



Array-based lists

part 2

Array-based implementations

of the **List** and **Queue** interfaces

	get(i) / set(i,x)	add(i,x) / remove(i)
ArrayStack	$O(1)$	$O(1 + n - i)$
ArrayDeque	$O(1)$	$O(1 + \min\{i, n - i\})$
DualArrayDeque	$O(1)$	$O(1 + \min\{i, n - i\})$
RootishArrayStack	$O(1)$	$O(1 + n - i)$

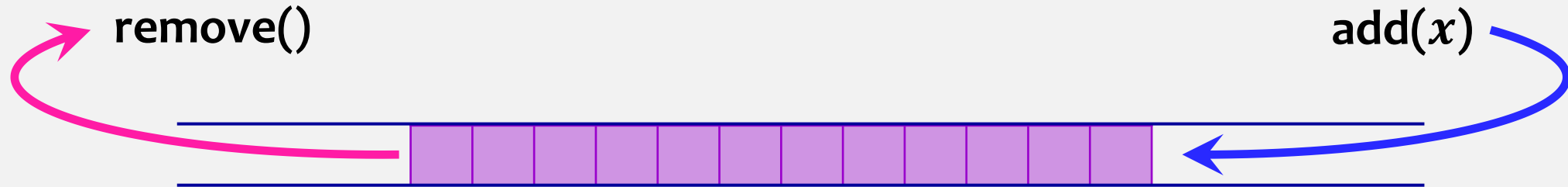
Review

Implementations of the **List** interface

	get(i) / set(i,x)	add(i,x) / remove(i)
we have seen { ArrayStack	$O(1)$	$O(1 + n - i)$
LinkedList	$O(1 + \min\{i, n - i\})$	$O(1 + \min\{i, n - i\})$
today → ods ArrayDeque	$O(1)$	$O(1 + \min\{i, n - i\})$

FIFO Queue

FIFO Queue represents a sequence of FIFO elements.
We add to the end of the queue and remove from the front.



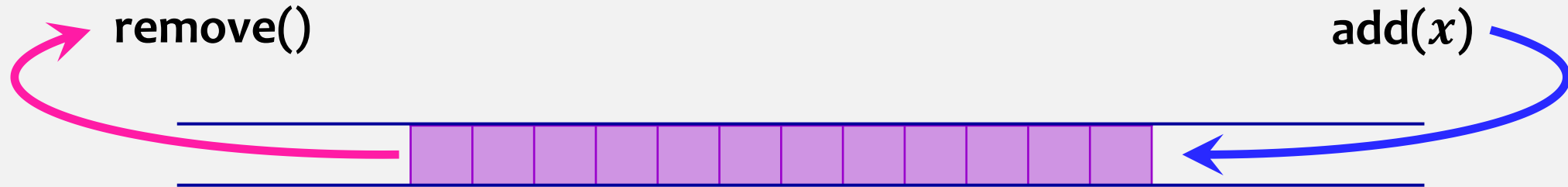
We can use **ArrayList** implementation and add/remove only to front/back. However, this won't get us our desired $O(1)$ time for add/remove operations.

size()
add(x)
remove() – remove
and return the
“oldest” element

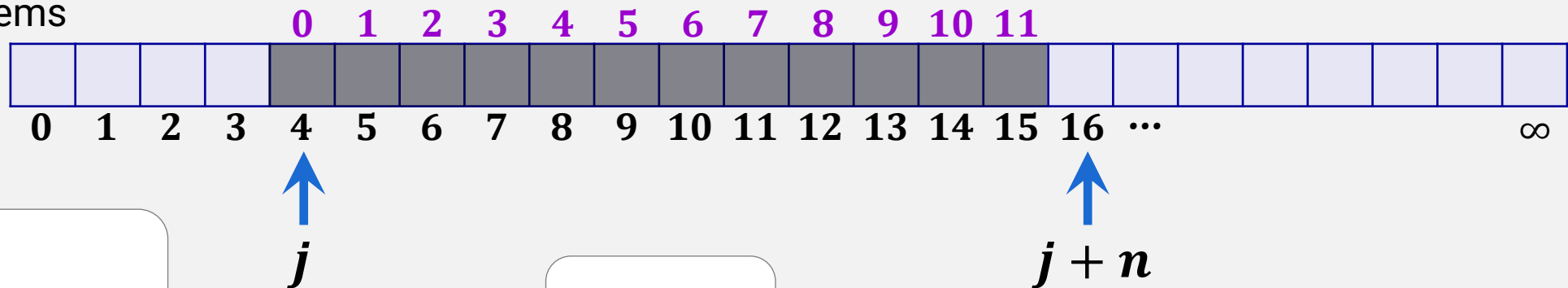
add(x)	ArrayList.add(size(), x)	or	ArrayList.add(0, x)
remove()	ArrayList.remove(0)		ArrayList.remove(size() - 1)

To avoid shifting we will use “pointer” to the front index of our queue elements (j)

FIFO Queue



we store queue items
at consecutive
locations
in this array



constructor:

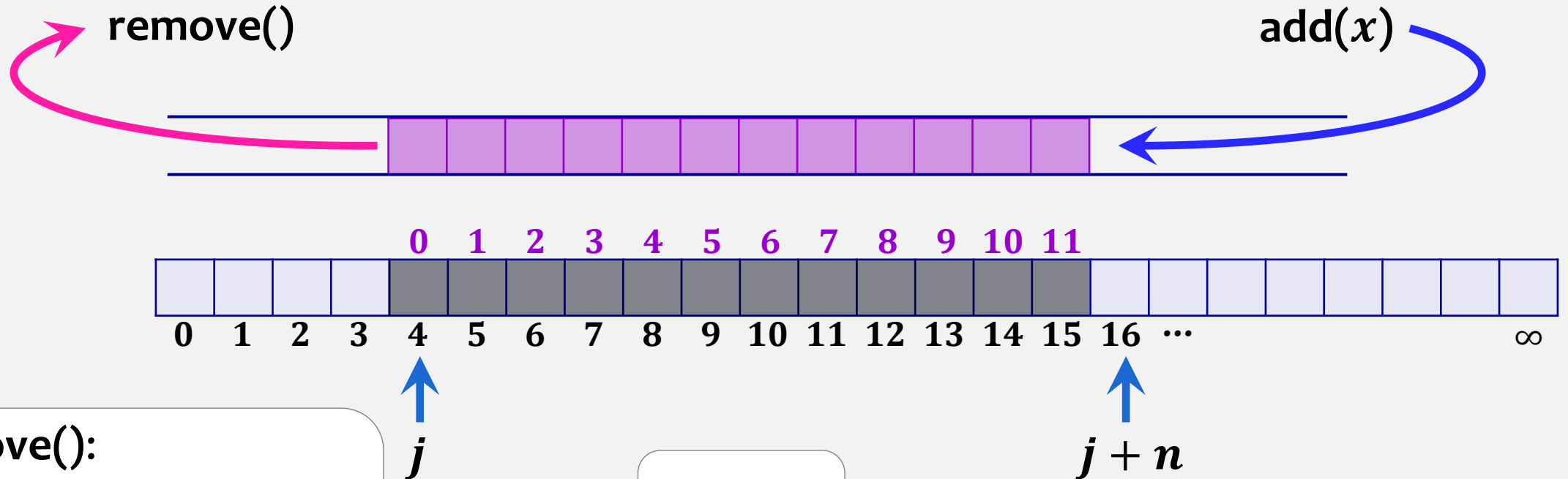
```
 $a$  = new T[ $\infty$ ];  
 $n$  = 0;  
 $j$  = 0;
```

```
T[]  $a$ ;  
int  $n$ ;  
int  $j$ ;
```

index at which queue begins

add(x) – which position do we add?
it is no longer at position **n**
in our example **$n = 12$** , **$j = 4$**

FIFO Queue



remove():

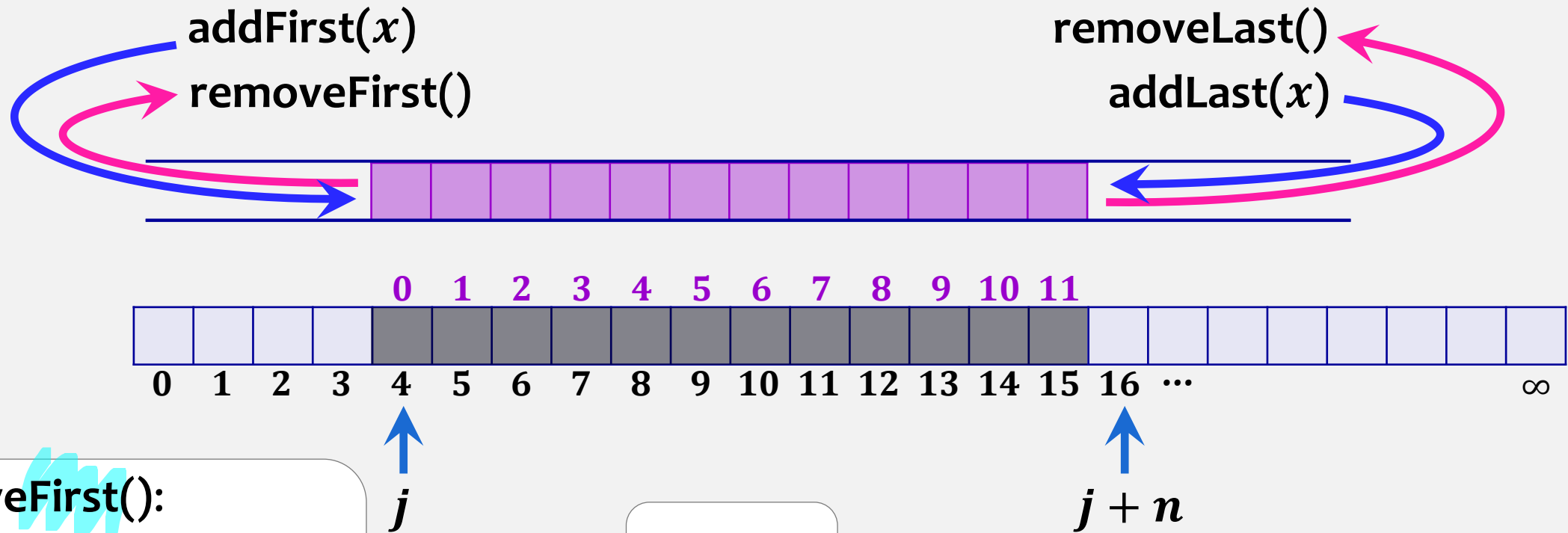
```
if ( $n == 0$ ) throw exception
 $x = a[j]$ ;
 $a[j] = \text{null}$ ;
 $j++$ ;
 $n--$ ;
return  $x$ ;
```

```
 $T[] a$ ;
int  $n$ ;
int  $j$ ;
```

add(x):

```
 $a[j + n] = x$ ;
 $n++$ ;
```


Deque



removeFirst():

```

if ( $n == 0$ ) throw exception
 $T\ x = a[j]$ ;
 $a[j] = \text{null}$ ;
 $j++$ ;
 $n--$ ;
return  $x$ ;
    
```

```

 $T[]\ a$ ;
int  $n$ ;
int  $j$ ;
    
```

addLast(x):

```

 $a[j + n] = x$ ;
 $n++$ ;
    
```

Deque

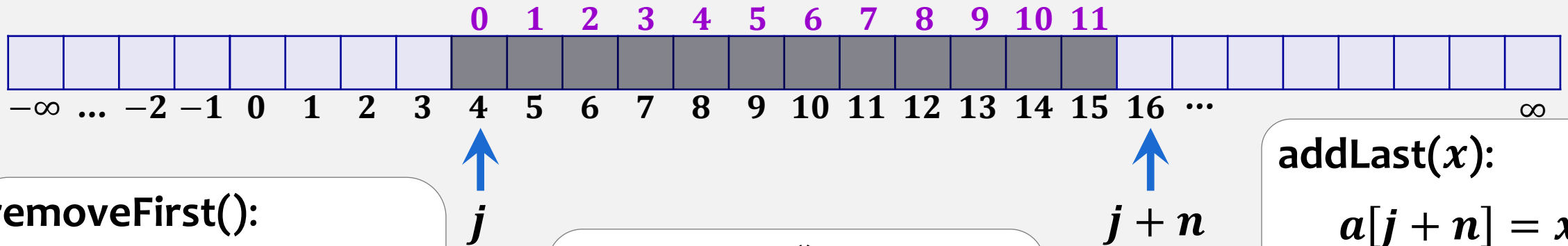
constructor:

```
a = new T[ $\infty$ ];  
n = 0;  
j = 0;
```

but you can choose
any other index

addFirst(*x*)
removeFirst()

removeLast()
addLast(*x*)



removeFirst():

```
if (n == 0) throw exception  
T x = a[j];  
a[j] = null;  
j ++;  
n --;  
return x;
```

removeLast():

```
if (n == 0) throw exception  
T x = a[j + n - 1];  
a[j + n - 1] = null;  
n --;  
return x;
```

addLast(*x*):

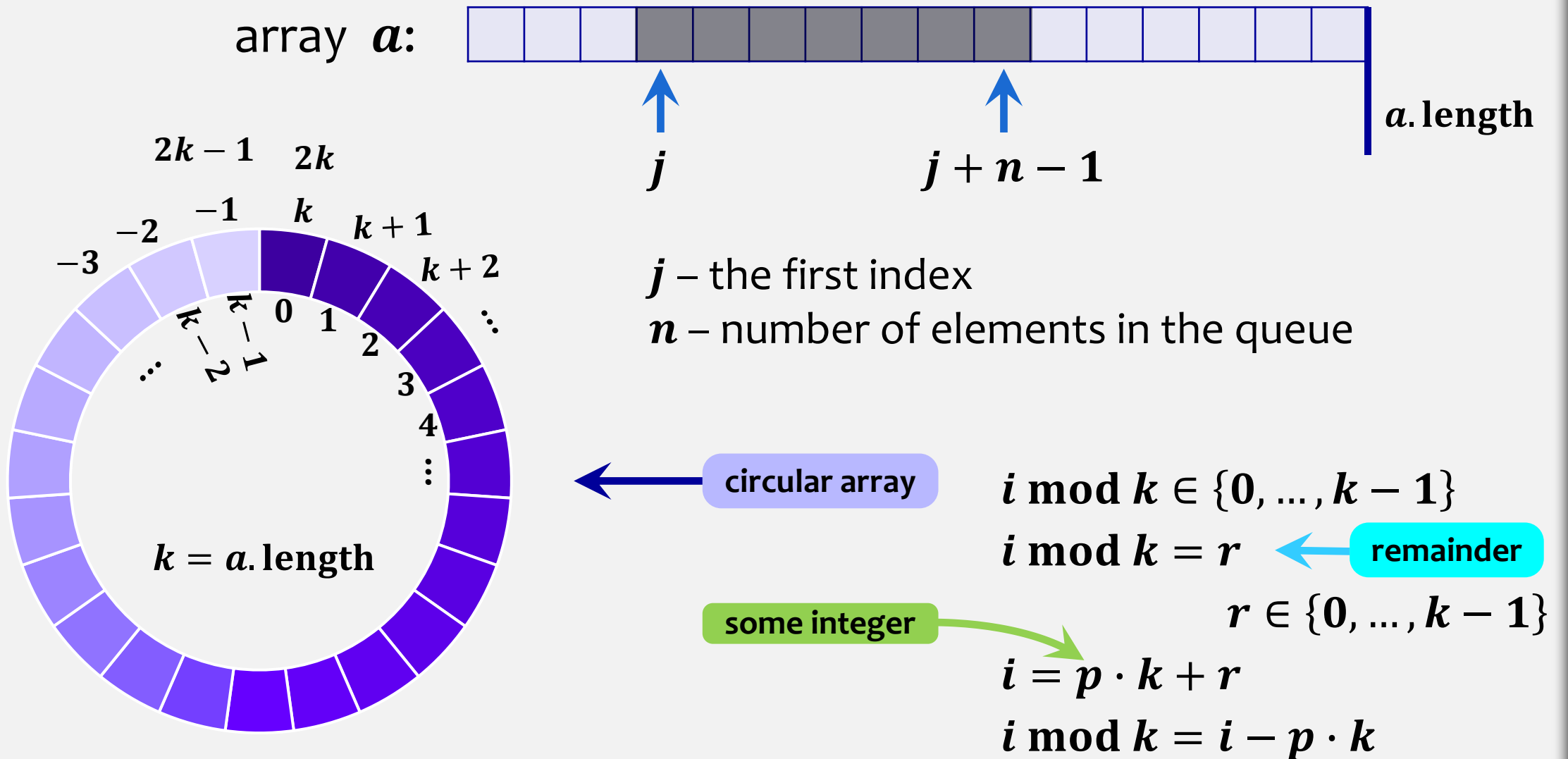
```
a[j + n] = x;  
n ++;
```

addFirst(*x*):

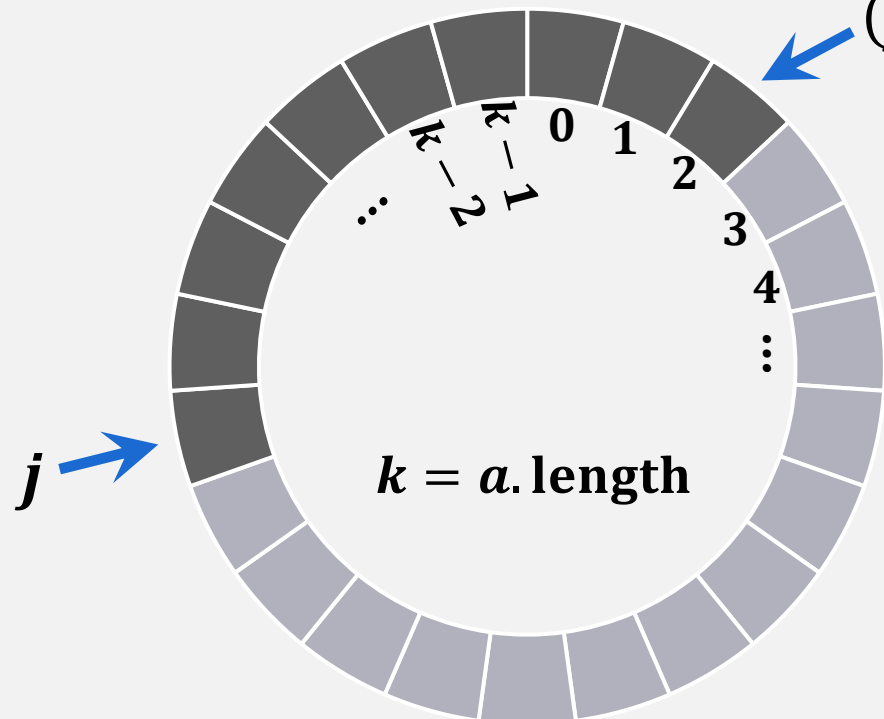
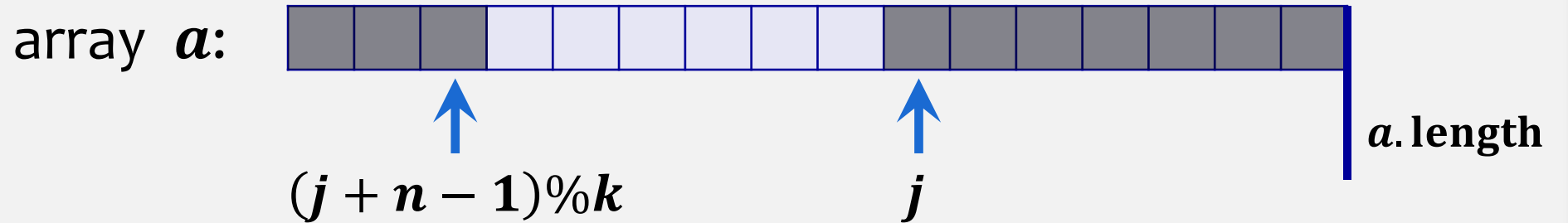
```
j --;  
a[j] = x;  
n ++;
```


Circular Array & MOD

In Java we write $i \% k$. Modulus operator (%) returns the division remainder.



Circular Array & MOD



Example:

$$j = 17$$

$$n = 11$$

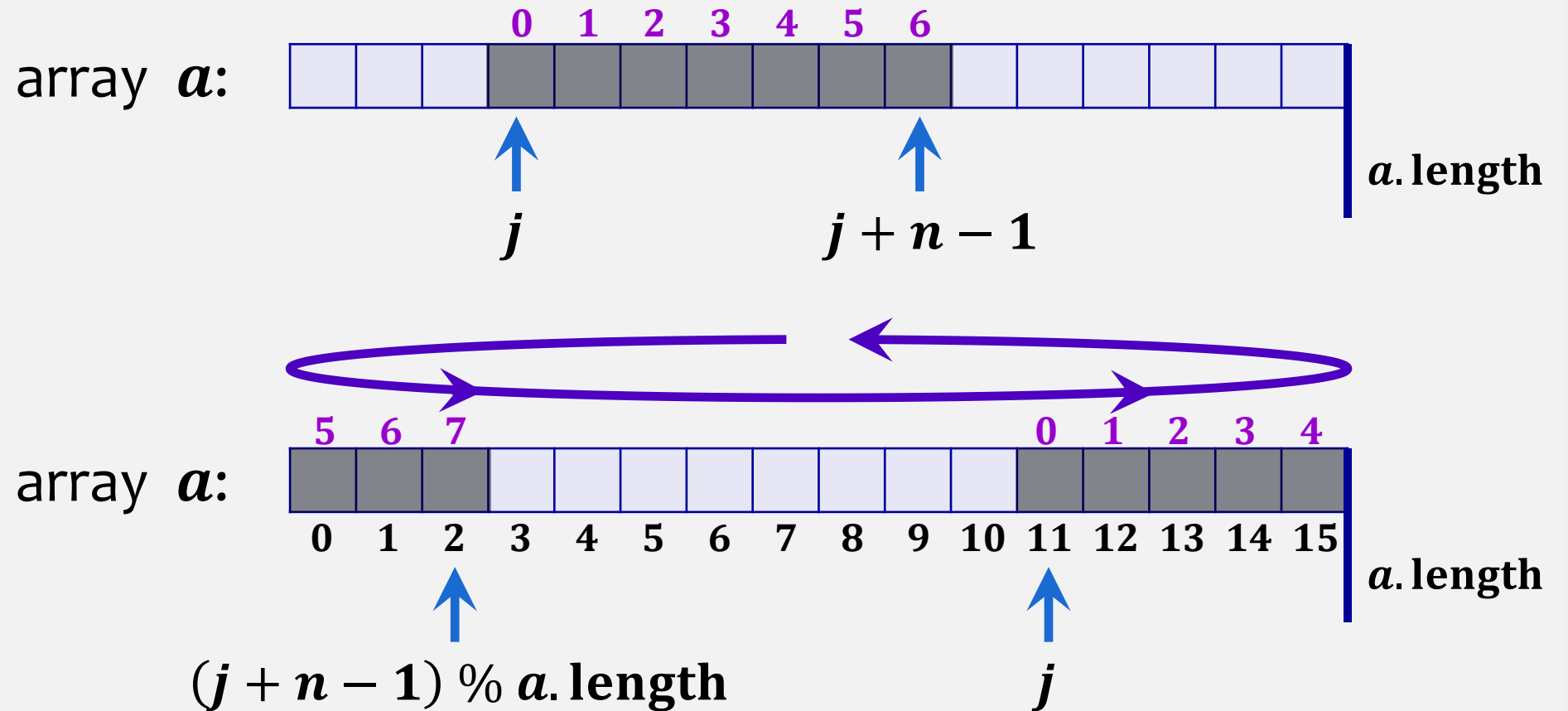
$$k = 24$$

$$\begin{aligned} & (j + n - 1) \% k \\ & (17 + 11 - 1) \% 24 \\ & 27 \% 24 \\ & 3 \end{aligned}$$

$$i \bmod k = i - p \cdot k$$

Circular arrays do not exist

Circular Array & MOD



Deque

constructor:

```
a = new T[1];
n = 0;
j = 0;
```

We need to guarantee that j is a valid index

removeFirst():

```
if (n == 0) throw exception
```

```
T x = a[j];
```

```
a[j] = null;
```

```
j = (j + 1) % a.length;
```

```
n --;
```

```
if (3n ≤ a.length): resize();
```

```
return x;
```

removeLast():

```
if (n == 0) throw exception
```

```
T x = a[(j + n - 1) % a.length];
```

```
a[(j + n - 1) % a.length] = null;
```

```
n --;
```

```
if (3n ≤ a.length): resize();
```

```
return x;
```

addFirst(x):

```
if (n + 1 > a.length) then resize();
```

```
j = (j == 0) ? a.length - 1 : j - 1;
```

```
a[j] = x;
```

```
n ++;
```

ignoring **resize()** **$O(1)$**

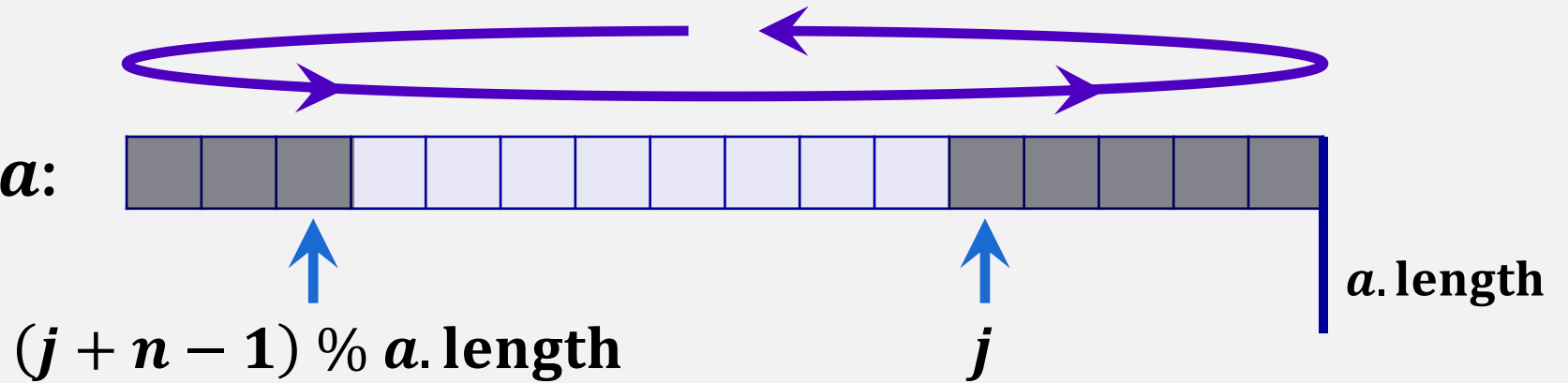
addLast(x):

```
if (n + 1 > a.length) then resize();
```

```
a[(j + n) % a.length] = x;
```

```
n ++;
```

array **a**:



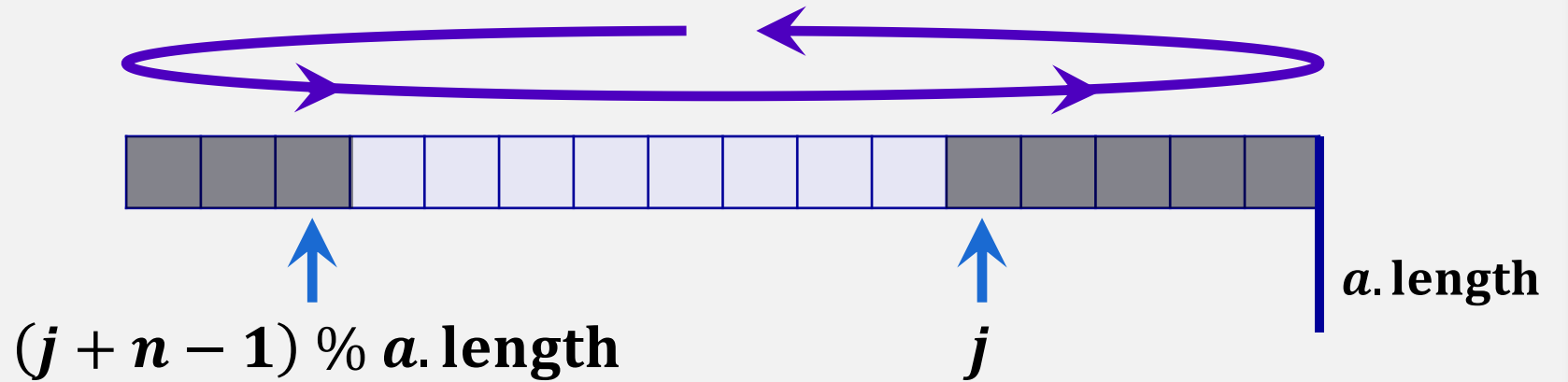
FIFO Queue

constructor:

```
a = new T[1];  
n = 0;  
j = 0;
```

remove():

```
if (n == 0) throw exception  
T x = a[j];  
a[j] = null;  
j = (j + 1) % a.length;  
n --;  
if (3n ≤ a.length): resize();  
return x;
```



Refer to ods textbook:
ArrayQueue implements the
FIFO Queue interface

ignoring **resize()** **$O(1)$**

add(x):

```
if (n + 1 > a.length) then resize();  
a[(j + n) % a.length] = x;  
n ++;
```

resize()

void **resize()**:

T[] **b** = new array(**max{2n, 1}**)

for (**i = 0; i < n; i++**)

b[i] = a[(j + i)%a.length];

a = b;

j = 0;

executes **n** times

to avoid 0-length array

$O(n)$

Theorem 2.2

An **ArrayQueue** implements the (FIFO) Queue interface. Ignoring the cost of calls to **resize()**, an **ArrayQueue** supports the operations **add(x)** and **remove()** in $O(1)$ time per operation. Furthermore, beginning with an empty **ArrayQueue**, any sequence of m **add(x)** and **remove()** operations results in a total of $O(m)$ time spent during all calls to **resize()**.

Review

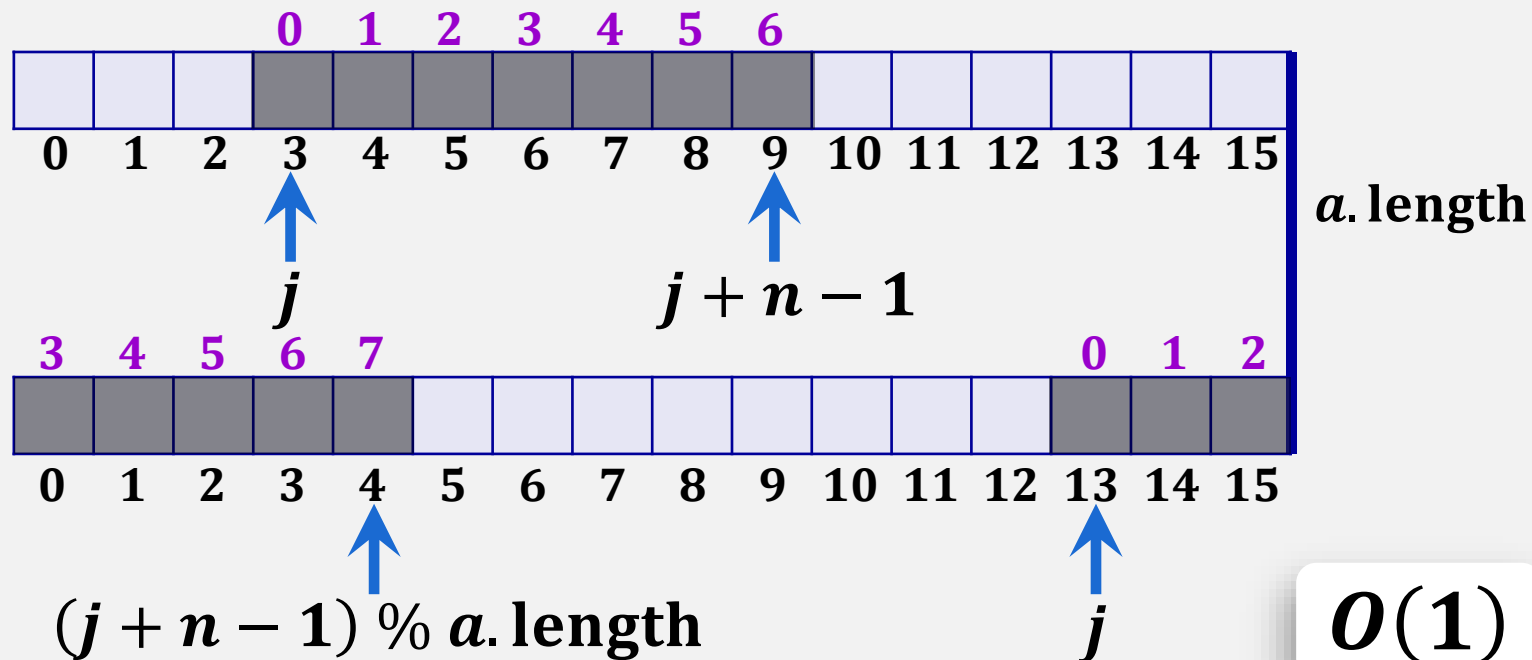
Implementations of the **List** interface

	get(i) / set(i,x)	add(i,x) / remove(i)
we have seen { ArrayStack	$O(1)$	$O(1 + n - i)$
LinkedList	$O(1 + \min\{i, n - i\})$	$O(1 + \min\{i, n - i\})$
today → ods ArrayDeque	$O(1)$	$O(1 + \min\{i, n - i\})$

ArrayDeque is faster than both ArrayStack and LinkedList

ArrayDeque

ArrayDeque implements the **List** interface using circular array with $O(1)$ amortized **Deque** operations (adding and removing to both ends of our sequence).



```
T[] a;  
int n;  
int j;
```

constructor:

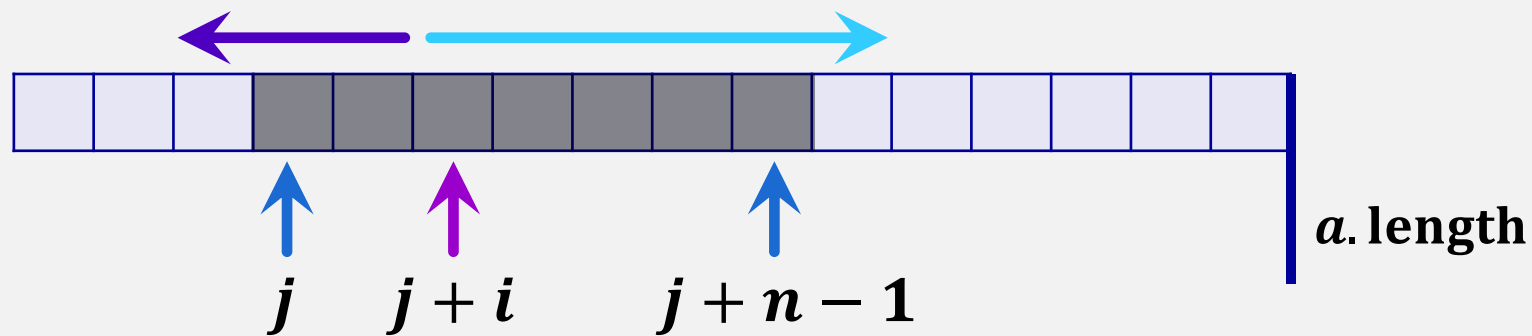
```
a = new T[1];  
n = 0;  
j = 0;
```

keep j private

```
get(i):    check bounds;  
           return a[(j + i) % a.length];
```

```
set(i,x):  check bounds;  
           T y = a[(j + i) % a.length]; // T y = get(i);  
           a[(j + i) % a.length] = x;  
           return y;
```

ArrayDeque



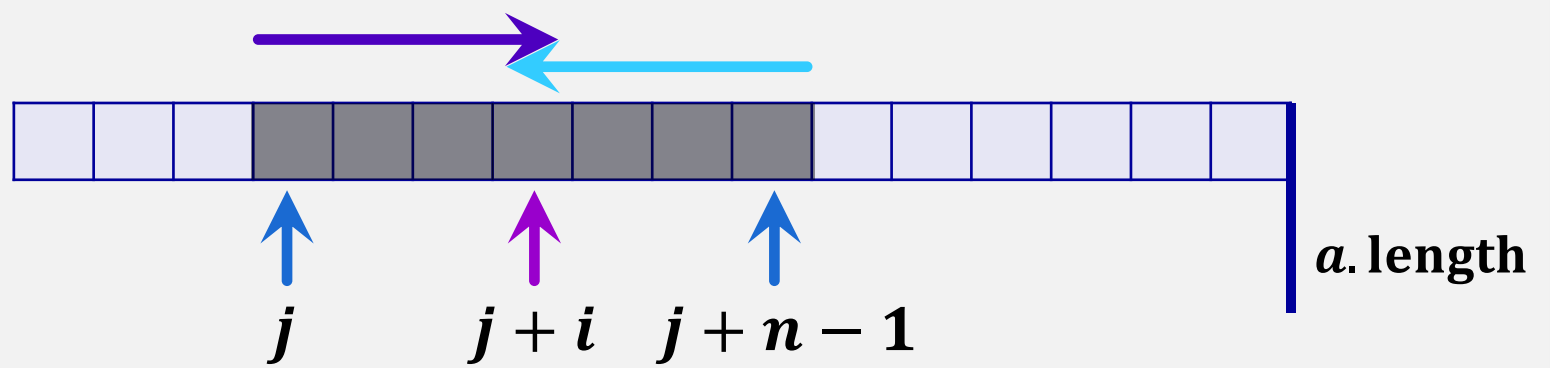
```

add(i,x):  if ( $n + 1 > a.length$ ) then resize();
            if ( $i < \frac{n}{2}$ ) then // i is in the first half
                 $j = (j == 0) ? a.length - 1 : j - 1;$  // move j left
                { shift to the left
                  for ( $k = 0; k \leq i - 1; k++$ )
                     $a[(j + k) \% a.length] = a[(j + k + 1) \% a.length];$ 
                }
            else
                { shift to the right
                  for ( $k = n; k > i; k--$ )
                     $a[(j + k) \% a.length] = a[(j + k - 1) \% a.length];$ 
                }
             $a[(j + i) \% a.length] = x;$ 
             $n++;$ 

```

Running time: $O(1 + \min(i, n - i))$ amortized

ArrayDeque



```

remove(i):
     $x = a[(j + i) \% a.length];$ 
    if  $(i < \frac{n}{2})$  then // shift  $a[0], \dots, [i - 1]$  right one position
         $O(i)$  shift { for  $(k = i; k > 0; k --)$ 
                      $a[(j + k) \% a.length] = a[(j + k - 1) \% a.length];$ 
                      $j = (j + 1) \% a.length$  // move  $j$  right
                }
    else // shift  $a[i + 1], \dots, a[n - 1]$  left one position
         $O(n - i)$  shift { for  $(k = i; k < n - 1; k ++)$ 
                      $a[(j + k) \% a.length] = a[(j + k + 1) \% a.length];$ 
                }
     $n --;$ 
    if  $(3n < a.length)$  then resize();
    return  $x$ ;

```

Running time: $O(1 + \min(i, n - i))$ amortized

Theorem 2.3

An **ArrayDeque** implements the **List** interface. Ignoring the cost of calls to **resize()**, an **ArrayDeque** supports the operations

- **get(*i*)** and **set(*i*, *x*)** in $O(1)$ time per operation; and
- **add(*i*, *x*)** and **remove(*i*)** in $O(1 + \min\{i, n - i\})$ time per operation.

Furthermore, beginning with an empty **ArrayDeque**, performing any sequence of m **add(*i*, *x*)** and **remove(*i*)** operations results in a total of $O(m)$ time spent during all calls to **resize()**.