Venkata Ramana Makkapati

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EDUCATION

Doctor of Philosophy, Aerospace Engineering

Aug' 2016 - Present

Georgia Institute of Technology

Focus: Optimal control under uncertainties, Autonomous vehicles, Cognitive hierarchy

theory, Pursuit-evasion games Advisor: Prof. Panagiotis Tsiotras

Master of Science, Computational Science and Engineering

Aug' 2017 - Present

Georgia Institute of Technology

Focus: Machine Learning

Master of Technology, Aerospace Engineering

July 2014 - May 2016

Indian Institute of Technology Kanpur Focus: Flight Dynamics and Control Advisor: Dr. Mangal Kothari

Bachelor of Technology, Aerospace Engineering

July 2010 - May 2014

Indian Institute of Technology Madras

Minor: Industrial Engineering

EXPERIENCE

Research Intern

May 2019 - Present

Foresight AI Inc, San Jose, CA

Topic: Research and development of motion planning and driving decision algorithms

& software

Mentor: Dr. Matheen Siddiqui

Summer Intern

May 2013 - July 2013

Vehicle Integration Department, Mahindra & Mahindra, Chennai

Topic: Approximation methods for the modal analysis of an exhaust system

Mentor: David Neihguk

Summer Intern

May 2012 - July 2012

Flight Mechanics and Control Division, CSIR-NAL, Bangalore

Topic: Evaluation of free-to-roll test technique to study unsteady motions of an

aircraft

Mentor: Dr. Mallesh Bommanahal

ARTICLES

Optimal Evading Strategies and Task Allocation in Multi-Player Pursuit-Evasion Problems

V. R. Makkapati and P. Tsiotras

Dynamic Games and Applications, 2019

Nested Saturation based Guidance Law for Unmanned Aerial Vehicles J. Patrikar, V. R. Makkapati, A. Pattanaik, H. Parwana, and M. Kothari ASME Journal of Dynamic Systems, Measurement, and Control, 2019

Optimal Evading Strategies for Two-Pursuer/One-Evader Problems V. R. Makkapati, W. Sun, and P. Tsiotras

Journal of Guidance, Control, and Dynamics (JGCD), 2018

A Comprehensive Differential Game Theoretic Solution to a Game of Two Cars R. Bera, V. R. Makkapati, and M. Kothari Journal of Optimization Theory and Applications (JOTA), 2017

Pursuit-Evasion Games of High Speed Evader M. V. Ramana and M. Kothari Journal of Intelligent & Robotic Systems (JINT), 2017

Pursuit Strategy to Capture High-Speed Evaders Using Multiple Pursuers M. V. Ramana and M. Kothari Journal of Guidance, Control, and Dynamics (JGCD), 2016

& TALKS

PROCEEDINGS Sequential Auto-Landing of Multiple UAVs using Control Constrained Path Following J. Patrikar, V. R. Makkapati, and M. Kothari

AIAA Guidance, Navigation, and Control Conference (GNC), SciTech, 2019

Trajectory Desensitization in Optimal Control Problems V. R. Makkapati, M. Dor, and P. Tsiotras IEEE Conference on Decision and Control (CDC), 2018

Optimal Strategies and Task Allocation in Multi-Pursuer Single-Evader Problems V. R. Makkapati and P. Tsiotras International Symposium on Dynamic Games and Applications, 2018 (Invited Talk)

Pursuit-Evasion Problems Involving Two Pursuers and One Evader V. R. Makkapati, W. Sun, and P. Tsiotras AIAA Guidance, Navigation, and Control Conference (GNC), SciTech, 2018

Motion Planning for a Fixed-Wing UAV in Urban Environments M. V. Ramana, S. A. Varma, and M. Kothari IFAC Conference on Advances in Control and Optimization of Dynamical Systems (ACODS), 2016

A Cooperative Pursuit-Evasion Game of a High Speed Evader M. V. Ramana and M. Kothari AIAA Guidance, Navigation, and Control Conference (GNC), SciTech, 2016

A Cooperative Pursuit-Evasion Game of a High Speed Evader M. V. Ramana and M. Kothari IEEE Conference on Decision and Control (CDC), 2015

TEACHING Graduate Teaching Assistant Aug' 2018 - Present

Multi-variable Linear Systems and Control

Teaching Assistant Aug' 2013 - May 2014

Flight Dynamics, Flight Stability & Control

SERVICE Consultative Group June 2019 - Present

Office of Principal Scientific Adviser, Government of India

Reviewer

IEEE Transaction on Automatic Control IEEE Robotics and Automation Letters Dynamics Games and Applications Journal of Aerospace Information Systems

Journal of Air Transportation

IEEE Conference on Decision and Control (CDC 2019)

American Control Conference (ACC 2018) AIAA Scitech Forum (GNC 2019, 2018)

Advances in Control and Optimization of Dynamical Systems (ACODS 2016)

EXTRA-CURRICULAR ACTIVITIES Long Distance Running

 $Bronze\ medal$ in the Dean's Trophy Road Race 2014 at IIT Madras

Team record for running the longest distance of 87 km on a treadmill in 6 hours at

Treadathon 2014, Chennai.

National Cadet Corps (NCC)

Leading Flight Cadet with B Certificate in the NCC examination