



# Introduction to Simulation

**Markov Chains** 

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- Markov Chain Research at the LfS

# **Motivation**

We want to build models that aid medical diagnoses.



## **Motivation**

#### The situation:

- We do not know which disease a patient has.
- We have a stochastic model of each disease.
- The disease has different stages.
- We know the daily probability of each state transition.
- We know the probability of each measurement at each stage.
- We can measure different symptoms.

We want to determine which disease is more likely.

#### But ...

we cannot directly observe the progress of the disease.



#### **Markov Chains**

## A Markov chain is a stochastic process ...

- with discrete states,
- with state changes at discrete points in time.

## For any pair of states, ...

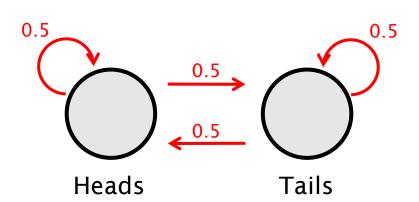
the state change between them has a fixed probability.

## Markov chain representations:

- Mathematically: Using linear algebra notation
- Graphically: As a directed, annotated graph

# A Very Simple Markov Chain

# Repeated coin tossing







# **Mathematical Representation**

#### Matrix P:

$$P = \begin{bmatrix} p_{hh} & p_{ht} \\ p_{th} & p_{tt} \end{bmatrix} = \begin{bmatrix} 0.5 & 0.5 \\ 0.5 & 0.5 \end{bmatrix}$$

#### Solution vector $\pi$ :

$$\pi = (\pi_{Heads}, \pi_{Tails})$$

## **Properties:**

- P is a stochastic matrix.
- $\pi$  is a probability row vector.



# **Mathematical Representation**

## Solving the Markov chain:

Iterated matrix-vector multiplication

$$\pi_k = \pi_{k-1} \cdot P$$

Example for coin tossing (Assume first result is *Heads*)

$$\pi_1 = (1.0,0.0)$$
 $\pi_2 = (0.5,0.5)$ 
 $\pi_3 = (0.5, 0.5)$ 
 $\vdots$ 

# A Slightly More Interesting Example

## Where does Graham go to eat every evening?

Three restaurants: Italian (I), Greek (G), Chinese (C)

## Observe Graham for 300 days:

CGIICGCICCGGCICGICGCGIICGCGCIGC...

#### Count # occurrences of each choice:

	С	G	I
С	20	30	50
G	10	30	60
	30	40	30

# A Slightly More Interesting Example

Solution vector: 
$$\pi = (\pi_C, \pi_G, \pi_I)$$

Stochastic matrix: 
$$P = \begin{bmatrix} p_{CC} & p_{CG} & p_{CI} \\ p_{GC} & p_{GG} & p_{GI} \\ p_{IC} & p_{IG} & p_{II} \end{bmatrix} = \begin{bmatrix} 0.2 & 0.3 & 0.5 \\ 0.1 & 0.3 & 0.6 \\ 0.3 & 0.4 & 0.3 \end{bmatrix}$$

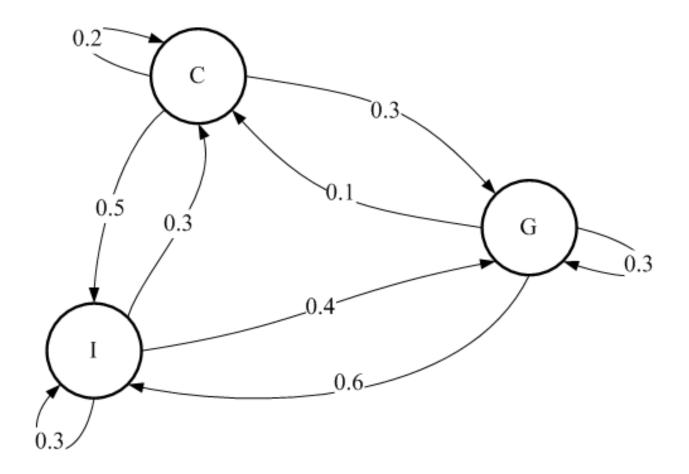
Solution (assuming first meal was C):

$$\pi_0 = (1.0000 \ 0.0000 \ 0.0000)$$
 $\pi_1 = (0.2000 \ 0.3000 \ 0.5000)$ 
 $\pi_2 = (0.2200 \ 0.3500 \ 0.4300)$ 
 $\pi_3 = (0.2080 \ 0.3430 \ 0.4490)$ 
 $\pi_4 = (0.2106 \ 0.3449 \ 0.4445)$ 
 $\pi_5 = (0.2100 \ 0.3445 \ 0.4456)$ 
 $\pi_6 = (0.2101 \ 0.3446 \ 0.4454)$ 
 $\pi_7 = (0.2101 \ 0.3445 \ 0.4454)$ 
 $\pi_8 = (0.2101 \ 0.3445 \ 0.4454)$ 



# A Slightly More Interesting Example

# Graphical representation of the Markov chain:





# **Applications**

Markov chains are extremely widespread.

## They are used in many fields of Science, for example:

- Physics (thermodynamics, mechanics)
- Chemistry (growth of molecules, enzyme behaviour)
- Informatics (data compression, pattern recognition)
- Operations Research (queues, logistics)
- Economics (market behaviour, pricing models)
- Biology (population dynamics)
- Medicine (epidemiology)



# Example

#### The situation to be modelled:

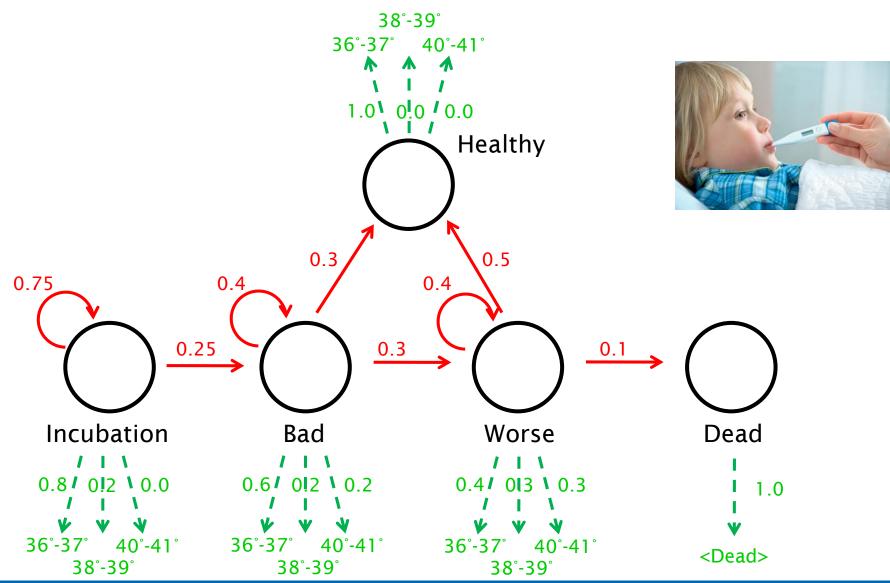
- The patient has either disease A or disease B.
- We can take their temperature once per day.
- We have a stochastic model of each disease.
- Each disease has three successive stages.
- We know the daily probability of each state transition.
- We know the probability of each temperature at each stage.

Which is more likely, disease A or disease B?





# **Example: The Model**







## **Direct Simulation is Problematic**

This model will allow us to perform a simulation.

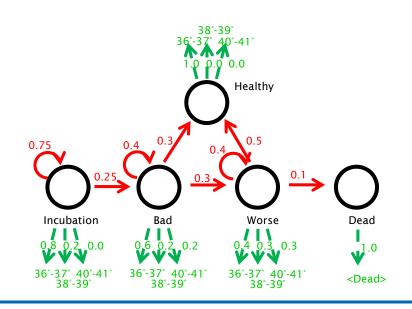
#### What can the simulation show us?

Individual samples of the dynamics of an unspecified patient.



# But what if we have a specific patient with specific symptoms?

- We would have to perform replications until we have seen the trace a sufficient number of times.
- This could take a very long time!







#### **Hidden Markov Chains**

#### A Hidden Markov Chain ...

- is based on a Markov chain,
- permits symbols to be emitted in each state,
- associates probabilities with each symbol emission.

## A *trace* is given:

A sequence of symbols that has been emitted by the HMM

# Questions that can be answered for a given HMM:

- What is the probability that it will produce the trace?
- What is the probability that a certain sequence of state changes generates the trace?

# **Applications**

#### When are HMMs used?

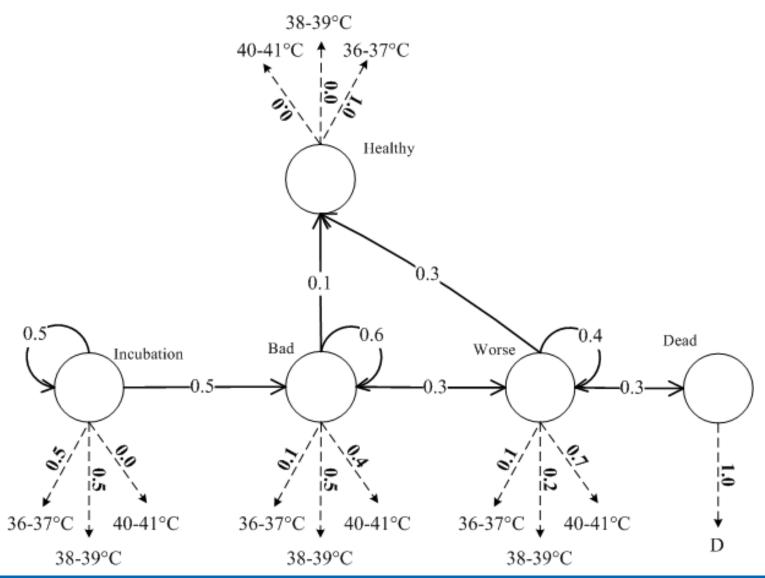
 To recover unobservable data sequences that can be inferred from associated data.

## Some examples:

- Handwriting recognition
- Speech recognition
- Gesture recognition
- Bioinformatics
- Cryptoanalysis



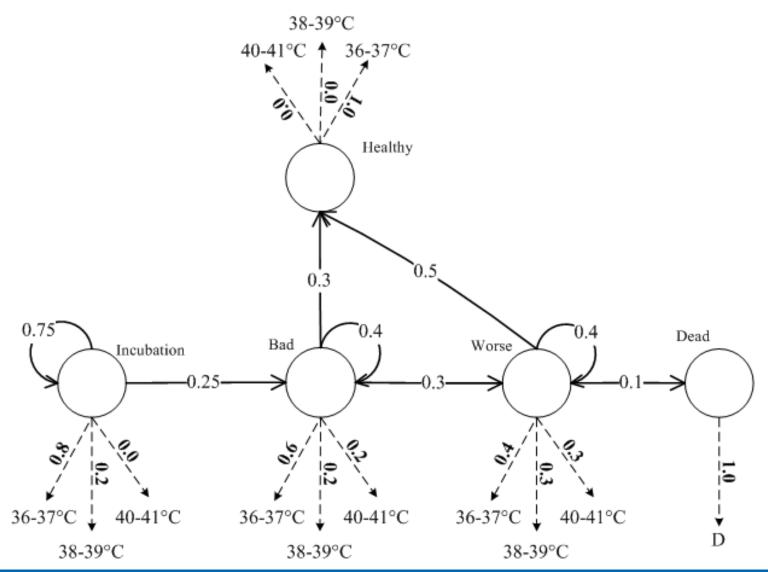
# **Model of Disease A**







# **Model of Disease B**





## **Nomenclature**

#### We have a set of states *S*:

$$S = \{Incubate, Bad, Worse, Healthy, Dead\}$$

We have a set of output symbols V:

$$V = \{36/37, 38/39, 40/41, Dead\}$$

We have the probabilities for the initial state:

$$\Pi = (1, 0, 0, 0, 0)$$

# The Analysis Task

# Given a sequence of observations *O*, ...

• For example, ...

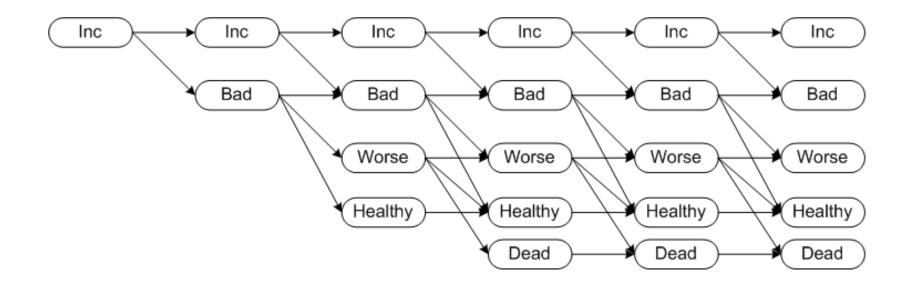
$$0 = (36, 37, 37, 40, 39, 37)$$

#### The task:

Compute which disease is more probable.

# **Analysis**

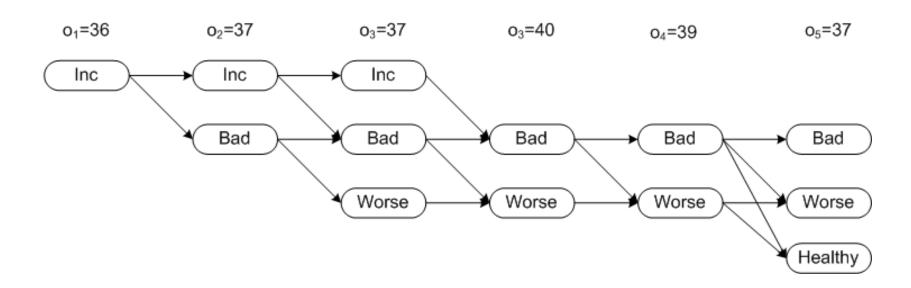
# The set of all possible paths of length 6:





# **Analysis**

The set of all paths that are consistent with the observation  $\mathcal{O}$ :



## Solution for Disease A

Compute the probability that model A will produce the trace.

#### Table of results:

Symbol	Incubate	Bad	Worse	Healthy	Dead
	1,000000	0,000000	0,000000	0,000000	0,000000
36°	0,500000	0,000000	0,000000	0,000000	0,000000
37°	0,125000	0,025000	0,000000	0,000000	0,000000
37°	0,031250	0,007750	0,000750	0,002500	0,000000
40°	0,000000	0,008110	0,001838	0,000000	0,000000
39°	0,000000	0,002433	0,000634	0,000000	0,000000
37°	0,000000	0,000146	0,000098	0,000433	0,000000

Total probability of the last row = 0.000678





# Solution for Disease B

## The analogous table for disease B:

Symbol	Incubate	Bad	Worse	Healthy	Dead
	1,000000	0,000000	0,000000	0,000000	0,000000
36°	0,800000	0,000000	0,000000	0,000000	0,000000
37°	0,480000	0,120000	0,000000	0,000000	0,000000
37°	0,288000	0,100800	0,014400	0,036000	0,000000
40°	0,000000	0,022464	0,010800	0,000000	0,000000
39°	0,000000	0,001797	0,003318	0,000000	0,000000
37°	0,000000	0,000431	0,000746	0,002198	0,000000

Total probability of the last row = 0.003376

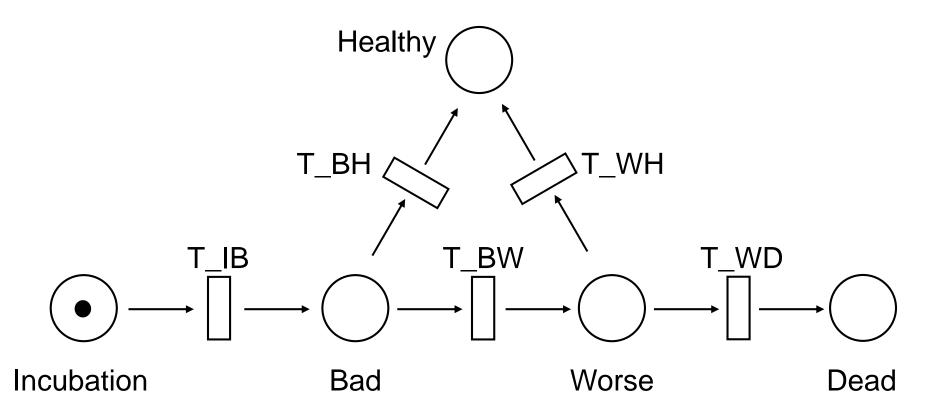
→ Disease B is more likely!



### A Real Time Model

#### Consider now a real-time model.

The state changes may have rates with general distributions.



#### A Real Time Model

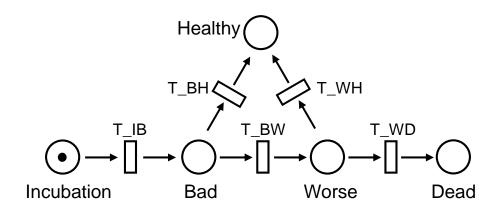
## Important consequence:

The model no longer corresponds to a Markov chain.

## Why not?

The state transition probabilities change as time progresses.

Until now, this case could not be modelled and simulated.



#### Research at the LfS

Research at the LfS is concerned with hidden models.

## We are interested in a more general case.

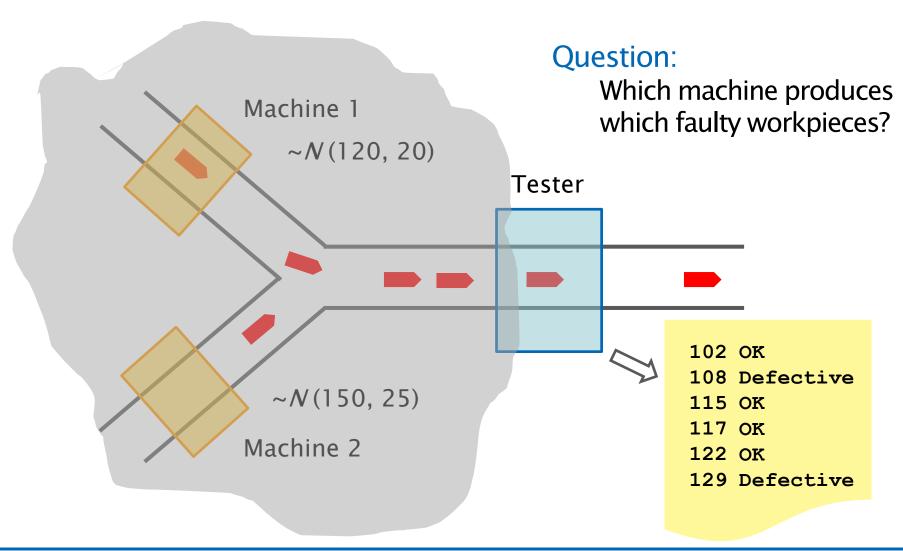
The stochastic process is not a Markov chain.

#### Some results:

- The HMM functionality can be achieved.
- However, many extra states must be added.
- The underlying Markov chain becomes larger and more complex.
- Several interesting possibilities are opened up.
- → Master-Module *Applied Discrete Modelling*



# **An Industrial Application**



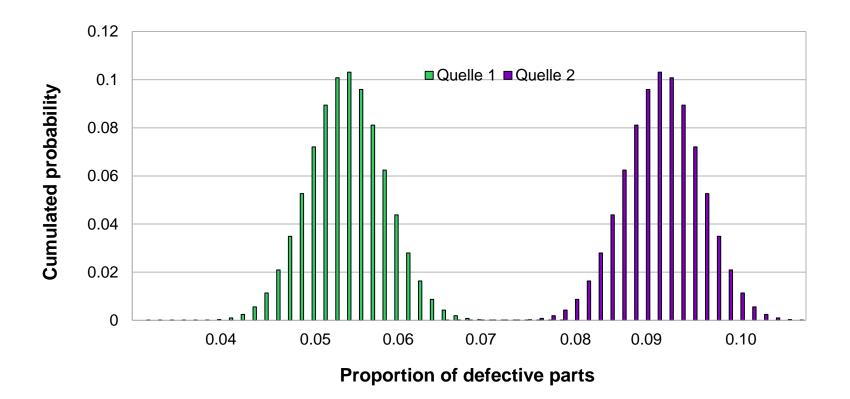




## **A Simulation Result**

# Distribution of the error probabilities for each machine

Machine 2 causes about twice as many errors as Machine 1.





### **Virtual Sensors**

#### A virtual sensor is ...

 A sensor that measures one quantity in order to infer a different one.

# Example:

 Use the electrical measurements of a sparking plug to determine the properties of the fuel mix.

# Virtual sensors have existed for a long time.

 They are used for continuous, physical, deterministic variables.





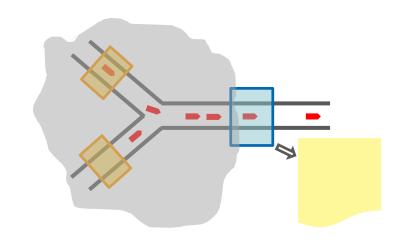
#### **Virtual Stochastic Sensors**

#### A virtual stochastic sensor is ...

 A sensor that measures one stochastic quantity in order to infer a different one.

# Example:

 Use the tester results in order to "virtually observe" the machines' behaviour.



Virtual stochastic sensors are an invention of the LfS.

#### **Current Research**

## Some of our current research questions

- What configurations are possible for virtual stochastic sensors?
- How do accuracy and computation time depend on the specific configuration?
- Can we develop efficient algorithms for specific classes of model?
- How much information must a symbol sequence have in order to reveal hidden system behaviour?



# **Scientific Papers**

# Robert Buchholz, Claudia Krull, Thomas Strigl, Graham Horton:

 Using Hidden non-Markovian Models to Reconstruct System Behaviour in Partially-Observable Systems

## Claudia Krull, Graham Horton:

 Hidden Non-Markovian Models: Formalization and Solution Approaches

# Claudia Krull, Robert Buchholz, Graham Horton:

Matching Hidden Non-Markovian Models: Diagnosing Illnesses
 Based on Recorded Symptoms

To be found at http://www.sim-md.de → Forschung

# **Learning Goals**

## Questions to test your knowledge:

- How is a DTMC defined?
- What is the mathematical representation of a DTMC?
- How would you compute the solution of a DTMC?
- Sketch the DTMC that is described by the following scenario: ...
- What is a Hidden Markov Chain? What is it used for?