Knot Theory Basics

victoria

January 7, 2025

1 Elementary Knot Moves

Elementary knot moves are reversible changes to the shape of a knot made by modifying its edges.

1.1 Operations:

- (1) Place a point C on an edge AB, dividing it into two edges AC and CB
- (1)' If AC and CB are adjacent edges such that removing C results in a straight line AB, then C may be erased, restoring the edge AB
- (2) For a point C that doesn't lie on the knot K, if the triangle $\triangle ABC$, formed by AB and C, does not intersect K (except at AB), then replace AB with two new edges AC and CB
- (2)' If $\triangle ABC$ contains two adjacent edges AC and CB, and this triangle does not intersect K (except at AC and CB), then AC and CB may be removed and replaced with AB

These four operations (1), (1)', (2), (2)' are called *elementary knot moves*.

Note: Typically, only (2) and (2)' are referred to as elementary knot moves, as they involve actual transformations or "moves." Operations (1) and (1)' are adjustments to the knot structure and are thus not considered moves in the usual sense.

2 The Equivalence of Knots

Knots that can be changed from one to the other by applying elementary knot moves are said to be *equivalent*. Two knots are equivalent if we can alter one continuously, without causing any self-intersections, until it is transformed into the other knot.

2.1 Homeomorphisms

Let f be a bijective map from a topological space X to a topological space Y. Let f^{-1} be the inverse map $f^{-1}: Y \to X$. When both f and f^{-1} are continuous maps, then the map f is a homeomorphism.

When X and Y have orientations assigned to them, we say f is an orientation-preserving homeomorphism if the original orientation of Y agrees with the orientation on Y.

A homeomorphism from X to itself is called an *auto-homeomorphism*.

2.1.1 Examples

Let X and Y be \mathbb{R}^2 . The parallel translation along a line, given by $(x,y) \mapsto (x+a,y+b)$, and a rotation about some fixed point are examples of orientation-preserving auto-homeomorphisms, as shown in the figure below.

However, the mirror image with respect to the x-axis, given by the homeomorphism f(x,y)=(x,-y), is not an orientation-preserving autohomeomorphism. In fact, the orientation is reversed, as illustrated in the figure below.

Thus, we can say two knots K_1 and K_2 are *equivalent* if there exists an orientation-preserving homeomorphism of \mathbb{R}^3 that maps K_1 to K_2 .

Since there exists a one-to-one correspondence between the 2-dimensional sphere \mathbb{S}^2 , excluding the North Pole, N, and the etire plane, \mathbb{R}^2 , $\mathbb{R}^2 \cup \{\infty\}$ and \mathbb{S}^2 are homeomorphic as shown below.

Similarly, the 3-dimensional sphere \mathbb{S}^3 is often thought of as $\mathbb{R}^3 \cup \{\infty\}$. Thus, we can think of a knot lying in \mathbb{S}^3 rather than in \mathbb{R}^3 as long as the knot K does not contain the point at infinity. Therefore, if two equivalent knots K_1 and K_2 lie in \mathbb{S}^3 , then their complements $\mathbb{S}^3 - K_1$ and $\mathbb{S}^3 - K_2$ are homeomorphic.

3 Links

A link is a finite, ordered collection of knots that do not intersect each other. Each knot K_i is called a *component* of the link.

Two links $L = \{K_1, K_2, \dots, K_m\}$ and $L' = \{K'_1, K'_2, \dots, K'_n\}$ are equivalent if:

- 1. m = n (L and L' have the same number of components)
- 2. There exists an auto-homeomorphism, φ such that $\varphi(K_1 \cup \ldots \cup K_m) = K'_1 \cup \ldots \cup K'_m$ preserves the orientation of \mathbb{R}^3 .

In this book, we will primarily use condition (2A) rather than condition (2). If each component of the link is oriented, then the definitions of equivalence extend naturally from the case of knots.

Alternate Equivalence Condition

Two links L and L' are equivalent if we can transform L into L' by performing elementary knot moves a finite number of times. More precisely, using elementary knot moves, we can transform K_1 to K'_1 , K_2 to K'_2 , ..., K_m to K'_m (with m=n). It is important to emphasize that the triangle involved in a given elementary knot move must not intersect any of the other components.