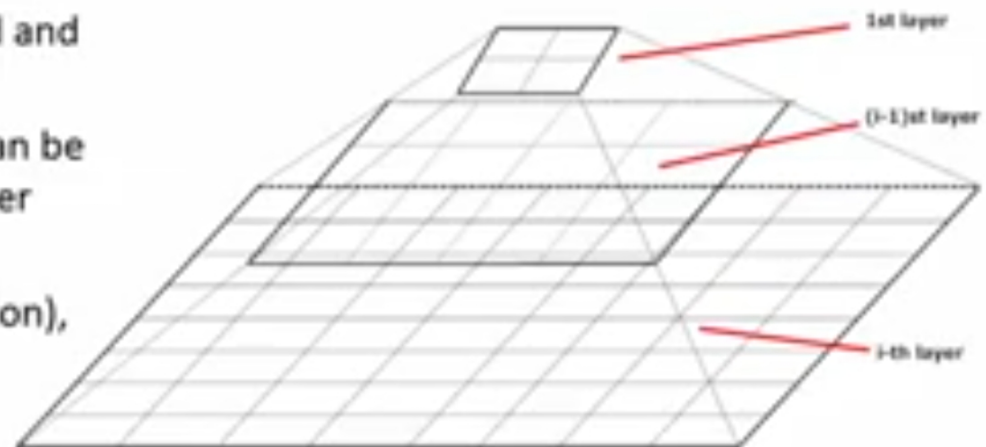


## Grid-Based Clustering Methods

- Grid-Based Clustering: Explore multi-resolution grid data structure in clustering
  - Partition the data space into a finite number of cells to form a grid structure
  - Find clusters (dense regions) from the cells in the grid structure
- Features and challenges of a typical grid-based algorithm
  - Efficiency and scalability: # of cells  $\ll$  # of data points
  - Uniformity: Uniform, hard to handle highly irregular data distributions
  - Locality: Limited by predefined cell sizes, borders, and the density threshold
  - Curse of dimensionality: Hard to cluster high-dimensional data
- Methods to be introduced
  - **STING** (a Statistical Information Grid Approach) (Wang, Yang and Muntz, VLDB'97)
  - **CLIQUE** (Agrawal, Gehrke, Gunopulos, and Raghavan, SIGMOD'98)
    - Both grid-based and subspace clustering

## STING: A Statistical Information Grid Approach

- ❑ STING (Statistical Information Grid) (Wang, Yang and Muntz, VLDB'97)
- ❑ The spatial area is divided into rectangular cells at different levels of resolution, and these cells form a tree structure
- ❑ A cell at a high level contains a number of smaller cells of the next lower level
- ❑ Statistical information of each cell is calculated and stored beforehand and is used to answer queries
- ❑ Parameters of higher level cells can be easily calculated from that of lower level cell, including
  - ❑ *count, mean, s*(standard deviation), *min, max*
  - ❑ type of distribution—*normal, uniform, etc.*



## Query Processing in STING and Its Analysis

- To process a region query
  - Start at the root and proceed to the next lower level, using the STING index
  - Calculate the likelihood that a cell is relevant to the query at some confidence level using the statistical information of the cell
  - Only children of likely relevant cells are recursively explored
  - Repeat this process until the bottom layer is reached
- Advantages
  - Query-independent, easy to parallelize, incremental update
  - Efficiency: Complexity is  $O(K)$ 
    - $K$ : # of grid cells at the lowest level, and  $K \ll N$  (i.e., # of data points)

## CLIQUE: Grid-Based Subspace Clustering

- ❑ CLIQUE (Clustering In QUES) (Agrawal, Gehrke, Gunopulos, Raghavan: SIGMOD'98)
- ❑ CLIQUE is a **density-based** and **grid-based** **subspace clustering** algorithm
  - ❑ **Grid-based**: It discretizes the data space through a grid and estimates the density by counting the number of points in a grid cell
  - ❑ **Density-based**: A cluster is a maximal set of connected dense units in a subspace
    - ❑ A unit is dense if the fraction of total data points contained in the unit exceeds the input model parameter
  - ❑ **Subspace clustering**: A subspace cluster is a set of neighboring dense cells in an arbitrary subspace. It also discovers some minimal descriptions of the clusters