EE3900 Gate Assignment-3

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Download all python codes from

https://github.com/vrahul02/EE3900/tree/main/ Gate-Assignment-3/Codes

and latex-tikz codes from

https://github.com/vrahul02/EE3900/tree/main/ Gate-Assignment-3/Gate-Assignment-3. tex

PROBLEM GATE EC-2002 Q.2.4

If the impulse response of a discrete-time system is $h[n] = -5^n u[-n-1]$, then the system function H(z) is equal to

- 1) $\frac{-z}{z-5}$ and the system is stable 2) $\frac{z}{z-5}$ and the system is stable 3) $\frac{-z}{z-5}$ and the system is unstable 4) $\frac{z}{z-5}$ and the system is unstable

Solution

Definition 1. The z-transform of a function is defined as

$$h[n] \stackrel{\mathcal{Z}}{\rightleftharpoons} H(z) \tag{0.0.1}$$

$$H(z) = \sum_{n=-\infty}^{\infty} h[n]z^{-n}$$
 (0.0.2)

Definition 2. The u[n] function is defined as

$$u[n] = \begin{cases} 1 & n \ge 0 \\ 0 & otherwise \end{cases}$$
 (0.0.3)

Lemma 0.1. If $h[n] = a^n u[n]$, then $h[n] \stackrel{\mathcal{Z}}{\rightleftharpoons} H[z] =$ $\frac{1}{1-az^{-1}} \text{ with } ROC = |z| > a$

Proof. Using the formula for the sum of an infinite GP, we get:

$$h[n] = \begin{cases} a^n & n \ge 0\\ 0 & otherwise \end{cases}$$
 (0.0.4)

$$\mathcal{Z}{h[n]} = H[z] = \sum_{n=-\infty}^{\infty} h[n]z^{-n}$$
 (0.0.5)

$$= \sum_{n=-\infty}^{0} 0 \times z^{-n} + \sum_{n=0}^{\infty} (az^{-1})^n$$
 (0.0.6)

$$= \frac{1}{1 - az^{-1}}, ROC = |az^{-1}| < 1 \tag{0.0.7}$$

$$= \frac{1}{1 - az^{-1}}, ROC = |z| > a \tag{0.0.8}$$

Lemma 0.2. If $h[n] = -a^n u[-n-1]$, then $h[n] \stackrel{\mathcal{Z}}{\rightleftharpoons}$ $H[z] = \frac{1}{1 - az^{-1}}$ with ROC = |z| < a

Proof. Using the formula for the sum of an infinite GP, we get:

$$h[n] = \begin{cases} -a^n & n \le -1\\ 0 & otherwise \end{cases}$$
 (0.0.9)

$$\mathcal{Z}\{h[n]\} = H[z] = \sum_{n=-\infty}^{\infty} h[n]z^{-n}$$
 (0.0.10)

$$= \sum_{n=-\infty}^{\infty} \left\{ -a^n u[-n-1] \right\} z^{-n} \tag{0.0.11}$$

$$= \sum_{n=-\infty}^{-1} -a^n z^{-n} + \sum_{n=-1}^{\infty} 0 \times z^{-1}$$
 (0.0.12)

$$= -\sum_{n=1}^{\infty} (a^{-1}z)^n = 1 - \sum_{n=0}^{\infty} (a^{-1}z)^n \quad (0.0.13)^n$$

$$= 1 - \frac{1}{1 - a^{-1}z}, ROC = |a^{-1}z| < 1$$
(0.0.14)

$$H[z] = \frac{1}{1 - az^{-1}}, ROC = |z| < a$$
 (0.0.15)

We are given h[n] as,

$$h[n] = -5^n u[-n-1]$$
 (0.0.16)

Then the z-transform of h[n] using (0.1) and (0.2) is,

$$H(z) = \frac{1}{1 - 5z^{-1}}, |z| < 5 \tag{0.0.17}$$

$$H(z) = \frac{z}{z - 5}, |z| < 5 \tag{0.0.18}$$

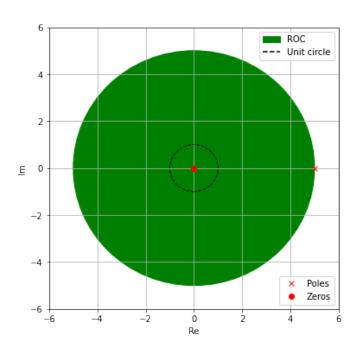


Fig. 4: Pole-zero plot of the system

Definition 3. An discrete-time system is BIBO stable if and only if its impulse response sequence h[n] is absolutely summable, i.e,

$$S = \sum_{n=-\infty}^{\infty} |h[n]| < \infty \tag{0.0.19}$$

Using (3) and (2)

$$S = \sum_{n=-\infty}^{\infty} |-5^n u[-n-1]| \qquad (0.0.20)$$

$$= \sum_{n=-\infty}^{-1} 5^n + \sum_{n=-1}^{\infty} 0 \times 5^n$$
 (0.0.21)

$$= -\sum_{n=1}^{\infty} 5^{-n} \tag{0.0.22}$$

$$=1-\sum_{n=0}^{\infty} (5^{-1})^n \tag{0.0.23}$$

Using the formula for the sum of an infinite GP, we get:

$$S = 1 - \frac{1}{1 - 5^{-1}} \tag{0.0.24}$$

$$=\frac{-1}{4}<\infty\tag{0.0.25}$$

So for a bounded input we get bounded output. Thus it is a stable system.

Thus option 2) is correct