

Data Science Dojo

Regression





Agenda

- Introduction
- Cost Function & Gradient Descent
 - Minimization
 - Implementation
- Hands-on Example
- Evaluating Regression Models
- Regularization

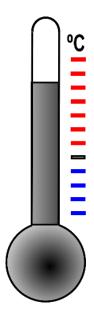


INTRODUCTION

Regression







Sales Forecasts

Housing Price Predictions

Daily Temperature Highs & Lows



Regression vs Classification

- Classification
 - Target is discrete with finite value set
 - **Examples:** survived/dead, face/non-face, fraud/non-fraud
- Regression
 - Target is continuous
 - Examples: price, weight, height, temperature



Notation: Titanic Dataset

| | | | | | | | | | | | Emparke |
|--------------|----------|--------|---|--------|-----|-------|-------|------------------|---------|-------|---------|
| Passenger Id | Survived | Pclass | Name | Sex | Age | SibSp | Parch | Ticket | Fare | Cabin | d |
| 1 | 0 | 3 | Braund, Mr. Owen Harris | male | 22 | 1 | 0 | A/5 21171 | 7.25 | | S |
| 2 | 1 | 1 | Cumings, Mrs. John Bradley (Florence Briggs Thayer) | female | 38 | 1 | 0 | PC 17599 | 71.2833 | C85 | С |
| 3 | 1 | 3 | Heikkinen, Miss. Laina | female | 26 | 0 | 0 | STON/O2. 3101282 | 7.925 | | S |
| 4 | 1 | 1 | Futrelle, Mrs. Jacques Heath (Lily May Peel) | female | 35 | 1 | 0 | 113803 | 53.1 | C123 | S |
| 5 | 0 | 3 | Allen, Mr. William Henry | male | 35 | 0 | 0 | 373450 | 8.05 | | S |

 x_{4}^{5}

5: The passenger is in the 5th row

4: The passenger's name is the 4th column



Notation: Ozone Dataset

So how do we describe all the rows?

| Row | 1 |
|-----|---|
| Row | 2 |
| Row | 3 |

| ozone | radiation | temperature | wind |
|-------|-----------|-------------|------|
| 41 | 190 | 67 | 7.4 |
| 36 | 118 | 72 | 8.0 |
| 12 | 149 | 74 | 12.6 |
| 18 | 313 | 62 | 11.5 |
| 23 | 299 | 65 | 8.6 |
| 19 | 99 | 59 | 13.8 |

$$x^{1} = [190, 67, 7.4]$$
 $x^{2} = [118, 72, 8.0]$
 $x^{3} = [149, 74, 12.6]$



Notation: Ozone Dataset

The ozone dataset uses radiation, temperature and wind to predict ozone levels.

| | | x_1 | x_2 | x_3 | |
|---|-------|-------------|------------|-------|---|
| | ozone | radiation t | emperature | wind | |
| | 41 | 190 | 67 | 7.4 | |
| | 36 | 118 | 72 | 8.0 | |
| Y | 12 | 149 | 74 | 12.6 | X |
| | 18 | 313 | 62 | 11.5 | |
| | 23 | 299 | 65 | 8.6 | |
| | 19 | 99 | 59 | 13.8 | |

Using this notation, we can describe all the columns of the dataset.

Notation Summary

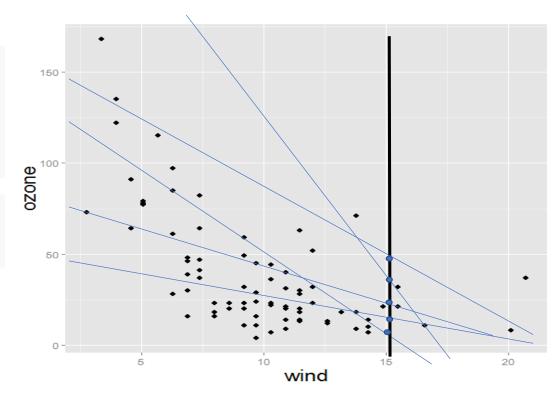
```
x^{i} – Each row of features
x_j – Each column of features X – Set of all the feature columns
                                            Features
y^i – Each row of the target
Y – The target column
n – Number of rows in the dataset
m – Number of columns in the dataset
```



COST FUNCTION AND GRADIENT DESCENT

What is a good regression line?

- Wind Speed=15 mph
- Ozone = ?
- Use the line that is somewhere in the middle
- How do we define "middle"?



$$h_{\theta}(x) = \theta_0 + \theta_1 x$$



Defining a line

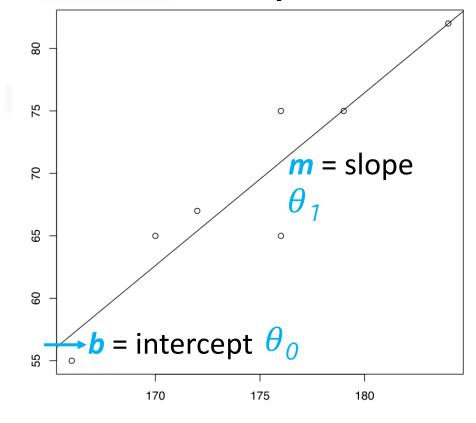
How do we define a line in slope-intercept

notation?

•
$$y = mx + b$$

In θ notation

•
$$h_{\theta}(x) = \theta_1 x + \theta_0$$





More Features

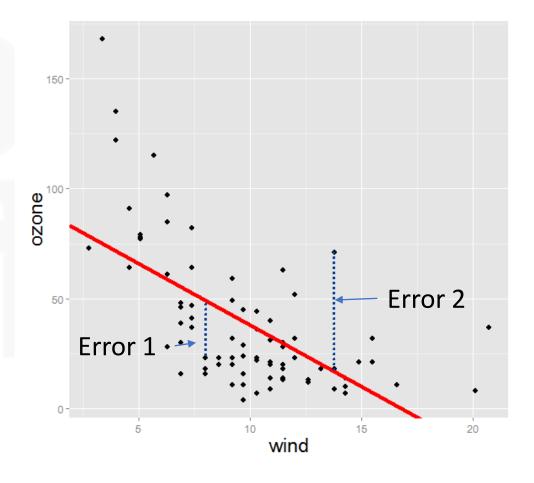
| \mathcal{Y} | x_1 | x_2 | x_3 |
|---------------|-----------|-------------|-------|
| ozone | radiation | temperature | wind |
| 41 | 190 | 67 | 7.4 |
| 36 | 118 | 72 | 8.0 |
| 12 | 149 | 74 | 12.6 |
| 18 | 313 | 62 | 11.5 |
| 23 | 299 | 65 | 8.6 |
| 19 | 99 | 59 | 13.8 |

$$h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3$$



Residuals (or "Errors")

Difference between hypothesis $h_{\theta}(x)$ (predicted value) and true value (known target)

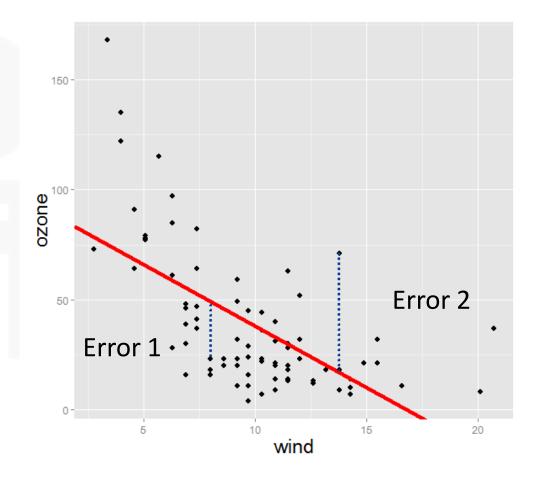


Cost Function

Minimize the 'cost' or 'loss' function $-J(\theta)$

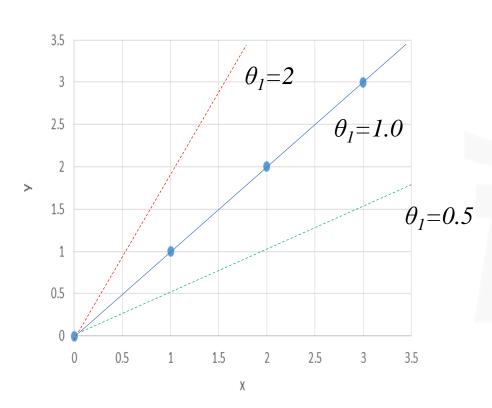
- Smaller for lower error
- Larger for higher error

$$J(\theta) = \frac{1}{2n} \sum_{i=1}^{n} \left(h_{\theta}(x^i) - y^i \right)^2$$



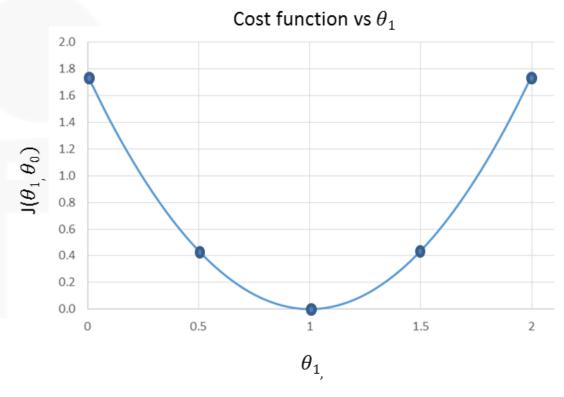
Cost Function

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$



$$\theta_0 = 0$$

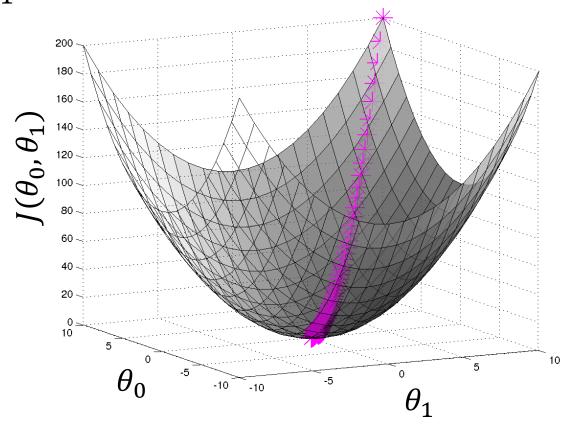
$$J(\theta) = \frac{1}{2n} \sum_{i=1}^{n} (h_{\theta}(x^i) - y^i)^2$$



Each point on the parabola corresponds to a line on the graph on the left

Cost function in three dimensions

$$J(\theta) = \frac{1}{2n} \sum_{i=1}^{n} \left(h_{\theta}(x^i) - y^i \right)^2$$





HOW DO WE FIND THE MINIMUM OF THE COST FUNCTION



Maximum/Minimum Problem

Find **two non-negative** numbers whose **sum is 9** and so that the product of one number and the square of the other number is a **maximum**.

Solution (1/2)

Sum of number is 9

$$9 = x + y$$

Product of two numbers is

$$P = x y^2$$
$$= x (9-x)^2$$

Solution (2/2)

Using the product rule and chain rule from Calculus 101:

$$P' = x (2) (9-x)(-1) + (1) (9-x)2$$

= $(9-x) [-2x + (9-x)]$
= $(9-x) [9-3x]$
= $(9-x) (3)[3-x]$
= 0

$$x=9 \text{ or } x=3$$

Maximum Problem

There are **50** apple trees in an orchard.

Each tree produces **800 apples**. For each additional tree planted in the orchard, the apple output per tree drops by **10 apples**.

Question: How many additional trees should be planted in the existing orchard in order to maximize the apple output of the orchard?



Solution

$$A = (50 + t) \times (800 - 10t)$$

$$A = 40,000 + 300t - 10t^2$$

Solve for A' and set to 0 to find maximum.

$$A' = -20t + 300 = 0$$

$$t = 15$$

Adding 15 trees will maximize apple production

Gradient Descent

- Goal : minimize $J(\theta)$
- Start with some initial θ and then perform an update on each θ_i in turn:

$$\theta_j^{k+1} \coloneqq \theta_j^k - \alpha \frac{\partial}{\partial \theta_j} J(\theta^k)$$

• Repeat until θ converges

Gradient Descent

$$\theta_j^{k+1} \coloneqq \theta_j^k - \alpha \frac{\partial}{\partial \theta_j} J(\theta^k)$$

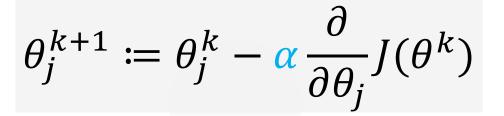
• α is known as the learning rate; set by user

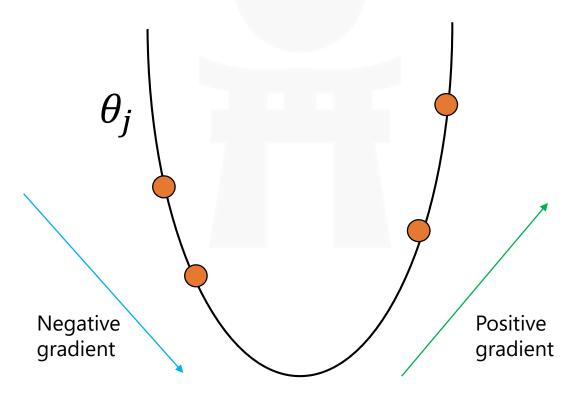
• Each time the algorithm takes a step in the direction of the steepest descent and $J(\theta)$ decreases.

• α determines how quickly or slowly the algorithm will converge to a solution



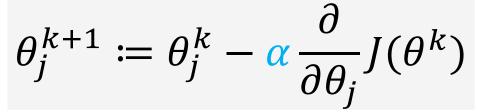
Effect of High Learning Rate: Large α

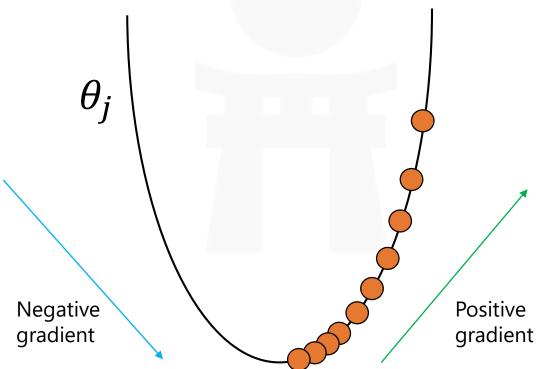






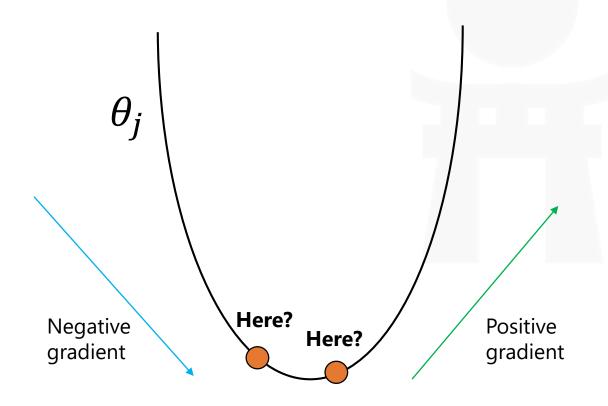
Learning Rate Effects Small α





Gradient Descent Implementation

When do we stop updating?



- When θ_j^{k+1} is close to θ_j^k
- When $J(\theta^{k+1})$ is close to $J(\theta^k)$ [Error does not change]

Batch Gradient Descent

$$\theta_j^{k+1} \coloneqq \theta_j^k - \alpha \frac{\partial}{\partial \theta_i} J(\theta^k)$$

Each $heta_i$ represents one feature

- How do we incorporate all our data?
- Loop!

For j from 0 to m:

$$\theta_j^{k+1} := \theta_j^k - \alpha \frac{1}{n} \sum_{i=1}^n (h_\theta(x^i) - y^i) x_j^i$$

- h_{θ} is updated only once the loop has completed
- Weaknesses?



Batch Gradient Descent

Loop!

For j from 0 to m:

| wind | temperature | radiation | ozone |
|------|-------------|-----------|-------|
| 7.4 | 67 | 190 | 41 |
| 8.0 | 72 | 118 | 36 |
| 12.6 | 74 | 149 | 12 |
| 11.5 | 62 | 313 | 18 |
| 8.6 | 65 | 299 | 23 |
| 13.8 | 59 | gg | 19 |

$$\theta_j^{k+1} \coloneqq \theta_j^k - \alpha \frac{1}{n} \sum_{i=1}^n (h_\theta(x^i) - y^i) x_j^i$$

Stochastic Gradient Descent

Consider an alternative approach:

```
for i from 1 to n:

for j from 0 to m:

\theta_j^{k+1} \coloneqq \theta_j^k - \alpha(h_{\theta}(x^i) - y^i)x_j^i
```

- h_{θ} is updated when inner loop is complete
- If the training set is big, converges quicker than batch
- May oscillate around a minimum of $J(\theta)$ and never converge

^{*} We're now only taking one random observation at a time as a sample, instead of averaging across observations



Batch vs. Stochastic

Which is the better to use? It depends.

| | Batch Gradient Descent | Stochastic Gradient Descent |
|-----------------------------|--|--|
| Function | Updates hypothesis by scanning whole dataset | Updates hypothesis by scanning one training sample at a time |
| Rate of convergence | Slowly | Quickly (but may oscillate at minimum) |
| Appropriate Dataset Size | Small | Large |



EVALUATING REGRESSION MODELS

Evaluation metrics for regression

Mean Absolute Error (MAE)

- Root-Mean-Square Error (RMSE)
 - Root-Mean-Square Deviation

Coefficient of Determination (R²)



Mean Absolute Error

$$MAE(\theta) = \frac{\sum_{i=1}^{n} |h_{\theta}(x^{i}) - y^{i}|}{n}$$

- Mean of residual values
- "Pure" measure of error

Mean Absolute Error - Example

$$y = \{36, 19, 34, 6, 1, 45\}$$

$$h_{\theta}(x) = \{27, -2.6, 13, -7.3, -2.6, 48\}$$

$$|h_{\theta}(x) - y| = \{9, 21.6, 21, 13.3, 3.6, 3\}$$

$$MAE(\theta) = \frac{71.5}{6} = 11.9$$



Root-Mean-Square Error

$$RMSE(\theta) = \sqrt{\frac{\sum_{i=1}^{n} (h_{\theta}(x^{i}) - y^{i})^{2}}{n}}$$

- Square root of mean of squared residuals
- Penalizes large errors more than small
- Good measure to use to accentuate outliers

RMSE - Example

$$y = \{36, 19, 34, 6, 1, 45\}$$

$$h_{\theta}(x) = \{27, -2.6, 13, -7.3, -2.6, 48\}$$

$$(h_{\theta}(x) - y)^2 = \{81, 467, 441, 177, 13, 9\}$$

$$RSME(\theta) = \sqrt{\frac{1187}{6}} = 14.1$$



Coefficient of Determination (R²)

$$R^2 = 1 - \frac{SS_{res}}{SS_{tot}}$$

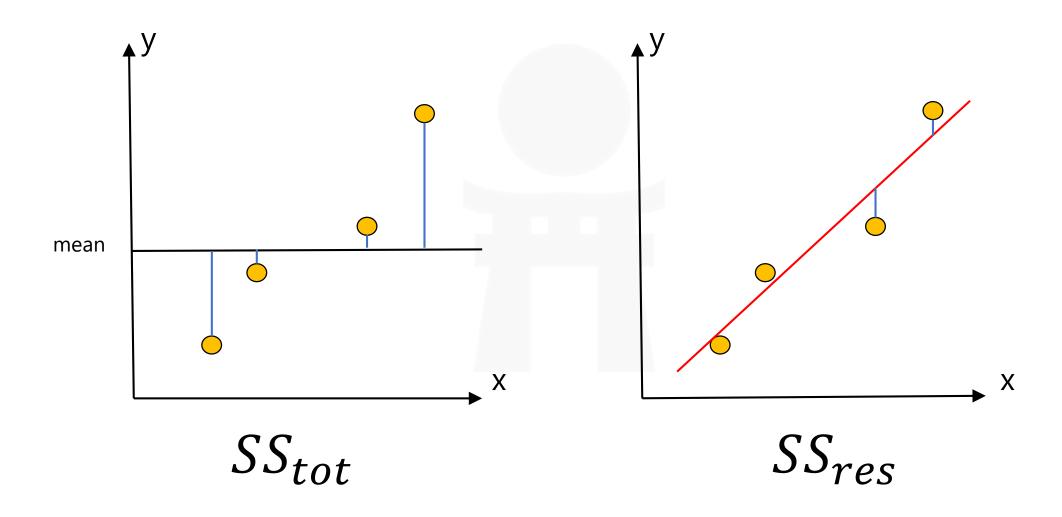
where
$$SS_{res} = \sum_{i=1}^{n} (h_{\theta}(x^{i}) - y^{i})^{2}$$
 $SS_{tot} = \sum_{i=1}^{n} (y^{i} - \bar{y})^{2}$

 SS_{res} – Sum of squared residuals (i.e. total squared error) SS_{tot} –Sum of squared differences from mean (i.e. total variation in dataset)

Result: Measure of how well the model explains the data

• "Fraction of variation in data explained by model"

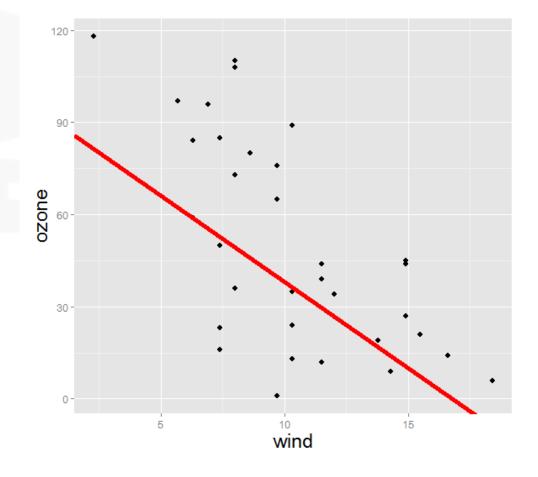
Coefficient of Determination





R² Example

- $R^2 = 0.277$
- Want a much better model for real application
- $R^2 = 0.6$ can be a good model

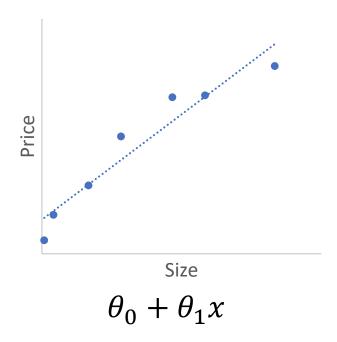


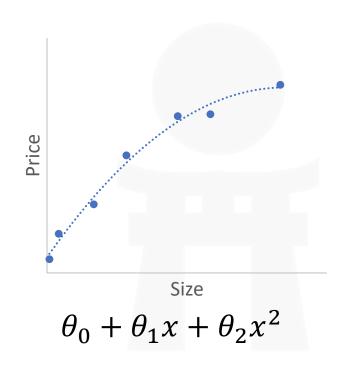


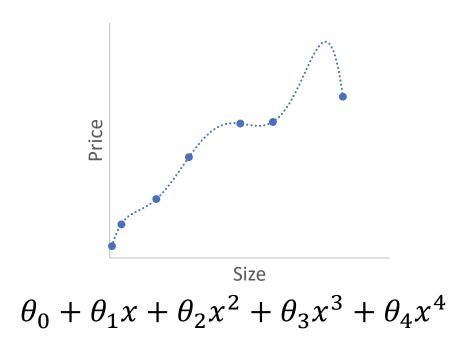
REGULARIZATION



Overfitting

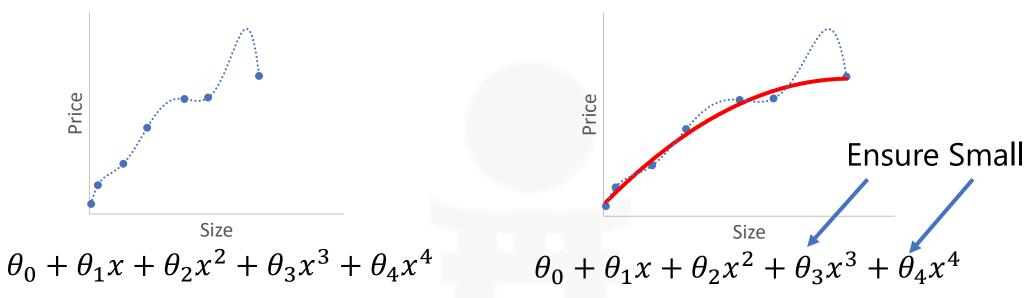








Intuition



- Want to discourage complex models automatically How?
- Adjust the cost function!
 - Penalize models with large high-order θ terms

$$J'(\theta) = J(\theta) + Penalty$$



Definitions

- Two most common methods
 - L1 regularization
 - lasso regression
 - L2 regularization
 - ridge regression
 - weight decay

$$J_{L1}(\theta) = \frac{1}{2n} \sum_{i=1}^{n} (h_{\theta}(x^{i}) - y^{i})^{2} + \lambda \sum_{j=1}^{m} |\theta_{j}|$$

$$J_{L2}(\theta) = \frac{1}{2n} \sum_{i=1}^{n} (h_{\theta}(x^{i}) - y^{i})^{2} + \lambda \sum_{j=1}^{m} \theta_{j}^{2}$$



Regularized Regression

$$J_{L1}(\theta) = \frac{1}{2n} \sum_{i=1}^{n} (h_{\theta}(x^{i}) - y^{i})^{2} + \lambda \sum_{j=1}^{m} |\theta_{j}|$$

$$J_{L2}(\theta) = \frac{1}{2n} \sum_{i=1}^{n} (h_{\theta}(x^{i}) - y^{i})^{2} + \lambda \sum_{j=1}^{m} |\theta_{j}|$$

$$J_{L2}(\theta) = \frac{1}{2n} \sum_{i=1}^{n} (h_{\theta}(x^{i}) - y^{i})^{2} + \lambda \sum_{j=1}^{m} \theta_{j}^{2}$$

- Find the best fit
- Keep the θ_i terms as small as possible.
- λ is a user-set parameter which controls the trade off

Regularized Regression

$$J_{L1}(\theta) = \frac{1}{2n} \sum_{i=1}^{n} (h_{\theta}(x^{i}) - y^{i})^{2} + \lambda \sum_{j=1}^{m} |\theta_{j}|$$

$$J_{L2}(\theta) = \frac{1}{2n} \sum_{i=1}^{n} (h_{\theta}(x^{i}) - y^{i})^{2} + \lambda \sum_{j=1}^{m} \theta_{j}^{2}$$

- Size of λ important
 - λ too high => no fitting
 - λ too low => no regularization



