# Bounding the Value of Extended Nonlocal Games Theory Seminar

Vincent Russo

University of Waterloo

September 15, 2016





#### Outline

Nonlocal games

Upper bounding nonlocal games

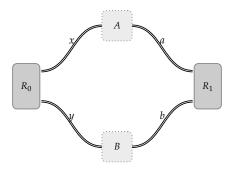
Extended nonlocal games

Upper bounding extended nonlocal games

# Nonlocal games

#### Nonlocal games

A nonlocal game is a cooperative game played between Alice and Bob against a referee.



- 1. Question and answer sets:  $(\Sigma_A, \Sigma_B)$  and  $(\Gamma_A, \Gamma_B)$ ,
- 2. Distributions on question pairs:  $\pi: \Sigma_A \times \Sigma_B \to [0,1]$ ,
- 3. A predicate  $V: \Gamma_A \times \Gamma_B \times \Sigma_A \times \Sigma_B \rightarrow \{0,1\}$ , where

$$V(a,b|x,y) = \begin{cases} 1 & \text{if Alice and Bob win,} \\ 0 & \text{if Alice and Bob lose.} \end{cases}$$

## Strategies for nonlocal games

Alice and Bob could use different types of strategies:

- ▶ Classical strategies: Alice and Bob answer deterministically, determined by functions of  $f: \Sigma_A \to \Gamma_A$  and  $g: \Sigma_B \to \Gamma_B$ .
- ▶ Quantum strategies: Alice and Bob share a joint quantum system  $\rho \in D(\mathcal{A} \otimes \mathcal{B})$  and allow their answers to be outcomes of measurements on this shared system.
- ▶ Commuting measurement strategies: Alice and Bob share a quantum system over a single Hilbert space  $\rho \in D(\mathcal{H})$  and allow their answers to be outcomes of measurements on this system.
- Non-signaling strategies: No instantaneous communication between parties.

## Values for nonlocal games

The *value* of a nonlocal game is the maximal winning probability for the players to win over all strategies of a specified type.

For a nonlocal game, G, we denote the classical and quantum values as

- ▶ Classical value:  $\omega(G)$ ,
- ▶ Commuting measurement value:  $\omega_c(G)$ ,
- Quantum value:  $\omega^*(G)$ ,
- ▶ Non-signaling value:  $\omega_{ns}(G)$ .

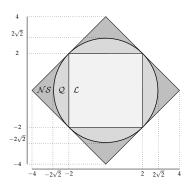
The values obey the following relationship for any nonlocal game:

$$\omega(G) \leq \omega^*(G) \leq \omega_c(G) \leq \omega_{\mathsf{ns}}(G).$$

# Optimizing over quantum strategies is hard

Want: Method to calculate the quantum value of a nonlocal game.

This figure shows representations of the space of joint distributions for fixed and finite number of possible questions and answers.

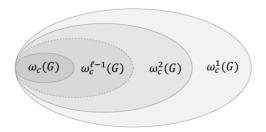


Unfortunately, the set Q is a non-polyhedral set with an infinite number of extreme points.

Upper bounding nonlocal games

# Upper bounds for nonlocal games

- ► The NPA hierarchy sis a method of placing *upper bounds* on the *quantum value* of nonlocal games.
- ▶ Hierarchy of semidefinite programs is *guaranteed* to converge to the commuting measurement value for some finite level,  $\ell$  of the hierarchy.
- ▶ The commuting measurement value is an upper bound on the quantum value,  $\omega^*(G) \leq \omega_c(G)$ , for all nonlocal games, G.



 $<sup>\</sup>P[\mathsf{Navascu\acute{e}s},\,\mathsf{Pironio},\,\mathsf{and}\,\,\mathsf{Ac\'{i}n},\,(2008)]$ 

► Finding a quantum state and measurements for a quantum strategy is a computationally difficult task.

- ► Finding a quantum state and measurements for a quantum strategy is a computationally difficult task.
- ▶ Instead then, let's think about a set of weaker conditions.

- ► Finding a quantum state and measurements for a quantum strategy is a computationally difficult task.
- ▶ Instead then, let's think about a set of weaker conditions.
- In the NPA hierarchy, each condition amounts to verifying the existence of a PSD matrix with structure that depends on algebraic properties satisfied by a quantum strategy.

- Finding a quantum state and measurements for a quantum strategy is a computationally difficult task.
- ▶ Instead then, let's think about a set of weaker conditions.
- In the NPA hierarchy, each condition amounts to verifying the existence of a PSD matrix with structure that depends on algebraic properties satisfied by a quantum strategy.
- ▶ If any of these conditions are violated, we know that

NPA states that there exists some matrix  $C^{(\ell)}$  that allows  $\omega_c(G)$  to be calculated by maximizing

$$\sum_{x,y,a,b} \pi(x,y) V(a,b|x,y) C^{(\ell)}((x,a),(y,b))$$

for some finite level,  $\ell$ , such that  $C^{(\ell)}$  satisfies certain linear constraints.

- ▶ These linear constraints can be checked via SDP!
- ▶ The next few slides will describe how  $C^{(\ell)}$  is defined.

# PSD operator

[\*\*\* More on intuition behind the  $C^{(\ell)}$  operator. \*\*\*]

# Strings

In order to index into  $C^{(\ell)}((x,a),(y,b))$ , we will consider strings.

Define alphabets

$$\Sigma_{\mathsf{A}} = X \times \mathsf{A}, \quad \Sigma_{\mathsf{B}} = Y \times \mathsf{B}, \quad \Sigma^* = \{\epsilon\} \cup \Sigma_{\mathsf{A}} \cup \Sigma_{\mathsf{B}}.$$

For example, we can refer to operators (or products of operators) as tuples of concatenated strings. For example:

$$A_a^{\times} \to (x, a), \quad \text{and}$$
  
 $A_{a_1}^{\times_1} \cdots A_{a_k}^{\times_k} \to (x_1, a_1) \cdots (x_k, a_k).$ 

Similarly for Bob.

# Equivalence relations for strings

The measurements in a commuting measurement strategy are *projective* and they *commute*. This property can be conveyed in terms of a string relation:

For all strings  $s,t\in\Sigma^*$ ,

- 1. Projective:  $s\sigma t \sim s\sigma \sigma t$  for all  $\sigma \in \Sigma$
- 2. Commute:  $s\sigma\tau t \sim s\tau\sigma t$  for all  $\sigma \in \Sigma_A$  and  $\tau \in \Sigma_B$ .

#### Admissible functions

The function

$$\phi: \Sigma^* \to \mathbb{C}$$

is admissible iff it satisfies the following conditions:

1. Measurements sum to identity:

$$\sum_{a} \phi(s(x,a)t) = \sum_{b} \phi(s(y,b)t) = \phi(st),$$

for all  $x, y \in X \times Y$ .

2. Something:

$$\phi(s(x,a)(x,a')t) = \phi(s(y,b)(y,b')t) = 0$$

3. For all  $s, t \in \Sigma^*$  where  $s \sim t$ 

$$\phi(s)=\phi(t).$$

#### $\ell$ -th order admissible matrices

We call the matrix  $C^{(\ell)}$  an  $\ell$ -th order admissible matrix if

1. There exists an admissible function

$$\phi: \Sigma^{\leq 2\ell} \to \mathbb{C},$$

such that

$$C^{(\ell)}(s,t) = \phi(s^R t) \quad \forall s,t \in \Sigma^{\leq \ell},$$

- 2. Normalization:  $C^{(\ell)}(\epsilon, \epsilon) = 1$ ,
- 3.  $C^{(\ell)}$  is positive semidefinite.

# ℓ-th order pseudo commuting measurement assemblages

Define an  $\ell$ -th order pseudo commuting measurement assemblage

$$K: A \times B \times X \times Y \to L(\mathbb{C}),$$

for which there exists an  $\ell$ -th order admissible matrix  $C^{(\ell)}$  such that

$$K(a,b|x,y) = C^{(\ell)}((x,a),(y,b)) \quad \forall x,y,a,b.$$

#### Example

Consider a nonlocal game where |X| = |Y| = |A| = |B| = 2. Let's compute  $C^{(1)}$ :

- ▶ Fill in matrix with products of row and column to generate element Z.
- ▶ For each Z computed in this way, the entry refers to an inner product between Z and the shared state  $\rho$ , i.e.  $\langle Z, \rho \rangle$ .

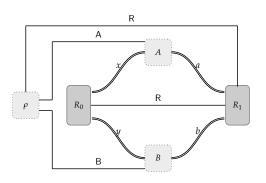
#### Example

Consider a nonlocal game where |X| = |Y| = |A| = |B| = 2. Let's compute  $C^{(1)}$ :

# Extended nonlocal games

#### Extended nonlocal games

An extended nonlocal game is a nonlocal game where the referee also holds a quantum system that he measures provided by Alice and Bob.



- 1. Question and answer sets  $(\Sigma_A, \Sigma_B)$  and  $(\Gamma_A, \Gamma_B)$ .
- 2. Distribution on question pairs:  $\pi: \Sigma_A \times \Sigma_B \to [0,1]$ .
- 3. A measurement operator  $V: \Gamma_A \times \Gamma_B \times \Sigma_A \times \Sigma_B \to \operatorname{Pos}(\mathcal{R})$ .

# Extended nonlocal games: Winning and losing probabilities

At the end of the protocol, the referee has:

1. The state at the end of the protocol:

$$\rho_{a,b}^{x,y} \in \mathrm{D}(\mathcal{R}).$$

2. A measurement the referee makes on its part of the state  $\rho$ :

$$V(a, b|x, y) \in Pos(\mathcal{R}).$$

The respective winning and losing probabilities are given by

$$\left\langle V(a,b|x,y), \rho_{a,b}^{x,y} \right\rangle$$
 and  $\left\langle \mathbb{1} - V(a,b|x,y), \rho_{a,b}^{x,y} \right\rangle$ .

## Standard quantum strategies

A standard quantum strategy consists of finite-dimensional complex Euclidean spaces  $\mathcal{R}, \mathcal{A}$ , and  $\mathcal{B}$  as well as the following:

- ▶ Shared state:  $\rho \in \mathcal{R} \otimes \mathcal{A} \otimes \mathcal{B}$ .
- ▶ Measurements:  $\{A_a^x\} \subset \operatorname{Pos}(\mathcal{A}), \{B_b^y\} \subset \operatorname{Pos}(\mathcal{B}).$

## Standard quantum strategies

A standard quantum strategy consists of finite-dimensional complex Euclidean spaces  $\mathcal{R}, \mathcal{A}$ , and  $\mathcal{B}$  as well as the following:

- ▶ Shared state:  $\rho \in \mathcal{R} \otimes \mathcal{A} \otimes \mathcal{B}$ .
- ▶ Measurements:  $\{A_a^x\} \subset \operatorname{Pos}(\mathcal{A}), \{B_b^y\} \subset \operatorname{Pos}(\mathcal{B}).$

Winning probability for a standard quantum strategy is given by:

$$\sum_{x,y} \pi(x,y) \sum_{a,b} \left\langle V(a,b|x,y) \otimes A_a^x \otimes B_b^y, \rho \right\rangle$$

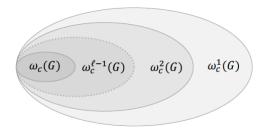
The standard quantum value, denoted as  $\omega^*(G)$ , is the supremum of the winning probability over all standard quantum strategies.

Upper bounding extended nonlocal games

# Upper bounds for extended nonlocal games

#### Extended NPA hierarchy:

- ▶ Uses the same idea as the NPA hierarchy. (For dim( $\mathcal{R}$ ) = 1, the NPA hierarchy is a special case.)
- ► Enables one to compute *upper bounds* on the *standard quantum value* for *extended nonlocal games*.
- Same idea as before, only now we need to take into account the actions of the referee.



# Commuting measurement strategies (for ENLG)

A commuting measurement strategy consists of a finite-dimensional complex Euclidean space  $\mathcal{H}$  as well as the following:

- ▶ Shared state:  $\rho \in \mathcal{R} \otimes \mathcal{H}$ .
- ▶ Measurements:  $\{A_a^x\} \subset \operatorname{Pos}(\mathcal{H}), \{B_b^y\} \subset \operatorname{Pos}(\mathcal{H}),$  where  $[A_a^x, B_b^y] = 0$  for all x, y, a, b.

# Commuting measurement strategies (for ENLG)

A commuting measurement strategy consists of a finite-dimensional complex Euclidean space  $\mathcal H$  as well as the following:

- ▶ Shared state:  $\rho \in \mathcal{R} \otimes \mathcal{H}$ .
- ▶ Measurements:  $\{A_a^x\} \subset \operatorname{Pos}(\mathcal{H}), \{B_b^y\} \subset \operatorname{Pos}(\mathcal{H}),$  where  $[A_a^x, B_b^y] = 0$  for all x, y, a, b.

The expected *pay-off* for a commuting measurement strategy is given by:

$$\sum_{(x,y)\in\Sigma_{\mathsf{A}}\times\Sigma_{\mathsf{B}}}\pi(x,y)\sum_{(a,b)\in\Gamma_{\mathsf{A}}\times\Gamma_{\mathsf{B}}}\left\langle V(a,b|x,y)\otimes A_{a}^{x}B_{b}^{y},\rho\right\rangle$$

The commuting measurement value, denoted as  $\omega_c(G)$ , is the supremum of the pay-off over all commuting measurement strategies.

#### Extended NPA theorem

There exists some matrix  $M^{(\ell)}$  that allows  $\omega_c(G)$  (where G is an ENLG) to be calculated by maximizing

$$\sum_{x,y,a,b} \pi(x,y) \left\langle V(a,b|x,y), M^{(\ell)}((x,a),(y,b)) \right\rangle$$

## Extended NPA hierarchy

Same idea, but now we're taking into account the referee, and therefore have a larger matrix.

For each  $\ell$ , now consider block matrices

$$M^{(\ell)} = \begin{pmatrix} M_{1,1}^{(\ell)} & \cdots & M_{1,m}^{(\ell)} \\ \vdots & \ddots & \vdots \\ M_{m,1}^{(\ell)} & \cdots & M_{m,m}^{(\ell)} \end{pmatrix}$$

where each block takes the form  $M_{i,j}^{(\ell)}: \Sigma^{\leq \ell} \times \Sigma^{\leq \ell} \to \mathbb{C}$ .

- Each submatrix has similar properties to what we saw for the NPA hierarchy.
- ► The overall matrix also has some structure, which is unique to this case.

# Supplementary material: Extended nonlocal games

# Winning probability for standard quantum strategies

The winning probability is given by the following equation:

$$\sum_{x,y} \pi(x,y) \sum_{a,b} \frac{\langle V(a,b|x,y), \operatorname{Tr}_{\mathcal{A} \otimes \mathcal{B}} (\mathbb{1}_{\mathcal{R}} \otimes A_{\mathsf{a}}^{\mathsf{x}} \otimes B_{\mathsf{b}}^{\mathsf{y}}) \rho) \rangle}{\operatorname{Tr} (\mathbb{1}_{\mathcal{R}} \otimes A_{\mathsf{a}}^{\mathsf{x}} \otimes B_{\mathsf{b}}^{\mathsf{y}}) \rho)} \operatorname{Tr} (\mathbb{1}_{\mathcal{R}} \otimes A_{\mathsf{a}}^{\mathsf{x}} \otimes B_{\mathsf{b}}^{\mathsf{y}}) \rho)$$

The probabilities cancel giving

$$\sum_{x,y} \pi(x,y) \sum_{a,b} \operatorname{Tr} \left( V(a,b|x,y) \operatorname{Tr}_{\mathcal{A} \otimes \mathcal{B}} \left( \mathbb{1}_{\mathcal{R}} \otimes A_a^x \otimes B_b^y \right) \rho \right)$$

The trace operator slips past the  $\mathbb{1}_{\mathcal{R}}$  giving

$$\sum_{\mathsf{x},\mathsf{y}} \pi(\mathsf{x},\mathsf{y}) \sum_{\mathsf{a},\mathsf{b}} \mathsf{Tr} \left( V(\mathsf{a},\mathsf{b}|\mathsf{x},\mathsf{y}) \otimes (A^\mathsf{x}_\mathsf{a} \otimes B^\mathsf{y}_\mathsf{b}) \rho \right)$$

Writing the trace in terms of the inner product, we have that

$$\sum_{x,y} \pi(x,y) \sum_{a,b} \left\langle V(a,b|x,y) \otimes A_a^x \otimes B_b^y, \rho \right\rangle.$$

# Supplementary material: Lower bounds for extended nonlocal games

#### Lower bounds for extended nonlocal games

Key idea: Fixing measurements on one system yields the optimal measurements of the other system via an  $SDP^\P$ 

#### Lower bounds for extended nonlocal games

Key idea: Fixing measurements on one system yields the optimal measurements of the other system via an  $SDP^{\P}$ 

Iterative "see-saw" algorithm between two SDPs:

- ► SDP-1: Fix Bob's measurements. Optimize over Alice's measurements.
- ► SDP-2: Fix Alice's measurements (from SDP-1). Optimize over Bob's measurements.
- Repeat.

Not guaranteed to give optimal value, as the algorithm can get stuck in a local minimum.

#### Lower bounds for extended nonlocal games

Define  $\{\rho_a^x : x \in \Sigma_A, \ a \in \Gamma_A\} \subset \operatorname{Pos}(\mathcal{R} \otimes \mathcal{B})$  as the residual states acting on the referee and Bob's systems and let

$$f = \sum_{(x,y) \in \Sigma_{A} \times \Sigma_{B}} \pi(x,y) \sum_{(a,b) \in \Gamma_{A} \times \Gamma_{B}} \left\langle V(a,b|x,y) \otimes B_{b}^{y}, \rho_{a}^{x} \right\rangle$$

$$\underline{\text{Lower bound (SDP-1)}} \qquad \underline{\text{Lower bound (SDP-2)}}$$

$$\max: \quad f \qquad \qquad \max: \quad f$$

$$\text{s.t.:} \quad \sum_{a \in \Gamma_{A}} \rho_{a}^{x} = \tau, \qquad \qquad \text{s.t.:} \quad \sum_{b \in \Gamma_{B}} B_{b}^{y} = \mathbb{1}_{\mathcal{B}},$$

$$\tau \in \mathrm{D}(\mathcal{R} \otimes \mathcal{B}). \qquad \qquad B_{b}^{y} \in \mathrm{Pos}(\mathcal{B}).$$

▶ Iterate between SDP-1 and SDP-2 until desired numerical precision is reached.