# JaeSung Ahn

- ♠ https://voyagerahn.github.io
- **o** github.com/voyagerahn

#### **EDUCATION**

**Seoul National University of Science and Techonology** Mar 2020 – Aug 2022 *B.S.* in Mechanical System Design Engineering (Advisor: Prof. Chibum Lee)

#### **EXPERIENCE**

**Korea Institute of Sience and Technology (KIST)**, Seoul, Korea Sep 2021 - Present *Undergraduate Student Researcher* (Advisor: Ph.D. Yisoo Lee)

- Implemented Quadratic Programming(QP) force-based control framework for 12DOF quadruped robot
- Initiated research project that used reinforcement learning to control how robots would move like real animals and react in challenging environments

## HONORS AND AWARDS

# **Merit-based Scholarship**

2018 - 2019

#### **Undergraudate Conference Award**

12/01/2018

#### **Outstanding Design Award**

01/11/2020

Awarded by The Hong Kong University of Science and Technology (HKUST), Sungkyunkwan University (SKKU)

#### 2021 SRC IRC Intelligent Robot

10/30/2021

4<sup>th</sup> place, Awarded by Dean of Engineering

#### **EXTRACURRICULAR ACTIVITIES**

## Member of Robotics Research Club 'Thot', SeoulTech

Feb 2020 – Sep 2020

Undergraduate Student (Advisor: Prof. Donghwan Kim)

- Designed, fabricated, tested robots(e.g. drones, manipulator)
- Contributed to Deep learning based Bin Picking & Inserting project that used fully convolutional model for real-time image segmentation

## Colloquium

Kakao Brain, 07/19/2021

- Self-supervised Representation Learning with Contrastive Loss

# PROFESSIONAL TRAINING

**Nvidia Certification**, Nvidia Deep Learning Institute, 12/02/2021 Fundamentals of Deep Learning

# **SKILLS**

- C, C++, Java, R, Python, Matlab, Swift
- Pytorch, TensorFlow, MuJoCo, Raisim
- Vim, git, cmake, shell script
- NX, OrCAD, ANSYS