VENKATA RAMANA MAKKAPATI

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https://vrmakkapati.github.io

EDUCATION

• Ph.D., Aerospace Engineering

(Expected) 2021

Georgia Institute of Technology

Advisor: Prof. Panagiotis Tsiotras

Focus: Differential games, Optimal control under uncertainties, Cognitive hierarchy theory

• M.S., Computational Science and Engineering

(Expected) 2021

Georgia Institute of Technology

Focus: Machine Learning

• M.Tech., Aerospace Engineering

2016

Indian Institute of Technology Kanpur

Advisor: Prof. Mangal Kothari Focus: Flight dynamics and control

• **B.Tech.**, Aerospace Engineering

2014

Indian Institute of Technology Madras

Minor: Industrial Engineering

EXPERIENCE

• Graduate Research Assistant

Aug 2016 – present

Mentor: Prof. Panagiotis Tsiotras Georgia Institute of Technology

- Sensitivity-based analysis to mitigate for control design of hypersonic vehicles
- o Safe, resilient and efficient operation of autonomous aerial and ground vehicles
- o Optimal strategies for uncertain differential games with applications

Research Intern

May 2019 – Aug 2019

Mentor: Dr. Matheen Siddiqui Foresight AI Inc, San Jose, CA

- o POMDPs and RL based motion planning and driving decisions algorithms & software
- Summer Intern

May 2013 – July 2013

Vehicle Integration Department

Mahindra & Mahindra, Chennai, India

o Approximation methods for the modal analysis of an exhaust system

2010

Summer Intern May 2012 – July 2012

Flight Mechanics and Control Division

CSIR - National Aerospace Laboratories, Bangalore, India

o Evaluation of free-to-roll test technique to study unsteady motions of an aircraft

CERTIFICATIONS

• Private Pilot (Airplane Single Engine Land)
Federal Aviation Administration (FAA)

Nov 2020

• Leading Flight Cadet

2011

4-TN Air Squadron, National Cadet Corps (NCC)

o B Certificate in the NCC examination

PUBLICATIONS _____

Peer-reviewed

JOURNAL ARTICLES

J1. Safe Optimal Control under Uncertainties

V. R. Makkapati, H. Sarabu, V. Comandur, P. Tsiotras, and S. Hutchinson *IEEE Robotics and Automation Letters (RA-L)*, 2020

J2. Optimal Evading Strategies and Task Allocation in Multi-Player Pursuit-Evasion Problems V. R. Makkapati and P. Tsiotras

Dynamic Games and Applications (DGAA), 2019

- J3. Nested Saturation based Guidance Law for Unmanned Aerial Vehicles J. Patrikar, V. R. Makkapati, A. Pattanaik, H. Parwana, and M. Kothari ASME Journal of Dynamic Systems, Measurement, and Control, 2019
- J4. Optimal Evading Strategies for Two-Pursuer/One-Evader Problems V. R. Makkapati, W. Sun, and P. Tsiotras Journal of Guidance, Control, and Dynamics (JGCD), 2018
- J5. A Comprehensive Differential Game Theoretic Solution to a Game of Two Cars R. Bera, V. R. Makkapati, and M. Kothari Journal of Optimization Theory and Applications (JOTA), 2017
- J6. Pursuit-Evasion Games of High Speed Evader
 M. V. Ramana and M. Kothari
 Journal of Intelligent & Robotics Systems (JINT), 2017
- J7. Pursuit Strategy to Capture High-Speed Evaders Using Multiple Pursuers M. V. Ramana and M. Kothari
 Journal of Guidance, Control, and Dynamics (JGCD), 2016

CONFERENCE PROCEEDINGS

- C1. Desensitized Trajectory Optimization for Hypersonic Vehicles V. R. Makkapati, J. Ridderhof, P. Tsiotras, J. Hart, and B. van Bloemen Waanders IEEE Aerospace Conference, 2021
- C2. Covariance Steering for Discrete-Time Linear-Quadratic Stochastic Dynamic Games V. R. Makkapati, T. Rajpurohit, K. Okamoto, and P. Tsiotras *IEEE Conference on Decision and Control (CDC)*, 2020
- C3. C-DOC: Co-state Desensitized Optimal Control V. R. Makkapati, D. Maity, M. Dor, and P. Tsiotras *American Control Conference (ACC)*, 2020
- C4. Sequential Auto-Landing of Multiple UAVs using Control Constrained Path Following J. Patrikar, V. R. Makkapati, and M. Kothari *AIAA Guidance, Navigation, and Control Conference (GNC), SciTech*, 2019
- C5. Trajectory Desensitization in Optimal Control Problems V. R. Makkapati, M. Dor, and P. Tsiotras *IEEE Conference on Decision and Control (CDC)*, 2018
- C6. Pursuit-Evasion Problem Involving Two Pursuers and One Evader V. R. Makkapati, W. Sun, and P. Tsiotras AIAA Guidance, Navigation, and Control Conference (GNC), SciTech, 2018
- C7. Motion Planning for a Fixed-Wing UAV in Urban Environments M. V. Ramana, S. A. Varma, and M. Kothari Advances in Control and Optimization of Dynamical Systems (ACODS), 2016
- C8. A Cooperative Pursuit Strategy for a High Speed Evader
 M. V. Ramana and M. Kothari
 AIAA Guidance, Navigation, and Control Conference (GNC), SciTech, 2016
- C9. A Cooperative Pursuit-Evasion Game of a High Speed Evader M. V. Ramana and M. Kothari

 IEEE Conference on Decision and Control (CDC), 2015

WORKSHOP PAPERS

W1. Apollonius Allocation Algorithm for Heterogeneous Pursuers to Capture Multiple Evaders V. R. Makkapati and P. Tsiotras Workshop on Heterogeneous Multi-Robot Task Allocation and Planning, Robotics: Science and Systems (RSS), 2020

INVITED TALKS

• Desensitization for Safe Planning under Parametric Uncertainties IRIM-Robograds Virtual Student Seminar on Robot Planning • Optimal Strategies and Task Allocation in Multi-Pursuer Single-Evader Problems July 2018 International Symposium on Dynamic Games and Applications

TEACHING

• Graduate Teaching Assistant, Georgia Institute of Technology

o AE 6511: Optimal Guidance & Control

Spring 2019

o AE 6530: Multi-Variable Linear Systems and Control

Fall 2018

• Teaching Assistant, Indian Institute of Technology Kanpur

o AE647A: Flight Dynamics

Fall 2015

o AE648A: Flight Stability & Control

Spring 2016

AWARDS

LONG DISTANCE RUNNING

• Bronze Medal
Dean's Trophy Road Race, IIT Madras

Apr 2014

• Team Record – Longest Distance (87 km) on a Treadmill Treadathon, Chennai

Mar 2014

SERVICE _____

INSTITUTE SERVICE

• **Graduate Representative**School of Aerospace Engineering Student Advisory Council (SAESAC), Georgia Tech

• Senator (Aerospace Engineering)
Graduate Student Government Association (Grad SGA), Georgia Tech

Jan 2020 – Aug 2020

EVENT ORGANIZATION

• Lectures Series on Learning and Control Virtual event

Nov 2020 - Jan 2021

REVIEWER

- Automatica
- IEEE Transactions on Automatic Control
- IEEE Transactions on Robotics
- IEEE Robotics and Automation Letters
- Dynamic Games and Applications

- Journal of Aerospace Information Systems
- Journal of Air Transportation
- IEEE International Conference on Robotics and Automation
- IEEE Conference on Decision and Control
- American Control Conference
- AIAA SciTech Forum
- Advances in Control and Optimization of Dynamical Systems

OTHER

• Consultant
Office of the Principal Scientific Adviser to Government of India

June 2019 – present