

AM- GM inequality

summarizes the sample with single representative which is centre of data. (measure of location)

$$X = (x_1, x_2, \dots, x_n)$$

$$Y = (f(x_1), f(x_2), \dots, f(x_n))$$

$$\sum_{i=1}^n L(X_i; \theta)$$



$$\hat{\theta}(X)$$

estimator
which we get
by minim
loss fun.



$$\hat{\theta}(Y)$$

we ~~can~~ hope

$$\hat{\theta}(Y) = f(\hat{\theta}(X))$$

Summary statistics that have this property (for monotone transformation) are known as transformation-invariant, (or equivariant).

Arithmetic Mean \rightarrow Generally not ~~in~~ equivariant.

Median \rightarrow ~~is~~ equivariant.

Exercise: For affine transformations of the type f

$f(x) = a + bx$, $b \neq 0$, the AM is invariant.

Although AM is not transformation equivariant, we can say something useful for convex and concave transformations.

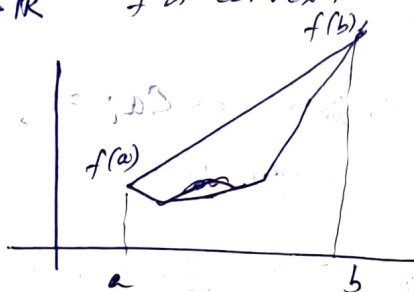
$$f: \mathbb{R} \rightarrow \mathbb{R}$$

f is convex.

if

$t f(a) + (1-t) f(b) > f(ta + (1-t)b)$
(parametric form
or linear
combination)

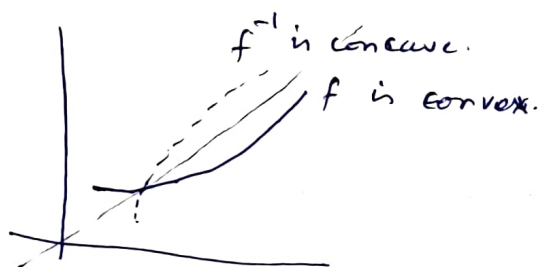
$f(ta + (1-t)b)$ $\left\{ \begin{array}{l} \text{Power} \\ \text{function} \\ \text{is concave} \\ \text{convex trans} \end{array} \right.$



for any $\lambda_1, \lambda_2 \in (0,1)$ s.t. $\lambda_1 + \lambda_2 = 1$.

$$f(\lambda_1 x_1 + \lambda_2 x_2) \leq \lambda_1 f(x_1) + \lambda_2 f(x_2)$$

$\forall x_1, x_2 \in \text{dom}(f)$.



Jensen's Inequality : For a real convex function ϕ , numbers $x_1, x_2, x_3, \dots, x_n$ in its domain, and positive weights ~~$x_1, x_2, x_3, \dots, x_n$~~ a_1, a_2, \dots, a_n such that $\sum_{i=1}^n a_i = 1$, we have

$$\phi \left(\sum_{i=1}^n a_i x_i \right) \leq \sum a_i \phi(x_i)$$

Similarly, $\phi \left(\sum a_i x_i \right) \geq \sum a_i \phi(x_i)$

Let's prove by induction for ϕ convex.

$n=2$: We want to show: for $a_1, a_2 \geq 0$ s.t. $a_1 + a_2 = 1$,

$$\phi \left(\sum_{i=1}^2 a_i x_i \right) \leq \sum_{i=1}^2 a_i \phi(x_i)$$

$$\phi(a_1 x_1 + a_2 x_2) \leq a_1 \phi(x_1) + a_2 \phi(x_2).$$

holds by definition of convexity.

say

for $n = m$ this is also true;

for any $a_1, a_2, \dots, a_n \geq 0$ s.t. $\sum a_i = 1$,

$$\phi \left(\sum a_i x_i \right) \leq \sum a_i \phi(x_i)$$

For $n = m+1$: Given, $a_1, a_2, \dots, a_{m+1} \geq 0$, $\sum_{i=1}^{m+1} a_i = 1$,

To show,
$$\phi \left(\sum_{i=1}^{m+1} a_i x_i \right) \leq \sum_{i=1}^{m+1} a_i \phi(x_i)$$

$$\begin{aligned}
 \phi \left(\sum_{i=1}^{m+1} a_i x_i \right) &= \phi \left(a_{m+1} x_{m+1} + (1-a_{m+1}) \left(\frac{\sum_{i=1}^m a_i x_i}{1-a_{m+1}} \right) \right) \\
 &\leq a_{m+1} \phi(x_{m+1}) + (1-a_{m+1}) \phi \left(\sum_{i=1}^m \lambda_i x_i \right) \\
 &\leq \dots + (1-a_{m+1}) \sum_{i=1}^m \frac{a_i}{(1-a_{m+1})} \phi(x_i) \quad \text{let } \lambda_i = \frac{a_i}{1-a_{m+1}}, \\
 &\hspace{15em} i=1, 2, \dots, m.
 \end{aligned}$$

This inequality allows us to compare any power transformation.

Exercise: Show that for a vector of positive observations, the GM is larger (or ~~equality~~ equal) to the HM.

Q. Can we extend location ~~estimators~~ or location statistics to higher dimensions?

We can be interested in bivariate data, say $(x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$.
 $(x_i, y_i) \rightarrow$ measurement from the same observational unit. \therefore

Loss function: $L \left(\begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} \theta_x \\ \theta_y \end{pmatrix} \right)$

\downarrow \downarrow
 Vectors location
 in data in x - y plane
 in x - y plane



$$= (x - \theta_x)^2 + (y - \theta_y)^2$$

$$\begin{aligned}
 d \left(\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \right) \\
 = \sqrt{(x_1 - y_1)^2 + (x_2 - y_2)^2}
 \end{aligned}$$

We want to minimize:

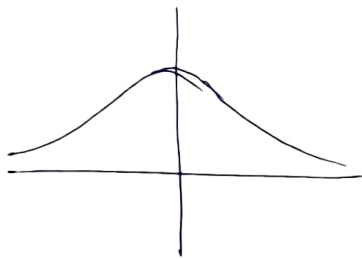
$$\begin{aligned}
 \lambda \begin{pmatrix} \theta_x \\ \theta_y \end{pmatrix} &= \sum_{i=1}^n (x_i - \theta_x)^2 + \sum_{i=1}^n (y_i - \theta_y)^2 \\
 \therefore \hat{\theta}_x &= \bar{x}_i, \hat{\theta}_y = \bar{y}_i \quad \begin{pmatrix} \hat{\theta}_x \\ \hat{\theta}_y \end{pmatrix} = \begin{pmatrix} \bar{x}_i \\ \bar{y}_i \end{pmatrix}
 \end{aligned}$$

If we have absolute errors:

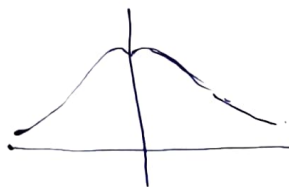
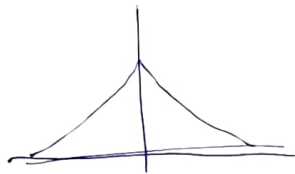
$$L\left(\begin{pmatrix} x \\ y \end{pmatrix}, \begin{pmatrix} \theta_x \\ \theta_y \end{pmatrix}\right) = \sqrt{(x - \theta_x)^2 + (y - \theta_y)^2}$$

$$\lambda(\theta_x, \theta_y) = \sum_{i=1}^n \sqrt{(x_i - \theta_x)^2 + (y_i - \theta_y)^2} \quad \rightarrow \text{not always differentiable}$$

↳ needs to be computed numerically.



We are now from now on think of statistics as estimators.



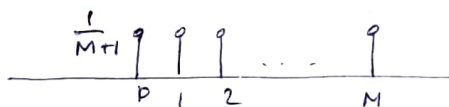
As we get more and more data ~~we can~~ our estimator will get closer to population estimator.

Median is more robust than mean but, not that efficient.

Location parameters } mean, median.
Scaling parameters } For now we consider these two.

Higher the scale parameter higher the spread.

Model 1:



$$Y \sim \text{Disc. Unif}(\{ \frac{0}{M}, \frac{1}{M}, \frac{2}{M}, \dots, \frac{M}{M} \})$$

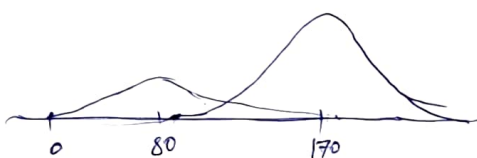
pt. of symmetry is 0.5.

There is some parameter θ which we want to estimate.

$$\text{mean}(T(X_1, X_2, \dots, X_n) - \theta)^2 = \text{MSE}(T)$$

↓
distribution.

$$r_{\text{dist}} \leftarrow \text{function}(n) \quad 5 + 3^{*}t(n, df=5)$$



$$170 \times \frac{99}{100} + 80 \times \frac{1}{100} = \text{population mean.}$$