E_2.result == 0 goto i); gen(igoto P.quad+1i);
   backpatch(makelist(N.quad), Q1);
   backpatch(makelist(P.guad), M.guad);
    backpatch(STMT_1.continue, N.quad+1);
   backpatch(STMT_1.next, N.quad+1);
   STMT.next := merge(STMT_1.break, makelist(Q1));
    STMT.break := makelist(NULL);
    STMT.continue := makelist(NULL); }
• M \rightarrow \epsilon { M.quad := nextguad; }
• N \rightarrow \epsilon { N.quad := nextguad; gen('goto'); }
• P \rightarrow \epsilon { P.quad := nextguad; gen('goto'); }
```

#### LATG for *If-Then-Else* Statement

Assumption: No short-circuit evaluation for E

```
If (E) S1 else S2
      code for E (result in T)
      if T<0 goto L1/* if T is false, jump to else part */
      code for S1 /* all exits from within S1 also jump to L2 */
      aoto L2 /* jump to exit */
L1: code for S2 /* all exits from within S2 also jump to L2 */
L2: /* exit */
S \rightarrow if E \{ N := nextquad; gen('if E.result <= 0 goto __'); \}
     S_1 else { M := nextguad; gen('goto');
               backpatch(N, nextquad); }
     S_2 { S.next := merge(makelist(M), S_1.next, S_2.next); }
```

#### LATG for While-do Statement

Assumption: No short-circuit evaluation for E

```
while (E) do S
L1:
         code for E (result in T)
         if T < 0 goto L2 /* if T is false, jump to exit */
         code for S /* all exits from within S also jump to L1 */
         goto L1 /* loop back */
L2:
         /* exit */
S \rightarrow while \{ M := nextquad; \}
     E { N := nextquad; gen('if E.result <= 0 goto '); }
     do S_1 { backpatch(S_1.next, M); gen('goto M');
              S.next := makelist(N); }
```

### LATG for Other Statements

```
• S \rightarrow A { S.next := makelist(NULL); }

• S \rightarrow \{SL\} { S.next := SL.next; }

• SL \rightarrow \epsilon { SL.next := makelist(NULL); }

• SL \rightarrow S; { backpatch(S.next, nextquad); }

• SL \rightarrow S; { SL.next := SL_1.next; }
```

- When a function ends, we perform { gen('func end'); }. No backpatching of SL.next is required now, since this list will be empty, due to the use of  $SL \rightarrow \epsilon$  as the last production.
- LATG for function declaration and call, and return statement are left as exercises



### LATG for Expressions

```
\bullet A \rightarrow I = F
  { if (L.offset == NULL) /* simple id */
     gen('L.place = E.result');
    else gen('L.place[L.offset] = E.result'); }
E' { E.result := E'.result; }
• E' \rightarrow + T { temp := newtemp(T.type);
               gen('temp = E'.left + T.result'); E'_1.left := temp; \}
         E'_1 { E'.result := E'_1.result; }
```

Note: Checking for compatible types, etc., are all required here as well. These are left as exercises.

- $E' \rightarrow \epsilon$  { E'.result := E'.left; }
- Processing T → F T', T' → \*F T' | ε, F → (E), boolean and relational expressions are all similar to the above productions

### LATG for Expressions(contd.)

```
• F \rightarrow L { if (L.offset == NULL) F.result := L.place;
           else { F.result := newtemp(L.type);
                  gen('F.result = L.place[L.offset]'); }

 F → num { F.result := newtemp(num.type);

               gen('F.result = num.value'); }

    L → id { search(id.name, vn); INDEX.arrayptr := vn; }

       INDEX { L.place := vn; L.offset := INDEX.offset; }
• INDEX \rightarrow \epsilon { INDEX.offset := NULL; }

    INDEX → [ { ELIST.dim := 1;

                  ELIST.arrayptr := INDEX.arrayptr; }
               ELIST ]
               { temp := newtemp(int); INDEX.offset := temp;
                ele size := INDEX.arrayptr -> ele size;
                gen('temp = ELIST.result * ele size'); }
```

### LATG for Expressions(contd.)

```
• ELIST \rightarrow E { INDEXLIST.dim := ELIST.dim+1;
                 INDEXLIST.arrayptr := ELIST.arrayptr;
                 INDEXLIST.left := E.result: }
            INDEXLIST { ELIST.result := INDEXLIST.result; }
• INDEXLIST \rightarrow \epsilon { INDEXLIST.result := INDEXLIST.left; }
• INDEXLIST \rightarrow, { action 1 }
                  ELIST { gen('temp = temp + ELIST.result');
                           INDEXLIST.result := temp; }
  action 1:
  { temp := newtemp(int);
   num elem := rem num elem(INDEXLIST.arrayptr,
                                  INDEXLIST.dim):
   gen('temp = INDEXLIST.left * num_elem');
   ELIST.arrayptr := INDEXLIST.arrayptr;
   ELIST.dim := INDEXLIST.dim: }
```

### LATG for Expressions(contd.)

• The function rem\_num\_elem(arrayptr, dim) computes the product of the dimensions of the array, starting from dimension dim. For example, consider the expression, a [i, j, k, 1], and its declaration int a [10, 20, 30, 40]. The expression translates to i\*20\*30\*40+j\*30\*40+k\*40+l. The above function returns, 24000(dim=2), 1200(dim=3), and 40(dim=3).

# Run-time Environments - 1

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### Outline of the Lecture

- What is run-time support?
- Parameter passing methods
- Storage allocation
- Activation records
- Static scope and dynamic scope
- Passing functions as parameters
- Heap memory management
- Garbage Collection

# What is Run-time Support?

- It is not enough if we generate machine code from intermediate code
- Interfaces between the program and computer system resources are needed
  - There is a need to manage memory when a program is running
    - This memory management must connect to the data objects of programs
    - Programs request for memory blocks and release memory blocks
    - Passing parameters to fucntions needs attention
  - Other resources such as printers, file systems, etc., also need to be accessed
- These are the main tasks of run-time support
- In this lecture, we focus on memory management

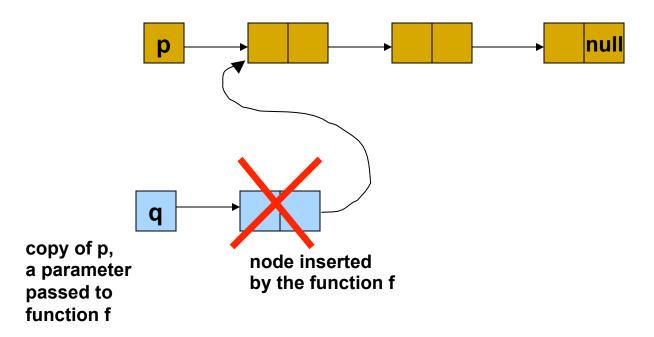


# Parameter Passing Methods

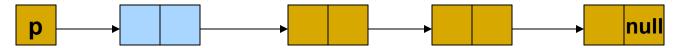
- Call-by-value
- At runtime, prior to the call, the parameter is evaluated, and its actual value is put in a location private to the called procedure
  - Thus, there is no way to change the actual parameters.
  - Found in C and C++
  - C has only call-by-value method available
    - Passing pointers does not constitute call-by-reference
    - Pointers are also copied to another location
    - Hence in C, there is no way to write a function to insert a node at the front of a linked list (just after the header) without using pointers to pointers



# Problem with Call-by-Value



### node insertion as desired





## Parameter Passing Methods

- Call-by-Reference
- At runtime, prior to the call, the parameter is evaluated and put in a temporary location, if it is not a variable
- The address of the variable (or the temporary) is passed to the called procedure
- Thus, the actual parameter may get changed due to changes to the parameter in the called procedure
  - Found in C++ and Java

# Call-by-Value-Result

- Call-by-value-result is a hybrid of Call-by-value and Call-byreference
- Actual parameter is calculated by the calling procedure and is copied to a local location of the called procedure
- Actual parameter's value is not affected during execution of the called procedure
- At return, the value of the formal parameter is copied to the actual parameter, if the actual parameter is a variable
- Becomes different from call-by-reference method
  - when global variables are passed as parameters to the called procedure and
  - the same global variables are also updated in another procedure invoked by the called procedure

Found in Ada



# Difference between Call-by-Value, Call-by-Reference, and Call-by-Value-Result

```
int a;
void Q()
   \{ a = a+1; \}
void R(int x);
   \{ x = x+10; Q(); \}
main()
   \{ a = 1; R(a); print(a); \}
```

call-by-	•	call-by-
value	reference	value-result
2	12	11

### Value of a printed

Note: In Call-by-V-R, value of x is copied into a, when proc R returns. Hence a=11.



## Parameter Passing Methods

- Call-by-Name
- Use of a call-by-name parameter implies a textual substitution of the formal parameter name by the actual parameter
- For example, if the procedure

```
void R (int X, int I); \{I = 2; X = 5; I = 3; X = 1; \} is called by R(B[J*2], J) this would result in (effectively) changing the body to \{J = 2; B[J*2] = 5; J = 3; B[J*2] = 1; \} just before executing it
```



# Parameter Passing Methods

- Call by Name
- Note that the actual parameter corresponding to X changes whenever J changes
  - Hence, we cannot evaluate the address of the actual parameter just once and use it
  - It must be recomputed every time we reference the formal parameter within the procedure
- A separate routine (called thunk) is used to evaluate the parameters whenever they are used
- Found in Algol and functional languages



# Example of Using the Four Parameter Passing Methods

```
1. void swap (int x, int y)
2. { int temp;
3. temp = x;
4. x = y;
5. y = temp;
6. } /*swap*/
8. \{i = 1;
9. a[i] =10; /* int a[5]; */
10. print(i,a[i]);
11. swap(i,a[i]);
12. print(i,a[1]); }
```

 Results from the 4 parameter passing methods (print statements)

call-by-		call-by-		call-by-		call-by-	
val	ue	reference val-result		name			
1	10	1	10	1	10	1	10
1	10	10	1	10	1	error!	

Reason for the error in the Call-by-name Example
The problem is in the swap routine

```
temp = i; /* => temp = 1 */
i = a[i]; /* => i =10 since a[i] ==10 */
a[i] = temp; /* => a[10] = 1 => index out of bounds */
```

