Analysis Output:

The problematic goal is 'Carry meals from the kitchen to all patient rooms.'. The system cannot achieve the sub-goal "Deliver 'meal' to 'r1'.".
The statements that cause the problem are:
'Carry meals from the kitchen to all patient rooms.' because of item(s): "Deliver 'meal' to 'r1'.".
"Don't go into any public rooms." because of item(s): "Do not go to 'hall_c'.".

No further analysis available.

SLURP Traceback:

- Start in the closet.
- Carry meals from the kitchen to all patient rooms.
  - Action: 'carry', Argument: 'meal', Source: 'kitchen', Destination: 'rooms'
    - Nothing is carried or delivered at the start.
    - Only pick up if you can carry more.
    - Only drop if you are carrying something.
    - Stay where you are when picking up and dropping.
    - Pick up 'meal' in 'kitchen'.
    - Deliver 'meal' to 'r1'.
      - ([](next(s.mem_deliver_r1) <-> (s.mem_deliver_r1 | (next(s.r1) & next(s.drop))))))
      - ([]<>(s.mem_deliver_r1))
    - Deliver 'meal' to 'r2'.
    - Deliver 'meal' to 'r3'.
    - Deliver 'meal' to 'r4'.
    - Deliver 'meal' to 'r5'.
    - Deliver 'meal' to 'r6'.
- Don't go into any public rooms.
  - Action: do not 'go', Location: 'rooms'
    - Do not go to 'hall_c'.
      - ([](!s.hall_c))
    - The robot does not begin in 'hall_c'.
    - Do not go to 'lounge'.
    - The robot does not begin in 'lounge'.