

Alex von Haffken
March 10, 2021

ECON 710 A EXAM

① (a) ~~Consider moment condition~~
 ~~$Cov(Z, \frac{Y - \beta_0}{X\beta}) = 0$~~

Follow method of moment like of argument.

① Independence of Z implies:

$$\cancel{E[Zu]} = \cancel{E[Z]E[u]} = \cancel{E[Z]E[u]}$$

$$Cov(Z, u) = 0.$$

$$\textcircled{2} \text{ Use } U = \frac{Y - \beta_0}{X\beta}$$

$$\begin{aligned} Cov(Z, Y/X\beta) &= Cov\left(Z, \frac{\beta_0 + X\beta U}{X\beta}\right) \\ &= Cov\left(Z, \frac{\beta_0}{X\beta}\right) \end{aligned}$$

$$\begin{aligned} &+ Cov\left(Z, \frac{\beta_1}{\beta} U\right) \\ &= \frac{\beta_0}{\beta} Cov\left(Z, \frac{1}{X}\right) + \frac{\beta_1}{\beta} Cov(Z, u) \\ &= \frac{\beta_0}{\beta} Cov\left(Z, \frac{1}{X}\right) \end{aligned}$$

~~if $\beta_1 = \beta$, then the moment condition is 0~~

True, I'm having trouble coming up w/ a moment condition that is zero when $\beta_1 = \beta$.

① (b) $\hat{\Theta} = \{\hat{\theta}(h) : h \in H\}$ be set of unbiased parameters for θ_0 .

Let $h^* \in H$ be $\text{Var}(\hat{\theta}(h^*)) \leq \text{Var}(\hat{\theta}(h)) \quad \forall h \in H$.

\Rightarrow For some $h \in H$,

$$\text{Var}(\hat{\theta}(h)) = \text{Var}(\hat{\theta}(h^*)) + X \quad \text{where } X > 0$$

...

\Leftarrow For an arbitrary $h \in H$

$$\begin{aligned} \hat{\theta}(h) &= \hat{\theta}(h^*) + Z(h) && \text{where } Z(h) \text{ is mean zero} \\ \Rightarrow \text{Var}(\hat{\theta}(h)) &= \text{Var}(\hat{\theta}(h^*) + Z(h)) && \text{\& uncorrelated} \\ &= \text{Var}(\hat{\theta}(h^*)) + \text{Var}(Z(h)) && \text{w/ } \hat{\theta}(h^*) \end{aligned}$$

~~True~~ ~~False~~ $\text{Var}(Z(h)) \geq 0$, so $\hat{\theta}(h^*)$ has weakly smaller variance than any $\hat{\theta}(h) \in \hat{\Theta}$.

False, I'm struggling to see why $\hat{\theta}(h)$ can't have a higher variance than $\hat{\theta}(h^*)$ is such a way that is correlated w/ $\text{Var}(\hat{\theta}(h^*))$.

Note that

- (2) (a) IID random variables are strictly stationary and functions (that do not depend on t) of strictly stationary random variables are strictly stationary.

$\{U_t, Z_t^*, X_t\}_{t=0}^T$ are iid. RVs, thus

~~$\{X_t\}_{t=0}^T$ is strictly stationary~~

they are all strictly stationary.

$\{Y_t\}_{t=0}^T$ is a function of $\{X_t\}_{t=0}^T$ and $\{U_t\}_{t=0}^T$, thus $\{Y_t\}_{t=0}^T$ is strictly stationary.

$\{Z_t\}_{t=0}^T$ is a function of $\{Z_t^*\}_{t=0}^T$ and $\{U_t\}_{t=0}^T$. Thus $\{Z_t\}_{t=0}^T$ is strictly stationary.

②(b) Since $\{u_t\}_{t=0}^T$ is iid, $E[u_t | z_t, u_{t-1}]$
 $= E[u_t | z_t]$. Thus

$$E[u_t | z_t] = E[u_t | z_t, u_{t-1}]$$

$$= E[u_t | z_t^*]$$

$$= 0.$$

②(c) No, ~~because~~ because z_{t+1} is a function of u_t .

$$\begin{aligned} & E[u_t | z_1, \dots, z_T] \\ &= E\left[\frac{z_{t+1} - z_{t+1}^*}{\gamma} \mid z_1, \dots, z_T\right] \\ &= \frac{z_{t+1}}{\gamma} - \frac{E[z_{t+1}^* | z_1, \dots, z_T]}{\gamma} \end{aligned}$$

$$\textcircled{2} \textcircled{d) } E[Z_t (Y_t - X_t \beta)]$$

$$= E[Z_t (X_t \beta_1 + u_t - X_t \beta)]$$

$$= \beta_1 E[Z_t X_t] + E[Z_t u_t] - \beta E[Z_t X_t]$$

"
 0 from (b)

$$= (\beta_1 - \beta) E[Z_t X_t] = 0$$

$$\text{If } \beta = \beta_1 \Rightarrow (\beta - \beta) E[Z_t X_t] = 0.$$

The moment function identifies β_1 iff

$$\beta = \beta_1 \Leftrightarrow E[Z_t (Y_t - X_t \beta)] = 0$$

Thus, we need $E[Z_t X_t] \neq 0$.

$$E[Z_t X_t] = E[(Z_t^* + \gamma u_{t-1}) X_t]$$

$$= E[Z_t^* X_t] + \gamma E[u_{t-1} X_t]$$

$[\{u_t\} \text{ and } \{X_t\} \text{ are independent}]$

$$= E[Z_t^* X_t] + \gamma E[E[u_{t-1} | Z^*]] E[X_t]$$

$$= E[Z_t^* X_t] \quad \text{" } 0$$

Thus, we need $E[Z_t^* X_t] \neq 0$. That is we need relevance for identification.

$$(2)(e) E[S | H_0 \text{ is true}]$$

$$= E\left[T^{-1/2} \sum_{t=1}^T W_t \mid \beta_1 = c\right]$$

$$= E\left[T^{-1/2} \sum_{t=1}^T Z_t (Y_t - X_t c) \mid \beta_1 = c\right]$$

$$= E\left[T^{-1/2} \sum_{t=1}^T Z_t [X_t \beta_1 + u_t - X_t c] \mid \beta_1 = c\right]$$

$$= E\left[T^{-1/2} \sum_{t=1}^T Z_t u_t\right]$$

$$= T^{-1/2} \sum_{t=1}^T E[Z_t u_t]$$

$$= T^{-1/2} \sum_{t=1}^T E[Z_t E[u_t | Z_t]]$$

"
0

$$= 0$$

Bound RVs
mean we can
apply LIE

$$\text{Var}(S | H_0 \text{ is true})$$

$$= E[S^2 | \beta_1 = c] - [E[S | \beta_1 = c]]^2$$

"
0

$$= E[S^2 | \beta_1 = c]$$

$$= E\left[\left(T^{-1/2} \sum_{t=1}^T Z_t (Y_t - X_t c)\right)^2 \mid \beta_1 = c\right]$$

$$= T^{-1} E\left[\left(\sum_{t=1}^T Z_t u_t\right)^2\right]$$

$$= T^{-1} E\left[\sum_{t=1}^T Z_t^2 u_t^2 + \sum_{t \neq s} Z_t Z_s u_t u_s\right]$$

$$= T^{-1} \sum_{t=1}^T E[Z_t^2 u_t^2]$$

$$= E[Z_t^2 u_t^2]$$

"
0, because u_t is iid
and applies LIE
w/ part (b)

(2) (e) cont

$$\text{Var}(S \mid H_0 \text{ is true}) = E[z_t^2 u_t^2]$$

$$= E[(z_t^* + \gamma u_{t-1})^2 u_t^2]$$

$$= E[(z_t^*)^2 + 2\gamma z_t^* u_{t-1} + \gamma^2 u_{t-1}^2] u_t^2]$$

$$= E[(z_t^*)^2 u_t^2] + \gamma E[z_t^* u_{t-1} u_t^2]$$

$[z_t^*, u_t \text{ are iid}]$

$$+ \gamma^2 E[u_{t-1}^2 u_t^2]$$

$$= E[(z_t^*)^2] E[u_t^2]$$

$$+ \gamma E[z_t^*] E[E[u_{t-1} | z_t^*]] E[u_t^2]$$

$$+ \gamma^2 E[u_{t-1}^2] E[u_t^2]$$

$$= E[(z_t^*)^2] E[u_t^2] + \gamma^2 [E[u_t^2]]^2$$

$$\left[\text{Let } \sigma_u^2 = \text{Var}(u_t) = E[u_t^2] \right]$$

$$= E[(z_t^*)^2] \sigma_u^2 + \gamma^2 \sigma_u^4$$

② (f) ~~Relevance~~

From (e), we have $V = E[(Z_x^*)^2] \sigma_u^2 + \gamma^2 \sigma_u^4$

~~replace population moments w/ sample moments~~

~~or~~

~~use the~~

We can estimate $\hat{\beta}_1^{IV} = \frac{\frac{1}{T} \sum_{t=0}^T Z_t Y_t}{\frac{1}{T} \sum_{t=0}^T Z_t X_t}$ based

on strict stationarity, ~~no~~ contemporaneous exogeneity, and relevance: $\hat{\beta}_1^{IV} \xrightarrow{p} \beta_1$. Thus,

$$\Rightarrow \hat{u}_t = Y_t - \hat{\beta}_1^{IV} X_t \rightarrow u_t$$

It seems difficult to estimate γ , but we can use an earlier equation in (e) to get an estimator of V :

$$V = E[u_t^2 Z_t^2]$$

$$\hat{V} = \frac{1}{T} \sum_{t=0}^T \hat{u}_t^2 Z_t^2$$

[Moment
exist, because
vectors are
bounded]

$\{\hat{u}_t\}$ and $\{Z_t\}$ are i.i.d, so based on the standard LLN:

$$\hat{V} = \frac{1}{T} \sum_{t=0}^T \hat{u}_t^2 Z_t^2 \rightarrow E[\hat{u}_t^2 Z_t^2] = V$$

When H_0 holds.

② (g) From (e), we have

$$S = T^{-1/2} \sum_{t=0}^T Z_t U_t$$

~~$$= T^{-1/2} \sum_{t=0}^T (Z_t^* + \gamma U_{t-1}) U_t$$~~

* Note that Z_t and U_t are strictly stationary,
so $Z_t U_t$ is strictly stationary.

* $E[Z_t^2 U_t^2] < \infty$ because the vectors are bounded.

$$* E[Z_t U_t | Z_{t-1}, U_{t-1}, \dots, Z_0, U_0]$$

$$= E[Z_t^* U_t | Z_{t-1}, U_{t-1}, \dots, Z_0, U_0]$$

$$+ \gamma [U_{t-1} U_t | Z_{t-1}, U_{t-1}, \dots, Z_0, U_0]$$

$$= 0.$$

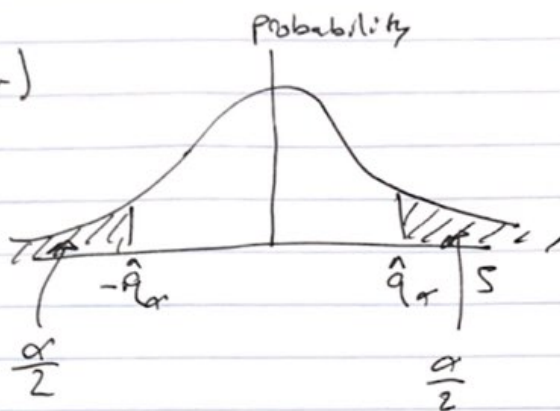
* By (f), $\frac{1}{T} \sum Z_t^2 U_t^2 \rightarrow E[Z_t^2 U_t^2],$

By the Martingale CLT

$$T^{-1/2} \sum_{t=0}^T Z_t U_t \xrightarrow{d} N(0, E(Z_t^2 U_t^2)) \\ = N(0, V).$$

②(4) Since S is asymptotically normal,
we can use standard normal cdfs.

$$P(|S| > \hat{q}_\alpha)$$



Let Φ be the CDF of a standard normal

$$\text{Thus } \hat{q}_\alpha = \Phi\left(1 - \frac{\alpha}{2}\right).$$