Interpolating Piecewise Cubic Bézier Curves with C¹ Continuity (Progressive Drawing)

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This report describes a simple strategy to draw an *interpolating* piecewise curve through user-provided points using *cubic Bézier* segments. C¹ continuity at joins is obtained by placing the inner control points along endpoint tangents computed from finite differences. The system draws the full curve *progressively* while points are being added, and supports moving points after placement; the curve updates immediately. Implementation details match the provided OpenGL/ImGui starter code.

1 PROBLEM SETTING

The starter program collects 2D points (x, y) from the user and, by default, shows the polyline. The goal is to replace the polyline display with a *piecewise cubic Bézier* interpolant that passes through all points and is C^1 -continuous at joins. The curve must update in real time both while new points are added and when existing points are dragged.

2 CUBIC BÉZIER AND BERNSTEIN BASIS

A cubic Bézier with control points $B_0, \ldots, B_3 \in \mathbb{R}^2$ is

$$B(t) = (1-t)^3 B_0 + 3(1-t)^2 t B_1 + 3(1-t)t^2 B_2 + t^3 B_3, \quad t \in [0,1].$$

The Bernstein basis functions are

$$b_0 = (1-t)^3$$
, $b_1 = 3(1-t)^2 t$, $b_2 = 3(1-t)t^2$, $b_3 = t^3$.

We render each segment by sampling $t_k = \frac{k}{N-1}$, k = 0, ..., N-1, and emitting the points $B(t_k)$ as a line strip (SAMPLES_PER_BEZIER = N).

3 INTERPOLATION AND C1 CONTINUITY

Let the user's points be P_0, \ldots, P_n . Between consecutive points (P_i, P_{i+1}) we build one cubic segment with

$$B_0 = P_i$$
, $B_3 = P_{i+1}$, $B_1 = P_i + \frac{1}{3}T_i$, $B_2 = P_{i+1} - \frac{1}{3}T_{i+1}$,

where T_i is the tangent at P_i . This guarantees interpolation: $B(0) = P_i$ and $B(1) = P_{i+1}$.

The derivative of a cubic Bézier is

$$B'(t) = 3(1-t)^{2}(B_{1}-B_{0}) + 6(1-t)t(B_{2}-B_{1}) + 3t^{2}(B_{3}-B_{2}),$$

hence $B'(0) = 3(B_1 - B_0)$ and $B'(1) = 3(B_3 - B_2)$. Using the same T_i for the segment ending at P_i and the segment starting at P_i makes the first derivative continuous at P_i , i.e. the curve is C^1 .

Tangent estimation. We estimate tangents by finite differences:

$$T_0 = P_1 - P_0,$$
 $T_i = \frac{1}{2}(P_{i+1} - P_{i-1}) \ (1 \le i \le n-1),$ $T_n = P_n - P_{n-1}.$

Interior tangents use a central difference; endpoints use forward/backward differences.

4 PROGRESSIVE DRAWING AND INTERACTION

Progressive drawing. As soon as the user places two points, the first cubic segment is drawn. Each additional point P_k adds a new segment (P_{k-1}, P_k) . On every add or drag operation we recompute the required tangents and rebuild the concatenated line strip.

Interaction.

- **Left click** on the canvas: add a new interpolation point.
- Right click: finish adding points; subsequent left click + drag selects and moves a point.
- The curve refreshes immediately in both modes (adding and editing).

5 IMPLEMENTATION NOTES

We store all positions in normalized device coordinates (NDC) and render with a pass-through shader. Three VAO/VBO pairs are used: control points, reference polyline (optional), and the piecewise Bézier line strip. When points change, we:

- (1) upload control points,
- (2) (optionally) rebuild the polyline samples,
- (3) rebuild the Bézier samples via the Bernstein basis and upload.

5.1 Key Function: calculatePiecewiseBezier()

The core routine follows exactly the strategy above: derive tangents, build inner controls as $P \pm T/3$, sample with the Bernstein basis, and emit vertices. (Listing abridged for clarity.)

```
void calculatePiecewiseBezier() {
 piecewiseBezier.clear();
 const int m = (int)controlPoints.size();
 if (m < 2*3) return;
 struct Pt { float x, y; };
 std::vector<Pt> P; P.reserve(m/3);
 for (int i=0; i+2<m; i+=3) P.push_back({controlPoints[i],controlPoints[i+1]});</pre>
 const int n = (int)P.size() - 1; if (n <= 0) return;</pre>
 // Tangents (one-sided at ends, central inside)
  std::vector<Pt> T(P.size());
  if (P.size()==2) { T[0]={P[1].x-P[0].x, P[1].y-P[0].y}; T[1]=T[0]; }
 else {
    T[0] = \{P[1].x-P[0].x, P[1].y-P[0].y\};
    T[n] = \{P[n].x-P[n-1].x, P[n].y-P[n-1].y\};
    for (int i=1;i<n;++i)</pre>
      T[i] = \{0.5f*(P[i+1].x-P[i-1].x), 0.5f*(P[i+1].y-P[i-1].y)\};
  }
 const int samples = std::max(2, SAMPLES_PER_BEZIER);
 const float dt = 1.0f / float(samples-1);
 for (int i=0; i<n;++i) {
    Pt B0=P[i], B3=P[i+1];
    Pt B1=\{P[i].x + T[i].x/3.0f, P[i].y + T[i].y/3.0f\};
    Pt B2=\{P[i+1].x - T[i+1].x/3.0f, P[i+1].y - T[i+1].y/3.0f\};
```

```
for (int k=0;k<samples;++k) {</pre>
   float t = k*dt, u = 1.0f-t;
   float b0=u*u*u, b1=3*u*u*t, b2=3*u*t*t, b3=t*t*t;
   float x=b0*B0.x + b1*B1.x + b2*B2.x + b3*B3.x;
   float y=b0*B0.y + b1*B1.y + b2*B2.y + b3*B3.y;
   if (i>0 && k==0) continue; // avoid duplicate joint vertex
   piecewiseBezier.insert(piecewiseBezier.end(), {x,y,0.0f});
}
```

RESULTS AND DISCUSSION

The method produces a visually smooth curve that interpolates all user points and preserves C¹ continuity by construction. Because tangents come from local finite differences, the curve responds well to local edits. Sampling with N = 10 already gives a clean line strip; increasing N refines the rendering.

Limitations / Extensions. This version does not expose handles for manual tangent editing. Straightforward extensions include: interactive tangent handles, and an optional tangent-length optimization step to better align the curve with the control polyline.

7 CONCLUSION

We implemented an interpolating, C1-continuous piecewise cubic Bézier curve that draws progressively while the user adds or moves points. The construction uses endpoint tangents and inner control points at $\pm T/3$, and a Bernstein-basis sampler for rendering. The approach is simple, robust, and integrates cleanly with the provided OpenGL/ImGui framework.