

Calibration results

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Camera-system parameters:

cam0 (/cam0/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.EquidistantDistortedPinholeCameraGeometry'>

distortion: [-0.08905471 0.09964706 -0.23720039 0.19913317] +- [0.02318941 0.15521665 0.41248469 0.36734492]

projection: [249.30868162 249.19232446 171.5984604 138.95095951] +- [1.71281353 1.75183746 0.46466354 0.46479797]

reprojection error: [0.000001, 0.000001] +- [0.147088, 0.157025]

Target configuration

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Type: aprilgrid

Tags:

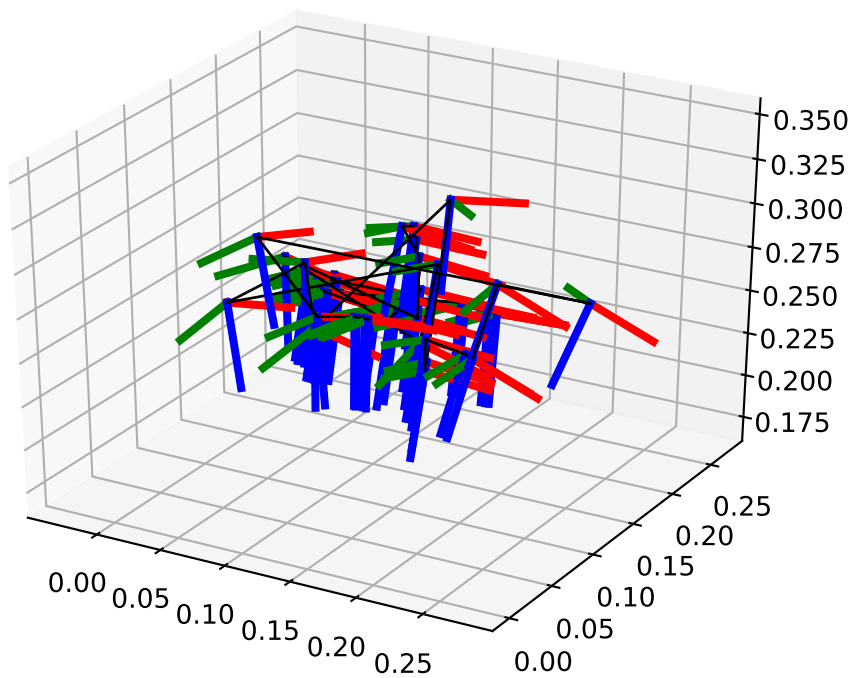
Rows: 6

Cols: 6

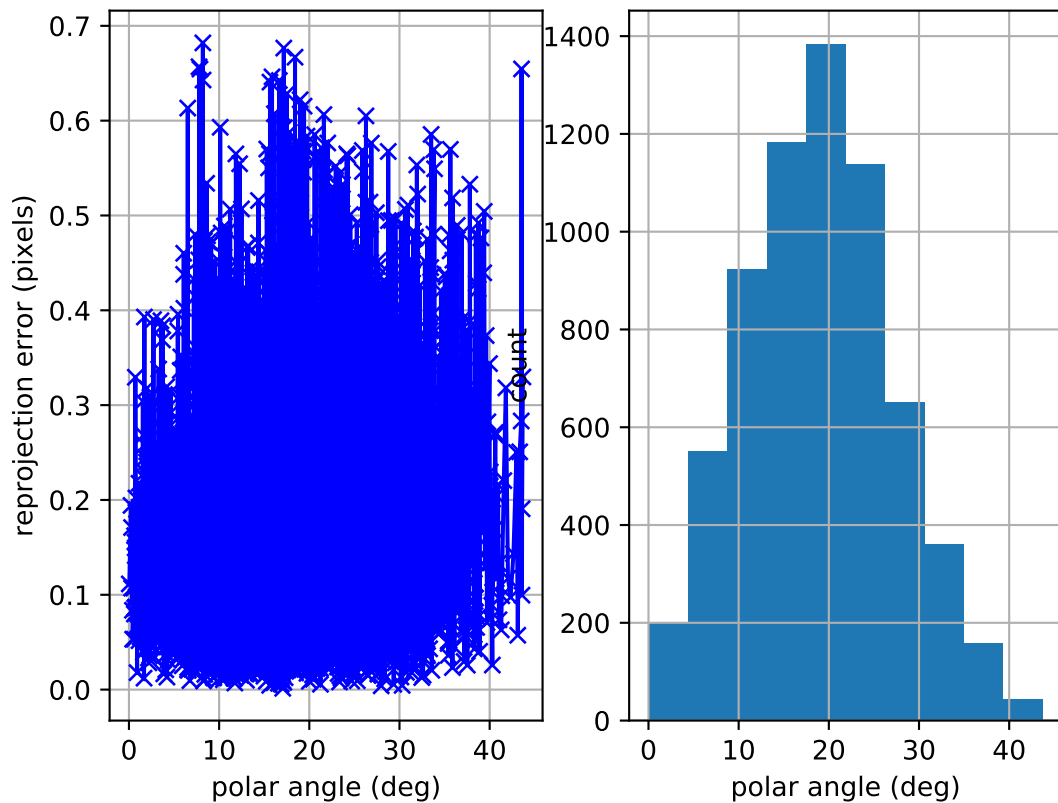
Size: 0.029 [m]

Spacing 0.0087 [m]

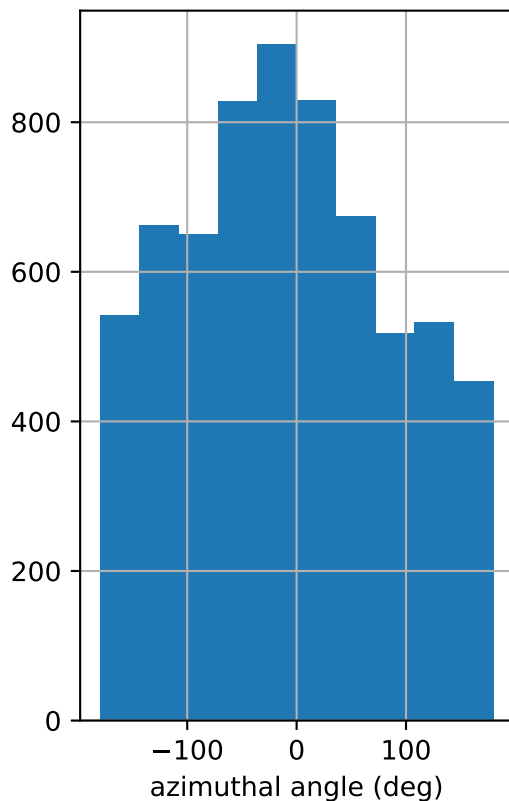
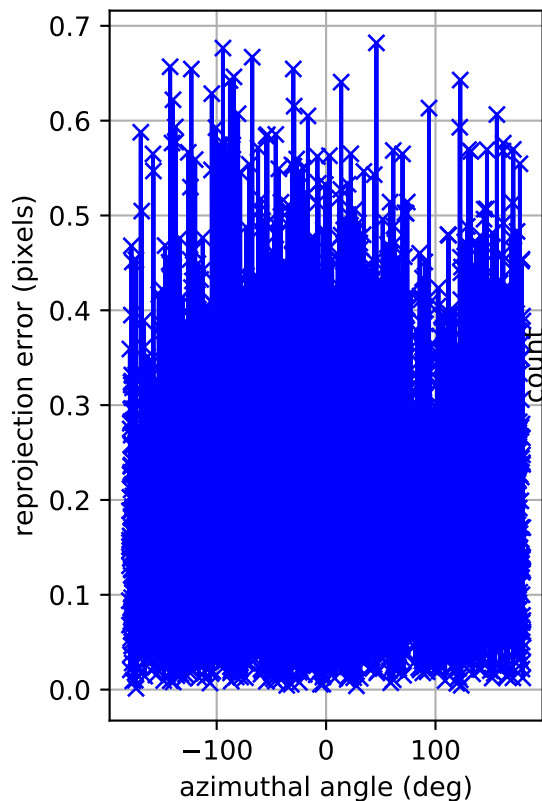
cam0: estimated poses



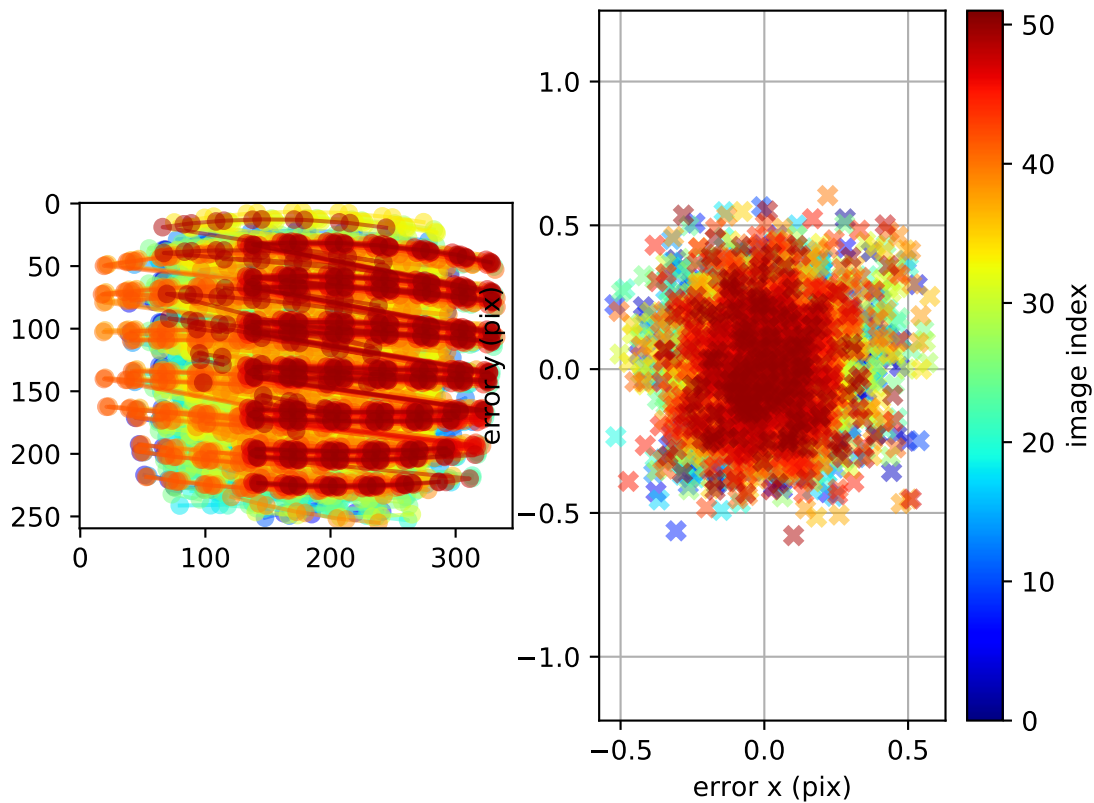
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

cam0

