

ECON 736A: Problem Set 3

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1 Atkeson, Chari, and Kehoe (2007)

1. Prove Propositions 2 and 3.

Proposition 2 (Determinacy of Equilibrium and the Taylor Principle). *The linear equilibria with interest rate rules of the Taylor rule form $i_t = \bar{i} + ax_t$ have outcomes of the form*

$$\begin{aligned}x_{t+1} &= i_t + c\eta_t \\ \pi_t &= x_t + (1 + \sigma c)\eta_t \\ y_t &= (1 + \sigma c)\eta_t\end{aligned}$$

For every $a < 1$ and \bar{i} , the economy has a continuum of equilibria indexed by the parameter c . For every $a \geq 1$ and \bar{i} , within the class of bounded linear equilibria, the economy has a unique equilibrium with $c = 0$.

Proof: First, verify that the candidate equilibrium satisfies the equilibrium conditions in the lemma:

$$\begin{aligned}E[y_t|h_{t-1}] &= E[(1 + \sigma c)\eta_t|h_{t-1}] \\ &= (1 + \sigma c)E[\eta_t|h_{t-1}] \\ &= 0 \\ E[\pi_{t+1}|h_{t-1}] &= E[x_{t+1} + (1 + \sigma c)\eta_{t+1}|h_{t-1}] \\ &= E[i_t + c\eta_t|h_{t-1}] + (1 + \sigma c)E[\eta_{t+1}|h_{t-1}] \\ &= i_t + cE[\eta_t|h_{t-1}] \\ &= i_t\end{aligned}$$

Second, verify that the candidate equilibrium satisfies the Phillips curve and the Euler equa-

tion:

$$\begin{aligned}
y_t &= \pi_t - x_t \\
\Rightarrow [(1 + \sigma c)\eta_t] &= [x_t + (1 + \sigma c)\eta_t] - x_t \\
\Rightarrow (1 + \sigma c)\eta_t &= (1 + \sigma c)\eta_t \\
y_t &= E[y_{t+1}|h_t] - \sigma(i_t - E[\pi_{t+1}|h_t]) + \eta_t \\
\Rightarrow (1 + \sigma c)\eta_t &= -\sigma(i_t - E[\pi_{t+1}|h_t]) + \eta_t \\
&= -\sigma(i_t - E[x_{t+1} + (1 + \sigma c)\eta_{t+1}|h_t]) + \eta_t \\
&= -\sigma(i_t - E[x_{t+1}|h_t]) + \eta_t \\
&= -\sigma(i_t - E[i_t + c\eta_t|h_t]) + \eta_t \\
&= -\sigma(-c\eta_t) + \eta_t \\
&= (1 + \sigma c)\eta_t
\end{aligned}$$

Finally, we can derive a first order difference equation for x using lemma, the Taylor rule, and agent optimize and representativeness $x_t(h_{t-1}) = z_t(h_{t-1}) = E[\pi_t|h_{t-1}]$:

$$\begin{aligned}
E[\pi_{t+1}|h_{t-1}] &= i_t \\
&= \bar{i} + ax_t(h_{t-1}) \\
\Rightarrow x_{t+1}(h_t) &= \bar{i} + ax_t(h_{t-1})
\end{aligned}$$

A solution to the first order difference equation for x is

$$x_t = a^{(t-s)} \left(x_s - \frac{\bar{i}}{1-a} \right) + \frac{\bar{i}}{1-a}$$

for some $s < t$. For an equilibrium to exist, x_t must not diverge. If $a < 1$, $x_t \rightarrow \frac{\bar{i}}{1-a}$, so for any c , an equilibrium exists. If $a > 1$, for x_t not to diverge, the following must hold:

$$x_s - \frac{\bar{i}}{1-a} = 0$$

for all s . Thus, $x_{s+1} = x_s$, so

$$\begin{aligned}
x_{s+1} &= \bar{i} + ax_{s+1} \\
&= \bar{i} + ax_s \\
&= i_s \\
\Rightarrow c &= 0
\end{aligned}$$

Proposition 3 (Rules Satisfying the Taylor Principle are Inefficient). *The outcomes under a Taylor rule of the form $i_t = \bar{i} + ax_t$ with $a > 1$ are dominated by the outcomes of an equilibrium with $a = 0$ and $\bar{i} = 0$.*

Proof: By Proposition 2, the outcome under the Taylor rule of the form $i_t = \bar{i} + ax_t$ with $a > 1$ is unique:

$$\begin{aligned}x_{t+1} &= i_t = \frac{\bar{i}}{1-a} \\ \pi_t &= x_t + \eta_t \\ y_t &= \eta_t\end{aligned}$$

Thus, representative agent expected payoff is

$$\begin{aligned}E\left[r^A\left(\frac{\bar{i}}{1-a}, \frac{\bar{i}}{1-a}, \frac{\bar{i}}{1-a} + \eta_t\right)\right] &= -\frac{1}{2}E\left[\left(\frac{\bar{i}}{1-a} - \left(\frac{\bar{i}}{1-a} + \eta_t\right)\right)^2 + (\eta_t - \bar{y})^2 + \left(\frac{\bar{i}}{1-a} + \eta_t\right)^2\right] \\ &= -\frac{1}{2}E\left[\eta_t^2 + (\eta_t^2 - 2\bar{y}\eta_t + \bar{y}^2) + \left(\frac{\bar{i}}{1-a}\right)^2 + 2\frac{\bar{i}}{1-a}\eta_t + \eta_t^2\right] \\ &= -\frac{1}{2}\left[2E[\eta_t^2] - 2\bar{y}E[\eta_t] + \bar{y}^2 + \left(\frac{\bar{i}}{1-a}\right)^2 + 2\left(\frac{\bar{i}}{1-a}\right)E[\eta_t] + E[\eta_t^2]\right] \\ &= -\frac{1}{2}\left[3\sigma_\eta^2 + \bar{y}^2 + \left(\frac{\bar{i}}{1-a}\right)^2\right]\end{aligned}$$

If $\bar{i} = a = 0$, then $i_t = 0$, but the equilibrium is not unique and for every c , the following is an equilibrium. Thus, there is an equilibrium for $c = 0$ where

$$\begin{aligned}x_{t+1} &= 0 \\ \pi_t &= \eta_t \\ y_t &= \eta_t\end{aligned}$$

And the representative agent expected payoff in that equilibrium is:

$$\begin{aligned}E[r^A(0, 0, \eta_t)] &= -\frac{1}{2}E[\eta_t^2 + (\eta_t - \bar{y})^2 + \eta_t^2] \\ &= -\frac{1}{2}\left[E[\eta_t^2] + E[\eta_t^2] - 2\bar{y}E[\eta_t] + \bar{y}^2 + E[\eta_t^2]\right] \\ &= -\frac{1}{2}\left[3\sigma_\eta^2 + \bar{y}^2\right]\end{aligned}$$

The equilibrium associated Taylor principle is not optimal, if there exists a c such that the representative agent is better off:

$$\begin{aligned}
E[r^A(0, 0, \eta_t)] &> E\left[r^A\left(\frac{\bar{t}}{1-a}, \frac{\bar{t}}{1-a}, \frac{\bar{t}}{1-a} + \eta_t\right)\right] \\
\iff -\frac{1}{2}\left[3\sigma_\eta^2 + \bar{y}^2\right] &> -\frac{1}{2}\left[3\sigma_\eta^2 + \bar{y}^2 + \left(\frac{\bar{t}}{1-a}\right)^2\right] \\
&\iff 0 < \left(\frac{\bar{t}}{1-a}\right)^2
\end{aligned}$$

Which holds for $a > 1$ and $\bar{t} > 0$.

2. *Consider a slight extension of the environment we saw in class. There, we assumed that the agents did not observe the money growth rate but only observed the inflation rate (which was a noisy signal of the money growth rate). Now suppose that in addition to observing the inflation, agents observe the true money growth rate choice but with a lag. In particular, suppose that μ_{t-1} is observable in period t after wages are chosen. Is transparency valuable in this case? More specifically, prove the analog of Proposition 6 in the paper for this environment.*