# Robot Arm

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# Declaration of Joint Authorship

The robotic arm project consist of three group members (Daniel Shelepinsky, Ali Khaliq and Matthew Gelfand) and is a joint effort on the completion of the project. The work for the project has been divided equally among the group members. Ali Khaliq and Matthew Gelfand has worked on the hardware aspect of the project; which includes connecting an Arduino with a Raspberry Pi, controlling the servo motors. Daniel Shelepinsky has worked on the design and functionality of the mobile application. Daniel Shelepinsky has worked on the database in terms of setting it up, connecting it with the app and maintaining it. Testing and maintenance for the hardware and software has been tested by all three members equally and all project updates and changes have been checked and approved by all members.

# Approved Proposal

September 2017 and reapproved January 2018

Prepared by Daniel Shelepinsky, Ali Khaliq and Matthew Galfand

## Executive Summary

As a student in the Computer Engineering Technology program, I will be integrating the knowledge and skills I have learned from our program into this Internet of Things themed capstone project. This proposal requests the approval to build the software app that will connect to a hardware as well as to a mobile device application. In the app, we will have incorporated a controller that will be used to control the hardware. The database will store the coordinates of the robot arm and the angles that the motor and arms need to be when it returns to rest position. The mobile device functionality will include some very basic test functions and commands to move the arm. It will create logs and save that data, so the developer can later look it at and make improvements to the hardware or software and other users can use these logs to reproduce experiments. In the winter semester I plan to form a group with the following students (Daniel Shelepinsky, Ali Khaliq and Matthew Galfand), who are in a different course. The hardware will be completed in CENG 317 Hardware Production Techniques independently and the application will be completed in CENG 319 Software Project. These will be integrated together in the subsequent term in CENG 355 Computer Systems Project as a member of a 3 student group.

# Abstract

The purpose of the Robot Arm project is to create a robot arm that has many purposes but for the main purpose would be an assembly line or sorting. The main components are servo motors, color sensor, mobile app, and the robotic arm will all be explained in great detail. The arm itself will be controlled by four analog feedback servo motors. One at the base of the arm to control left and right in a 180 ° Than two more for the arm itself to extend it and retract. The last motor controls the grip which will open and close it. Than all servo motors will report back to the database their positions. Which the user can edit through the mobile application. The arm itself is made out of acrylic parts. It will be connected to a Raspberry Pi 3 and an Arduino. The Pi being handling all software aspects of the project and the Arduino handling the PWM. The main focus of this technical report is to give the users a full understanding of the project and how it came to be.

# Table of contents

Declaration of Joint Authorship

Proposal

Abstract

Illustrations or Diagrams

1. Introduction
2. Project Description
   1. Requirements specifications
      * 2.1.1 Mobile Application Concept
      * 2.1.2 Project Schedule
      * 2.1.3 Application Screen
      * 2.1.4 Hardware Interfaces
      * 2.1.5 Software Interfaces
      * 2.1.6 Communication Interfaces
   2. Build Instructions
      * 2.2.1 Introduction
      * 2.2.2 Bill of Materials/Budget
      * 2.2.3 Time Commitment
      * 2.2.4 Mechanical Assembly
      * 2.2.5 Power Up
      * 2.2.6 Unit Testing
   3. Specific Requirements
      * 2.3.1 Database
      * 2.3.2 Application
      * 2.3.3 Hardware
   4. Progress Reports
   5. Problem Encountered
      * 2.5.1 Hardware Problems
      * 2.5.2 Software Problems
3. Conclusion
4. Appendix
5. Reference

# Introduction

Our hands can only do the same task over and over without stopping to take a break. A robot arm when programmed and built correctly can fix this issue and allow the user to repeat the same task over and over and does not need to stop for breaks like a human arm does. If any injuries were to happen on the job. It would happen to the robot arm and not the human/user which would mean reduced work place injuries where the arm can be applied to. The arm itself is cheap and easy to setup and replace parts if the arm does break down. This would mean production in a company would not fall as much as if a human would got injured. The arm can be automated or controlled from a distance with a mobile application which would again leave the user free of harm.

The Arm consists of four motors and a color sensor. The four motors will control the arms and movement going from left to right and extension/retraction. The color sensor is used to detect objects by color and can be programmed to ignore certain objects or pick them up and sort them depending on what the user wishes the arm to do. If the user does not like to use a mobile application or automation they can use buttons/controller that will move the arm if they so prefer.

# Project Description 2

## Requirements specifications 2.1

### Mobile application Concept 2.1.1

The Concept for the mobile application is to control the Robot arm from afar with either a phone, iPad, computer etc. The application will allow the user to move and report positions of the arm and possibly debugging if the arm ever gets in trouble/stuck. The application also includes a database which stores information about the arm and positions/ presets the user sets for it. The database currently in use is firebase.