

ECON 703 - PS 5

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- (1) In this exercise you will prove the following theorem. Suppose X and Y are normed vector spaces and $T \in L(X, Y)$. The inverse function $T^{-1}(\cdot)$ exists and is a continuous linear operator on $T(X)$ if and only if there exists some $m > 0$ such that $m\|x\| \leq \|T(x)\|$ for all $x \in X$.
 - (a) Show that if there exists some $m > 0$ such that $m\|x\| \leq \|T(x)\|$, then T is one-to-one (and therefore invertible on $T(X)$). Hint: Think about the norm of elements which are glued together if T is not one-to-one.
 - (b) Use theorem with five equivalent properties (various continuity notions and boundedness) from the lecture notes to show that $T^{-1}(\cdot)$ is continuous on $T(X)$.
 - (c) Use the same theorem from the lecture notes to show that if T^{-1} is continuous on $T(X)$, then there exists some $m > 0$ such that $m\|x\| \leq \|T(x)\|$.
- (2) Consider a linear operator $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(x, y) = (x + 5y, 8x + 7y)$.
 - (a) Calculate $\|T\|$ given the norm $\|(x, y)\|_1 = |x| + |y|$ in \mathbb{R}^2 .
 - (b) Calculate $\|T\|$ given the norm $\|(x, y)\|_\infty = \max\{|x|, |y|\}$ in \mathbb{R}^2 .
- (3) Consider the standard basis in \mathbb{R}^2 , W , and another orthonormal basis $V = \{(a_1, a_2), (b_1, b_2)\}$ (written in coordinates of W). Prove that Euclidean norm (length) of any vector $(x, y) \in \mathbb{R}^2$ is the same in W and V . (Thus, length of a vector does not depend on a choice of orthonormal basis.) Reminder: Orthonormal basis means that $a_1^2 + a_2^2 = b_1^2 + b_2^2 = 1, a_1b_1 + a_2b_2 = 0$.
- (4) In this exercise you will learn to solve first order linear differential equations in n variables. We want to find an n -dimensional process $y(t)$, such that

$$\frac{d}{dt}y(t) = Ay(t) \tag{1}$$

where $A \in M_{n \times n}$ and $y(0) \in \mathbb{R}^n$ are given. When $n = 1$ we know that solution to Eq. (1) is $y(t) = e^{At}y(0)$. Turns out, it remains the same when $n > 1$, thus, it involves exponent of a matrix, which we have not defined before. To properly define e^{At} , $A \in M_{n \times n}$ we use Taylor expansion and say that

$$e^{At} = I + A + \frac{1}{2}A^2t^2 + \frac{1}{6}A^3t^3 + \dots = \sum_{k=0}^{\infty} \frac{1}{k!}A^k t^k.$$

To calculate e^{At} we will use diagonalization. Suppose that $A = P \text{diag}\{\lambda_1, \dots, \lambda_n\} P^{-1}$, so that $A^k = P \text{diag}\{\lambda_1^k, \dots, \lambda_n^k\} P^{-1}$ and

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$$e^{At} = P \left(\sum_{k=0}^{\infty} \frac{1}{k!} \text{diag}\{t^k \lambda_1^k, \dots, t^k \lambda_n^k\} \right) P^{-1} = P \left(\text{diag}\left\{ \sum_{k=0}^{\infty} \frac{1}{k!} t^k \lambda_1^k, \dots, \sum_{k=0}^{\infty} \frac{1}{k!} t^k \lambda_n^k \right\} \right) P^{-1} = P \text{diag}\{e^{t\lambda_1}, \dots, e^{t\lambda_n}\} P^{-1} \quad (2)$$

Thus, solution to Eq. 1 is

$$y(t) = P \text{diag}\{e^{t\lambda_1}, \dots, e^{t\lambda_n}\} P^{-1} y(0)$$

Implement the above approach to solve for $y(t) \in \mathbb{R}^2$

$$\frac{d}{dt}y(t) = \begin{pmatrix} 1 & 1 \\ 3 & -1 \end{pmatrix} y(t), y(0) = \begin{pmatrix} 1 \\ 3 \end{pmatrix}.$$

Simplify your answer as much as possible.

- (5) Solution to differential equation (1) is stable if small perturbation of the initial condition $y(0)$ does not significantly change the solution $y(t)$. Formally, it means that $\forall \varepsilon > 0$ there exists $\delta > 0$ such that if $\|y(0) - \tilde{y}(0)\| < \delta$, then $\|y(t) - \tilde{y}(t)\| < \varepsilon$, where $\tilde{y}(t)$ is the solution with initial condition $\tilde{y}(0)$. Notice that if one of the eigenvalues λ_i is positive (has positive real part if they are complex), then the solution will have a term $c(y(0))e^{\lambda_i t}$, $\lambda_i > 0$ where $c(\cdot)$ is a constant which depends on the initial condition. Hence, $\|y(t) - \tilde{y}(t)\| \geq |c(y(0)) - c(\tilde{y}(0))|e^{\lambda_i t} \rightarrow \infty$ as $t \rightarrow \infty$. Thus, the solution is not stable. In contrast, if all eigenvalues are negative (have negative real part if they are complex), then for all $i = 1, \dots, n$, $e^{\lambda_i t} \rightarrow 0$ as $t \rightarrow \infty$, and solutions do not diverge, i.e. are stable. Check whether your solution to Problem 4 is stable.