

Technical Safety Concept Lane Assistance

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# Document history

**[Instructions: Fill in the date, version and description fields. You can fill out the Editor field with your name if you want to do so. Keep track of your editing as if this were a real world project.**

**For example, if this were your first draft or first submission, you might say version 1.0. If this is a second submission attempt, then you'd add a second line with a new date and version 2.0]**

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| 02/11/2018 | 1.0 | Anatolii Volkodav | Initial version |
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# Purpose of the Technical Safety Concept

**[Instructions: Answer what is the purpose of a technical safety concept?]**

Technical safety concept is document that defines the safety requirements of sensors, control unit, and actuators.

# Inputs to the Technical Safety Concept

## Functional Safety Requirements

**[Instructions: Provide the functional safety requirements derived in the functional safety concept ]**

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Functional Safety Requirement** | **ASIL** | **Fault Tolerant Time Interval** | **Safe State** |
| Functional  Safety  Requirement  01-01 | The lane keeping item shall ensure that the lane departure oscillating torque amplitude is below Max\_Torque\_Amplitude | C | 50 ms. | Amplitude set to 0 |
| Functional  Safety  Requirement  01-02 | The lane keeping item shall ensure that the lane departure oscillating torque frequency is below Max\_Torque\_Frequency | C | 50 ms. | Frequency set to 0 |
| Functional  Safety  Requirement  02-01 | The electronic power steering ECU shall ensure that the lane keeping assistance torque is applied for only Max\_Duration | B | 500 ms. | Lane Keeping Assistance (LKA) torque set to 0 |

## Refined System Architecture from Functional Safety Concept

**[Instructions: Provide the refined system architecture from the functional safety concept]**



### Functional overview of architecture elements

**[Instructions: Provide a description for each functional safety element; what is each element's purpose in the lane assistance item? ]**

|  |  |
| --- | --- |
| **Element** | **Description** |
| Camera Sensor | Make picture of the road and send it to Camera Sensor ECU |
| Camera Sensor ECU - Lane Sensing | Detecting lane lines and determining when the vehicle leaves the lane by mistake |
| Camera Sensor ECU - Torque request generator | Generate a torque request signal for the Electronic Power Steering (EPS) ECU |
| Car Display | Display status of Lane Keeping Assistance |
| Car Display ECU - Lane Assistance On/Off Status | Update display based on Lane Assistance On/Off Status |
| Car Display ECU - Lane Assistant Active/Inactive | Update display based on Lane Assistance Active/Inactive Status |
| Car Display ECU - Lane Assistance malfunction warning | Update display based on Lane Assistance malfunction warning |
| Driver Steering Torque Sensor | Measure the torque provided by the driver |
| Electronic Power Steering (EPS) ECU - Driver Steering Torque | Receives driver’s torque request from the steering wheels |
| EPS ECU - Normal Lane Assistance Functionality | Receives Camera Sensor ECU torque request |
| EPS ECU - Lane Departure Warning Safety Functionality | Ensure that the lane departure oscillating torque amplitude is below Max\_Torque\_Amplitude and torque frequency is below Max\_Torque\_Frequency |
| EPS ECU - Lane Keeping Assistant Safety Functionality | Ensure that the lane keeping assistance torque is applied for only Max\_Duration |
| EPS ECU - Final Torque | Combines torque request from Lane Departure Warning and Lane Keeping Assistant and issue result torque request to motor |
| Motor | Turns the steering wheel based on feedback from EPS ECU - Final Torque |

# Technical Safety Concept

## Technical Safety Requirements

**[Instructions: Fill in the technical safety requirements for the lane departure warning first functional safety requirement. We have provided the associated functional safety requirement in the first table below. Hint: The technical safety requirements were discussed in the lesson videos. The architecture allocation column should contain element names such as LDW Safety block, Data Transmission Integrity Check, etc. Allocating the technical safety requirements to the "EPS ECU" does not provide enough detail for a technical safety concept.]**

**Lane Departure Warning (LDW) Requirements:**

Functional Safety Requirement 01-01 with its associated system elements

(derived in the functional safety concept)

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Functional Safety Requirement** | **Electronic Power Steering ECU** | **Camera ECU** | **Car Display ECU** |
| Functional  Safety  Requirement  01-01 | The lane keeping item shall ensure that the lane departure oscillating torque amplitude is below Max\_Torque\_Amplitude | X |  |  |

Technical Safety Requirements related to Functional Safety Requirement 01-01 are:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **ID** | **Technical Safety Requirement** | **ASIL** | **Fault Tolerant Time Interval** | **Architecture Allocation** | **Safe State** |
| Technical  Safety  Requirement  01 | The LDW safety component shall ensure that the amplitude of the 'LDW\_Torque\_Request' sent to the 'Final electronic power steering Torque' component is below 'Max\_Torque\_Amplitude. | C | 50 ms. | LDW Safety Component | LDW torque set to 0 |
| Technical  Safety  Requirement  02 | As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light. | C | 50 ms. | LDW Safety Component | LDW torque set to 0 |
| Technical  Safety  Requirement  03 | As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the 'LDW\_Torque\_Request' shall be set to zero. | C | 50 ms. | LDW Safety Component | LDW torque set to 0 |
| Technical  Safety  Requirement  04 | The validity and integrity of the data transmission for 'LDW\_Torque\_Request' signal shall be ensured. | C | 50 ms. | Data Transmission Integrity Check (SW) | LDW torque set to 0 |
| Technical  Safety  Requirement  05 | Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory. | A | ignition cycle | Memory Test (SW) | LDW torque set to 0 |

**[Instructions: Fill in the technical safety requirements for the lane departure warning second functional safety requirement. We have provided the associated functional safety requirement in the table below. Hint:. Most of the technical safety requirements will be the same. At least one technical safety requirement will have to be slightly modified because we are talking about frequency instead of amplitude. These requirements were not given in the lessons]**

Functional Safety Requirement 01-2 with its associated system elements

(derived in the functional safety concept)

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Functional Safety Requirement** | **Electronic Power Steering ECU** | **Camera ECU** | **Car Display ECU** |
| Functional  Safety  Requirement  01-02 | The lane keeping item shall ensure that the lane departure oscillating torque frequency is below Max\_Torque\_Frequency | X |  |  |

Technical Safety Requirements related to Functional Safety Requirement 01-02 are:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **ID** | **Technical Safety Requirement** | **ASIL** | **Fault Tolerant Time Interval** | **Architecture Allocation** | **Safe State** |
| Technical  Safety  Requirement  01 | The LDW safety component shall ensure that the frequency of the 'LDW\_Torque\_Request' sent to the 'Final electronic power steering Torque' component is below 'Max\_Torque\_Frequency. | C | 50 ms. | LDW Safety Component | LDW torque set to 0 |
| Technical  Safety  Requirement  02 | As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light. | C | 50 ms. | LDW Safety Component | LDW torque set to 0 |
| Technical  Safety  Requirement  03 | As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the 'LDW\_Torque\_Request' shall be set to zero. | C | 50 ms. | LDW Safety Component | LDW torque set to 0 |
| Technical  Safety  Requirement  04 | The validity and integrity of the data transmission for 'LDW\_Torque\_Request' signal shall be ensured. | C | 50 ms. | Data Transmission Integrity Check (SW) | LDW torque set to 0 |
| Technical  Safety  Requirement  05 | Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory. | A | ignition cycle | Memory Test (SW) | LDW torque set to 0 |

**Lane Departure Warning (LDW) Verification and Validation Acceptance Criteria:**

**[OPTIONAL: For each technical safety requirement, identify both the verification and validation acceptance criteria. “Validation” asks whether or not you chose the appropriate parameters. “Verification” involves testing to make sure the vehicle behaves as expected when the parameter value is crossed. There is not necessarily one right answer. Look at your verification and validation acceptance criteria from the functional safety concept for inspiration.]**

**Lane Keeping Assistance (LKA) Requirements:**

**[Instructions: Fill in the technical safety requirements for the lane keeping assistance functional safety requirement 02-01. We have provided the associated functional safety requirement in the table below. Hint:. You can reuse the technical safety requirements from functional safety requirement 01-01. But you need to change the language because we are now looking at a different system. The ASIL and Fault Tolerant Time Interval are different as well.]**

Functional Safety Requirement 02-1 with its associated system elements

(derived in the functional safety concept)

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Functional Safety Requirement** | **Electronic Power Steering ECU** | **Camera ECU** | **Car Display ECU** |
| Functional  Safety  Requirement  02-01 | The lane keeping item shall ensure that the lane keeping assistance torque is applied for only Max\_Duration | X |  |  |

Technical Safety Requirements related to Functional Safety Requirement 02-01 are:

|  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- |
| **ID** | **Technical Safety Requirement** | **ASIL** | **Fault Tolerant Time Interval** | **Allocation to Architecture** | **Safe State** |
| Technical  Safety  Requirement  01 | The LKA shall ensure that the ‘lane keeping assistance torque’ sent to the ‘Final electronic power steering Torque’ component is applied for only ‘Max\_Duration’ | B | 500 ms. | LKA Safety Component | LKA torque set to 0 |
| Technical  Safety  Requirement  02 | As soon as the LKA function deactivates the LKA feature, the LKA Safety' software block shall send a signal to the car display ECU to turn on a warning light. | B | 500 ms. | LKA Safety Component | LKA torque set to 0 |
| Technical  Safety  Requirement  03 | As soon as a failure is detected by the LKA function, it shall deactivate the LKA feature. | B | 500 ms. | LKA Safety Component | LKA torque set to 0 |
| Technical  Safety  Requirement  04 | The validity and integrity of the data transmission for 'LKA\_Torque\_Request' signal shall be ensured. | B | 500 ms. | Data Transmission Integrity Check (SW) | LKA torque set to 0 |
| Technical  Safety  Requirement  05 | Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory. | A | ignition cycle | Memory Test (SW) | LKA torque set to 0 |

**Lane Keeping Assistance (LKA) Verification and Validation Acceptance Criteria:**

**[OPTIONAL: For each technical safety requirement, identify both the verification and validation acceptance criteria. “Validation” asks whether or not you chose the appropriate parameters. “Verification” involves testing to make sure the vehicle behaves as expected when the parameter value is crossed. There is not necessarily one right answer. Look at your verification and validation acceptance criteria from the functional safety concept for inspiration.]**

## Refinement of the System Architecture

**[Instructions: Include the refined system architecture. Hint: The refined system architecture should include the system architecture from the end of the technical safety lesson, including all of the ASIL labels.]**

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## Allocation of Technical Safety Requirements to Architecture Elements

**[Instructions: We already included the allocation as part of the technical requirement tables. Here you can state that for this particular item, all technical safety requirements are allocated to the Electronic Power Steering ECU]**

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Technical Safety Requirement** | **Electronic Power Steering ECU** | **Camera ECU** | **Car Display ECU** |
| Technical  Safety  Requirement  01-01 | The LDW safety component shall ensure that the amplitude of the 'LDW\_Torque\_Request' sent to the 'Final electronic power steering Torque' component is below 'Max\_Torque\_Amplitude. | X |  |  |
| Technical  Safety  Requirement  01-02 | As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light. | X |  |  |
| Technical  Safety  Requirement  01-03 | As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the 'LDW\_Torque\_Request' shall be set to zero. | X |  |  |
| Technical  Safety  Requirement  01-04 | The validity and integrity of the data transmission for 'LDW\_Torque\_Request' signal shall be ensured. | X |  |  |
| Technical  Safety  Requirement  01-05 | Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory. | X |  |  |
| Technical  Safety  Requirement  02-01 | The LDW safety component shall ensure that the frequency of the 'LDW\_Torque\_Request' sent to the 'Final electronic power steering Torque' component is below 'Max\_Torque\_Frequency. | X |  |  |
| Technical  Safety  Requirement  02-02 | As soon as the LDW function deactivates the LDW feature, the 'LDW Safety' software block shall send a signal to the car display ECU to turn on a warning light. | X |  |  |
| Technical  Safety  Requirement  02-03 | As soon as a failure is detected by the LDW function, it shall deactivate the LDW feature and the 'LDW\_Torque\_Request' shall be set to zero. | X |  |  |
| Technical  Safety  Requirement  02-04 | The validity and integrity of the data transmission for 'LDW\_Torque\_Request' signal shall be ensured. | X |  |  |
| Technical  Safety  Requirement  02-05 | Memory test shall be conducted at start up of the EPS ECU to check for any faults in memory. | X |  |  |

## Warning and Degradation Concept

**[Instructions: We've already identified that for any system malfunction, the lane assistance functions will be turned off and the driver will receive a warning light indication. The technical safety requirements have not changed how functionality will be degraded or what the warning will be.**

**So in this case, the warning and degradation concept is the same for the technical safety requirements as for the functional safety requirements. You can copy the functional safety warning and degradation concept here.**

**Oftentimes, a technical safety analysis will lead to a more detailed warning and degradation concept. ]**

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Degradation Mode** | **Trigger for Degradation Mode** | **Safe State invoked?** | **Driver Warning** |
| WDC-01 | Lane Departure Warning (LDW) turn off functionality | Malfunction\_01, Malfunction\_02 | YES | Lane Departure Warning status showed on car display |
| WDC-02 | Lane Keeping Assistance (LKA) turn off functionality | Malfunction\_03 | YES | Lane Keeping Assistance status showed on car display |