

Linear Algebra(I)

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Plan

The following topics will be covered:

- Linear spaces, Norms and inner product;
- Span, basis and dimensions
- Affinity and hyperplane;
- Linear operators and linear functionals;
- Matrix algebra on \mathbb{R}^n .

Vector Spaces

Vector space (over a field F) is a set V , whose elements are called vectors, together with two binary operation rules that satisfy certain axioms:

- A rule, called vector addition, such that $\forall \alpha, \beta, \gamma \in V$:
 - $\alpha + \beta \in V$
 - $\alpha + \beta = \beta + \alpha, \quad \alpha + (\beta + \gamma) = (\alpha + \beta) + \gamma$
 - $\exists 0 \in V$ such that $\forall \alpha \in V, \quad 0 + \alpha = \alpha$
 - $\forall \alpha \in V, \exists (-\alpha) \in V$ such that $\alpha + (-\alpha) = 0$
- A rule, called scalar multiplication, such that $\forall c, c_1, c_2 \in F$ and $\forall \alpha \in V$:
 - $c \cdot \alpha \in V$
 - $\exists 1 \in F$ such that $\forall \alpha \in V, \quad 1 \cdot \alpha = \alpha$
 - $(c_1 \times c_2) \cdot \alpha = c_1 \cdot (c_2 \cdot \alpha), \quad c \cdot (\alpha + \beta) = c \cdot \alpha + c \cdot \beta,$
 $(c_1 + c_2) \cdot \alpha = c_1 \cdot \alpha + c_2 \cdot \alpha$

Vector spaces

- A **real vector space** is a space where the scalars are real numbers.
- A subset Y of the vector space X is called a **subspace** of X if $\forall x, y \in Y$ we have $x + y \in Y$ and $\forall \alpha \in \mathbb{R}, \alpha x \in Y$.

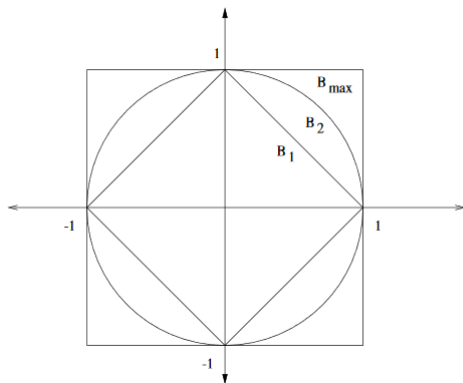
Normed vector spaces

- Let X be a real vector space. **Norm** $\|\cdot\| : X \rightarrow \mathbb{R}$ is a function such that $\forall x \in X, \forall \alpha \in \mathbb{R}$:
 - $\|x\| \geq 0$ and $\|x\| = 0 \Leftrightarrow x = 0$
 - $\|\alpha x\| = |\alpha| \|x\|$
 - $\|x + y\| \leq \|x\| + \|y\|$
- A vector space is said to be a normed vector space if it admits a norm.
- Every normed space is also a metric space with the metric $d : X \times X \rightarrow \mathbb{R}$ where $d(x, y) = \|x - y\|$, but the converse is not always true(counterexample?)
- A complete normed space is called a **Banach Space**.

Euclidean Spaces

- The vector space \mathbb{R}^n with the usual addition and multiplication allows for several norms:

- $\|(x_1, \dots, x_n)\|_p = \left(\sum_{i=1}^n |x_i|^p \right)^{1/p}, \quad p \in [1, \infty)$
- $\|(x_1, \dots, x_n)\|_\infty = \max\{|x_1|, \dots, |x_n|\}$



Inner Product Spaces

- Let X be a real vector space. **Inner product** $\langle \cdot, \cdot \rangle: X \times X \rightarrow \mathbb{R}$ is a function such that $\forall x, y, z \in X, \forall \alpha \in \mathbb{R}$:
 - $\langle x, x \rangle \geq 0$ and $\langle x, x \rangle = 0 \Leftrightarrow x = 0$
 - Symmetry: $\langle x, y \rangle = \langle y, x \rangle$
 - Linearity: $\langle \alpha x, y \rangle = \alpha \langle x, y \rangle$ and $\langle x + y, z \rangle = \langle x, z \rangle + \langle y, z \rangle$
- A vector space is said to be an inner product space if it admits an inner product.
- Every inner product space is also a normed space with the norm $\|x\| = \sqrt{\langle x, x \rangle}$.
- A complete inner product space is called a **Hilbert Space**.
 - Every Hilbert space is a Banach space.

Euclidean Vector Spaces

- In Euclidean vector spaces, the usual inner product (dot product) is defined as:

$$\langle x, y \rangle = x \cdot y = x_1y_1 + x_2y_2 + \dots + x_ny_n$$

- In Euclidean vector spaces, the usual norm is defined as:

$$\|x\| = \sqrt{\langle x, x \rangle} = \sqrt{\sum_{i=1}^n x_i^2}$$

- All Euclidean spaces are Hilbert Spaces with the usual inner product.

Normed and Inner Product Spaces

- **Cauchy Schwartz Inequality:** Let X be an inner product space and $x, y \in X$. If $x = 0$ and $y = 0$ then the inequality holds trivially. Assume $x \neq 0$ or $y \neq 0$:

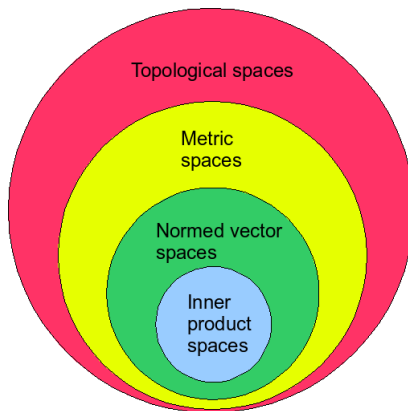
$$| \langle x, y \rangle | \leq \|x\| \|y\|$$

- A normed vector space X is an inner product space if and only if for every $x, y \in X$:

$$2\|x\|^2 + 2\|y\|^2 = \|x + y\|^2 + \|x - y\|^2$$

- l_p and L_p are Hilbert space if and only if $p = 2$.

Hierarchy of mathematical spaces



Linear Dependence

- Given a set of vectors $\{x_1, \dots, x_k\} \subset X$ and a set of scalars $\{\alpha_1, \dots, \alpha_k\}$, a **linear combination** of these vectors is
$$x = \sum_{i=1}^k \alpha_i x_i.$$
- A set of vectors $\{x_1, \dots, x_k\} \subset X$ is called **linearly dependent** if one of them can be written as a linear combination of the others.
 - There exist numbers c_1, c_2, \dots, c_k , not all equal to zero, such that $\sum_{i=1}^k c_i x_i = 0$.
- A set of vectors $\{x_1, \dots, x_k\} \subset X$ is called **linearly independent** if none of them can be written as a linear combination of the others.

Span

- Take a set of vectors $V = \{x_1, \dots, x_k\} \subset X$. **Span** of V is the set of all linear combinations of V :

$$\text{span}(V) = \{x \in X \mid \exists \alpha_1, \dots, \alpha_k \in \mathbb{R}, x = \sum_{i=1}^k \alpha_i x_i\}$$

- Span of any set of vectors forms a vector subspace. (Proof?)
- The span of V is the smallest linear subspace that contains V .
- If every vector of a vector space X can be written as a linear combination of vectors in set V , we say that V spans X .

Basis and Dimension

- Assume a set of vectors span the subspace Y of the vector space X . If the set of vectors are linearly independent, then it is called a **basis** of the subspace of Y .
- Any basis of a vector space contains the same number of elements.
 - The number of elements of the basis of a vector space is called the **dimension** of the vector space.
- A basis for \mathbb{R}^3 is $\{(1, 2, 0), (0, 1, 2), (2, 0, 1)\}$. Therefore dimension of \mathbb{R}^3 is 3.

Orthogonal and Orthonormal Basis

- If the inner product of two vectors gives zero, these vectors are said to be **orthogonal**.
 - Elements of $\{(2, 0, 0), (0, 2, 0), (0, 0, 2)\}$ are orthogonal to each other.
- If the vectors of the basis of a vector space are orthogonal, we call it an orthogonal basis.
- If the vectors of the basis of a vector space are orthogonal and the norm of each is 1, we call it an **orthonormal** basis.
 - $\{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$ is an orthonormal basis of \mathbb{R}^3 .
- Any set of basis vectors can be converted into an orthonormal basis by the **Gram-Schmidt** process.

Orthogonal Complement

- Given a set of vectors S in the Hilbert space X , S^\perp denotes the **orthogonal complement** of S :

$$S^\perp = \{x \in X \mid \forall s \in S, \langle x, s \rangle = 0\}$$

- Orthogonal complement of any set is a linear subspace.
- Orthogonal complement of k linearly independent vectors in an n -dimensional vector space is of dimension $n - k$.
- If S is a linear subspace, then $S \cap S^\perp = \{0\}$

Orthogonal projection

- Let S be a linear subspace of \mathbb{R}^n . Then $x \in V$ can be **uniquely** defined as

$$x = s_x + s_x^\perp$$

We call s_x the orthogonal decomposition of x onto S .

- s_x is the closest element in S to x in the sense that:

$$\|s_x - x\| \leq \|s - x\| \forall s \in S$$