

COMP 2402 Random Binary Search Trees

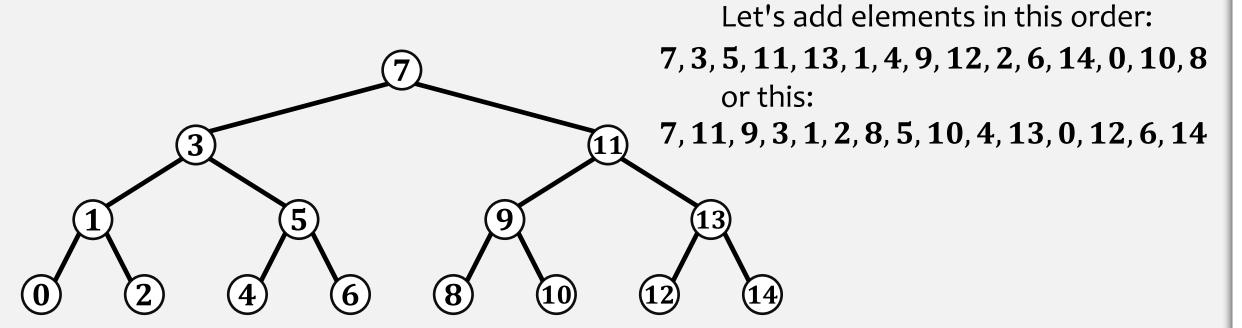
Alina Shaikhet

Let's build a Tree

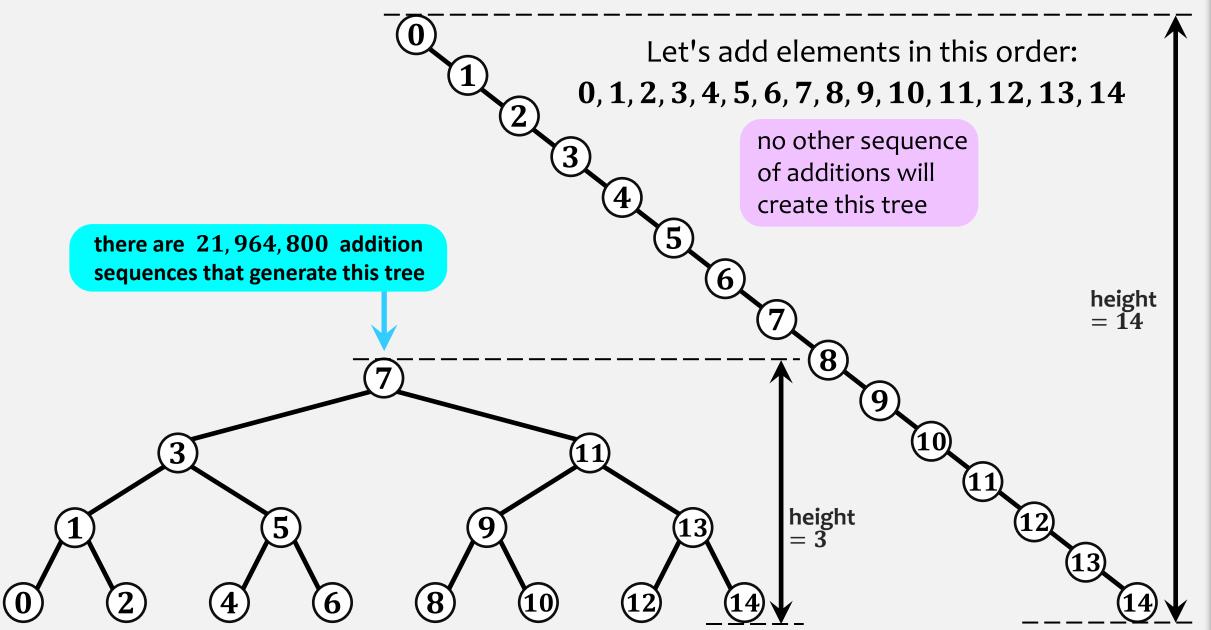
We want to create a binary search tree containing the integers $0, \dots, 14$.

- Start with an empty tree,
- Add elements to the tree one at a time.

Shape of the tree will depend on the order, in which we add elements to the tree.



Two binary search trees containing the integers 0, ..., 14



Random Binary Search Tree

- Take a random permutation of n distinct values (ranks) (for example 0, ..., n-1).
- Insert elements according to their ranks one at a time into a binary search tree.

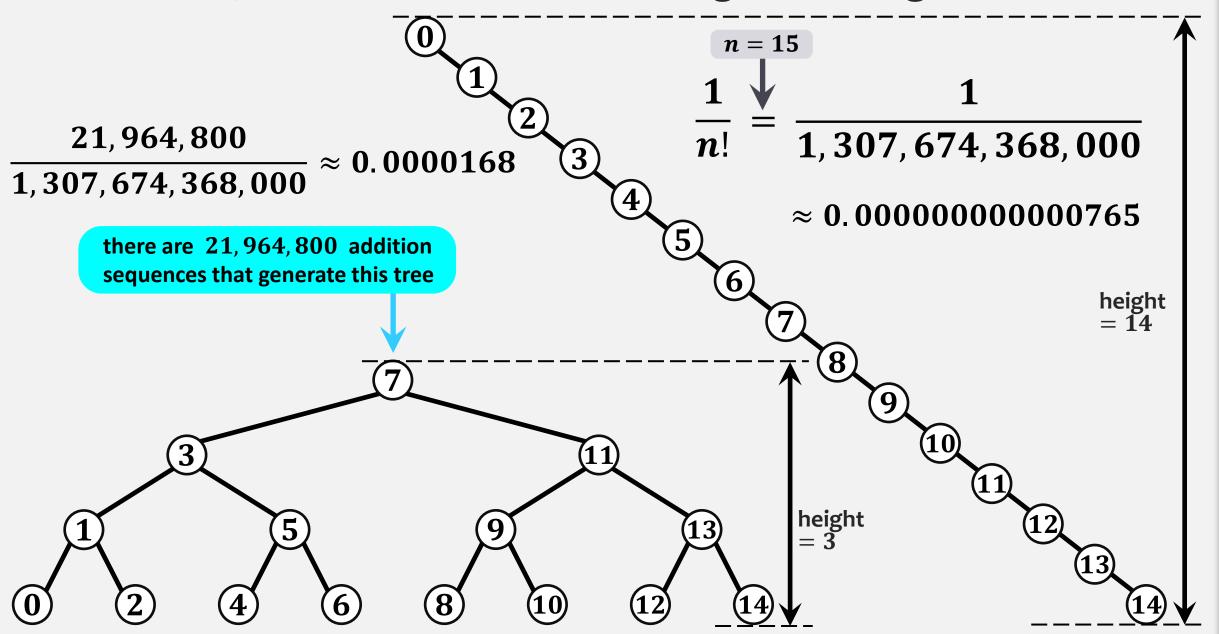
In how many ways can we permute n elements?

$$n! = 1 \times 2 \times 3 \times \cdots \times (n-1) \times n$$

By random permutation we mean that each of the possible n! permutations (orderings) of 0, ..., n-1 is equally likely,

So, the probability of obtaining any particular permutation is $\frac{1}{n}$

Two binary search trees containing the integers 0, ..., 14



Lemma 7.1

In a random binary search tree with n nodes, the expected length of the search path for any value x (whether x is stored in the tree or not) is at most

$$2 \ln n + 2 \approx 1.38 \log_2 n + 2$$

Recall: The expected length of a search path in a SkipList is at most $2 \log_2 n + O(1)$.

This result is with respect to the random permutation used to create the random binary search tree. We cannot maintain this result under add(x) and remove(x) operations.

The problem with random binary search trees is that they are not dynamic.

Random binary search trees don't support the add(x) or remove(x) operations.

So, we cannot use them to implement the **SSet** interface.

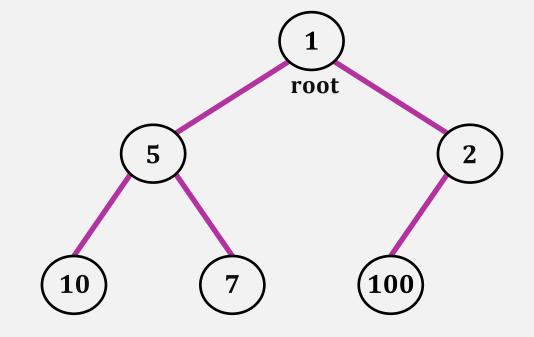
Heap

Heap is a binary tree where each node u has a priority u. p

(Min-)Heap Property:

For each node u except the root:

u. parent. p < u. p

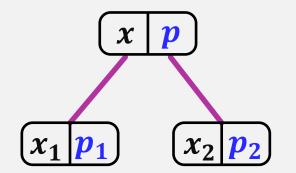


The node with minimum priority has to be the root.

You cannot effectively search for things in heaps. They are not designed for this.

A **Treap** is a binary tree T where each node has:

- a value *x* (**key**)
- a priority p



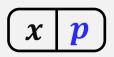
T is a binary search tree with respect to the x values:

T is a heap with respect to the p values. (each node has a priority smaller than that of its two children):

$$x_1 < x < x_2$$

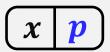
$$p < p_1$$
 and $p < p_2$

Priority values in a Treap are unique and assigned at random.



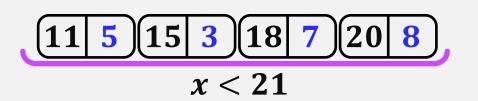
- Node with the smallest priority is a root (r).
- All nodes with keys **smaller** than r.x are stored in the subtree rooted at r.left. All nodes with keys **larger** than r.x are stored in the subtree rooted at r.right.
- Repeat recursively

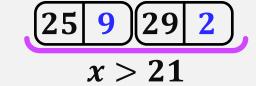
root

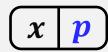


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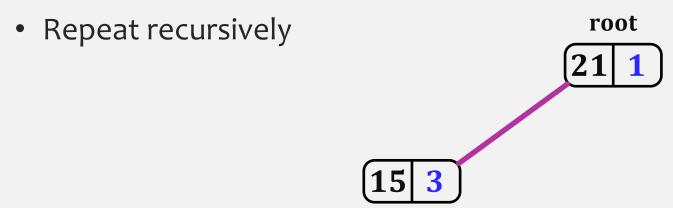
root (21 1)

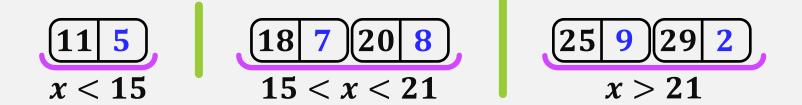


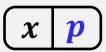




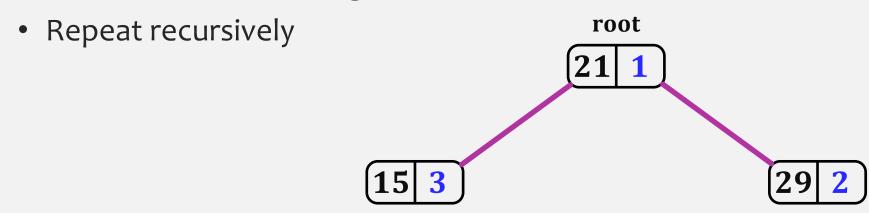
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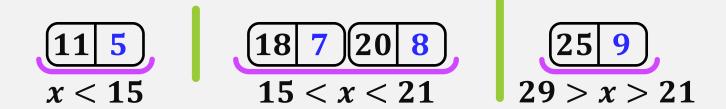


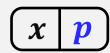




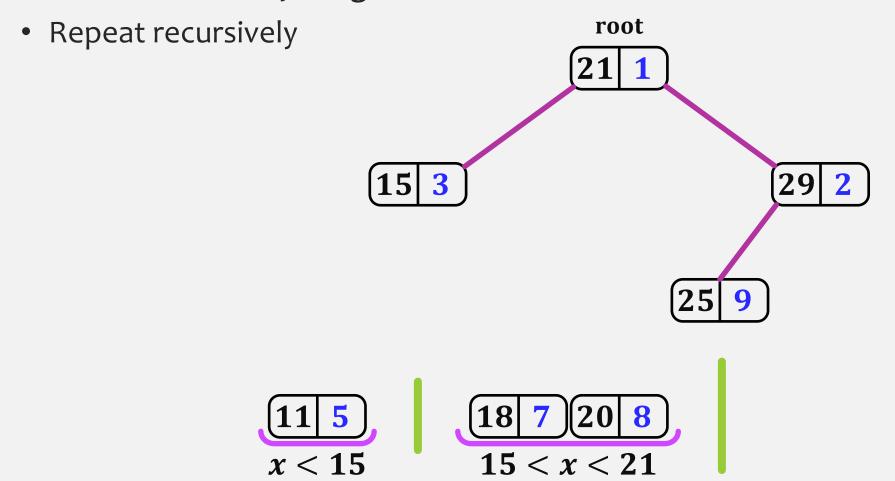
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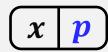




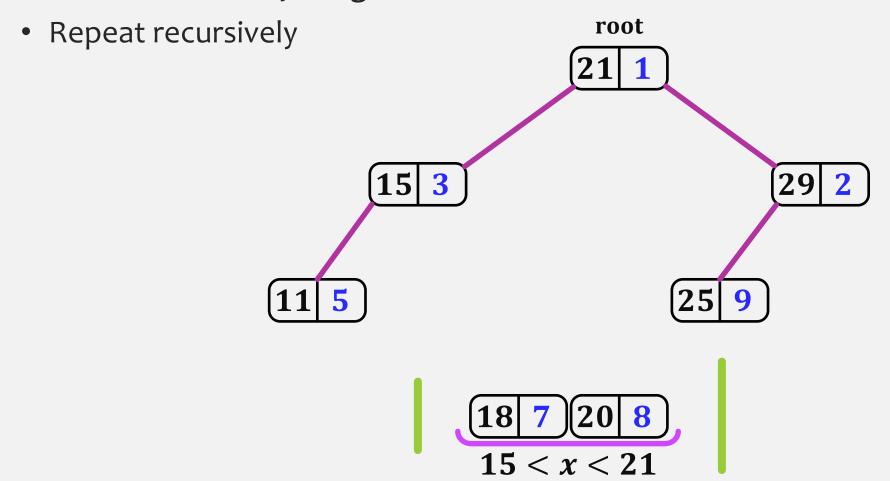


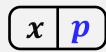
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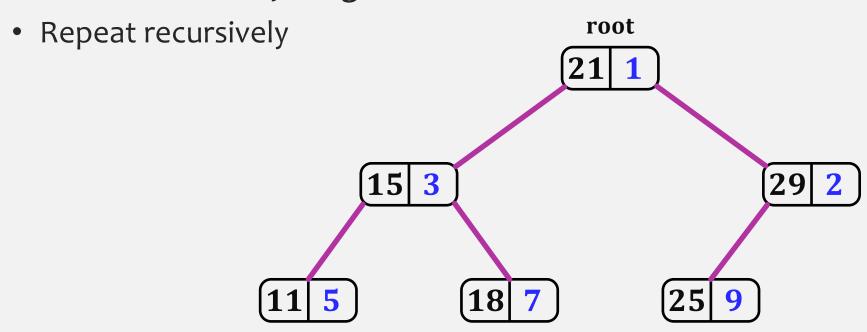


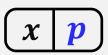
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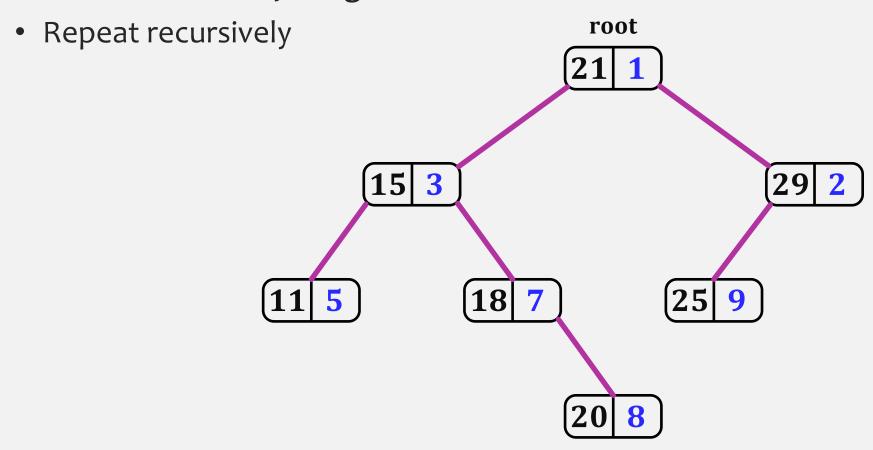


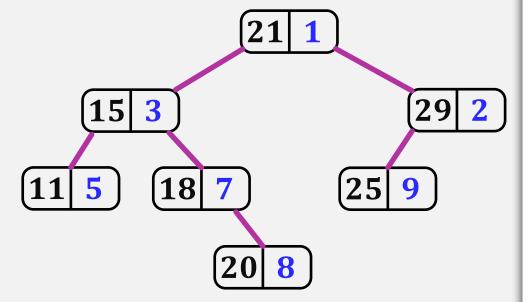
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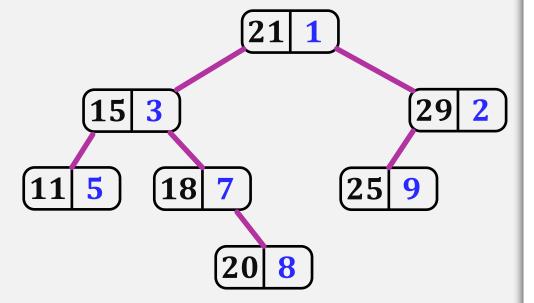


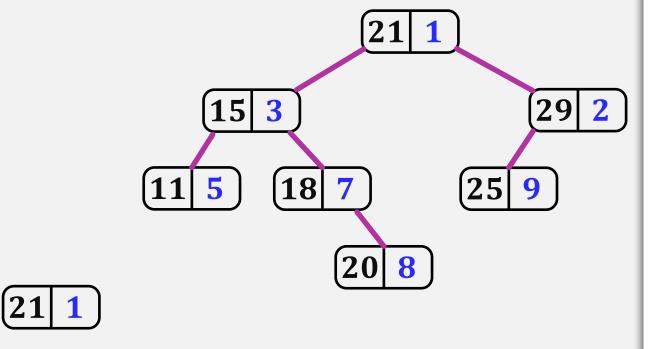


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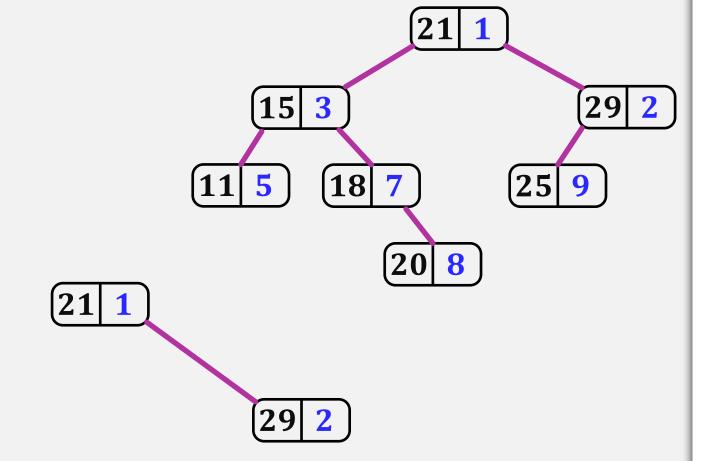






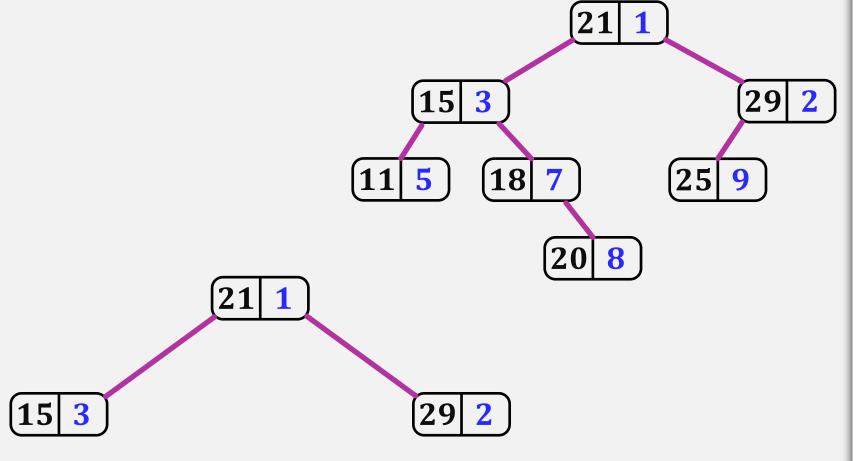
sorted by priority

29 2 15 3 11 5 18 7 20 8 25 9



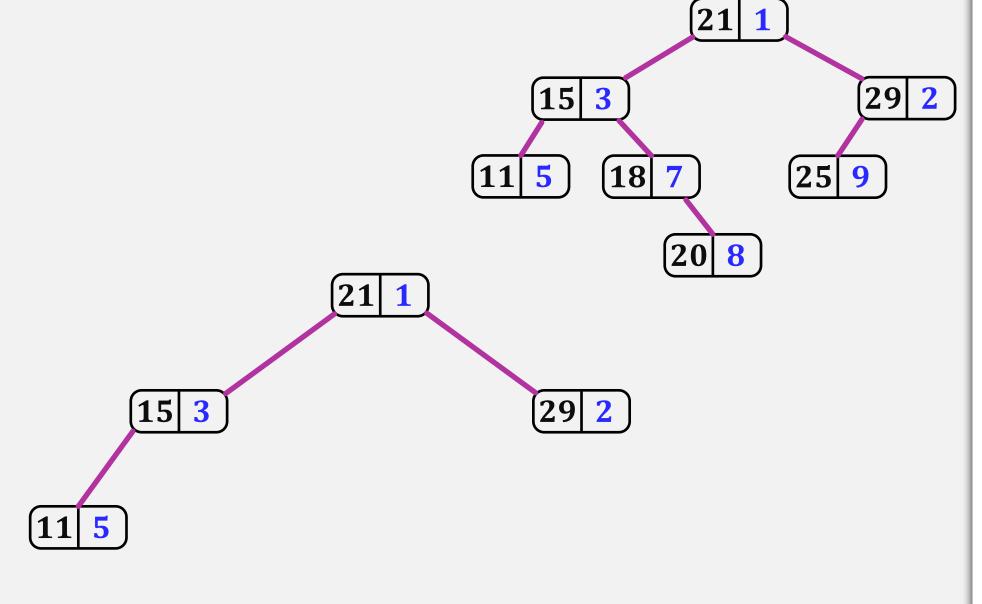






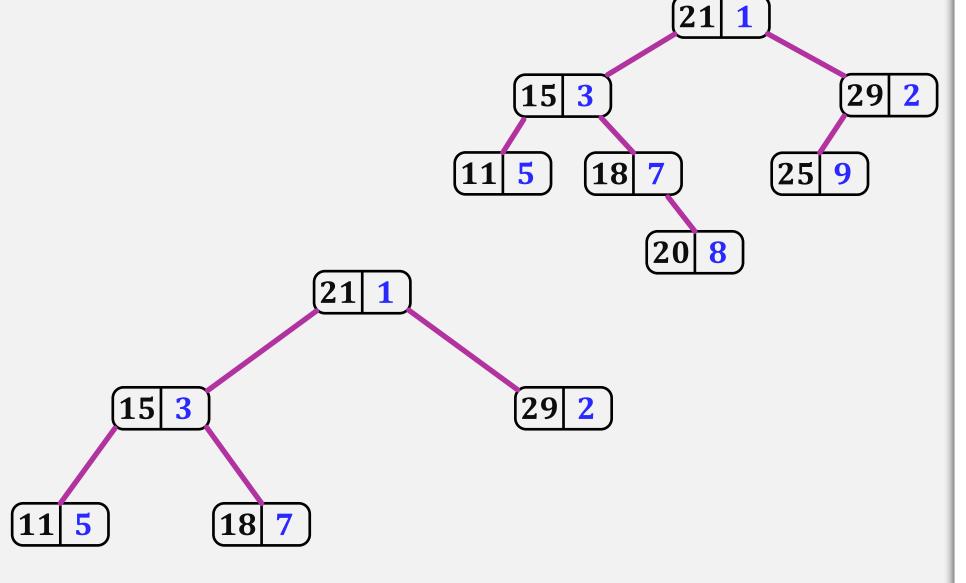
sorted by priority





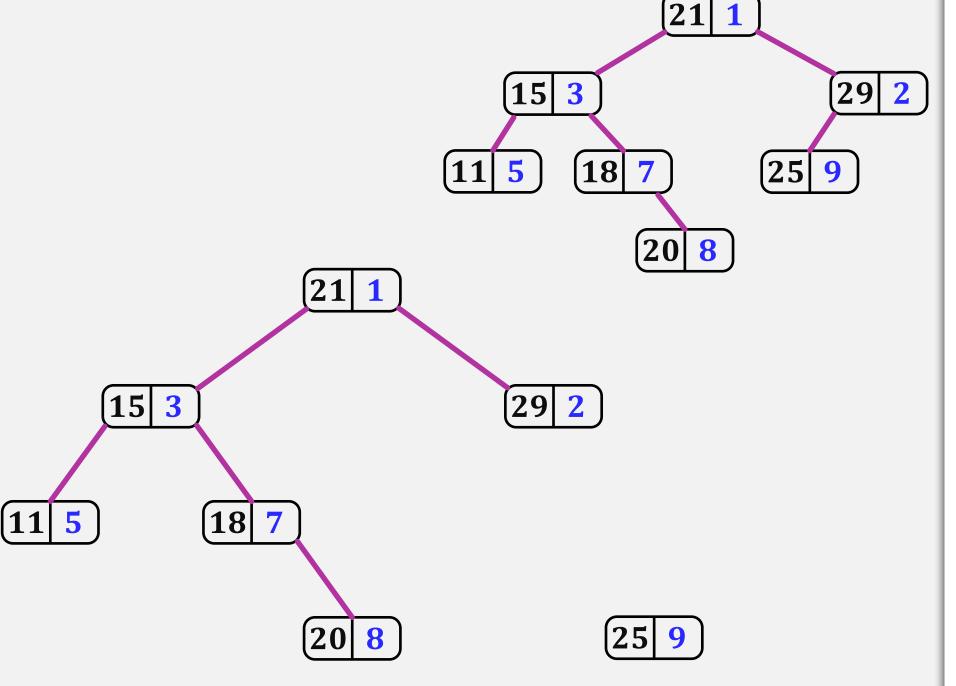
sorted by priority

(18 | 7)(20 | 8)(25 | 9)



sorted by priority

20 <mark>8</mark> 25 9



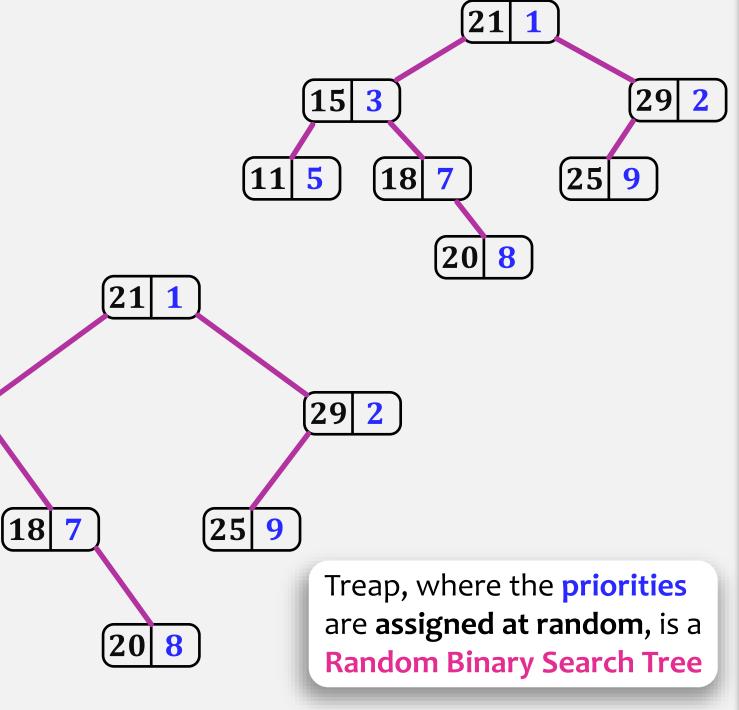
Alternative definition of a Treap:

We can think of a Treap as a BinarySearchTree whose nodes were added in increasing order of priority.

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Lemma 7.2

In a Treap (where the priorities are assigned at random) with n nodes, the expected length of the search path for any value x (whether x is stored in the treap or not) is at most

$$2 \ln n + 2 \approx 1.38 \log_2 n + 2$$

Treap: SSet implementation

- add(x),
- remove(*x*),
- find(x) find the **smallest** value that is $\geq x$.

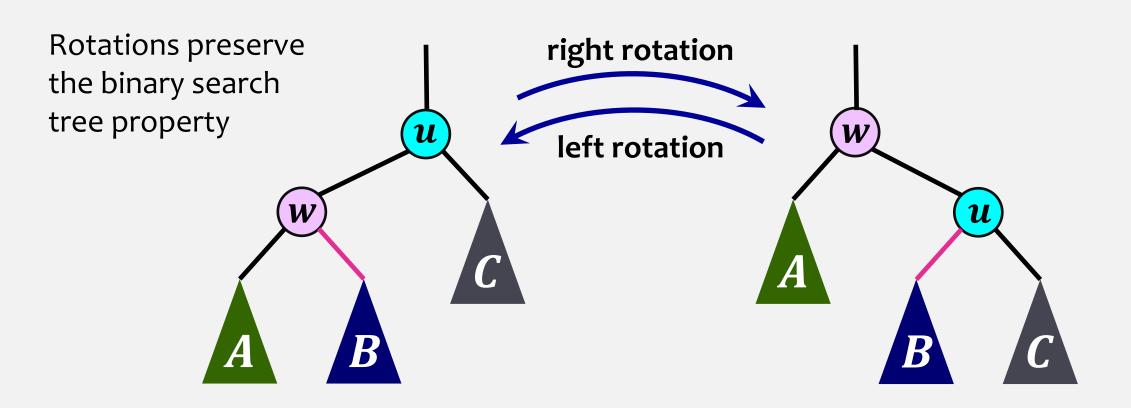
Search in a Treap for x. It will take $O(\log n)$ expected time.

if we can maintain a random treap

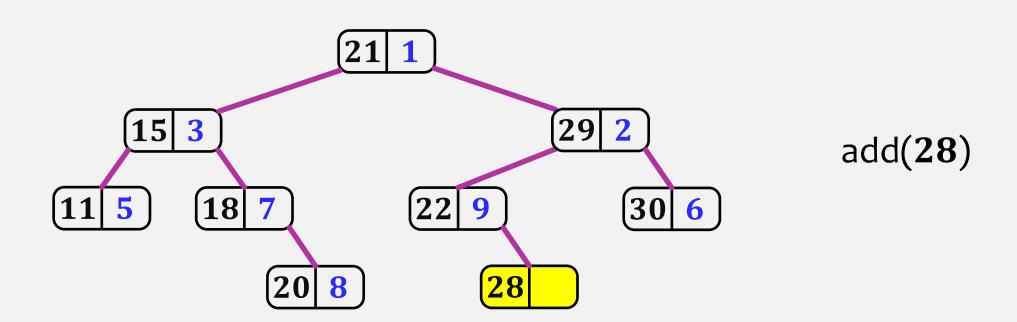
To support the add(x) and remove(x) operations, a treap needs to perform **rotations** in order to maintain the heap property.

Rotation

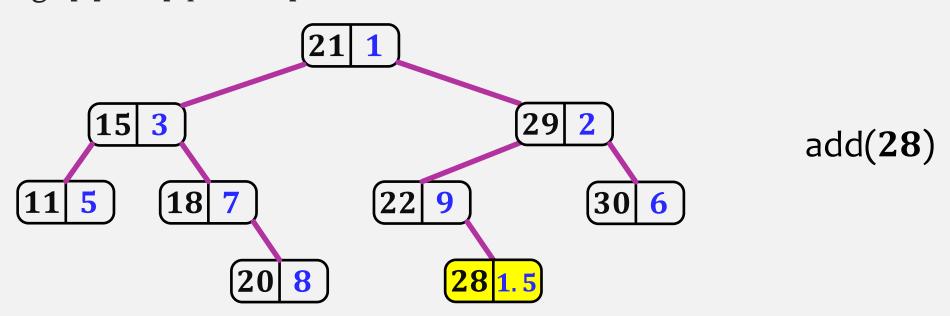
the most important property of a rotation (right) is that the depth of \boldsymbol{w} decreases by one while the depth of \boldsymbol{u} increases by one.



- Search for x in the tree
- If it is not there, add x as a leaf: q

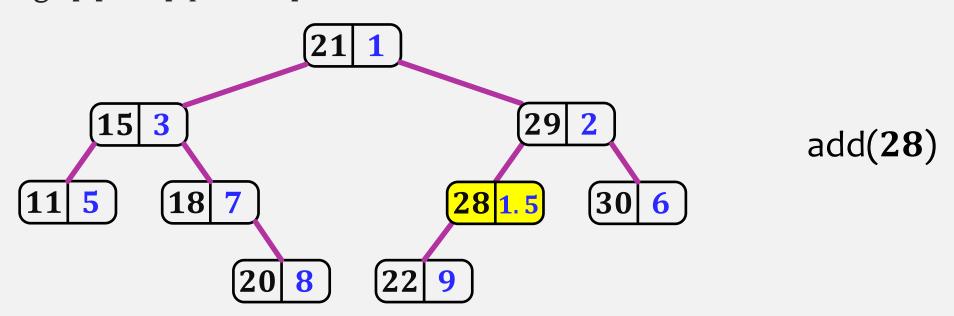


- Search for x in the tree
- If it is not there, add x as a leaf: q
- Give it a random priority: q.p
- As long q.p < q. parent. p rotate it.



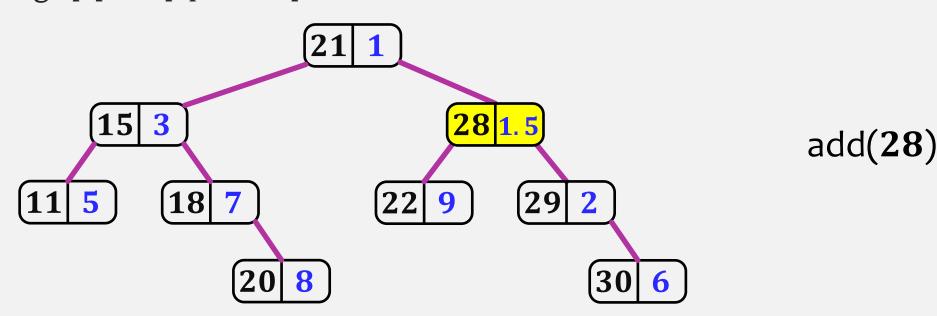
W

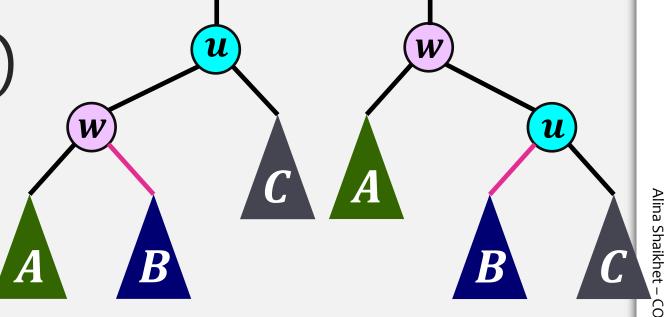
- Search for x in the tree
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W

- Search for x in the tree
- If it is not there, add x as a leaf: q
- Give it a random priority: q.p
- As long q.p < q. parent. p rotate it.





What is the running time of add(x) operation?

Search for x in the tree

 $O(\log n)$

Scarcinion to in the tree

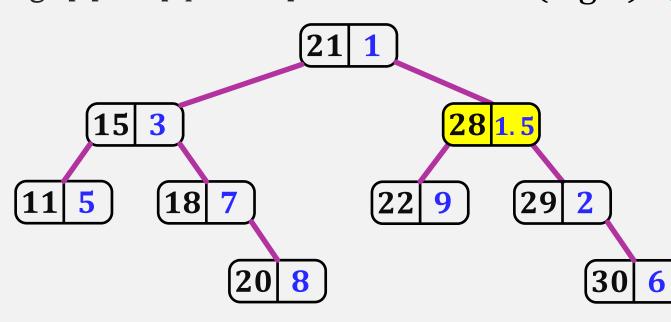
O(1)

Give it a random priority: q.p

- O(1)
- As long q.p < q parent. p rotate it.

If it is not there, add x as a leaf: q

 $O(\log n)$

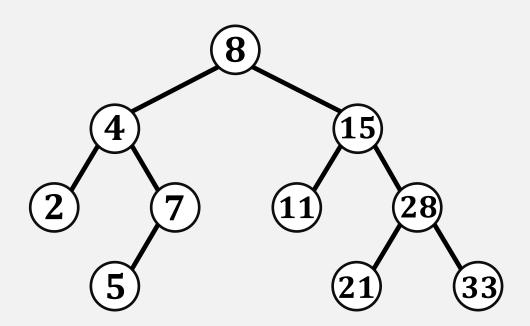


Each time we rotate we get closer to the root. That means that we can't rotate more times than the length of the search path.

 $O(\log n)$ expected

Each rotation takes O(1) time (it affects at most 6 pointers).

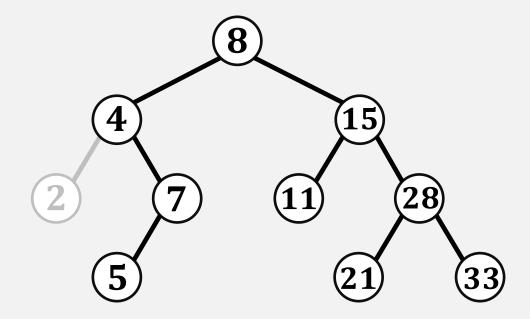
remove(2)



To delete a value stored in **BinarySearchTree**:

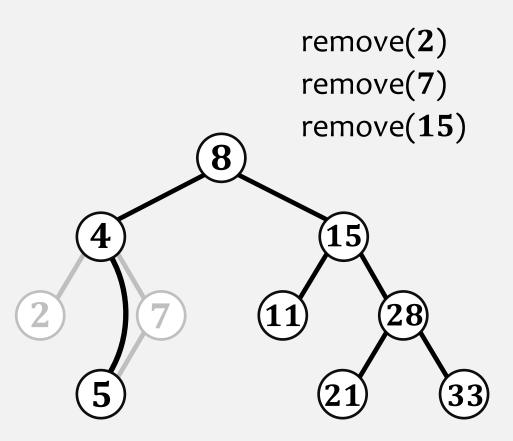
- Find node u that contains value x.
- If u is a leaf, then we can just detach u from its parent.

remove(2) remove(7)



To delete a value stored in **BinarySearchTree**:

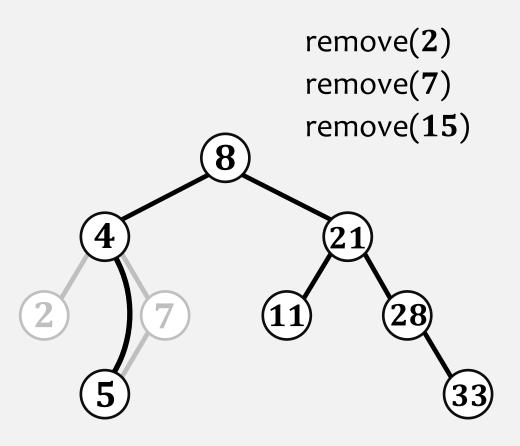
- Find node u that contains value x.
- If u is a leaf, then we can just detach u from its parent.
- If u has only one child, then we can splice u from the tree by having u.parent adopt u's child.



To delete a value stored in **BinarySearchTree**:

- Find node u that contains value x.
- If u is a leaf, then we can just detach u from its parent.
- If u has only one child, then we can splice u from the tree by having u.parent adopt u's child.
- If u has two children, then find a node w, that has less than two children, such that w.x can replace u.x.

Choose **w**, such that **w**. **x** is the smallest value in the subtree rooted at **u**.right. This node has no left child.

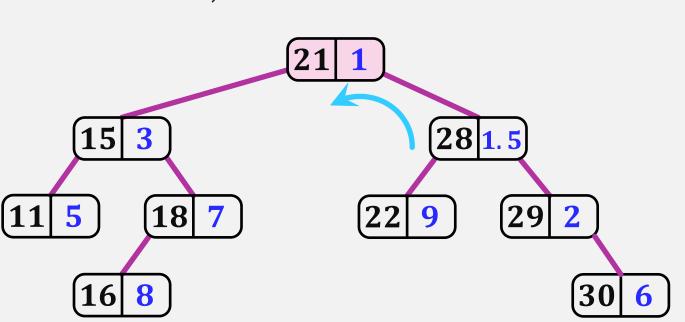


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- Find node q that contains value x.
- If q is a leaf, then we can just detach q from its parent.
- If **q** is not a leaf, then rotate it down until it is a leaf; then detach.



e(x)

w

C

A

B

C

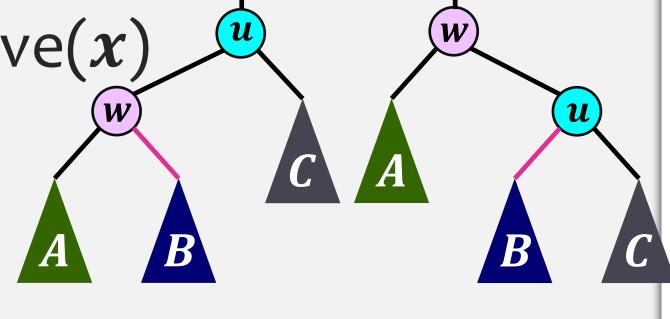
remove(21)

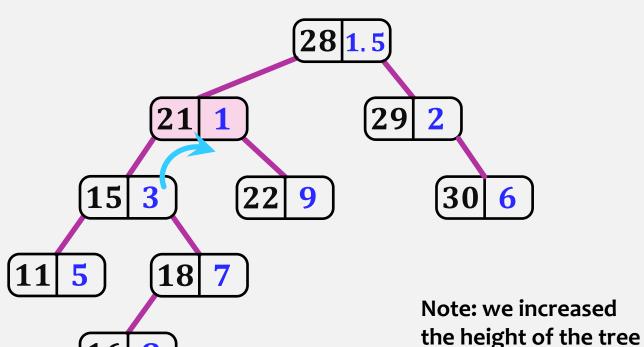
q. left. p>q. right. p

3 > 1.5

do **Left** Rotation

- Find node q that contains value x.
- If q is a leaf, then we can just detach q from its parent.
- If **q** is not a leaf, then rotate it down until it is a leaf; then detach.



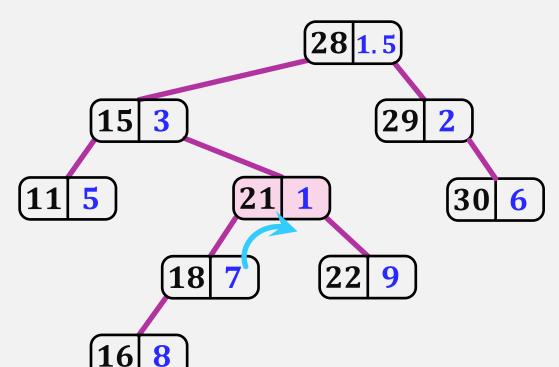


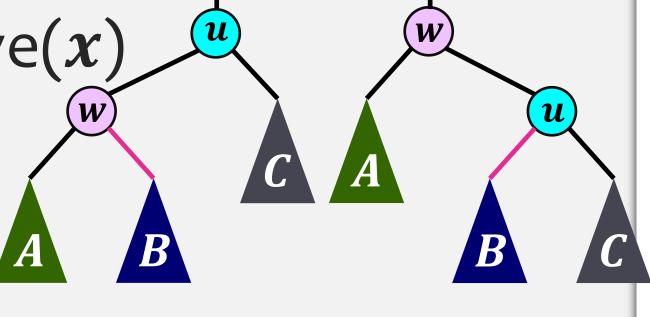
remove(21)

q. left. p < q. right. p

do **Right** Rotation

- Find node q that contains value x.
- If q is a leaf, then we can just detach q from its parent.
- If **q** is not a leaf, then rotate it down until it is a leaf; then detach.



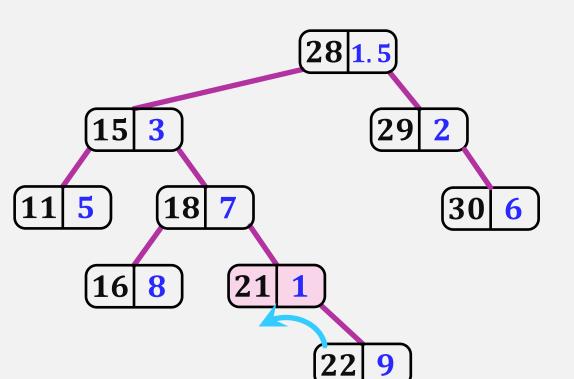


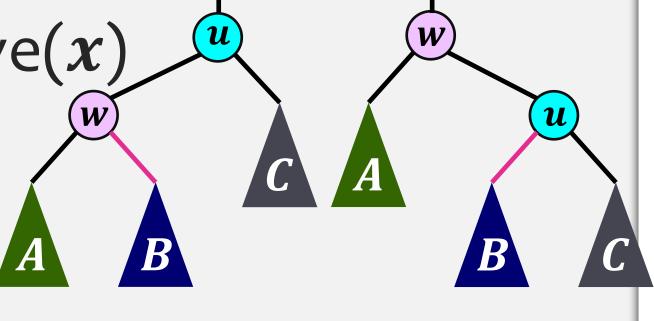
remove(21)

q. left. p < q. right. p

do **Right** Rotation

- Find node q that contains value x.
- If q is a leaf, then we can just detach q from its parent.
- If **q** is not a leaf, then rotate it down until it is a leaf; then detach.



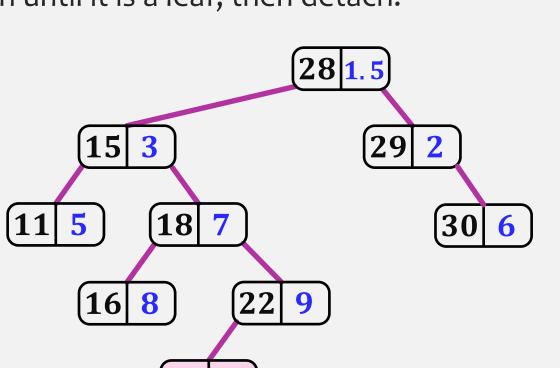


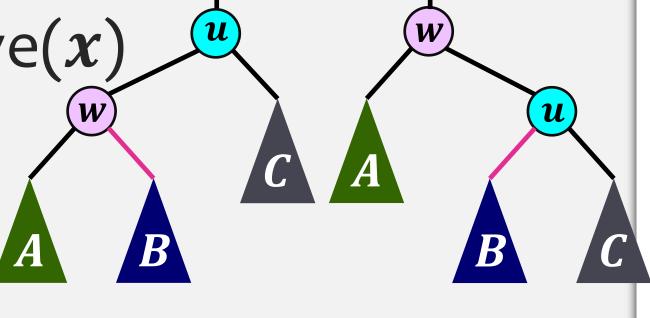
remove(21)

q. left = null

do Left Rotation

- Find node q that contains value x.
- If q is a leaf, then we can just detach q from its parent.
- If **q** is not a leaf, then rotate it down until it is a leaf; then detach.



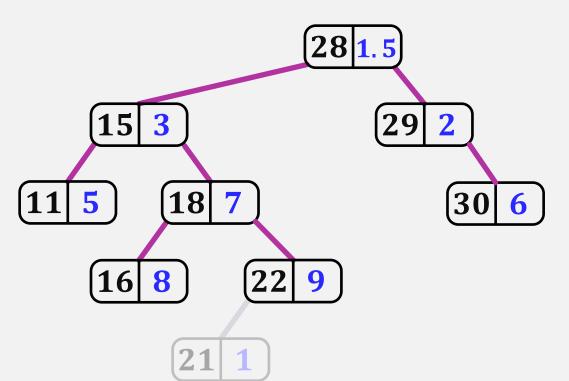


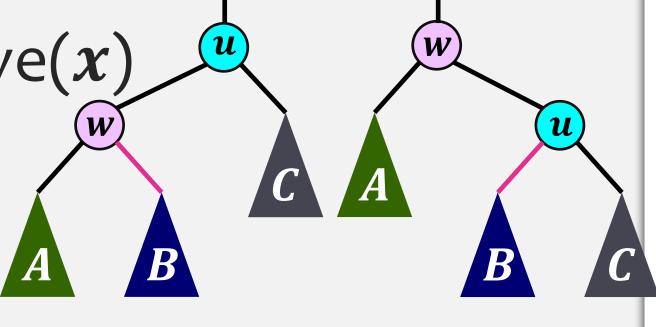
remove(21)

q. left = q. right = null

Remove the leaf 21

- Find node q that contains value x.
- If q is a leaf, then we can just detach q from its parent.
- If **q** is not a leaf, then rotate it down until it is a leaf; then detach.





remove(21)

- Find node q that contains value x.
- If **q** is a leaf, then we can just detach **q** from its parent.

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• If **q** is not a leaf, then rotate it down until it is a leaf; then detach.

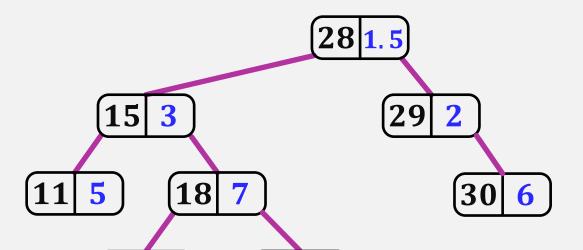
 $O(\log n)$

O(1)

 $O(\log n)$

What is the running time of remove(x) operation?

 $O(\log n)$ expected



Think about adding node 21|1

Each time we rotate we get further away from the root. That means that we can't rotate more times than the length of the longest path (which is n-1).

The time it takes to do a deletion on a tree with n nodes is equal to the time it takes to do an insertion on a tree with n-1 nodes.

Theorem 7.2

A **Treap** implements the **SSet** interface. A **Treap** supports the operations add(x), remove(x), and find(x) in $O(\log n)$ expected time per operation.

The search paths in a **Treap** are considerably shorter compared to **SkipLists** and this translates into noticeably faster operations.