

# ECON 703 - PS 5

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9/16/2020

- (1) In this exercise you will prove the following theorem. Suppose  $X$  and  $Y$  are normed vector spaces and  $T \in L(X, Y)$ . The inverse function  $T^{-1}(\cdot)$  exists and is a continuous linear operator on  $T(X)$  if and only if there exists some  $m > 0$  such that  $m\|x\| \leq \|T(x)\|$  for all  $x \in X$ .
- (a) Show that if there exists some  $m > 0$  such that  $m\|x\| \leq \|T(x)\|$ , then  $T$  is one-to-one (and therefore invertible on  $T(X)$ ). Hint: Think about the norm of elements which are glued together if  $T$  is not one-to-one.

Proof: A theorem on slide 11 of lecture 8 states that  $T \in L(X, Y)$  is one-to-one iff  $\ker T \equiv \{\bar{0}\}$ . Consider  $x \in \ker\{T\}$ ,  $m\|x\| \leq \|T(x)\| \implies m\|x\| \leq 0$ . Since  $m > 0$ ,  $\|x\| = 0$  because norms cannot be negative. By definition of a norm,  $\|x\| = 0 \iff x = \bar{0}$ . Thus,  $T$  is one-to-one.  $\square$

- (b) Use theorem with five equivalent properties (various continuity notions and boundedness) from the lecture notes to show that  $T^{-1}(\cdot)$  is continuous on  $T(X)$ .

Proof: By (a),  $T$  is invertible. Thus, for all  $x \in X$ ,  $m\|x\| \leq \|T(x)\| \implies \|T^{-1}(y)\| \leq m^{-1}\|y\|$  where  $y = T(x) \in T(X)$ . Thus, because  $m > 0 \implies m^{-1} \in \mathbb{R}$ ,  $T^{-1}$  is bounded on  $T(X)$ . By a theorem on slide 5 of lecture 11,  $T^{-1}$  is continuous on  $T(X)$ .  $\square$

- (c) Use the same theorem from the lecture notes to show that if  $T^{-1}$  is continuous on  $T(X)$ , then there exists some  $m > 0$  such that  $m\|x\| \leq \|T(x)\|$ .

Proof: If  $T^{-1}$  is continuous on  $T(X)$ , then  $T^{-1}$  is bounded on  $T(X)$ . Thus, we can choose  $\beta$  such that  $\|T^{-1}(y)\| \leq \beta\|y\| \forall y \in T(X)$ . Note that, since norms are nonnegative, we can choose  $\beta > 0$ , so  $\beta^{-1}$  is positive and finite. Thus,  $\beta^{-1}\|x\| \leq \|T(x)\|$  where  $x = T^{-1}(y) \in X$ . Define  $m = \beta^{-1}$ , so  $m\|x\| \leq \|T(x)\|$  for  $m > 0$ .  $\square$

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\*I worked on this problem set with a study group of Michael Nattinger, Andrew Smith, and Ryan Mather. I also discussed problems with Emily Case, Sarah Bass, and Danny Edgel.

(2) Consider a linear operator  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by  $T(x, y) = (x + 5y, 8x + 7y)$ .

(a) Calculate  $\|T\|$  given the norm  $\|(x, y)\|_1 = |x| + |y|$  in  $\mathbb{R}^2$ .

By the theorem on slide 5 of lecture 11, since  $\dim \mathbb{R}^2 = 2$ ,  $T$  is bounded. So,

$$\|T\| = \sup_{\|(x, y)\|_1=1} \{\|T(x, y)\|_1\}$$

Since  $|x|, |y| \geq 0$ , we can assume that  $x, y \geq 0$  without loss of generality. Further, we can rewrite  $y = 1 - x$ , so

$$\begin{aligned}\|T\| &= \sup_{x \in [0, 1]} \{|x + 5(1 - x)| + |8x + 7(1 - x)|\} \\ &= \sup_{x \in [0, 1]} \{|5 - 4x| + |x + 7|\} \\ &= 5 + 7 \\ &= 12\end{aligned}$$

(b) Calculate  $\|T\|$  given the norm  $\|(x, y)\|_\infty = \max\{|x|, |y|\}$  in  $\mathbb{R}^2$ .

By the theorem on slide 5 of lecture 11, since  $\dim \mathbb{R}^2 = 2$ ,  $T$  is bounded. So,

$$\|T\| = \sup_{\|(x, y)\|_\infty=1} \{\|T(x, y)\|_\infty\}$$

Define  $X = \{(x, y) \in \mathbb{R}^2 : \|(x, y)\|_\infty = 1\} = \{(1, w), (x, 1), (-1, y), (-1, z) : w, x, y, z \in [-1, 1]\}$ . Since the linear transformation is increasing in  $x, y$ , it is maximized at  $(1, 1)$ . Thus,  $\|T\| = \sup\{X\} = \max\{6, 15\} = 15$ .

- (3) Consider the standard basis in  $\mathbb{R}^2$ ,  $W$ , and another orthonormal basis  $V = \{(a_1, a_2), (b_1, b_2)\}$  (written in coordinates of  $W$ ). Prove that Euclidean norm (length) of any vector  $(x, y) \in \mathbb{R}^2$  is the same in  $W$  and  $V$ . (Thus, length of a vector does not depend on a choice of orthonormal basis.) Reminder: Orthonormal basis means that  $a_1^2 + a_2^2 = b_1^2 + b_2^2 = 1, a_1b_1 + a_2b_2 = 0$ .

Proof: Define  $M = \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix}$ . Consider  $(x, y)'$  in the standard basis for  $\mathbb{R}^2$ . There exists  $(w, z)' \in \mathbb{R}^2$  such that

$$\begin{aligned} \begin{pmatrix} x \\ y \end{pmatrix} &= M \begin{pmatrix} w \\ z \end{pmatrix} \\ &= \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix} \begin{pmatrix} w \\ z \end{pmatrix} \\ &= \begin{pmatrix} wa_1 + zb_1 \\ wa_2 + zb_2 \end{pmatrix} \\ &= w \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} + z \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \end{aligned}$$

Thus,  $(w, z)'$  represent  $(x, y)'$  in basis  $V = \{(a_1, a_2), (b_1, b_2)\}$ . Notice that  $M'M = I$ :

$$\begin{aligned} \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix}' \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix} &= \begin{pmatrix} a_1 & a_2 \\ b_1 & b_2 \end{pmatrix} \begin{pmatrix} a_1 & b_1 \\ a_2 & b_2 \end{pmatrix} \\ &= \begin{pmatrix} a_1^2 + a_2^2 & a_1b_1 + a_2b_2 \\ a_1b_1 + a_2b_2 & b_1^2 + b_2^2 \end{pmatrix} \\ &= \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \\ &= I \end{aligned}$$

Thus, we can show the Euclidean norms of  $(w, z)'$  and  $(x, y)'$  are equal:

$$\begin{aligned} \|(x, y)'\| &= \sqrt{(x, y)'(x, y)} \\ &= \sqrt{M(w, z)'\overline{M(w, z)'}} \\ &= \sqrt{(w, z)M'M(w, z)'} \\ &= \sqrt{(w, z)(w, z)'} \\ &= \sqrt{(w, z)'(w, z)} \\ &= \|(w, z)'\| \end{aligned}$$

□

- (4) In this exercise you will learn to solve first order linear differential equations in  $n$  variables. We want to find an  $n$ -dimensional process  $y(t)$ , such that

$$\frac{d}{dt}y(t) = Ay(t) \quad (1)$$

where  $A \in M_{n \times n}$  and  $y(0) \in \mathbb{R}^n$  are given. When  $n = 1$  we know that solution to Eq. (1) is  $y(t) = e^{At}y(0)$ . Turns out, it remains the same when  $n > 1$ , thus, it involves exponent of a matrix, which we have not defined before. To properly define  $e^{At}$ ,  $A \in M_{n \times n}$  we use Taylor expansion and say that

$$e^{At} = I + At + \frac{1}{2}A^2t^2 + \frac{1}{6}A^3t^3 + \dots = \sum_{k=0}^{\infty} \frac{1}{k!}A^k t^k.$$

To calculate  $e^{At}$  we will use diagonalization. Suppose that  $A = P \text{diag}\{\lambda_1, \dots, \lambda_n\} P^{-1}$ , so that  $A^k = P \text{diag}\{\lambda_1^k, \dots, \lambda_n^k\} P^{-1}$  and

$$\begin{aligned} e^{At} &= P \left( \sum_{k=0}^{\infty} \frac{1}{k!} \text{diag}\{t^k \lambda_1^k, \dots, t^k \lambda_n^k\} \right) P^{-1} \\ &= P \left( \text{diag}\left\{ \sum_{k=0}^{\infty} \frac{1}{k!} t^k \lambda_1^k, \dots, \sum_{k=0}^{\infty} \frac{1}{k!} t^k \lambda_n^k \right\} \right) P^{-1} \\ &= P \text{diag}\{e^{t\lambda_1}, \dots, e^{t\lambda_n}\} P^{-1} \end{aligned}$$

Thus, solution to Eq. (1) is

$$y(t) = P \text{diag}\{e^{t\lambda_1}, \dots, e^{t\lambda_n}\} P^{-1} y(0) \quad (2)$$

Implement the above approach to solve for  $y(t) \in \mathbb{R}^2$

$$\frac{d}{dt}y(t) = \begin{pmatrix} 1 & 1 \\ 3 & -1 \end{pmatrix} y(t), y(0) = \begin{pmatrix} 1 \\ 3 \end{pmatrix}.$$

Simplify your answer as much as possible.

To find  $A$ 's eigenvalues, use the characteristic polynomial of  $A$ :

$$\begin{aligned}(1 - \lambda)(-1 - \lambda) - 1 * 3 &= \lambda^2 - 4 \\ &= (\lambda - 2)(\lambda + 2)\end{aligned}$$

The eigenvalues are  $\lambda_1 = 2$  and  $\lambda_2 = -2$ . The corresponding eigenvectors are:

$$\begin{aligned}\begin{pmatrix} -1 & 1 \\ 3 & -3 \end{pmatrix} \mathbf{v}_1 &= 0 \\ \mathbf{v}_1 &= \begin{pmatrix} 1 \\ 1 \end{pmatrix} \\ \begin{pmatrix} 3 & 1 \\ 3 & 1 \end{pmatrix} \mathbf{v}_2 &= 0 \\ \mathbf{v}_2 &= \begin{pmatrix} -1 \\ 3 \end{pmatrix}\end{aligned}$$

We have  $P$  and  $P^{-1}$ .

$$\begin{aligned}P &= \begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix} \\ P^{-1} &= \begin{pmatrix} 3/4 & 1/4 \\ -1/4 & 1/4 \end{pmatrix}\end{aligned}$$

Substituting into Eq. 2,

$$\begin{aligned}y(t) &= P \text{diag}\{e^{t\lambda_1}, \dots, e^{t\lambda_n}\} P^{-1} y(0) \\ &= \begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} e^{2t} & 0 \\ 0 & e^{-2t} \end{pmatrix} \begin{pmatrix} 3/4 & 1/4 \\ -1/4 & 1/4 \end{pmatrix} \begin{pmatrix} 1 \\ 3 \end{pmatrix} \\ &= \begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} e^{2t} & 0 \\ 0 & e^{-2t} \end{pmatrix} \begin{pmatrix} 3/2 \\ 1/2 \end{pmatrix} \\ &= \begin{pmatrix} 1 & -1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} (3/2)e^{2t} \\ (1/2)e^{-2t} \end{pmatrix} \\ &= \begin{pmatrix} (3/2)e^{2t} - (1/2)e^{-2t} \\ (3/2)e^{2t} + (1/2)e^{-2t} \end{pmatrix}\end{aligned}$$

Here's R code that implements this approach as well.

```
library(matlib)
a <- matrix(c(1, 3, 1, -1), ncol = 2)
print(a)

##      [,1] [,2]
## [1,]    1    1
## [2,]    3   -1

ev <- eigen(a)
p <- t(t(ev$vectors))
print(p)

##      [,1]      [,2]
## [1,] 0.7071068 -0.3162278
## [2,] 0.7071068  0.9486833

y_0 <- c(1, 3)
for (t in 0:5) {
  print(paste("For t =", t))
  print(p %*% diag(exp(t*ev$values)) %*% inv(p) %*% y_0)
}

## [1] "For t = 0"
##      [,1]
## [1,]    1
## [2,]    3
## [1] "For t = 1"
##      [,1]
## [1,] 11.01592
## [2,] 11.28659
## [1] "For t = 2"
##      [,1]
## [1,] 81.88807
## [2,] 81.92470
## [1] "For t = 3"
##      [,1]
## [1,] 605.1419
## [2,] 605.1469
## [1] "For t = 4"
##      [,1]
## [1,] 4471.437
## [2,] 4471.437
## [1] "For t = 5"
##      [,1]
## [1,] 33039.7
## [2,] 33039.7
```

- (5) Solution to different equation (1) is stable if small perturbation of the initial condition  $y(0)$  does not significantly change the solution  $y(t)$ . Formally, it means that  $\forall \varepsilon > 0$  there exists  $\delta > 0$  such that if  $\|y(0) - \tilde{y}(0)\| < \delta$ , then  $\|y(t) - \tilde{y}(t)\| < \varepsilon$ , where  $\tilde{y}(t)$  is the solution with initial condition  $\tilde{y}(0)$ . Notice that if one of the eigenvalues  $\lambda_i$  is positive (has positive real part if they are complex), then the solution will have a term  $c(y(0))e^{\lambda_i t}$ ,  $\lambda_i > 0$  where  $c(\cdot)$  is a constant which depends on the initial condition. Hence,  $\|y(t) - \tilde{y}(t)\| \geq |c(y(0)) - c(\tilde{y}(0))|e^{\lambda_i t} \rightarrow \infty$  as  $t \rightarrow \infty$ . Thus, the solution is not stable. In contrast, if all eigenvalues are negative (have negative real part if they are complex), then for all  $i = 1, \dots, n$ ,  $e^{\lambda_i t} \rightarrow 0$  as  $t \rightarrow \infty$ , and solutions do not diverge, i.e. are stable. Check whether your solution to Problem 4 is stable.

My solution to Problem 4 is not stable because  $\lambda_1 = 2 > 0$ .