

Performance of the MICE diagnostic systems

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This paper will describe:

- The detectors as we have it installed in the MICE Hall at November 2017
- The performances of the detectors
- The absorbers models and their validation
- The track matching

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We'll make reference to the published papers wherever possible.

We're targeting the JINST volume.

1 Introduction

To include:

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- Motivation
- Outline of the experiment

2 Time-of-Flight Detectors

2.1 Introduction

Three time-of-flight detectors (TOF0, TOF1, TOF2) have been built and installed at RAL in 2008 and 2009
20 to measure the position and the time of crossing particles. TOF0 and TOF1 [1], [2], [3] are placed upstream of the cooling channel, and TOF2 [4] is downstream of the channel, mounted in front of the KL, as shown in Fig. ???. The time of flight between two TOF stations provides particle identification information and can also be used for momentum measurement. TOF1 served most of the time also as an experimental trigger. They have smoothly operated during the so-called Step I and Step IV [5], [6] running periods of the MICE experiment
25 and were essential for all the measurements done.

The good performances of the TOF detectors, over an extended period of time, has enabled the MICE experiment to characterize fully its muon beams during Step I data-taking, by measuring their emittance [7] and assessing their pion contamination [8].

Each TOF station is made of two planes of fast 1" thick scintillator counters along X/Y directions (to increase
30 measurement redundancy) read out at both edges by R4998 Hamamatsu fast photomultiplier tubes¹. R4998 PMTs have been delivered by Hamamatsu in assemblies (H6533MOD) that include the PMT tube, the voltage divider chain and a 1 mm thick μ -metal shield, extending 30 mm beyond the photocathode surface. The increase the count rate stability active dividers were used, instead of conventional resistive ones. A simple design with flat fish-tail PMMA light guides, as respect to tilted ones (to reduce the influence of magnetic
35 field) or Winston cones, has been chosen to optimize the timing detector resolution (favouring the collection of straight light) and to allow an easy mechanical assembly. TOF0, TOF1, and TOF2 have active areas of 40×40 cm², 42×42 cm², and 60×60 cm² respectively. The slabs in TOF0 are 4 cm wide, while the slabs of TOF1 and TOF2 are 6 cm wide respectively. The PMTs signal, after ~34 m long RG213 cable and a

¹one-inch linear focused PMTs with 10 stages, typical gain G~5.7×10⁶ at -2250 V and B=0 T, rise time 0.7 ns, transit time spread (TTS) ~160 ps

50% – 50% passive splitter, arrive to a leading-edge CAMAC Lecroy 4115 discriminator followed by a CAEN
40 V1290 TDC for time measurements and to a CAEN V1724 FADC for pulse-height measurements, to correct time-walk. As reported in reference [2], RG213 cables² have a better temperature stability than conventional RG58 cables. Their delay have been individually measured in laboratory, before installation in the experimental hall. Time calibration of individual counters has been done with impinging beam particles by using the detector X/Y redundancy [9].

45 Due to the low residual magnetic field produced by the last quadrupole of the beam line in the proximity of the TOF0 detector (≤ 50 G), the used conventional PMTs had to use elongated μ -metal shielding. The other two TOF stations (TOF1/TOF2) had to work instead in the stray fields of the cooling channel solenoids, that are only partially shielded by a 100 mm thick annular iron plates. As residual magnetic fields are up to 0.13 T (with a component along the PMTs axis up to 0.04 T), a local or global magnetic shielding for TOF1 and
50 TOF2 detectors had to be envisaged. The local shielding option was chosen, at the end, for convenience and easiness of implementation. As magnetic shielding is a mass effect, box-shaped soft iron shielding are more effective than cylindrical ones. This idea pioneered in the D0 experiment has been tested in the case of MICE using different geometrical configuration for the iron shielding boxes and different iron materials (e.g. Fe360, ARMCO³, etc). The problem is usually the longitudinal component of the magnetic field, while the orthogonal
55 component may be more easily shielded. Systematic studies have been done, using a built on purpose solenoid of 23 cm inner diameter, 40 cm length⁴ and are fully reported in reference [10]. A composite structure based on the 1 mm μ -metal shielding of the H6533Mod assemblies and an external additional $6 \times 6 \text{ cm}^2$ ($5.6 \times 5.6 \text{ cm}^2$) ARMCO box, 15 cm long, with an internal hole of 3.2 cm diameter has been adopted for the PMT's magnetic shielding of TOF2 (TOF1) [11]. Fig. 1 show how the local shielding has been implemented in TOF2, using
60 different sheets of ARMCO to make a “single bar structure” for all the PMTs of one side, instead of single boxes for individual PMTs. The effective shielding amounts to ~ 6.6 cm of ARMCO thickness, with extra shielding effect due to the fact that all bars shielding the TOF2 PMTs are magnetically linked between them and to both the KL shielding and the shielding plate making a single magnetic loop. Fig. 2 shows some steps of the assembly procedure for the TOF2 detector at INFN MIB mechanics workshop.

65 For what attains performances, TOF0, TOF1, and TOF2 had timing resolutions around 50-60 ps respectively, over the 8 years running period, consistent with design requirements, with the spatial resolution around 1 cm. Fig. 3 shows distributions of the time of flight between TOF0 and TOF1 where electrons, muons and pions fall into three well defined peaks.

2.2 Performance

70 3 Cherenkov Detectors

3.1 Introduction

The Cherenkov detectors are primarily designed to provide π - μ separation in the higher momentum ranges, where TOF separation is not sufficient for conclusive particle identification.

In order to provide separation over a large range of momenta, two high density silica aerogel Cherenkov
75 detectors (CkovA and CkovB) with refractive indices $n=1.07$ and $n=1.12$ are used. They are each read out by four 200 mm photomultiplier tubes and placed directly one after another in the beamline, located just after the first TOF counter. In Fig. 4 an exploded view of one detector is shown.

²CERN type C-50-6-1, with rated delay 4.08 ns/m

³ARMCO steel from AkSteel is a pure iron with a maximal carbon content of 0.025% and very high magnetic saturation

⁴built by TBM srl, Ubondo (VA), Italy

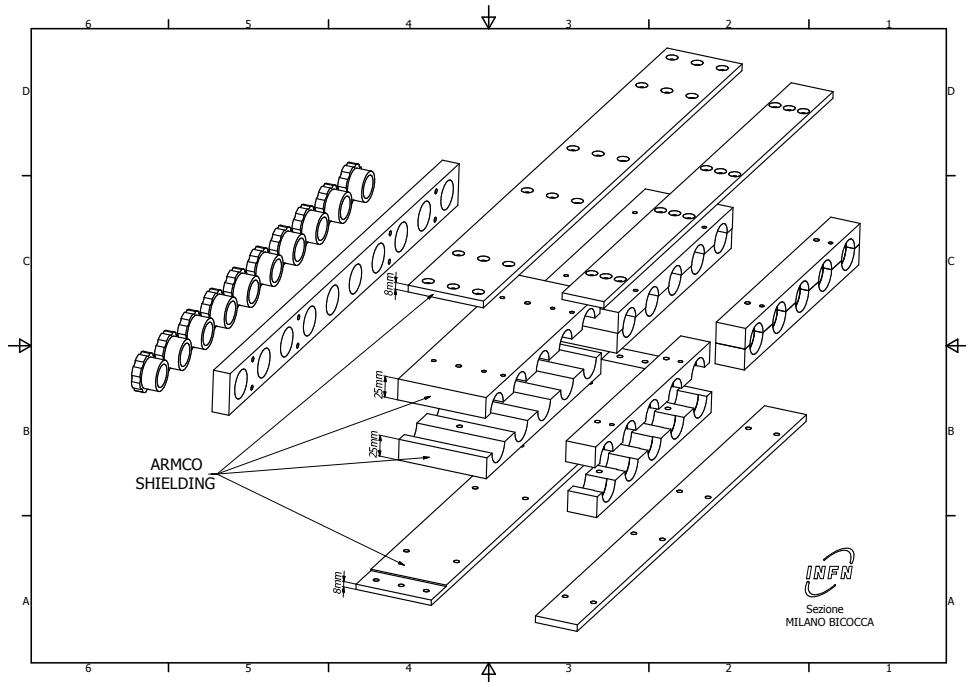


Figure 1: Exploded view of the TOF2 detector magnetic shielding for one row of PMTs.



Figure 2: Assembly of TOF2 at INFN MIB mechanics workshop. Left to right: from the bare magnetic shielding to the installed counters of a plane.

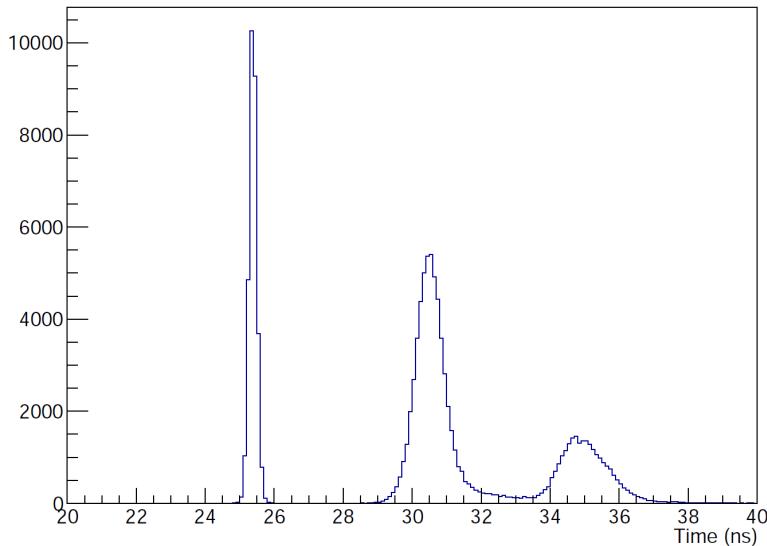


Figure 3: Time of flight between TOF0 and TOF1 for a “pion” beam. From the left: the well separated electron, muon and pion peaks.

Their respective thresholds provide different responses in four distinct momentum ranges, i.e. in the 200 MeV/c beams, pions are below the threshold which would fire the detector for both CkovA and CkovB whereas muons are above only for CkovB, while for the 240 MeV/c beams, pions are above the threshold for CkovB while muons are above for both CkovA and CkovB. Using this information algorithms can be written that produce likelihood distributions of particle type. Below the CkovB muon threshold of about 217.9 MeV/c, where there is no separation, the TOFs provide good separation, whereas the momentum range above the CkovA pion threshold (367.9) MeV/c is outside of the MICE running parameters [12].

85 3.2 Performance

4 KLOE-Light Calorimeter

4.1 Introduction

The KLOE-Light (KL) pre-shower sampling calorimeter is composed of extruded lead foils in which scintillating fibres are placed in volume ratio scintillator:lead $\sim 2:1$, “lighter” than the one of the KLOE experiment calorimeter (1:1).

The fibres are 1 mm diameter BICRON BCF-12, scintillating in the blue, 1.35 mm distant from each other within a layer. The distance between two layers is 0.98 mm, one layer being shifted by half the fibre pitch with respect to the next. Scintillation light is guided from each slab into a total of six PMTs (three on each side). Iron shields are fitted to each photomultiplier to mitigate against large stray magnetic fields from the cooling channel (see Fig. 5). The signal from each PMT is sent to a shaping amplifier (SA) module, which shapes and stretches the signal in time in order to match the sampling rate of the flash ADCs (Fig. 6 shows the design of a single slab). A total of 7 slabs forms the whole detector, which has an active volume of $93\text{ cm} \times 93\text{ cm} \times 4\text{ cm}$.

With its 2.5 radiation lengths the KL is used to distinguish muons from decay electrons providing energy deposition and timing information and to act as pre-shower in front of the EMR. The detector has been used to estimate the level of pion contamination within the MICE muon beams to be around 1% [8].

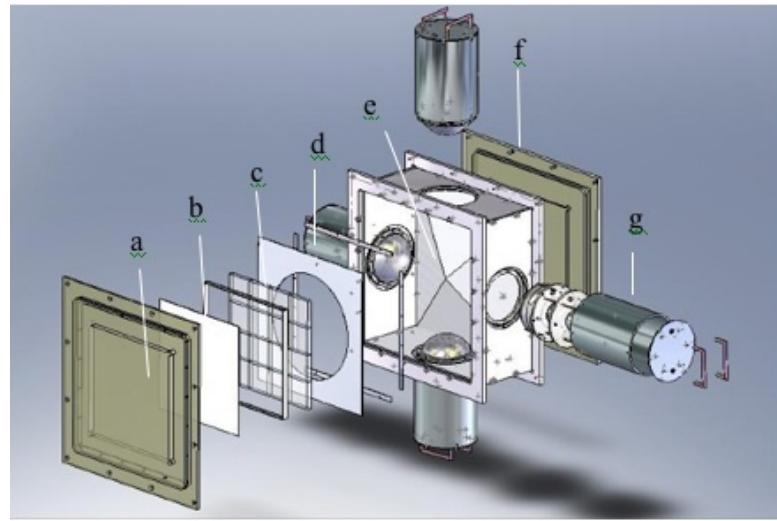


Figure 4: MICE aerogel Cherenkov counter blowup: a) entrance window, b) mirror, c) aerogel mosaic, d) acetate window, e) GORE reflector panel, f) exit window and g) 8 inch PMT in iron shield.

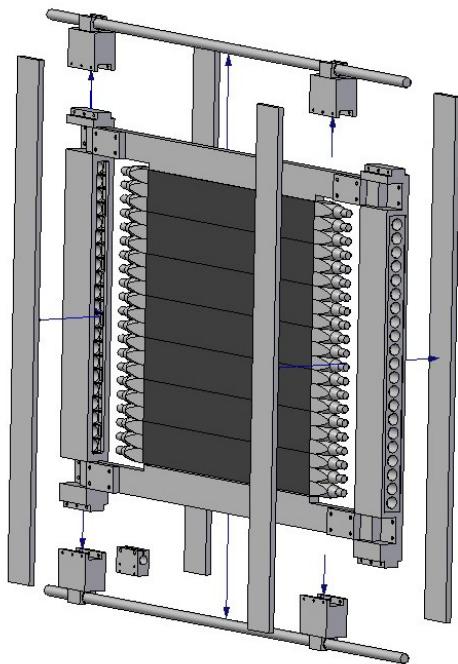


Figure 5: Magnetic shielding of KLOE-Light PMTs.

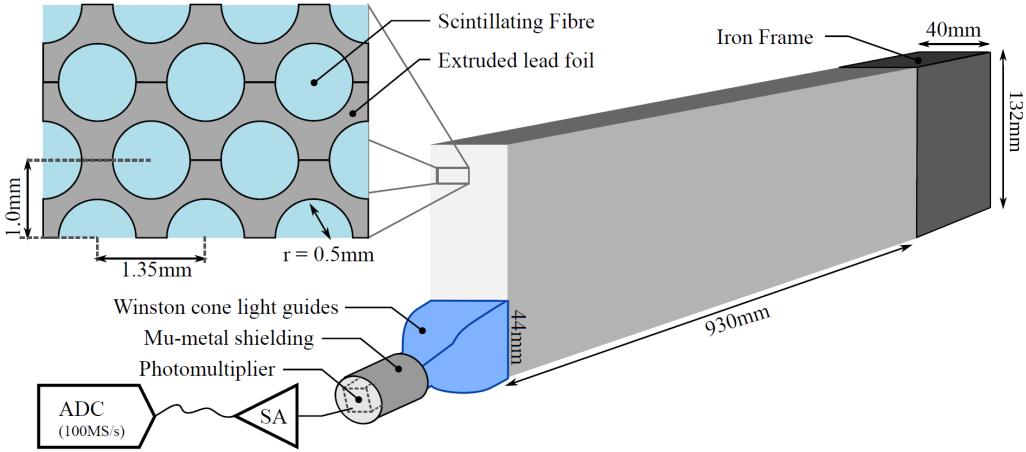


Figure 6: Single slab design of MICE KLOE-Light Calorimeter.

4.2 Performance

5 Electron Muon Ranger

5.1 Introduction

Franois provided this

The Electron-Muon Ranger (EMR) is a fully-active scintillator detector [13]. It can be classified as a tracking-calorimeter as its granularity allows for track reconstruction. The EMR consists of extruded triangular scintillator bars arranged in planes. One plane contains 59 bars and covers an area of 1.27 m^2 . Each even bar is rotated by 180 degrees with respect to the odd one. A cross-section of bars and their arrangement in a plane is shown in Fig. 7. This configuration does not leave dead area in the detector for particles crossing a plane with angles that do not exceed 45 degrees with respect to the beam axis. Each plane is rotated through 90 degrees with respect to the previous one, such that a pair of planes defines a horizontal and vertical (x, y) interaction coordinate. The light, produced when a particle crosses a bar, is collected by a wave-length shifting (WLS) fibre glued inside the bar. At both ends, the WLS fibre is coupled to clear fibres that transport the light to a photomultiplier tube (PMT). Signals produced in a plane are read out collectively on one end by a single-anode PMT for an integrated charge measurement and separately on the other by a multi-anode PMTs for individual bar hit reconstruction. The full detector is composed of 24 X-Y modules for a total active volume of $\sim 1 \text{ m}^3$.

An array of analyses were conducted to characterize the hardware of the EMR and determine whether the detector performs to specifications [14]. The clear fibres coming from the bars were shown to transmit the desired amount of light, and only four dead channels were identified in the electronics. Two channels had indubitably been mismatched during assembly and the DAQ channel map was subsequently corrected. The level of crosstalk is within acceptable values for the type of multi-anode photomultiplier used with an average of $0.20 \pm 0.03\%$ probability of occurrence in adjacent channels and a mean amplitude equivalent to $4.5 \pm 0.1\%$ of the primary signal intensity. The efficiency of the signal acquisition, defined as the probability of recording a signal in a plane when a particle goes through it in beam conditions, reached $99.73 \pm 0.02\%$.

The primary purpose of the EMR is to distinguish between muons and their decay products, identifying muons that have crossed the entire cooling channel. Muons and electrons exhibit distinct behaviours in the detector. A muon follows a single straight track before either stopping or exiting the scintillating volume, while electrons shower in the lead of the KL and create a broad cascade of secondary particles. Two main

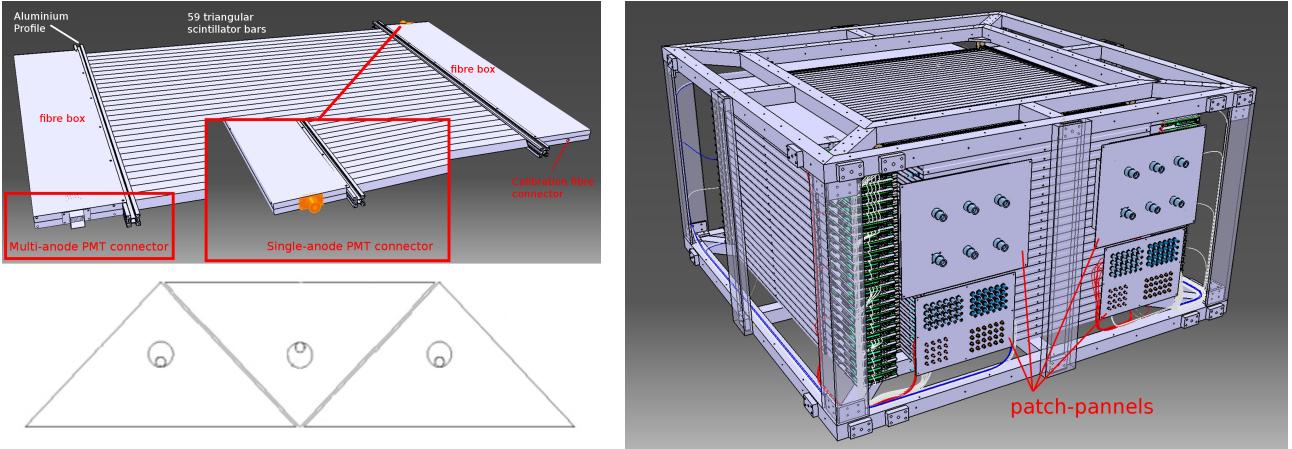


Figure 7: Drawing of one EMR plane (top left), cross section of 3 bars and their wavelength shifting fibres (bottom left) and drawing of the full detector (right).

geometric variables, the plane density and the shower spread, are used to differentiate them. The detector
 130 is capable of identifying electrons with an efficiency of 98.6 %, providing a purity for the MICE beam that exceeds 99.8 %. The EMR also proved to be a powerful tool for the reconstruction of muon momenta in the range 100–280 MeV/c [15].

5.2 Performance

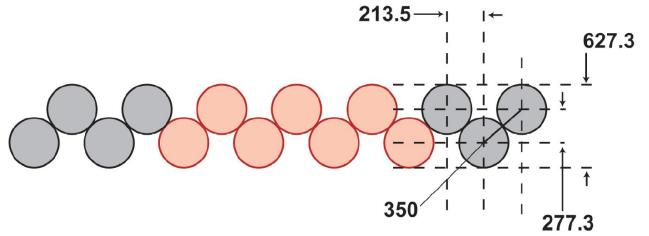
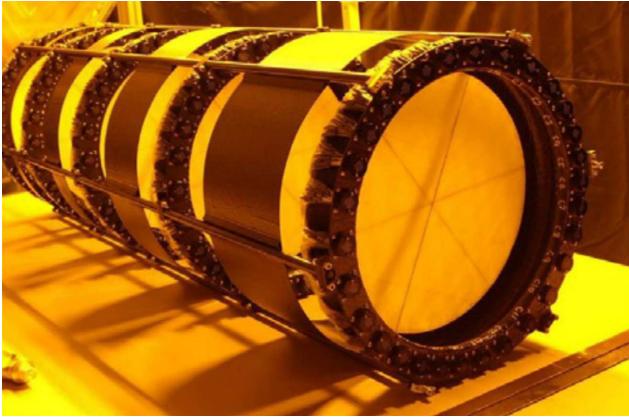


Figure 8: Photograph of one tracker showing the five stations (left) and cross-section of a tracker plane (right) .

6 Tracker

¹³⁵ 6.1 Introduction

The emittance measurement in MICE is performed by two scintillating fibre trackers, placed upstream and downstream of the cooling channel, which will allow for the change in emittance across the cooling channel to be measured.

¹⁴⁰ The trackers are positioned within the bore of superconducting solenoids used to induce helical motion in the incoming particles, from which position and momentum of the particles can be reconstructed and measured. Each tracker is formed by five stations placed at non-equal intervals to minimize the possible degeneracy in the position measurement Fig. 8 (left). Each station is composed of three planes of doped scintillating fibre of diameter 350μ , each orientated at 120° . The fibres are arranged in doublets as in Fig. 8 (right). Scintillation light produced by ionization radiation is readout by visible light photo counters [16].

¹⁴⁵ The fibres are grouped into channels (seven fibres per channel). Regarding the tracker reconstruction, hits in individual channel are combined into cluster formed with the neighbour channel. Spacepoints in each plane are then formed from either two or three clusters. Spacepoints are associated with individual tracks using a pattern recognition algorithm before a Kalman filter is applied, accounting scattering and energy loss within the tracker. [17].

¹⁵⁰ **6.2 Performance**

6.3 Tracker resolution in field

7 PID

7.1 Introduction

7.2 Performance of the PID

¹⁵⁵ **8 Track Matching**

8.1 Introduction

8.2 Performance

8.3 Beam based magnet alignment

9 Detector alignment

¹⁶⁰ **9.1 Introduction**

9.2 Beam based detector alignment

10 Magnets and Beam Optics

10.1 Introduction

10.2 Beam based magnet alignment

¹⁶⁵ **10.3 Beam line optics**

11 Absorber

11.1 Introduction

11.2 Validation of the absorber model

12 Conclusions

¹⁷⁰ To be written at last.

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