

# APPROXIMATION ALGORITHMS FOR NETWORK DESIGN

IT 584: APPROXIMATION ALGORITHMS PROJECT PRESENTATION

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# INTRODUCTION

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- Network design problems have many practical applications ranging from the design process of **telecommunication and traffic networks** to **VLSI chip design**.
- Many of these design problems are proven to be **computationally intractable**.
- We discuss some Approximation Algorithms techniques as a possible way to navigate this deadlock.
- Here we will discuss the Approximation techniques on a very popular network design problem, **the minimum spanning tree**.

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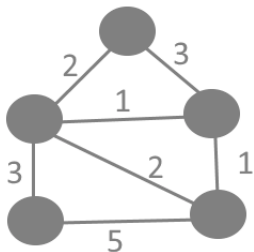
## THE GREEDY APPROACH FOR MST

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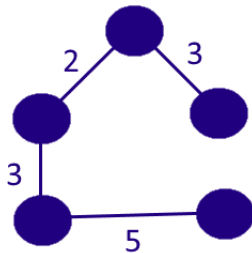
## WHAT IS A MST?

$G = (V, E)$  be a connected, undirected graph with vertex set  $V$  and edge set  $E$ . A minimum spanning tree  $T$  of  $G$  is a spanning tree of  $G$  such that the sum of the weights of its edges is minimized.

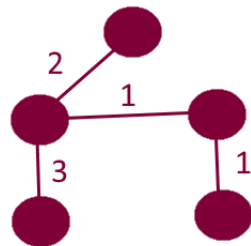
## EXAMPLE



Graph



Spanning Tree  
Cost = 13



Minimum Spanning  
Tree, Cost = 7

Figure 1: Graph to MST

Given a connected graph  $G(V,E)$ :

1. Sort all edges in ascending order of their weights.
2. Pick the smallest edge and check if it forms a cycle with the Spanning Tree formed so far.
3. Repeat the step until  $V-1$  edges are covered.

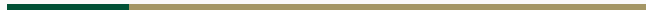


We will prove that each step we computed is correct for obtaining our optimal solution.

- Another way to think about Kruskal's algorithm is through the cut property.
- At any step we are crossing a cut(connecting previously unconnected groups of vertices) if the vertex is previously disconnected and has the minimum weight.

- This assumes that in each iteration we are connecting  $S$  and  $V-S$  such that the connecting edge, say  $(u,v)$ , is the edge of the minimum cost.
- Assume that it was not the case and there was another MST possible. There will be an edge  $(u',v')$  that cuts  $S$ ,  $V-S$  in this tree. But we know that  $(u,v)$  is the minimum edge that cuts  $S$  and  $V-S$ .

## ITERATIVE ROUNDING



Consider  $x_e$  primal variable for each edge  $e \in E$ , and  $c_e$  is the cost of each edge.  
We want to

$$\begin{aligned}
 & \text{minimize} && \sum_{e \in E} c_e x_e \\
 & \text{subject to} && \mathcal{X}(E(V)) = n - 1 \\
 & && \mathcal{X}(E(S)) \leq |S| - 1, \quad S \subset V, \\
 & && x_e \geq 0, \quad \forall e \in E
 \end{aligned} \tag{1}$$

where  $|V| = n - 1$ ,

- $E(S)$  : set of edges whose both endpoints lies in  $S$
- $\mathcal{X}(A) = \sum_{e \in A} x_e$

### Lemma

*Let  $G$  be a connected graph with at least two vertices and let  $x^*$  be a basic solution of (1) and let  $E^* = \{e \in E : x_e^* > 0\}$ . There exists a node  $v$  such that  $v$  is exactly incident to one edge in  $E^*$ .*

## LEMMA: INTUITION

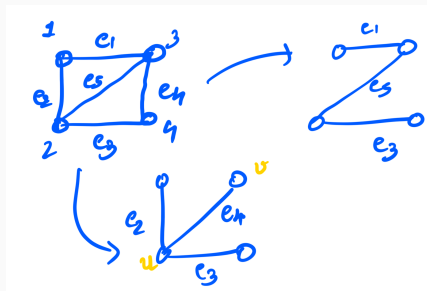


Figure 2: Caption

- Basic solution :  $x^* = (x_{e_1}, x_{e_3}, x_{e_3}, x_{e_4}, x_{e_5})$ ,
- Each node is covered by at least one edge in  $E^*$ .
- Due to constraints of LP we have  $x_{uv} = 1$

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**Algorithm 2** Iterative MST Algorithm

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Require: Connected graph  $G = (V, E)$

- 1:  $F = \phi$
  - 2: **while**  $V(G) \neq \phi$  and  $|V| > 1$  **do** :
    - 3:   Compute optimum basic solution  $x^*$  of (3) and remove all edges with  $x_e^* = 0$  from  $G$ .
    - 4:   Find vertex  $u$  as in Lemma (4.1) and let  $uv$  be the single support edge incident to it.
    - 5:   Add edge  $uv$  to  $F$ .
    - 6:   Delete  $u$  and all incident edges from  $G$ .
  - 7: **end while**
  - 8: Return  $F$ .
- 

Figure 3: Algorithm for MST

## ITERATIVE ALGORITHM : EXAMPLE

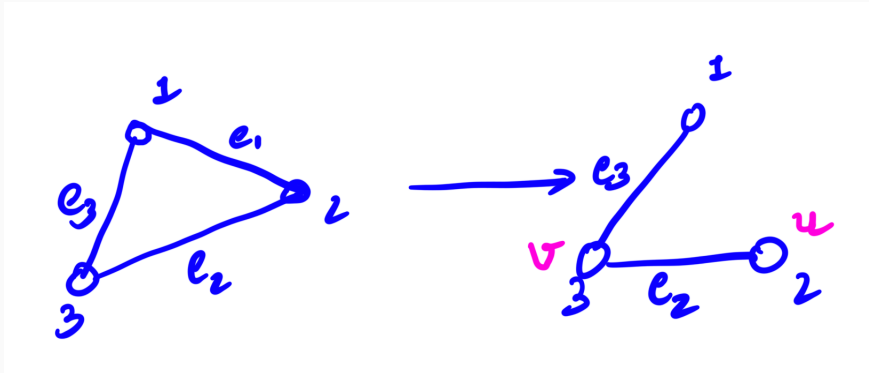


Figure 4: Algorithm Example



- Case 1: For one vertex is  $G$ , algorithm returns  $\phi$ .
- Case 2: For more than two vertices  
Obtain  $G' = (V', E')$  from  $G$  by deleting vertex  $u$  and its incident edges.
- Let  $x'$  be the projection of  $x^*$  onto edge set of  $G$ . Hence  $x' \in E'$  and  $x$  and  $x'_e = x_e^*$ .
- $x'$  is feasible for graph  $G'$ .

- For iteration 2 and on, we have  $c(F') \leq \sum_{e \in E'} c_e x_e^*$ .
- For  $F = F' \cup uv$ ,

$$c(F) = c(F') + c_{uv} \leq \sum_{e \in E} c_e x_e^*$$

## RANDOMIZED ROUNDING



- The intuition behind this algorithm is to let the decision variables  $x_i$  from the LP solution denote the probability of edge  $i$  getting selected.

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- We later see how this approach yields a tree with an expected cost of at most  $O(Z^* \log(n))$ , where  $Z^*$  is the cost of any feasible solution to the minimum spanning tree LP relaxation.

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**Algorithm 3** Random-Round-MST

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```
1:  $i \leftarrow 0$ 
2: repeat
3:    $i \leftarrow i + 1$ 
4:   Let  $A_i$  be the set of edges obtained by picking each edge  $e$  independently with probability  $x_e$ .
5: until  $G_i = (V, \bigcup_{j \leq i} A_j)$  is connected
6: return any spanning tree of  $G_i$ 
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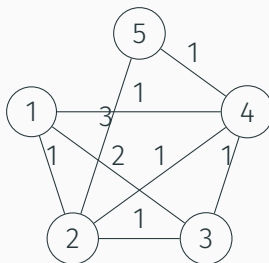
Figure 5: Randomized Rounding Algorithm

## RANDOMIZED ROUNDING ALGORITHM: EXAMPLE

Consider the graph:

Vertices:  $V = \{1, 2, 3, 4, 5\}$

Edges:  $E = \{(1, 2, 1), (1, 3, 2), (1, 4, 1), (2, 3, 1), (2, 4, 1), (2, 5, 3), (3, 4, 1), (4, 5, 1)\}$



**Intuition:** Let the Probability of getting a head be  $x_i$ . Now for each edge, toss a coin. If it's a head(success), include the edge; otherwise, exclude it.

- Iteration 1:
  - Example selection:  $A_1 = \{(1, 2), (2, 3), (4, 5)\}$
  - Check connectivity:  $G_1$  is not connected.

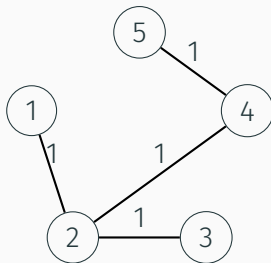


## RANDOMIZED ROUNDING ALGORITHM: ITERATIONS

- **Iteration 1:**
  - Example selection:  $A_1 = \{(1, 2), (2, 3), (4, 5)\}$
  - Check connectivity:  $G_1$  is not connected.
- **Iteration 2:**
  - Example selection:  $A_2 = A_1 \cup \{(1, 4), (2, 4)\}$
  - Check connectivity:  $G_2$  is connected.

## RANDOMIZED ROUNDING ALGORITHM: ITERATIONS

- **Iteration 1:**
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- **Iteration 2:**
  - Example selection:  $A_2 = A_1 \cup \{(1, 4), (2, 4)\}$
  - Check connectivity:  $G_2$  is connected.
- $G_2$  is connected, so we return any spanning tree of  $G_2$ .



## LEMMA: PROBABILISTIC BOUND ON NUMBER OF COMPONENTS

### Lemma

*Given any (multi)graph  $H = (U, E)$  and a feasible solution  $\{x_e\}_{e \in E}$  to the Primal Problem for this graph, suppose we pick each edge with probability  $x_e$  independently. Then the number of components is at most  $0.9|U|$  with probability at least  $\frac{1}{2}$ .*

### Proof.

- Isolated Vertex - Vertex not incident to any edge selected by the random process.
- Probability that a vertex  $u$  is isolated is:  $\prod_{e \in \delta(\{u\})} (1 - x_e)$
- Since,  $(1 - x) \leq e^{-x}$  and  $\sum_{e \in \delta(\{u\})} x_e \geq 1$
- We have  $\prod_{e \in \delta(\{u\})} (1 - x_e) \leq e^{-\sum_{e \in \delta(\{u\})} x_e} \leq \frac{1}{e}$ .
- Now, by the linearity of expectation, expected number of isolated vertices are at most  $|U|/e$ .
- Applying Markov Inequality, we get  $\Pr(X \leq 2|U|/e) \geq \frac{|U|/e}{2|U|/e} = \frac{1}{2}$ .

□

### Proof.

- Since, number of non-isolated nodes must be part of component of size at least 2.
- Total Number of Components = Number of Isolated Nodes +  $\frac{1}{2}$  Number of remaining Nodes.
- Therefore, Total Number of Components is at most  $|U|(2/e + 1/2(1 - 2/e)) < 0.9|U|$  with probability at least  $\frac{1}{2}$



## THEOREM: EXPECTED COST

### Theorem

*The expected cost of the tree returned by MST-Rand-Round is  $O(\log n)$  times the cost of the LP solution  $Z^*$ .*

### Proof.

- We show that the expected number of rounds before the procedure stops is  $\log n$ .
- Let  $L = 20 \log n$ . **We claim** that the graph  $G_L = (V, \cup_{j \leq L} A_j)$  is disconnected with probability at most  $1/2$ .
- If  $G_L$  is disconnected, an identical argument shows that  $G_{2L}$  will also be disconnected with probability at most  $1/2$ , and so on.
- Therefore, the expected number of rounds will be at most  $2L$ , i.e.  $O(\log n)$ .  
For instance, consider a graph with  $n = 8$  vertices. Let  $L = 20 \log 8 = 60$ . It means that after 60 rounds, the expected number of rounds for the algorithm to stop is  $2L = 120$ .



### Proof.

- To prove  $G_L$  is disconnected with probability at most  $1/2 \sim G_L$  is connected with probability at least  $1/2$ ;
- Let  $C_i$  denote the number of components of the graph  $G_i$ . An index  $i$  is considered successful if either:
  - $G_{i-1}$  is connected (i.e., if  $C_{i-1} = 1$ )
  - if  $C_i \leq 0.9 \cdot C_{i-1}$ .
- **Claim:** The probability of  $i$  being successful is at least  $1/2$  **regardless of all random choices made in previous rounds.**





### Proof.

**Claim:** The probability of  $i$  being successful is at least  $1/2$ .

### Proof:

- If  $G_{i-1}$  is connected, then  $i$  is always successful.
- Otherwise, let  $H_{i-1}$  be the graph on  $C_{i-1}$  vertices obtained by contracting all edges in  $G_{i-1}$ . Since each cut in  $H_{i-1}$  corresponds to a cut in  $G_{i-1}$ ,
- $\sum_{e \in \delta(S)} x_e \geq 1$  holds for  $H_{i-1}$ . By Lemma, the number of components after another round of randomly adding edges will cause  $C_i \leq 0.9 \cdot C_{i-1}$  with probability at least  $1/2$ .



### Proof.

- The probability that the graph  $G_L$  is not connected is bounded above by the probability that a sequence of  $L$  independent unbiased coin-flips contains fewer than  $10 \log n$  heads.
- Note that while the events in the random rounding process are not independent, we proved a lower bound of  $\frac{1}{2}$  on the probability of success regardless of the history.
- Since the number of rounds  $L$  is  $20 \log n$ , we observe that  $10 \log n$  "heads" suffice to ensure the graph remains connected with high probability.
- Hence the probability we see fewer than  $10 \log n$  heads (and hence the probability that  $G_L$  is not connected) is at most  $\frac{1}{2}$ , which completes the proof.



## MATCHING BASED AUGMENTATION

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Matching-based augmentation approximates minimum spanning trees (MSTs) in graphs. The idea is to iteratively grow a spanning tree by augmenting it with edges obtained from near-perfect matchings of the graph's nodes. It is most useful when the graph is represented as a metric space.

## MATCHING BASED AUGMENTATION: ALGORITHM

Let a metric space  $(V,d)$  where the cost of matching two nodes  $(u,v)$  is the distance  $d(u,v)$  between them. The algorithm is as follows:

1. Start with a metric space  $(V,d)$  and define  $V_0 = V$ .

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1. Start with a metric space  $(V,d)$  and define  $V_0 = V$ .
2. Then find a min-cost near-perfect matching  $M_0$  (which leaves at most one node unmatched) on the nodes  $V_0$ .

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4. Find a min-cost near-perfect matching  $M_1$  on  $V_1$ ; pick one of the newly matched vertices (and the unmatched vertex, if any) and form  $V_2$ .



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5. Continue the same as in *step 4* until  $|V_t| = 1$  for some  $t$ .

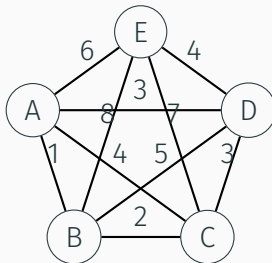
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5. Continue the same as in *step 4* until  $|V_t| = 1$  for some  $t$ .
6. Return the set of edges  $T = \cup_{j=0}^{t-1} M_j$ .

## MATCHING BASED AUGMENTATION: EXAMPLE

Let's illustrate this algorithm with a simple example:



We have vertices  $V = \{A, B, C, D, E\}$  and edge weights as follows:

- $d(A, B) = 1$ ,  $d(A, C) = 4$ ,  $d(A, D) = 3$ ,  $d(A, E) = 6$
- $d(B, C) = 2$ ,  $d(B, D) = 5$ ,  $d(B, E) = 8$
- $d(C, D) = 3$ ,  $d(C, E) = 7$
- $d(D, E) = 4$

## MATCHING BASED AUGMENTATION: EXAMPLE

→ Iteration 1:

- $M_0 = \{(A,B), (C,D)\}$
- $V_1 = \{A,D,E\}$

## MATCHING BASED AUGMENTATION: EXAMPLE

→ Iteration 1:

- $M_0 = \{(A,B), (C,D)\}$
- $V_1 = \{A,D,E\}$

→ Iteration 2:

- $M_1 = \{(A,D)\}$
- $V_2 = \{A,E\}$

## MATCHING BASED AUGMENTATION: EXAMPLE

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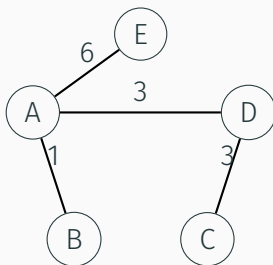
→ Iteration 3:

- $M_2 = \{(A,E)\}$
- $V_3 = \{A\}$

And the algorithm terminates here. The set of edges we got for the MST is  $\{(A, B), (C, D), (A, D), (A, E)\}$ . The cost of MST is = 13.

## MATCHING BASED AUGMENTATION: EXAMPLE

The MST formed is as follows:



The cost of MST given by our algorithm = 13.

### Theorem

*The above algorithm returns a tree of cost at most  $O(\log n)$  times that of the MST.*



The claim is that for each iteration  $i$ , all nodes in  $V \setminus V_i$  are connected to at least one node in  $V_i$  using the edges in the matchings  $\bigcup_{j < i} M_j$ . This is proven inductively:

- **Base Case:** For  $i = 0$ ,  $V_0 = V$ , and no nodes are removed yet. Hence, all nodes are connected to themselves in  $V_0$ .
- **Inductive Step:** Assume the claim is true for iteration  $i - 1$ . In iteration  $i$ , nodes in  $V_i \setminus V_{i-1}$  are newly selected nodes, taken from the previously matched pairs. These nodes are dropped because they were already connected to other nodes using the matching  $M_{i-1}$ . Therefore, the nodes in  $V_i \setminus V_{i-1}$  are still connected to  $V_i$ , confirming the inductive step.

- **Termination:** When the process stops (when  $|V_t| = 1$ ), all other nodes are connected to this one remaining node. As the algorithm connects all nodes and adds edges between nodes, the resulting set of edges forms a spanning tree.
- Since the final set of edges  $T$  consists of exactly  $n - 1$  edges (one less than the total number of nodes), it is a **spanning tree**.

## MATCHING BASED AUGMENTATION: PROOF OF COST OF MST

- As we find a near-perfect matching take a node from each edge of the matching and add it to the set  $V_i$ . Hence, at each step, we reduce the size of the vertices to *at most half* and the algorithm stops when  $|V_i| = 1$ . Hence, it takes at most  $\mathcal{O}(\log n)$  rounds.

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- Now, to prove our theorem, we need to show that the cost of each matching is at most  $d(T^*)$ , i.e. the cost of the optimal MST  $T^*$ .

## MATCHING BASED AUGMENTATION: PROOF OF COST OF MST

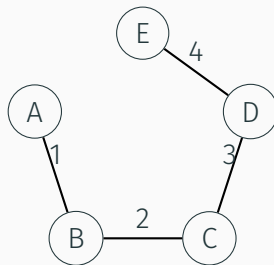
- As we find a near-perfect matching take a node from each edge of the matching and add it to the set  $V_i$ . Hence, at each step, we reduce the size of the vertices to *at most half* and the algorithm stops when  $|V_i| = 1$ . Hence, it takes at most  $\mathcal{O}(\log n)$  rounds.
- Now, to prove our theorem, we need to show that the cost of each matching is at most  $d(T^*)$ , i.e. the cost of the optimal MST  $T^*$ . Now, the Euler Tour  $C$  of the MST  $T^*$  has cost at most  $2d(T^*)$  since the Euler Tour might take an edge multiple times to travel all the nodes in the graph. To make the argument simpler, assume there are ' $2k$ ' nodes in  $V_i$ . If we rename these nodes to be  $\{x_0, x_1, \dots, x_{2k-1}, x_{2k} = x_0\}$  in the order we encounter them as we go around the tour, then by the triangle inequality,  $\sum_{i=0}^{2k-1} d(x_i, x_{i+1}) \leq 2d(T^*)$ . Now, we partition the Euler tour  $C$  into  $k$  pairs of nodes, either  $\{x_{2i}, x_{2i+1}\}$  or  $\{x_{2i+1}, x_{2i+2}\}$ , where  $0 \leq i < k - 1$ . So, one of the sums is at most half the cost of the Euler tour, i.e.,  $d(T^*)$ . And this is a valid matching of the nodes in  $V_i$ , therefore the cost of each matching  $M_i$  is at most  $d(T^*)$ , the cost of the MST  $T^*$ .

thus

$$M_i \leq d(T^*);$$
$$\sum M_i \leq \mathcal{O}(\log n)d(T^*)$$

.

The optimal MST formed will be as follows:



The cost of optimal MST formed = 10.

And,  $(\log(n)) * 10 = (\log(5)) * 10 = 23$ .

and our cost = 13.

# THANK YOU!

ANY QUESTIONS?