

# **Tackling Many Objectives**

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# **What is SUSTech?**

- **Southern University of Science and Technology (SUSTech)**
- **The youngest public university in China**
- **Started officially in 2012 as a research intensive international university**
- **Only 6 year old**

# Where is SUSTech?

- Shenzhen.
- But where is Shenzhen?



# Shenzhen: Silicon Valley in China



"Shenzhen is the city that most resembles the Silicon Valley."

--- *Business*

*Week (2014)*



# The most competitive city economically in China



✓ High technology

✓ Finance services

✓ Logistics industry

✓ Culture industry

# **Department of Computer Science and Engineering (CSE)**

- **Only established in 2016**
- **Currently 20 tenure track faculty members, recruited from all over the world (many more researchers)**
- **Growth plan: 55 tenure track faculty members**

# OPAL (OPTimisation And Learning) Group

- 5 tenure track professors
  - Ran Cheng, Hisao Ishibuchi, Yuhui Shi, Ke Tang, Xin Yao
- ~10 research professors and postdoc researchers.
- International recognition
  - 3 IEEE fellows (H-indices: 90, 66, 47): ~120K Google Scholar citations;
    - Hisao Ishibuchi, Yuhui Shi, Xin Yao;
  - IEEE Computational Intelligence Society (CIS) *Evolutionary Computation Pioneer Award* (Xin) and *Fuzzy Systems Pioneer Award* (Hisao)
  - IEEE CIS *Early Career Award* (Ke Tang)
  - IEEE CIS *Outstanding PhD Dissertation Award* (Ran Cheng)
  - JSPS Award (Hisao)
  - Royal Society Wolfson Research Merit Award (Xin)
  - Royal Society Newton Advanced Fellowship (Ke)



# Some Research Topics



计算机科学与工程系

Department of Computer Science and Engineering

- **Evolutionary learning and optimisation**
  - Multi-objectivity
  - Dynamics
  - Uncertainty
- **Ensemble machine learning**
  - Online learning
  - Class imbalance learning
- **Neural network learning**
- **Real-world applications**
  - Smart logistics
  - Search-based software engineering
  - Fault diagnosis
  - Reconfigurable computing architectures



# **We Have Many Openings**

- **There is nothing more exiting than being part of a growing story.**
- **We recruit**
  - Faculty members
  - Postdoctoral research fellows
  - PhD students
  - Visitors
- **We teach in English.**
- **Email: [xiny@sustc.edu.cn](mailto:xiny@sustc.edu.cn)**

# Outline

- **Introduction**
- **Objective Reduction**
- **Alternative Dominance Relationship**
- **Improved Two-Archive Algorithm (Two\_Arch2)**
- **Conclusions and Future Work**

# What is multi-objective optimisation?

- More than one objective to be optimised, with or without constraints.

$$\min/\max f_m(\mathbf{x}), \quad m=1, 2, \dots, M$$

$$\text{subject to } g_j(\mathbf{x}) \geq 0, \quad j=1, 2, \dots, J$$

$$h_k(\mathbf{x}) = 0, \quad k=1, 2, \dots, K$$

$$\underset{\substack{\text{lower} \\ \text{bound}}}{x_i^{(L)}} \leq x_i \leq \underset{\substack{\text{upper} \\ \text{bound}}}{x_i^{(U)}}, \quad i=1, 2, \dots, n$$



# Multi-objective Evolutionary Algorithms

- MOEAs have been widely used in the last 20 years for multi-objective optimisation.
- They can provide a *set of non-dominated solutions in a single run without requiring the set of weights.*
- They do not require the objective functions to be convex, smooth, or even continuous.
- They can handle nonlinear constraints.
- They can deal with uncertainty and dynamics.

# An Indicator of MOEA's Impact

- Deb, K., Pratap, A., Agarwal, S., and Meyarivan, T. (2002). A fast and elitist multiobjective genetic algorithm: NSGA-II. *IEEE Transaction on Evolutionary Computation*, 6(2), 181-197. (**29,491 Google Scholar citations**)

# **Wow!**

- **That's impressive.**



# Unfortunately

- NSGA-II and other early MOEAs work well only with 2 or 3 objectives.
- They do not work well when the number of objectives goes beyond that.
- There is a scalability issue in terms of the number of objectives.
- In this talk, we consider **Many Objective Optimisation**, indicating the number of objectives is greater than three.

# **Two Possible Approaches to Problem-Solving**

- 1. Develop more sophisticated solutions to complex problems.**
- 2. Simplify a complex problem so that an existing solution can be applied.**

**Can we simplify MaOPs into MOPs?**

**Can we reduce the number of  
objectives?**



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- Objective Reduction

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# Objective Reduction

- If two objectives are positively correlated, we need to optimise only one of them.
- There are many methods that could be used to reduce the number of objectives.
- We give one example here.

# Nonlinear Correlation Information

## Entropy (NCIE)

- NCIE is an entropy measure.
- NCIE firstly divides variables  $X$  and  $Y$  into  $b*b$  uniform rank grids. Then, the probabilities  $p_{ij}$  can be approximated by counting the samples in those grids. In other words,  $p_{ij}$  in the  $ij$ -th grid can be calculated by the number of solutions in  $ij$ -the grid ( $n_{ij}/N$ ).
- Parameter  $b$  can be set as  $N^{0.5}$ .

$$H^r(X) = -\sum_{i=1}^b \frac{n_i}{N} \log_b \left( \frac{n_i}{N} \right)$$

$$H^r(X, Y) = -\sum_{i=1}^b \sum_{j=1}^b \frac{n_{ij}}{N} \log_b \left( \frac{n_{ij}}{N} \right)$$

$$NCIE(X, Y) = H^r(X) + H^r(Y) - H^r(X, Y)$$

# Objective Reduction Based on NCIE

- Correlation analysis is based on the matrix of modified NCIE  $R^N$  of *the non-dominated population*.

$$R^N = \{Sgn(cov_{ij})NCIE_{ij}\}, (1 \leq i, j \leq m)$$

- Objective selection aims to choose the most conflicting objectives.

- Our approach is applied in **every generation** of MOEAs to update the correlation information among objectives.

# Objective Selection: An Example

- Select the most conflicting objective
- Remove the objectives that are positively correlated to the selected objective

	$f_1$	$f_2$	$f_3$	$f_4$	$f_5$
$f_1$	1.0000	0.4959	0.4244	0.5348	-0.3552
$f_2$	0.4959	1.0000	0.3972	0.4686	-0.3381
$f_3$	0.4244	0.3972	1.0000	0.4765	-0.4352
$f_4$	0.5348	0.4686	0.4765	1.0000	-0.4488
$f_5$	-0.3552	-0.3381	-0.4352	-0.4488	1.0000
$\sum NCIE < 0$	-0.3552	-0.3381	-0.4352	-0.4488	-1.5773

- ✓  $f_5$  is selected, because it has the most conflicting degree with other objectives.
- ✓ There is no objective positively correlated to  $f_5$ , thus, there is not a redundant objective with  $f_5$  in the remaining objectives.
- ✓  $f_4$  is selected, because it has the largest absolute sum of NCIEs to other objectives.  $f_1$ ,  $f_2$ , and  $f_3$  are omitted, they are all positively correlated to  $f_4$ .
- ✓ Output  $\{f_5, f_4\}$



**Objective reduction can remove  
redundant objectives, but what if there  
is no redundancy?**

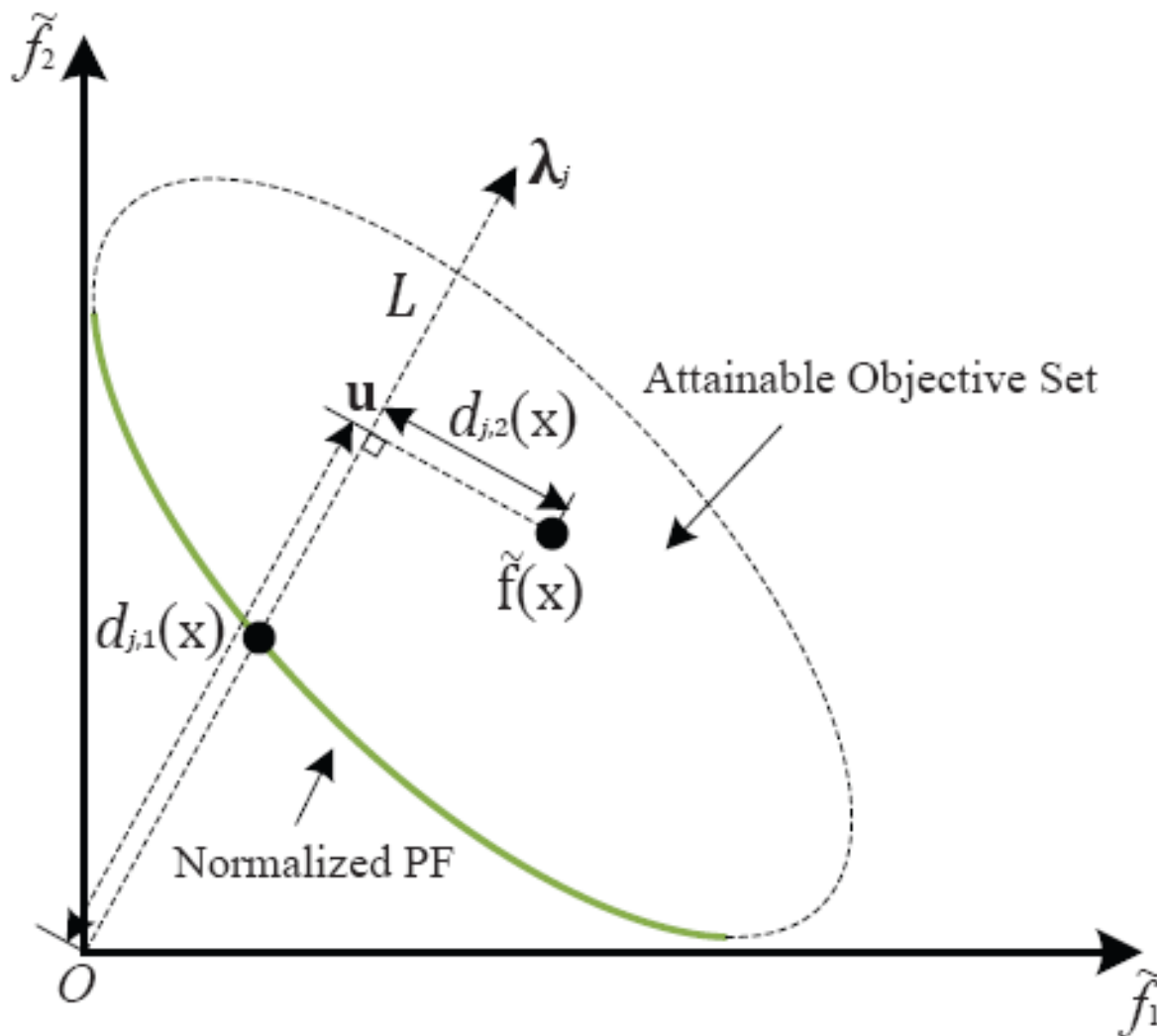
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- Objective Reduction
- **Alternative Dominance Relationship**
- Improved Two-Archive Algorithm (Two\_Arch2)
- Conclusions and Future Work

# **Why Are Many Objectives Hard?**

- **The number of non-dominated solutions increases exponentially as the number of objectives grows.**
- **As a result, there is no selection pressure in MaOEAs to drive the evolutionary search.**
- **Can we use alternative dominance relationship other than Pareto dominance?**

# $\Theta$ -dominance --- Intuition



- $\tilde{f}$ s are normalised objective functions.
- $\lambda$  is the reference direction (point).

•Y. Yuan, H. Xu, B. Wang and X. Yao, "A New Dominance Relation Based Evolutionary Algorithm for Many-Objective Optimization," *IEEE Transactions on Evolutionary Computation*, 20(1):16-37, February 2016.

Fig. 3. Illustration of distances  $d_{j,1}(x)$  and  $d_{j,2}(x)$ .

# $\Theta$ -dominance --- Definition

*Definition 7:* Given two solutions  $\mathbf{x}, \mathbf{y} \in S_t$ ,  $\mathbf{x}$  is said to  $\theta$ -dominate  $\mathbf{y}$ , denoted by  $\mathbf{x} \prec_{\theta} \mathbf{y}$ , iff  $\mathbf{x} \in C_j$ ,  $\mathbf{y} \in C_j$ , and  $\mathcal{F}_j(\mathbf{x}) < \mathcal{F}_j(\mathbf{y})$ , where  $j \in \{1, 2, \dots, N\}$ .

$$\mathcal{F}_j(\mathbf{x}) = \bar{d}_{j,1}(\mathbf{x}) + \theta d_{j,2}(\mathbf{x})$$

Y. Yuan, H. Xu, B. Wang and X. Yao, "A New Dominance Relation Based Evolutionary Algorithm for Many-Objective Optimization," *IEEE Transactions on Evolutionary Computation*, 20(1):16-37, February 2016.

# Balancing Convergence and Diversity

■ The form of  $F_j(x)$  indicates that the balance between convergence and diversity is very important in MaOEAs.

■ Why not manipulating the balance explicitly?

- Y. Yuan, H. Xu, B. Wang, B. Zhang and X. Yao, "Balancing Convergence and Diversity in Decomposition-Based Many-Objective Optimizers," *IEEE Transactions on Evolutionary Computation*, 20(2):180-198, April 2016.

■ Don't know how to strike the balance?

- B. Li, K. Tang, J. Li and X. Yao, "Stochastic Ranking Algorithm for Many-Objective Optimization Based on Multiple Indicators," *IEEE Transactions on Evolutionary Computation*, 20(6):924-938, December 2016.



**What if alternative dominance relationships still do not provide a satisfactory solution to a MaOP?**

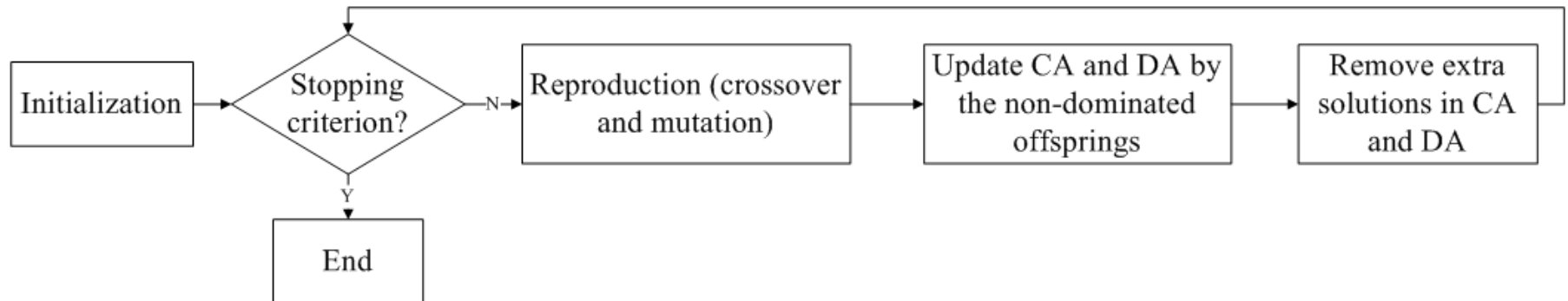
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# Two-Archive Algorithm

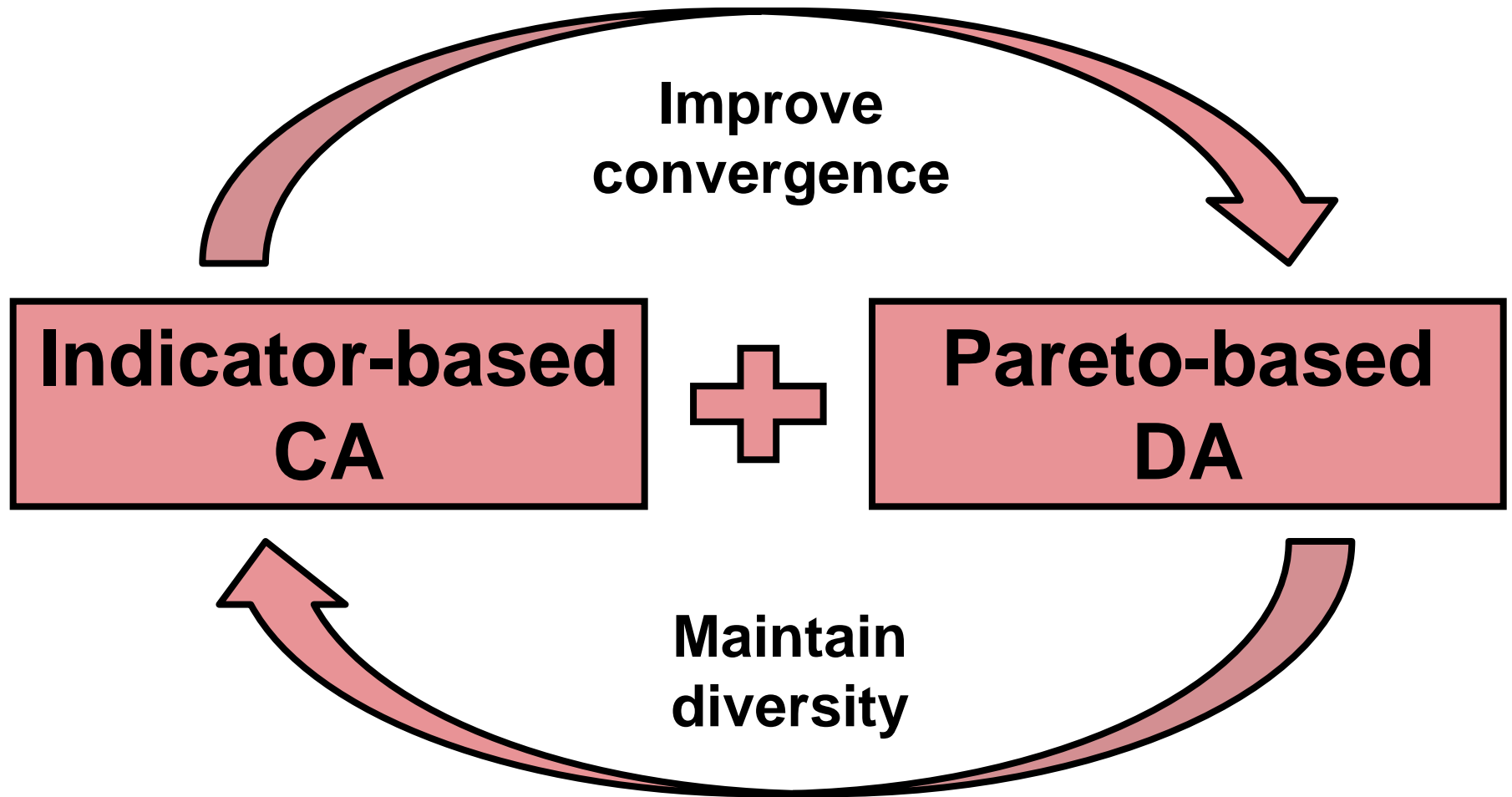
- Two-Archive algorithm (Two\_Arch) maintains two archives (CA and DA) to promote **convergence** and **diversity** separately.

•K. Praditwong and X. Yao, "A New Multi-objective Evolutionary Optimisation Algorithm: The Two-Archive Algorithm," *Proc. of the 2006 International Conference on Computational Intelligence and Security (CIS'2006)*, 3-6/11/2006, Ramada Pearl Hotel, Guangzhou, China. IEEE Press, Volume 1, pp.286-291.



# Improved Two-Archive Algorithm:

## Main Idea



# Two\_Arch2: Main Steps

**Step 1: Initialization.**

**Step 2: Output DA if the stopping criterion is met, otherwise continue.**

**Step 3: Generate new solutions from CA and DA by crossover and mutation.**

**Step 4: Update CA and DA separately, go Step 2.**

- H. Wang, L. Jiao and X. Yao, “Two\_Arch2: An Improved Two-Archive Algorithm for Many-Objective Optimization,” *IEEE Transactions on Evolutionary Computation*, 19(4):524-541, August 2015.

# Convergence Archive (CA)

- The quality indicator  $I_{\varepsilon+}$  in IBEA is used in selection of CA.  $I_{\varepsilon+}$  is an indicator that describes the minimum distance that one solution needs to dominate another solution in the objective space.

$$I_{\varepsilon+}(x_1, x_2) = \min_{\varepsilon} (f_i(x_1) - \varepsilon \leq f_i(x_2), 1 \leq i \leq m)$$

- The fitness is assigned as below, the solution with the smallest fitness is removed from CA first.

$$F(x_1) = \sum_{x_2 \in P \setminus \{x_1\}} -e^{-I_{\varepsilon+}(x_2, x_1)/0.05}$$



# Diversity Archive (DA)

- **Update DA**
  - **When DA overflows, boundary solutions (solutions with maximal or minimal objective values) are firstly selected.**
  - **In the iterative process, the most different solution from the current DA is added until reaching the size.**
- **$L_p$ -norm distance is adopted as the similarity measure in DA.**
- **DA is used as the final output of Two\_Arch2.**

# Degraded Euclidean Distance (Distance Concentration) in High-Dimensional Space

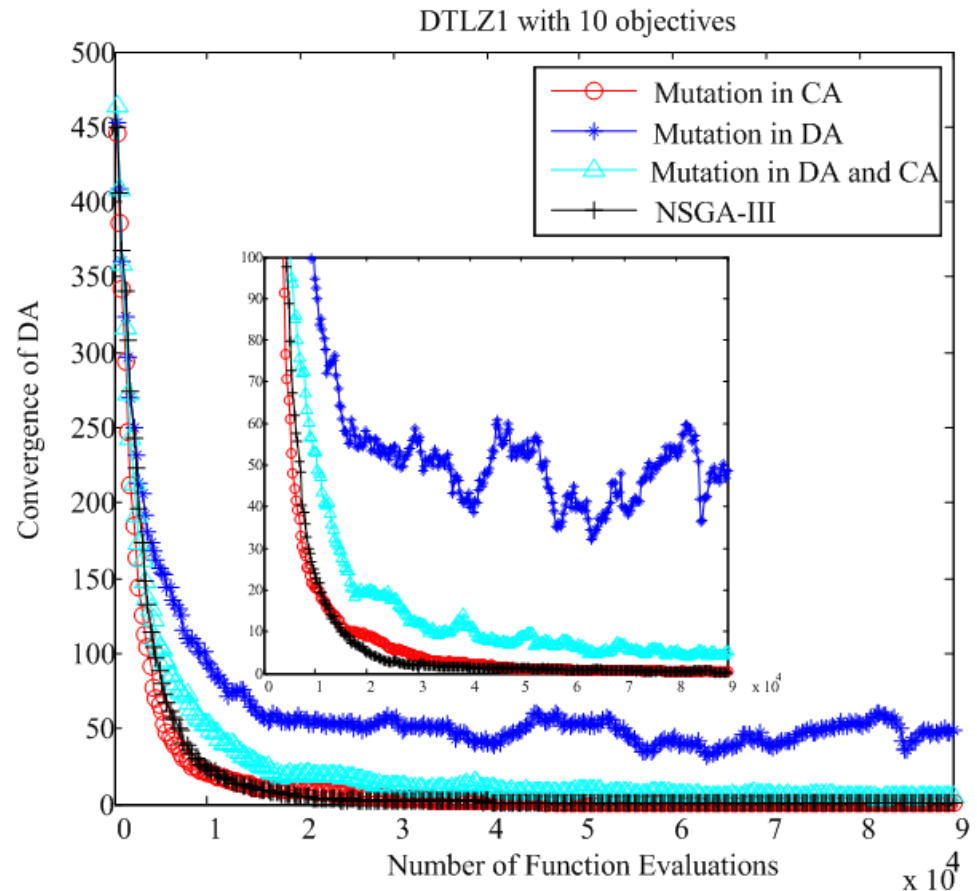
- The Euclidean distance ( $L_2$ -norm) degrades its similarity indexing performance in a high-dimensional space.
- Most of existing diversity maintenance methods use the Euclidean distance to measure similarity among solutions for MaOPs.

# Similarity in High-Dimensional Space

- The fractional distances ( $L_p$ -norm,  $p < 1$ ) perform better in a high-dimensional space.
- $L_{1/m}$ -norm is employed in Two\_Arch2, where  $m$  is the number of objectives.

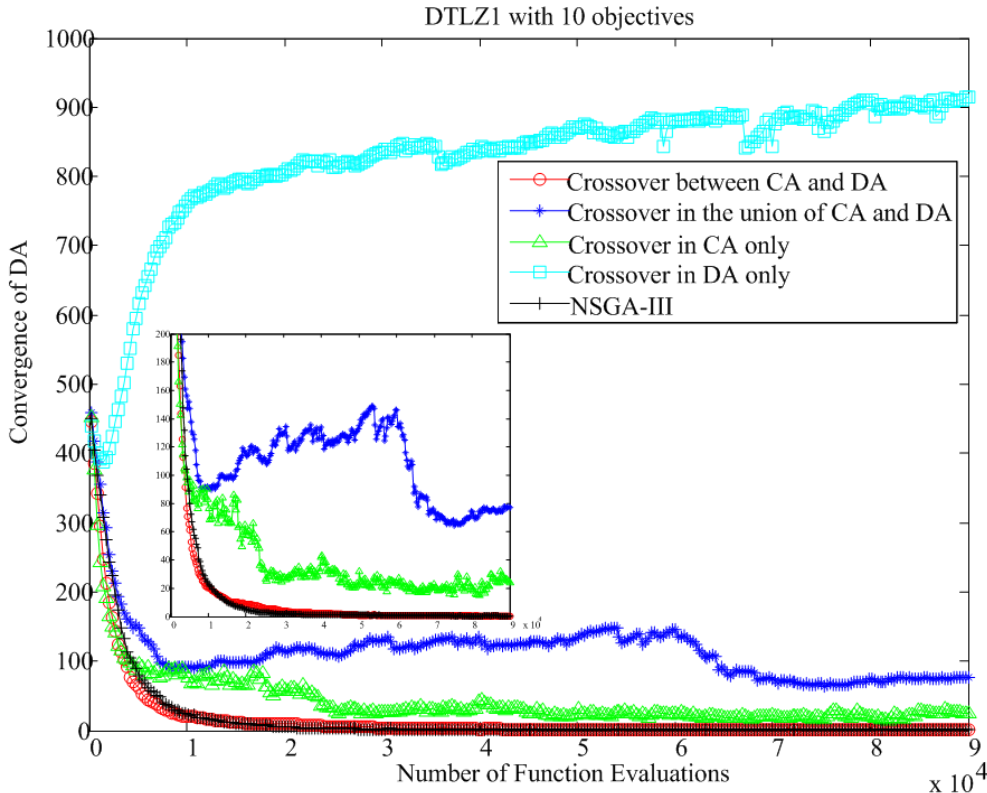
# Interaction between CA and DA: Mutation

- Mutation to DA does not speed up convergence, and disturbs the guidance of CA to DA.
- Mutation is applied to CA only in Two\_Arch2.



CA leads convergence

# Interaction between CA and DA: Crossover



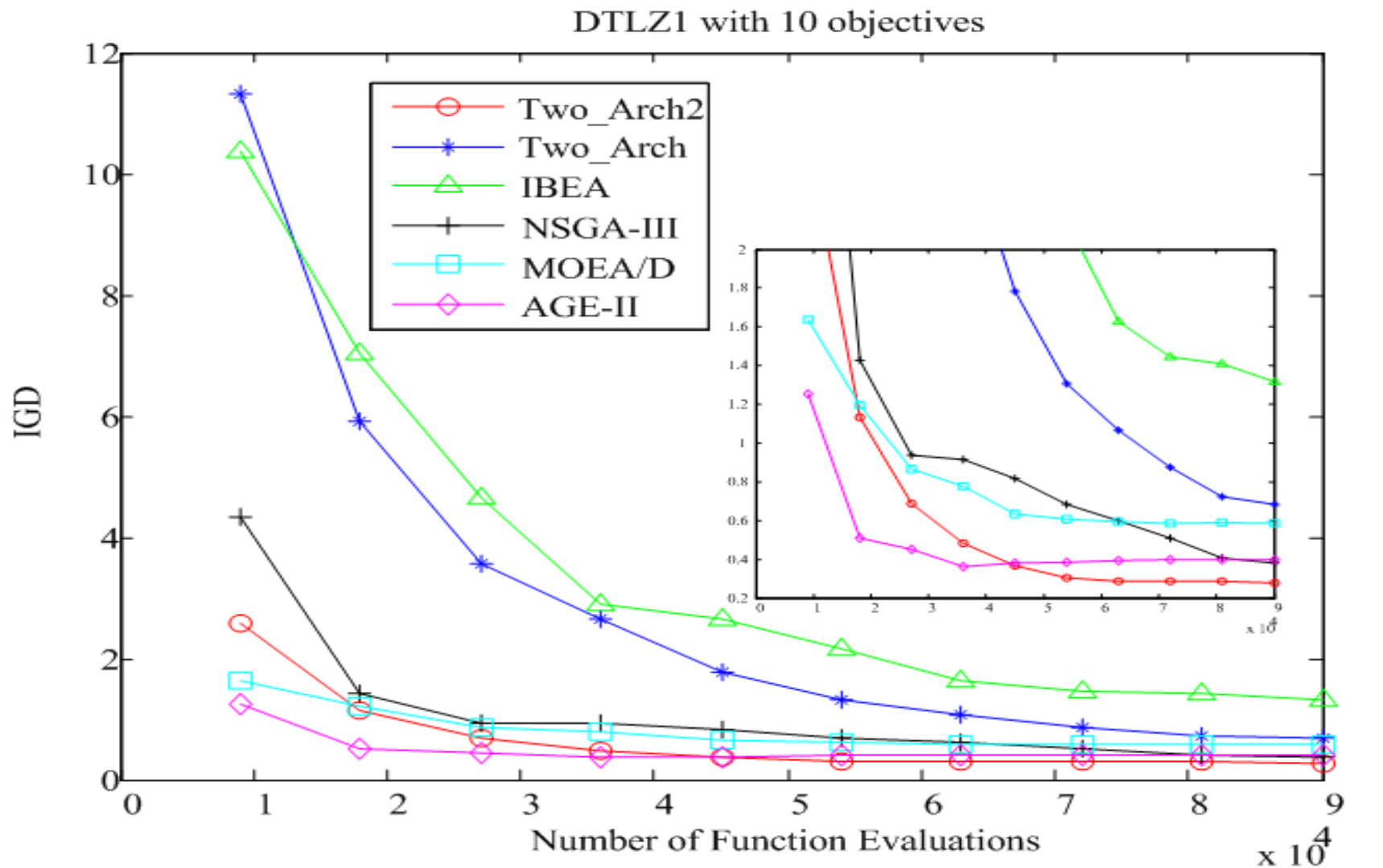
- The crossover between CA and DA has the fastest convergence speed.
- The crossover between CA and DA is employed in Two\_Arch2.

# Experimental Comparisons

- **Two\_Arch2**: Developed here
- **Two\_Arch**: a reference to show the improvement of Two\_Arch2 on MaOPs
- **IBEA**: indicator-based ( $I_{\varepsilon+}$ ) MOEA with good convergence but poor diversity
- **NSGA-III**: newly-proposed MOEA with reference points for MaOPs
- **MOEA/D**: aggregation function-based MOEA
- **AEG-II**: Pareto-based MOEA with the  $\varepsilon$ -grid approximation in the objective space



# DTLZ1 with 10 Objectives



# More Problems, More Objectives

- More experimental results are in
  - H. Wang, L. Jiao and X. Yao, “Two\_Arch2: An Improved Two-Archive Algorithm for Many-Objective Optimization,” *IEEE Transactions on Evolutionary Computation*, 19(4):524-541, August 2015.

Including Matlab code.

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# Conclusions

- There are three major approaches to dealing with a large number of objectives:
  - ① Objective reduction
  - ② Alternative dominance relationship
  - ③ New algorithms
  
- This talk touches on only a tiny proportion of all the work. For more comprehensive review:
  - B. Li, J. Li, K. Tang and X. Yao, “Many-Objective Evolutionary Algorithms: A Survey,” *ACM Computing Surveys*, 48(1), Article 13, 35 pages, September 2015.

# Future Work

## 1. Dynamic number of objectives, e.g.,

- R. Chen, K. Li and X. Yao, "**Dynamic Multiobjectives Optimization With a Changing Number of Objectives**," *IEEE Transactions on Evolutionary Computation*, vol. 22, no. 1, pp. 157-171, Feb. 2018.

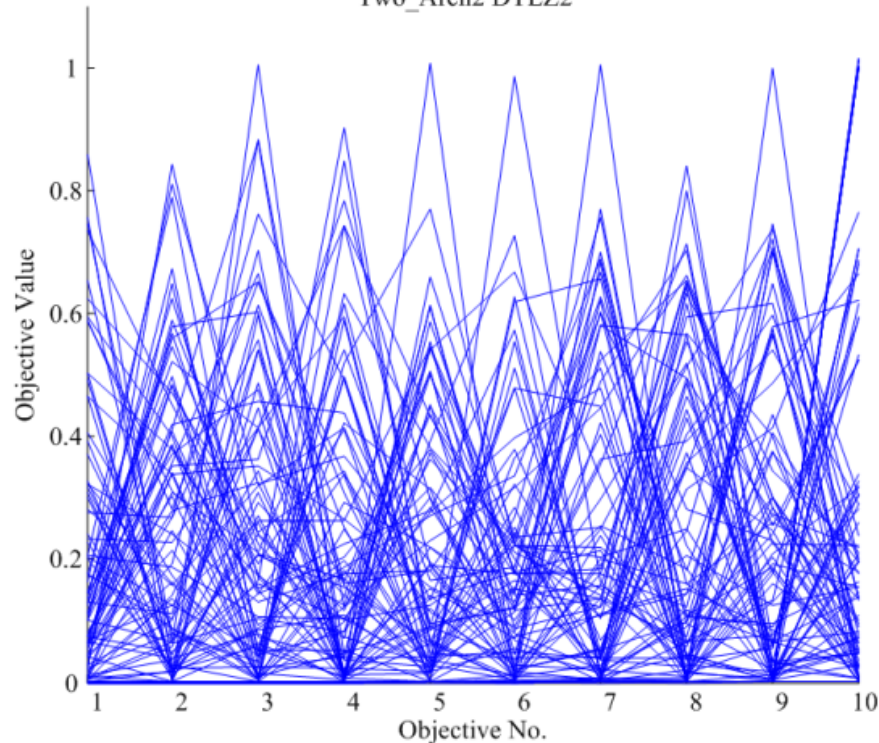
## 2. Constraint handling, e.g.,

- K. Li, R. Chen, G. Fu and X. Yao, "**Two-Archive Evolutionary Algorithm for Constrained Multi-Objective Optimization**," *IEEE Transactions on Evolutionary Computation*, online on 19/7/2018.  
DOI: 10.1109/TEVC.2018.2855411

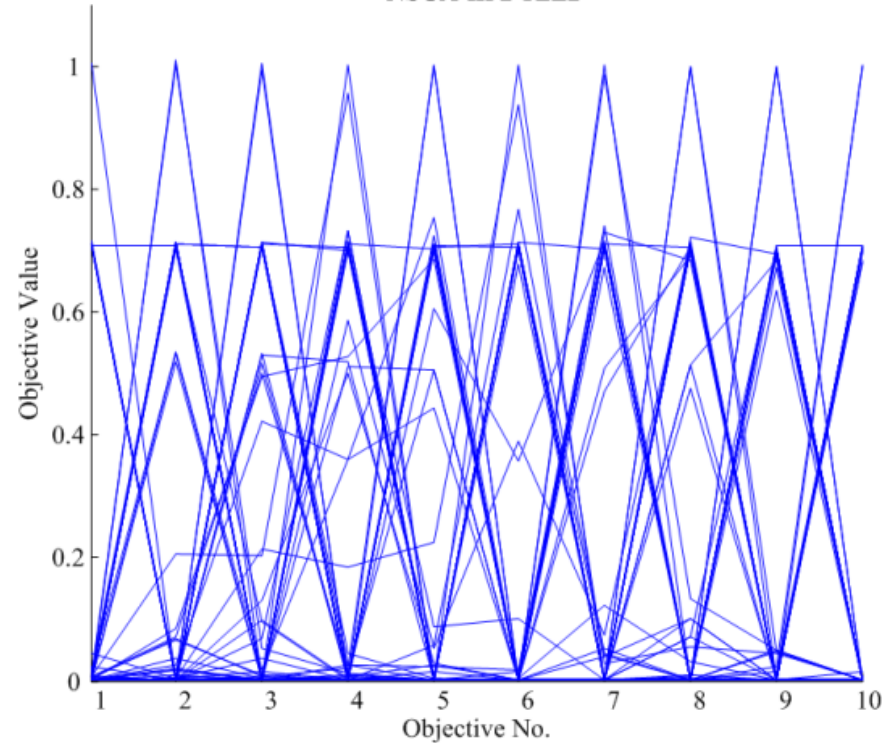
# Two\_Arch2 vs. NSGA-III on DTLZ2 with 10 Objectives

	Convergence	Diversity	Extreme point
Two_Arch2	Good	Good	Fair
NSGA-III	Good	Fair	Good

Two\_Arch2 DTLZ2

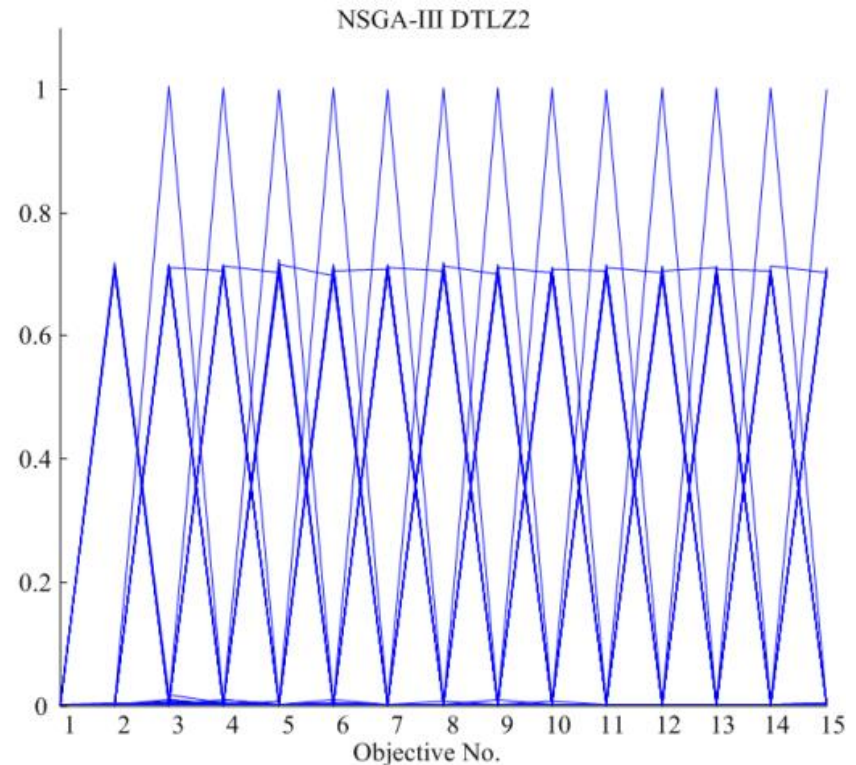
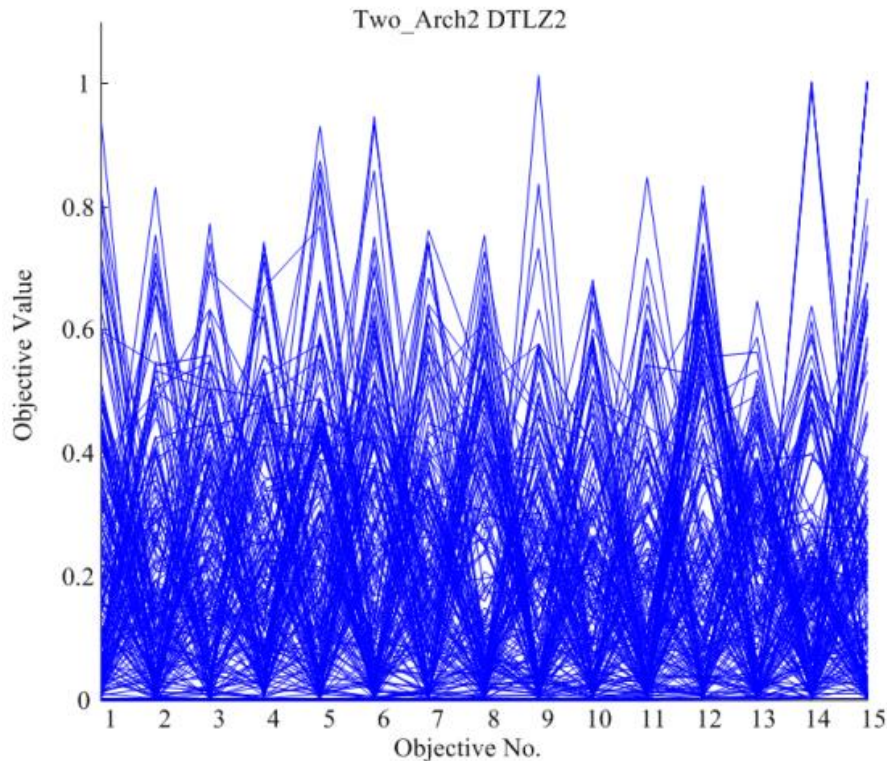


NSGA-III DTLZ2



# Two\_Arch2 vs. NSGA-III on DTLZ2 with 15 Objectives

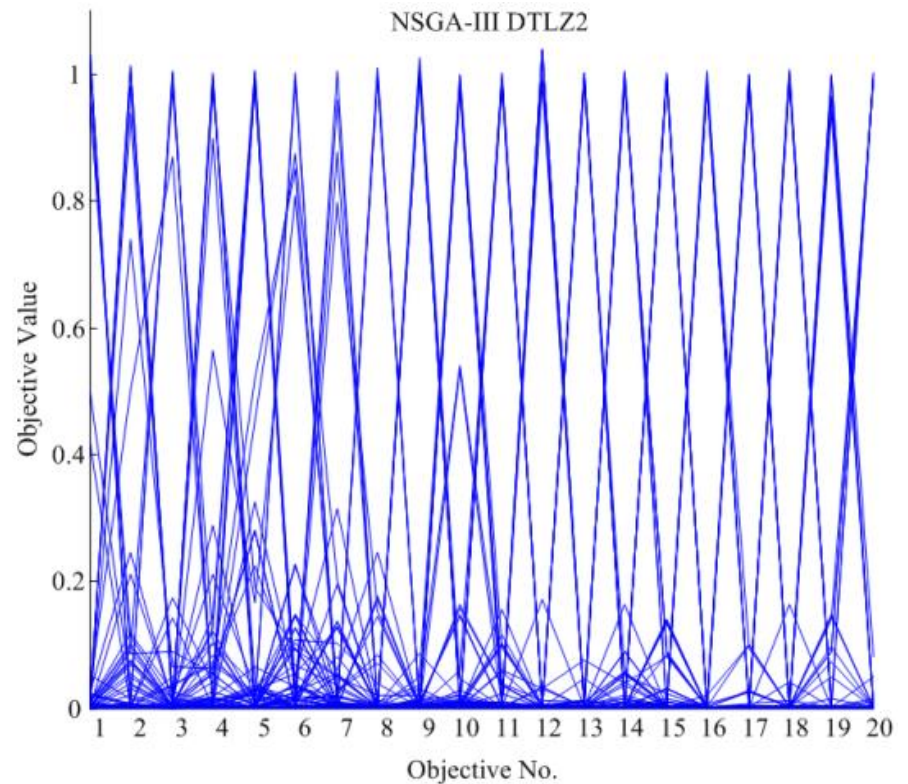
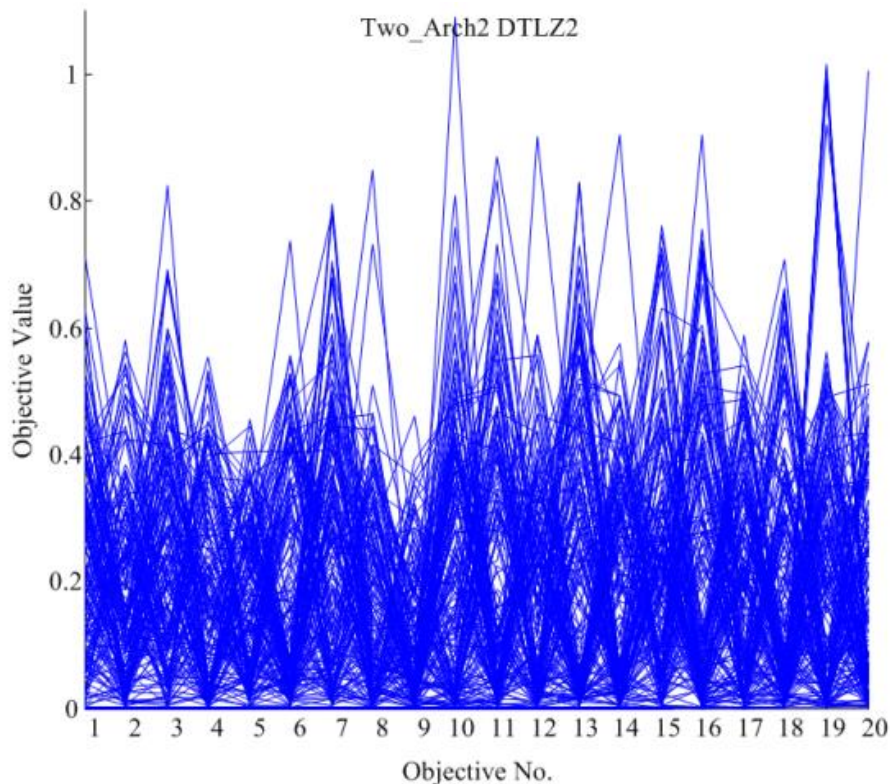
	Convergence	Diversity	Extreme point
Two_Arch2	Good	Good	Poor
NSGA-III	Good	Fair	Good





# Two\_Arch2 vs. NSGA-III on DTLZ2 with 20 Objectives

	Convergence	Diversity	Extreme point
Two_Arch2	Good	Good	Poor
NSGA-III	Good	Fair	Good





# Two\_Arch2 vs. NSGA-III

	Two_Arch2	NSGA-III
<b>Convergence methodology</b>	$I_{\varepsilon+}$	Pareto dominance
<b>Convergence degeneration</b>	No	No
<b>Diversity maintenance</b>	$L_{1/m}$ -norm-based distance	Minimal perpendicular distances to reference points
<b>Diversity degeneration</b>	No	Increase with the dimension of objective space
<b>Manual Settings</b>	None	Reference points