Hyperspectral Image Compression & Decompression On FPGAs

Team HEALTH (Hyperspectral Earth Acquisition of Longwave Thermal Heat)

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Overview of Topic

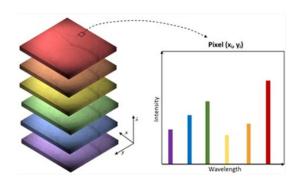
- What is it
 - 3D hyperspectral image compression and decompression pipeline
 - FPGAs accelerate image compression/decompression
- Why is it important
 - Images may require many KB/MB of space
 - o Project aiming for use in a small satellite payload
 - Real-time constraints
 - Size/memory constraints



How are hyperspectral images different from normal images?

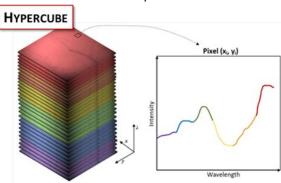
MULTISPECTRAL IMAGING

N separated bands



HYPERSPECTRAL IMAGING

Continuous spectrum

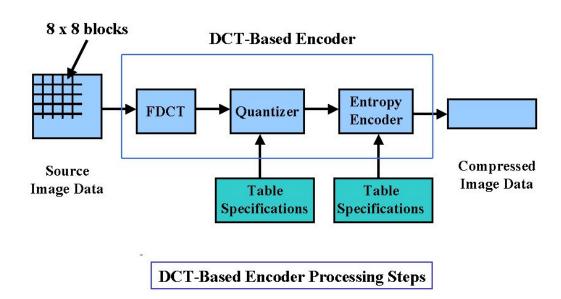


ENABLES SPECTRAL ANALYSIS

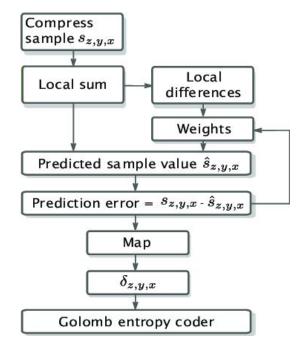
- Segmentation
- Spectral unmixing
- Evolution of spectra in time

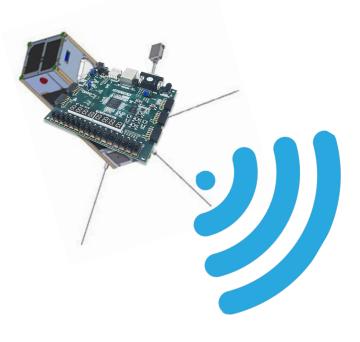
Compression Algorithms

DCT

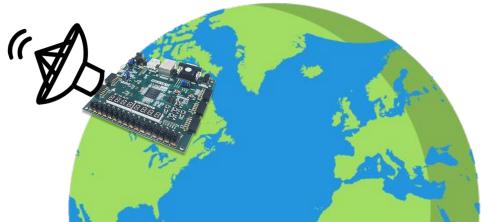


CCSDS-123

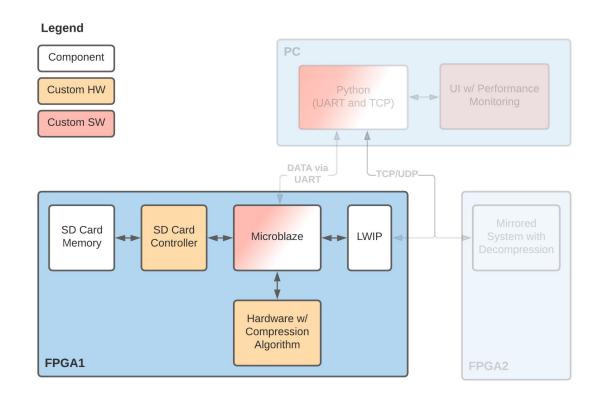




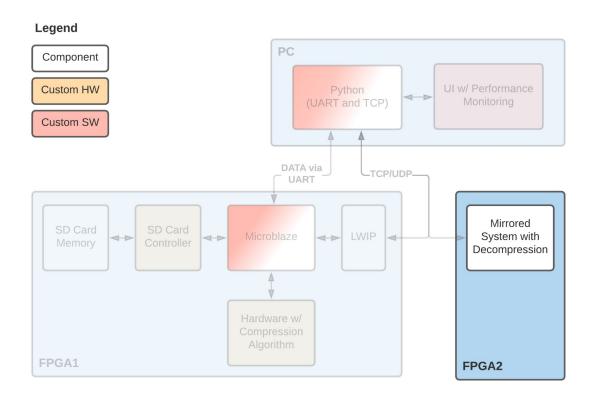
Why Multi-FPGA?



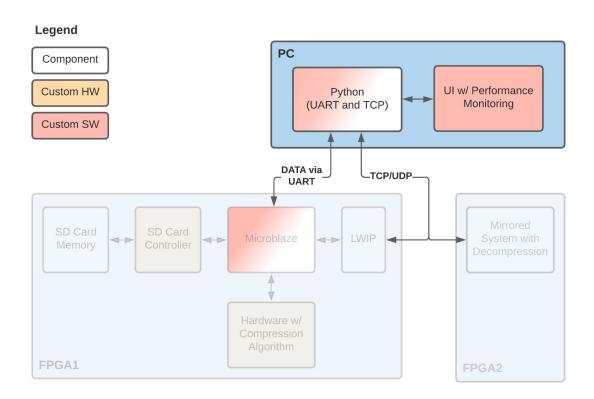
- Core of the system is an FPGA compression/decompression block using DCT (baseline) or CCSDS-123.0-B-2 (exceed)
- SD card contains images from compression/decompression
- Microblaze processor runs the whole show and manages connectivity. Some custom and some existing code.



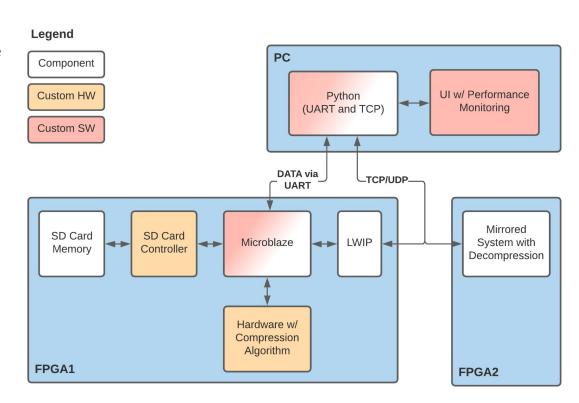
- Decompression stage is a mirror of the first, although with the complementary algorithm
- Both FPGAs are collecting hardware performance monitoring data including throughput and compression ratio.



- Host PC controls both FPGAs at a high level via TCP/UDP
- Host PC also sends/receives images from each FPGA
- Performance monitoring data is transferred from FPGAs and visualized in UI



- Entire system simulates a remote sensing satellite mission with RF link bandwidth constraints and large data cubes
- FPGA-FPGA TCP/UDP communications stands in for the RF link
- Host PC mimics a TT&C link which would also be present in a real system
- PC collects and visualizes performance data to help development



Implementation Plan

Brytni: SD card implementation & data handling, 25% of performance visualization

Dylan: Image compression/decompression blocks, 75% of performance visualization

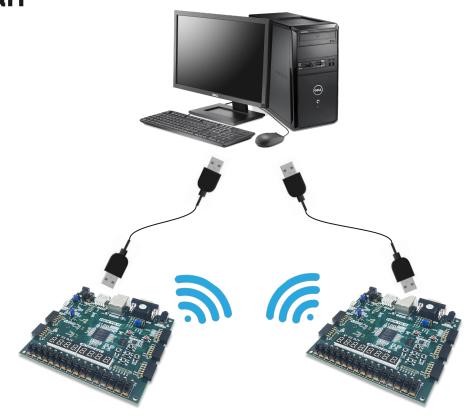
Lorna: Network connectivity (FPGA-FPGA and FPGA-PC TCP/UDP, UART to PC)

All: System integration (hard)

| Milestone # | High-Level Target |
|-------------|---|
| 1 | Research phase |
| 2 | SDIO/SPI physical layer implementation, DCT running in testbench, PC to FPGA via UART |
| 3 | SD card testbench, visualization started, initial network implementation done |
| 4 | Begin integrating SD card, microblaze, and compression/decompression blocks. |
| 5 | Finish SD card image transfer and network pipeline, pull performance monitoring stats |
| 6 | Road to final systems integration, time for exceed goals |

Testing and Integration Plan

- 1. Compression/Decompression Algorithm
 - a. Speed (bits per sample)
 - b. Losses (absolute pixel intensity difference)
- 2. Networking
 - a. Host PC to FPGA connectivity
 - b. FPGA to FPGA connectivity
- 3. Performance Monitoring
 - a. Basic terminal commands
 - b. fAnCY GUI
- 4. SD Card
 - a. Can write to it
 - b. Can read from it



Risks & Mitigation Plan

Human Resources

- In case of schedule conflict: Plan ahead and according to expected workload
- In case of drop-out: Blood pact to pull through together

Hardware Failures

- In case of single FPGA failure: Test early, switch stations and inform TAs the abnormality
- Insufficient RAM/LUTs: Test early, track usage space, de-scope image quality or algorithm complexity if necessary

Software Failures

- o <u>Infinite Loops</u>: Be very careful with blocking operations. Consider interrupt-based event loop or real-time OS
- <u>Unknown Bugs</u>: Reach out to professor and TAs early. Switch to another similar IP or algorithm.

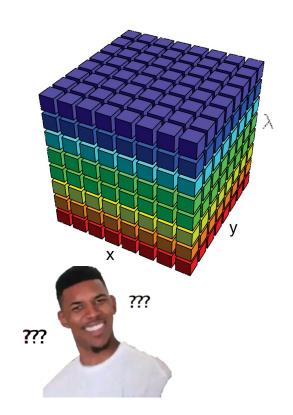
Network Failures

- <u>DESL network too slow:</u> Test early and figure out the bandwidth of both wired/wireless networks. If still too slow
 just queue up image and demo one image transfer at a time
- Lost access to DESL: Have a backup copy in the clouds or our personal machines



Uncertainties

- 1. The software structure
 - a. **Event loop** is simple to implement but beware of blocking operations
 - b. **RTOS** has nice threading and locking mechanism, but more complex
- 2. Compression algorithms
 - a. **DCT** is a simple starting point, working with only real numbers. However, it's quite bad in terms of compression loss
 - b. **CCSDS** more complex, but is lossless and "industry standard" for space applications/remote sensing
- Which dataset to test?
 - a. Variety in image sizes, resolutions, bit-depths, band numbers and etc.
 - b. Should the program be adaptive to various input? (auto-detect image size and quality etc.)
 - c. Starting with this image set from Columbia University (CAVE Project)



Q&A Portion

Any and all questions welcome.