

02 - Ch2 Intro, 2.1, 2.2

Vinicius Prado da Fonseca, Ph.D.
vpradodafons@mun.ca

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Outline

Ch 2 Intro

A robot is mechanically constructed by connecting **rigid bodies**, called **links**, together by means of **joints**, so that relative motion between adjacent links becomes possible. **Actuation** of the joints, typically by electric motors, then causes the robot to move and exert forces in desired ways.

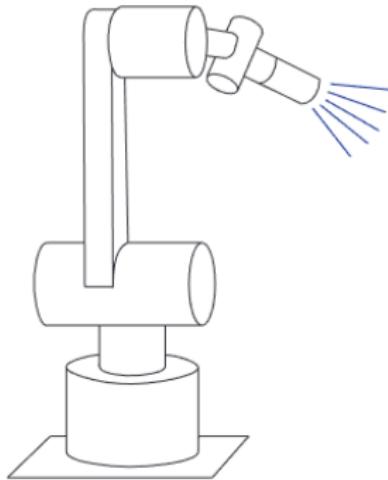


Figure 2.14: A spray-painting robot.

Questions?

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