

# Vraj Prajapati

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## EDUCATION

**University of Toronto** **May, 2026**  
*B.ASc (Bachelors of Applied Science) Engineering Science* *Toronto, ON*  
▪ Relevant courses: Digital and Computer Systems, Data Structures and Algorithms (100%), Intro to CS (99%)

## EXPERIENCE

**University of Toronto Machine Intelligence Student Team (UTMIST)** **September 2023 – Present**  
*Project Director* *Toronto, ON*  
▪ **Founded** and leading Spiking Neural Networks project, highlighting **novel & efficient** approaches to AI.  
▪ Creating **neuromorphic computing** hardware with **memristors** for spiking algorithms & **CNN** inference.  
▪ **Directing a team** of 8 talented HWE developers and SWE developers on project with a **SCRUM** workflow

**IEEE University of Toronto Student Branch** **May 2023 – Present**  
*Technical Director* *Toronto, ON*  
▪ **Spearheading** a team of 13 associates in creating professional development initiatives for **embedded** engineers.  
▪ **Mentoring** student projects, organizing hardware distribution at **Canada's Largest Makeathon**, MakeUofT.  
▪ Hosting workshops with topics such as **eAI Quantization**, **Computer Vision**, **Altium PCB Design**, etc...

**University of Toronto Robotics Association (UTRA)** **June 2023 – Present**  
*Executive Electrical Advisor* *Toronto, ON*  
▪ Designed a **milestone-based** workflow with five **robot design** teams to hold **design reviews** with faculty  
▪ Advising teams with **robotics design** decisions related to **odometry**, **mobile CV**, **localization**, **PID control**

**University of Toronto Engineering Orientation (F!Rosh) Tech Team** **June 2023 – August 2023**  
*Full Stack Web Developer* *Remote*  
▪ Used **MERN stack** to develop features for [orientation.skule.ca](https://orientation.skule.ca) such as **on-the-fly PDF generation**  
▪ Demonstrated proficiency in working **asynchronously** with a team all over Canada using **git**, **docker**, **SCRUM**

**University of Toronto Formula SAE** **February 2023 – May 2023**  
*Driverless Team - Embedded Engineer* *Toronto, ON*  
▪ Worked with **SocketCAN** and **ROS2** to create features and code to drive FSAE Car in **driverless** competition

## PROJECTS

**Magnetic Accelerator** **MakeUofT 2023 - Best Use of Qualcomm 8450HDK**  
▪ Created a magnetic coil gun by applying fundamental **electromagnetics** with a team, and I leveraged the **DSP** and **eAI platform** of the Snapdragon 8450 to **efficiently detect** lifeless objects for the **targeting system**.

**Pepsi Turret** **IEEE 2023 Internal Summer Project**  
▪ To highlight my **deep hatred** of Pepsi I created an **accelerated obj detection algorithm** on an RPi, designed a double flywheel system, and an **actuating 2-axis turret** base to detect pepsi cans and fire marbles at them.

## SKILLS

**Programming** in C, C++, Python, Java, JS, Verilog  
**Collaborative Leadership**, Mentorship, Teaching  
**Engineering** AI, Robotics, Microcontrollers, Web

## CERTIFICATES & COURSES

**Imperial College London** - Mathematics for ML  
**Stanford** - CS229: Machine Learning

## ACHIEVEMENTS

Qualified for 2022 World **FIRST** Robotics Competitions  
**NASA** Space Apps 2023 - International Qualifier

## INTERESTS

Making funny robots, Cooking, Going to the gym, Table Tennis, Punny Puns, Cheddar Broccoli Soup