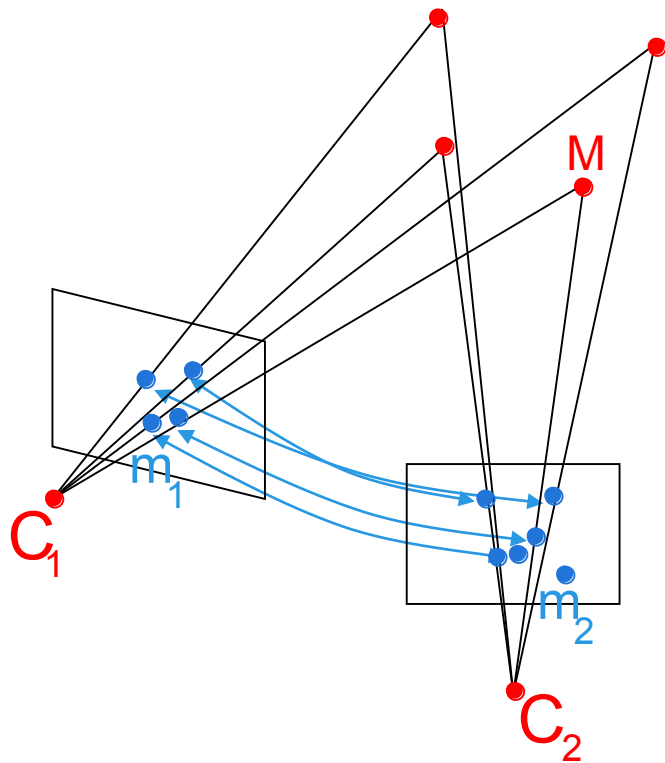
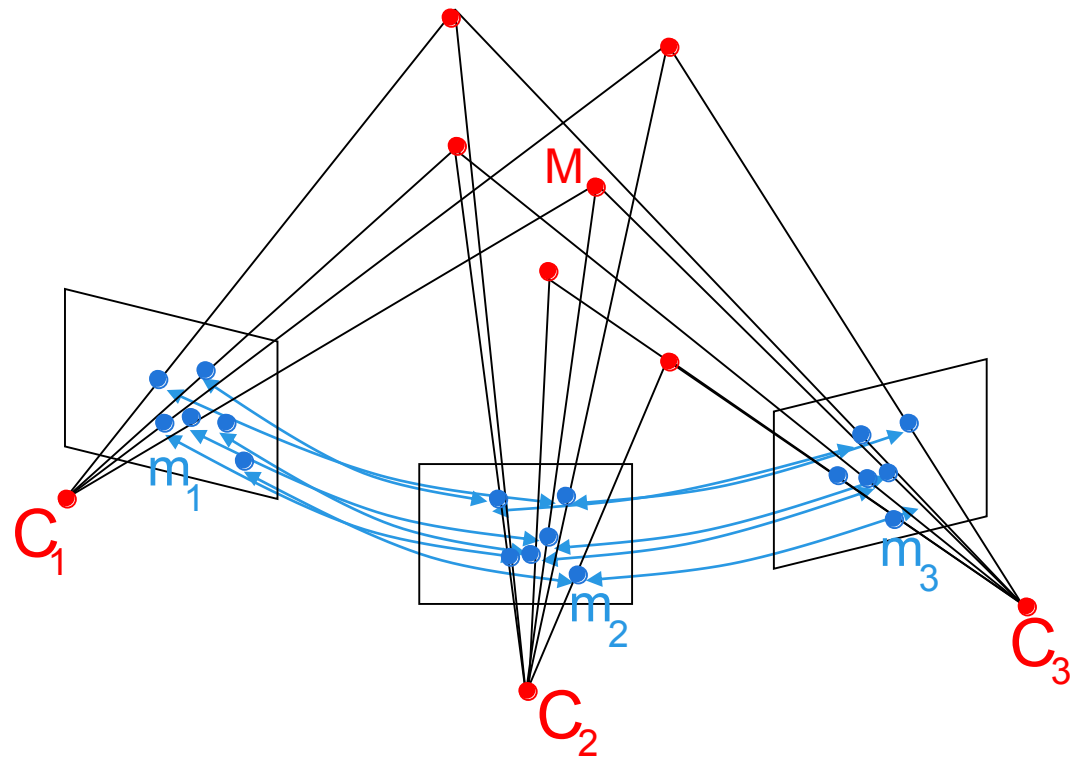


a) Setting first camera pose



b) Initial pair pose estimation



c) Other camera pose estimation
from 2D - 3D correspondences