

Venkata Ramana Makkapati

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<https://vrmakkapati.github.io/>

EDUCATION	<i>Doctor of Philosophy, Aerospace Engineering</i> Georgia Institute of Technology Focus: Optimal control under uncertainties, Autonomous vehicles, Hypersonic vehicles, Cognitive hierarchy theory, Pursuit-evasion games Advisor: Prof. Panagiotis Tsiotras	Aug' 2016 - <i>Present</i>
	<i>Master of Science, Computational Science and Engineering</i> Georgia Institute of Technology Focus: Machine Learning	Aug' 2017 - <i>Present</i>
	<i>Master of Technology, Aerospace Engineering</i> Indian Institute of Technology Kanpur Focus: Flight Dynamics and Control Advisor: Dr. Mangal Kothari	July 2014 - May 2016
	<i>Bachelor of Technology, Aerospace Engineering</i> Indian Institute of Technology Madras Minor: Industrial Engineering	July 2010 - May 2014
EXPERIENCE	<i>Research Intern</i> Foresight AI Inc, San Jose, CA Topic: Research and development of motion planning and driving decision algorithms & software Mentor: Dr. Matheen Siddiqui	May 2019 - Aug' 2019
	<i>Summer Intern</i> Vehicle Integration Department, Mahindra & Mahindra, Chennai Topic: Approximation methods for the modal analysis of an exhaust system	May 2013 - July 2013
	<i>Summer Intern</i> Flight Mechanics and Control Division, CSIR-NAL, Bangalore Topic: Evaluation of free-to-roll test technique to study unsteady motions of an aircraft. Mentor: Dr. Mallesh Bommanahal	May 2012 - July 2012
ARTICLES	<i>DesNets: Desensitized Deep Neural Networks</i> V. R. Makkapati, H.Sarabu, P.Tsiotras, and J. Hoffman (in preparation)	
	<i>Covariance Steering for Discrete-Time Linear-Quadratic Stochastic Dynamic Games</i> V. R. Makkapati, T. Rajpurohit, K. Okamoto, and P. Tsiotras (in preparation)	
	<i>Safe Optimal Control under Parametric Uncertainties</i> V. R. Makkapati, H. Sarabu, V. Comandur, P. Tsiotras, and S. Hutchinson IEEE Robotics and Automation Letters (submitted)	

Optimal Evading Strategies and Task Allocation in Multi-Player Pursuit-Evasion Problems

V. R. Makkapati and P. Tsiotras

Dynamic Games and Applications, 2019

Nested Saturation based Guidance Law for Unmanned Aerial Vehicles

J. Patrikar, V. R. Makkapati, A. Pattanaik, H. Parwana, and M. Kothari

ASME Journal of Dynamic Systems, Measurement, and Control, 2019

Optimal Evading Strategies for Two-Pursuer/One-Evader Problems

V. R. Makkapati, W. Sun, and P. Tsiotras

Journal of Guidance, Control, and Dynamics (JGCD), 2018

A Comprehensive Differential Game Theoretic Solution to a Game of Two Cars

R. Bera, V. R. Makkapati, and M. Kothari

Journal of Optimization Theory and Applications (JOTA), 2017

Pursuit-Evasion Games of High Speed Evader

M. V. Ramana and M. Kothari

Journal of Intelligent & Robotic Systems (JINT), 2017

Pursuit Strategy to Capture High-Speed Evaders Using Multiple Pursuers

M. V. Ramana and M. Kothari

Journal of Guidance, Control, and Dynamics (JGCD), 2016

PROCEEDINGS & TALKS

C-DOC: Co-State Desensitized Optimal Control

V. R. Makkapati, D. Maity, M. Dor, and P. Tsiotras

American Control Conference (ACC), 2020

Sequential Auto-Landing of Multiple UAVs using Control Constrained Path Following

J. Patrikar, V. R. Makkapati, and M. Kothari

AIAA Guidance, Navigation, and Control Conference (GNC), SciTech, 2019

Trajectory Desensitization in Optimal Control Problems

V. R. Makkapati, M. Dor, and P. Tsiotras

IEEE Conference on Decision and Control (CDC), 2018

Optimal Strategies and Task Allocation in Multi-Pursuer Single-Evader Problems

V. R. Makkapati and P. Tsiotras

International Symposium on Dynamic Games and Applications, 2018 ([Invited Talk](#))

Pursuit-Evasion Problems Involving Two Pursuers and One Evader

V. R. Makkapati, W. Sun, and P. Tsiotras

AIAA Guidance, Navigation, and Control Conference (GNC), SciTech, 2018

Motion Planning for a Fixed-Wing UAV in Urban Environments

M. V. Ramana, S. A. Varma, and M. Kothari

IFAC Conference on Advances in Control and Optimization of Dynamical Systems (ACODS), 2016

A Cooperative Pursuit-Evasion Game of a High Speed Evader

M. V. Ramana and M. Kothari

AIAA Guidance, Navigation, and Control Conference (GNC), SciTech, 2016

A Cooperative Pursuit-Evasion Game of a High Speed Evader
M. V. Ramana and M. Kothari
 IEEE Conference on Decision and Control (CDC), 2015

SKILLS

Python, MATLAB, Simulink, C

SERVICE

Graduate Student Senator Jan' 2020 - *Present*
 School of Aerospace Engineering, Georgia Tech

Graduate Representative Jan' 2020 - *Present*
 School of Aerospace Engineering Student Advisory Council

Consultative Group June 2019 - *Present*
 Office of Principal Scientific Adviser, Government of India

Reviewer
 Automatica
 IEEE Transaction on Automatic Control
 IEEE Robotics and Automation Letters
 Dynamics Games and Applications
 Journal of Aerospace Information Systems
 Journal of Air Transportation
 International Conference on Robotics and Automation (ICRA 2020)
 IEEE Conference on Decision and Control (CDC 2019)
 American Control Conference (ACC 2020, 2018)
 AIAA Scitech Forum (GNC 2019, 2018)
 Advances in Control and Optimization of Dynamical Systems (ACODS 2016)

TEACHING

Graduate Teaching Assistant Aug' 2018 - *Present*
 Optimal Guidance & Control, Multi-variable Linear Systems and Control

Teaching Assistant Aug' 2013 - May 2014
 Flight Dynamics, Flight Stability & Control

EXTRA-CURRICULAR ACTIVITIES

Long Distance Running
Bronze medal in the Dean's Trophy Road Race 2014 at IIT Madras
Team record for running the longest distance of 87 km on a treadmill in 6 hours at Treadathon 2014, Chennai.

National Cadet Corps (NCC)
Leading Flight Cadet with *B Certificate* in the NCC examination