
FO definable Transformations of Infinite strings

Vrunda Dave, S. Krishna, Ashutosh Trivedi

Outline

- **Introduction**
 - Three formalisms for transductions
 - Related work
- Aperiodic transformations for Infinite strings
 - Aperiodic two way transducer
 - Aperiodic streaming string transducer
- Equivalence results and Proof ideas
 - $\text{SST}_{\text{sf}} \subset \text{FOT} = 2\text{WST}_{\text{sf}} \subset \text{SST}_{\text{sf}}$
- Conclusion

Introduction

- Three formalisms for transformations:

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- Logic

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- Two way machines

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- Three formalisms for transformations:
- Logic
- Two way machines
- One way machines with finite registers

Logic Transducer

Logic Transducer

[Courcelle'94]

Logic Transducer

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input

Logic Transducer

[Courcelle'94]

input a_1 a_2 a_3 a_4 a_5 a_6 a_7 a_8

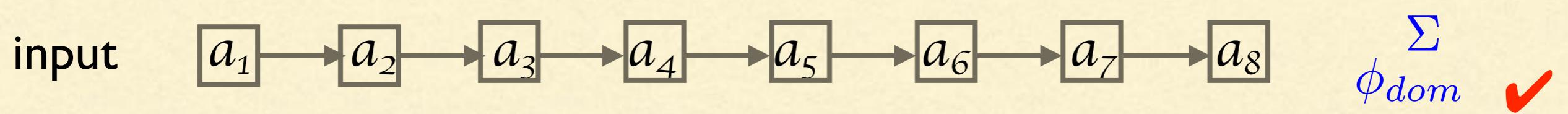
Logic Transducer

[Courcelle'94]

input a_1 a_2 a_3 a_4 a_5 a_6 a_7 a_8 ϕ_{dom}^{Σ} ✓

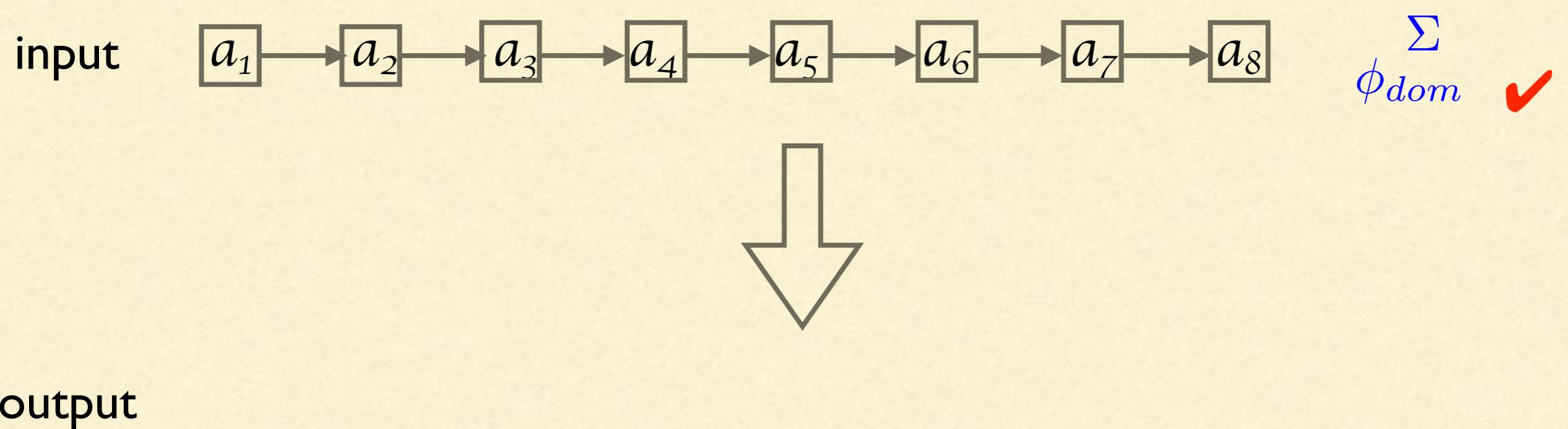
Logic Transducer

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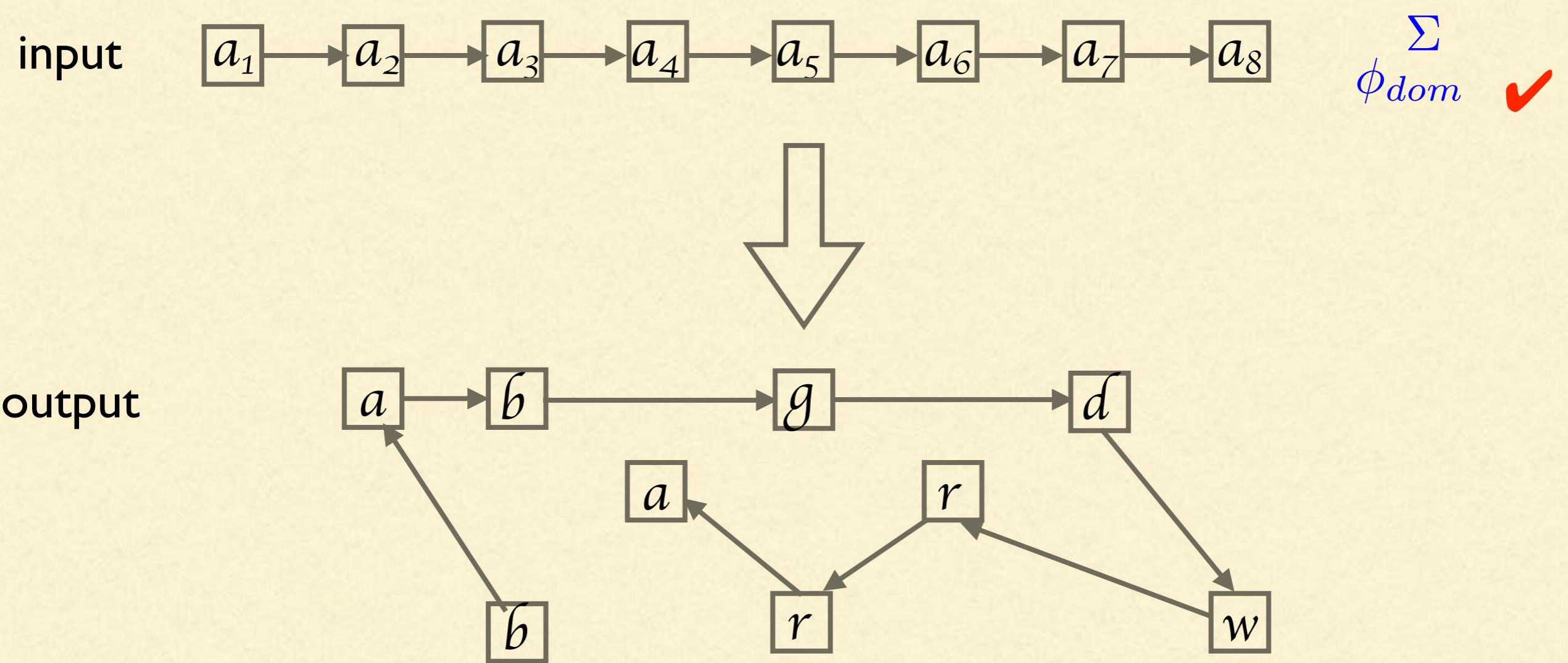
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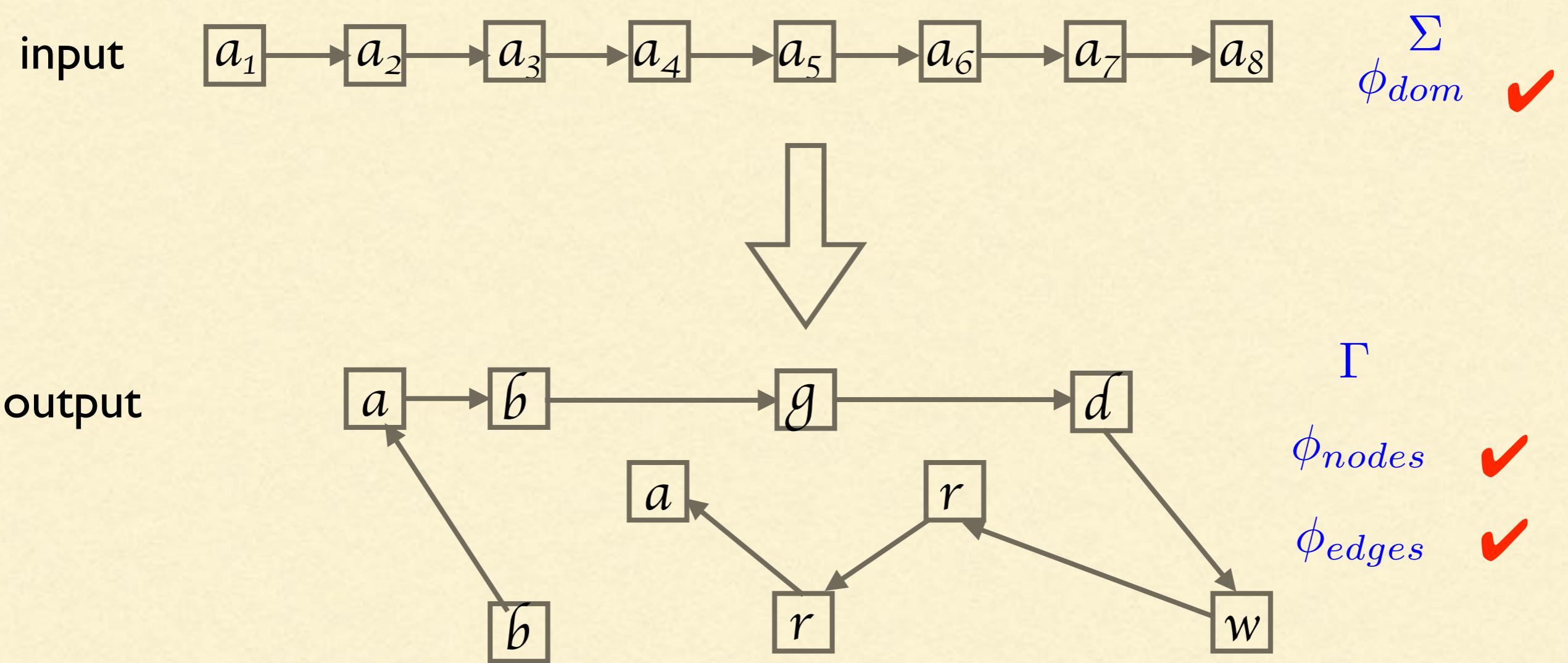
Logic Transducer

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Logic Transducer

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$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

FO/ MSO transducer

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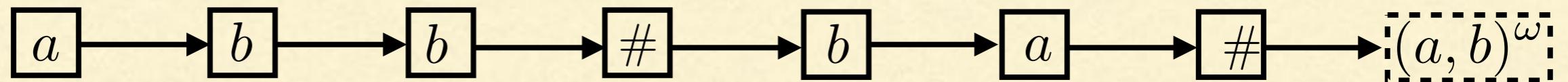
input: a b b $\#$ b a $\#$ $(a, b)^\omega$

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

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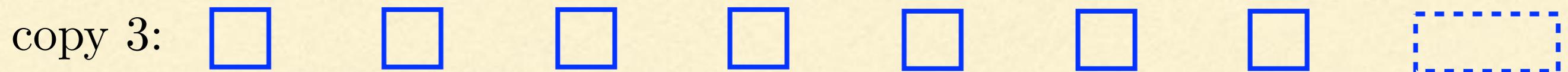
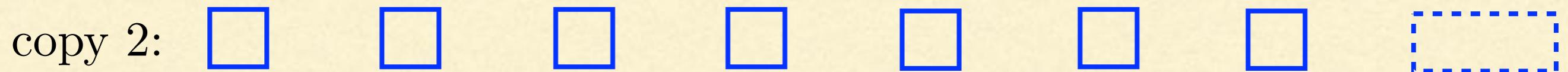
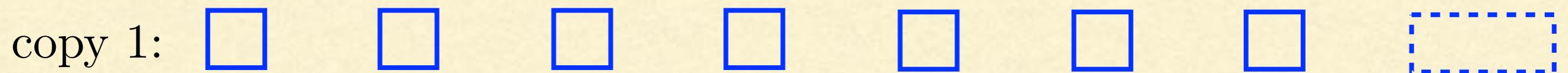
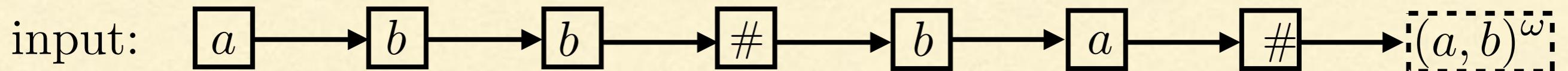
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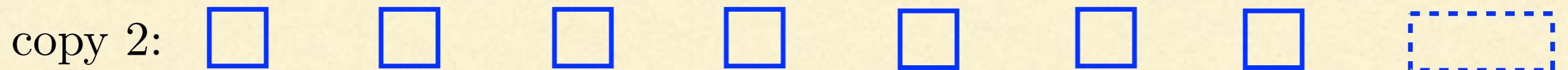
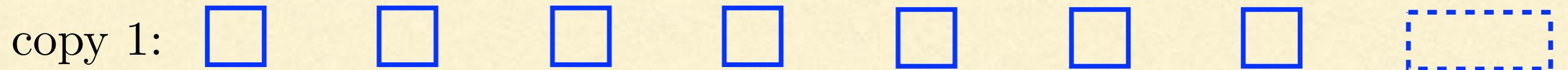
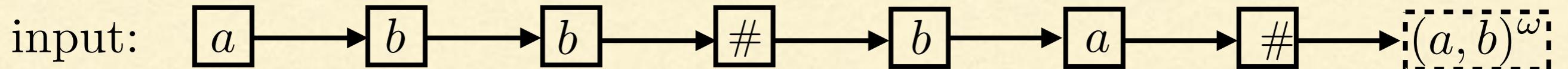
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FO/ MSO transducer



$$\phi_\gamma^1(x) = \phi_\gamma^2(x) = L_\gamma(x) \wedge \neg L_\#(x) \wedge \text{reach}_\#(x)$$

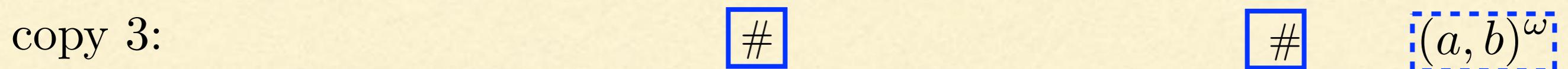
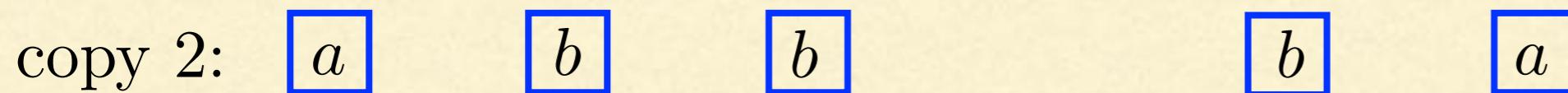
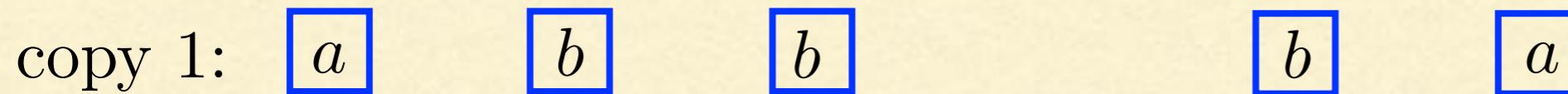
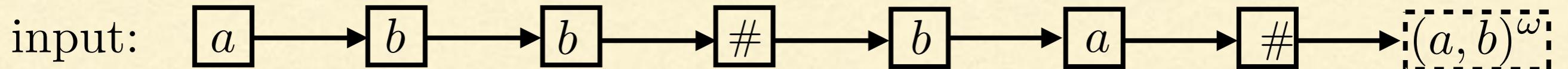
$$\phi_\gamma^3(x) = L_\#(x) \vee \neg \text{reach}_\#(x)$$

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$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

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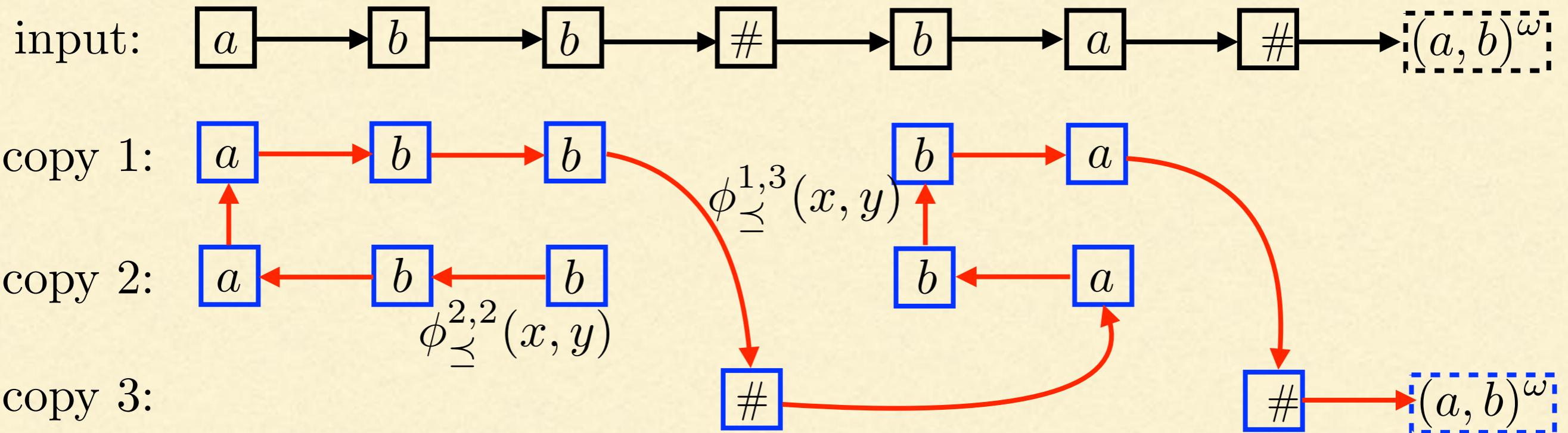
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Two way machine

Two way machine

[Rabin, Scott'59]

[Ehrich, Yau'71]

Two way machine

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input

Two way machine

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input a_1 a_2 a_3 a_4 a_5 a_6 a_7 a_8

Two way machine

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input a_1 a_2 a_3 a_4 a_5 a_6 a_7 a_8

output

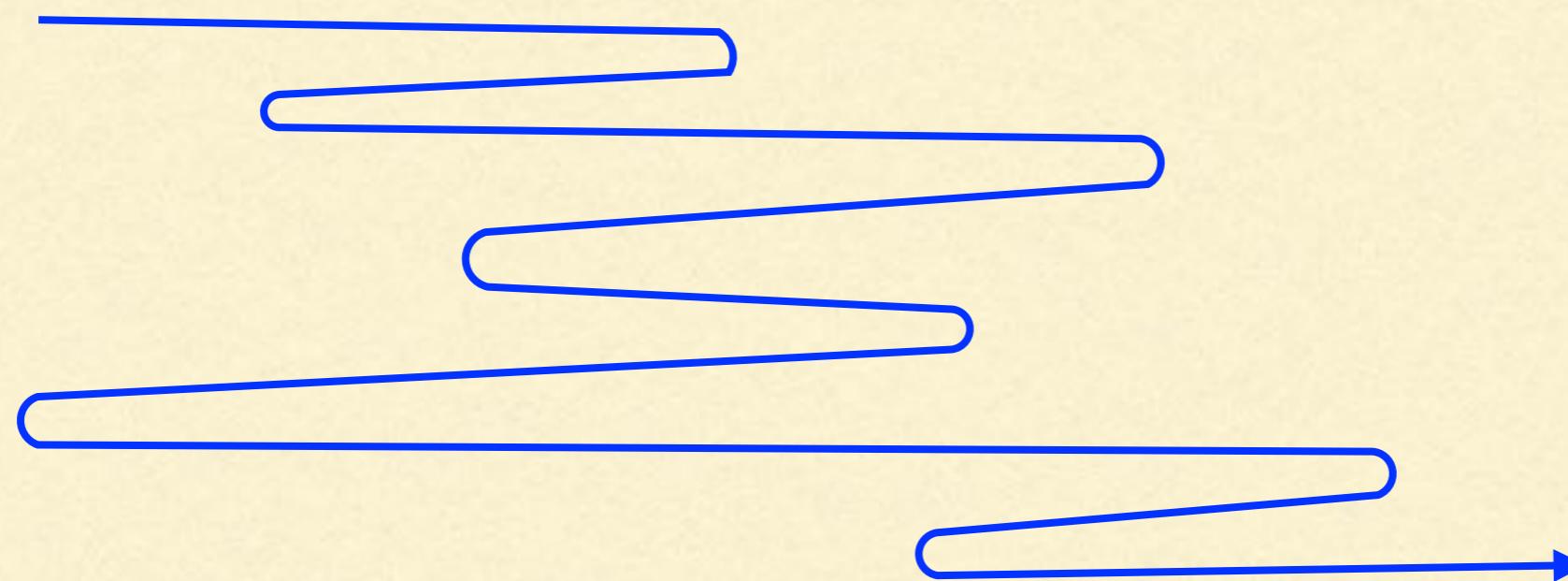
Two way machine

[Rabin, Scott'59]

[Ehrich, Yau'71]

input

$a_1 \quad a_2 \quad a_3 \quad a_4 \quad a_5 \quad a_6 \quad a_7 \quad a_8$



output



Look-around automaton

Look-around automaton

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

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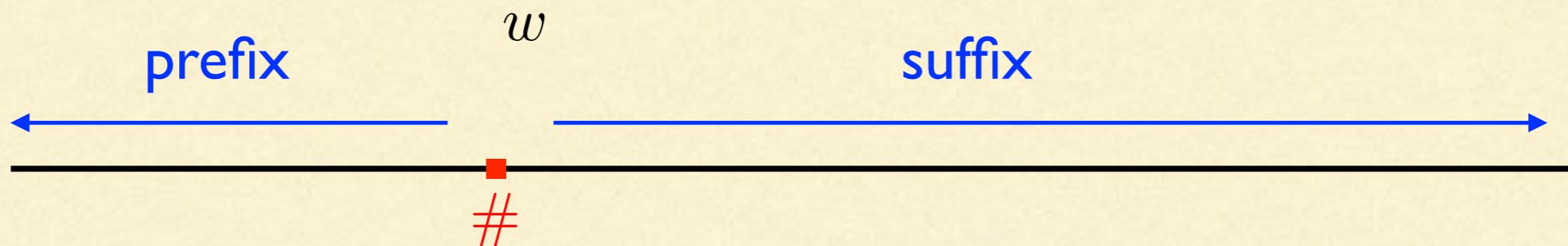
w



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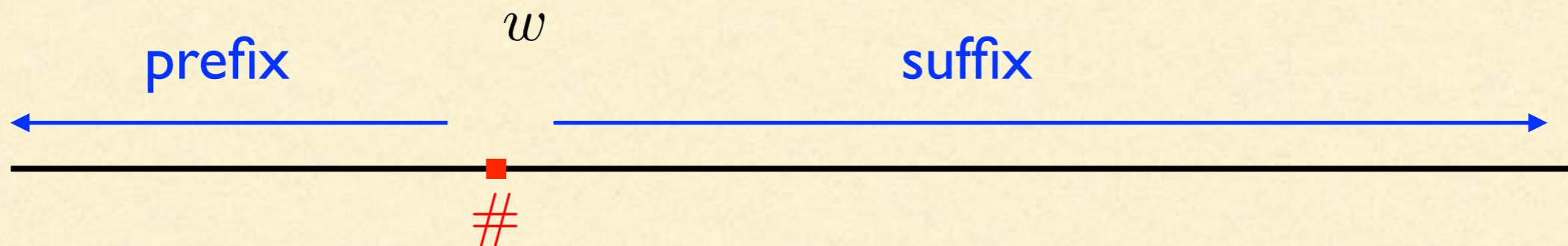
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Look-around automaton

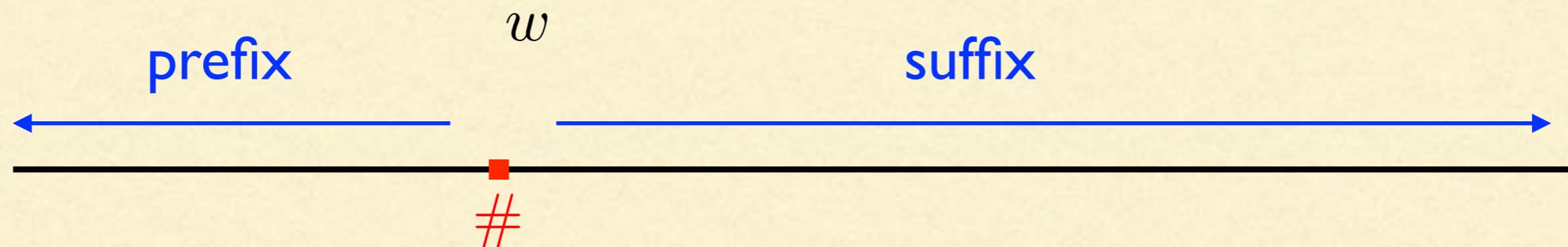
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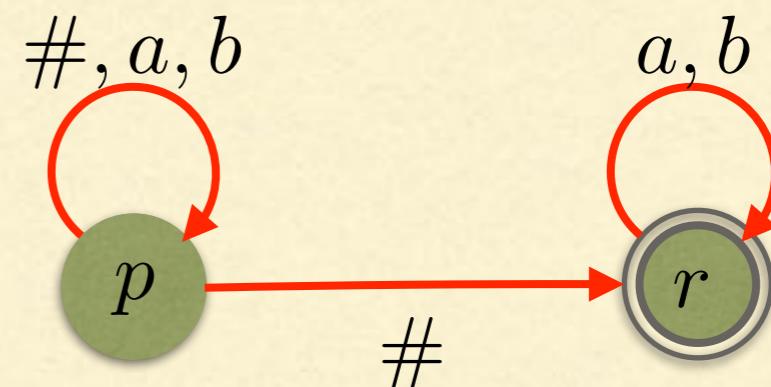
property: suffix does not contain #

Look-around automaton

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property: suffix does not contain #



$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

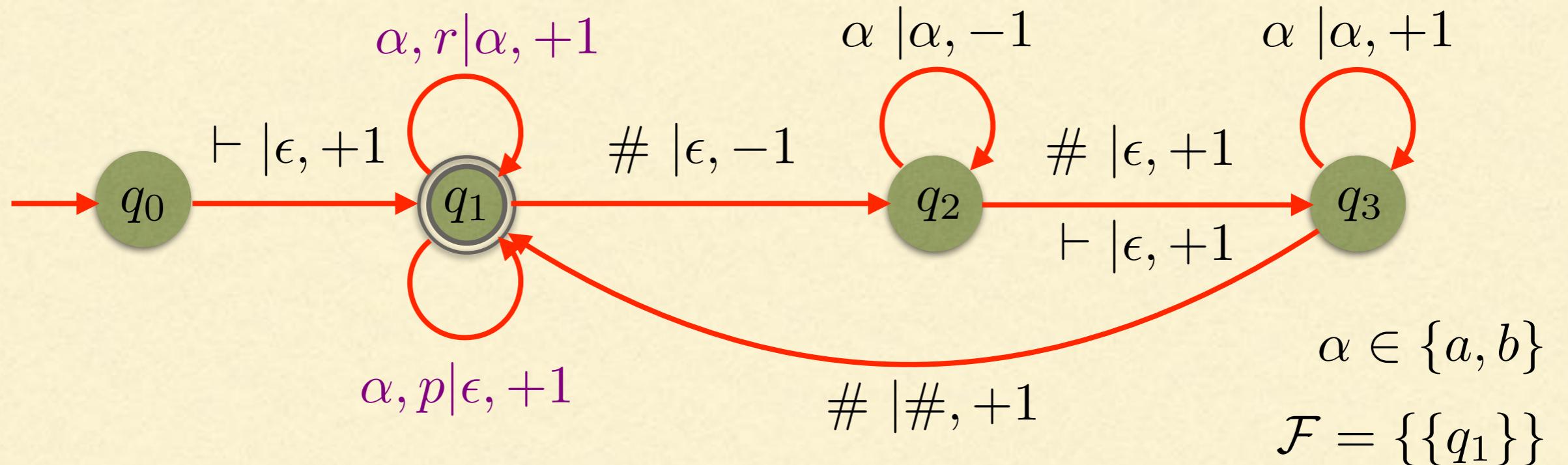
where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

Two way Transducer (2WST)

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

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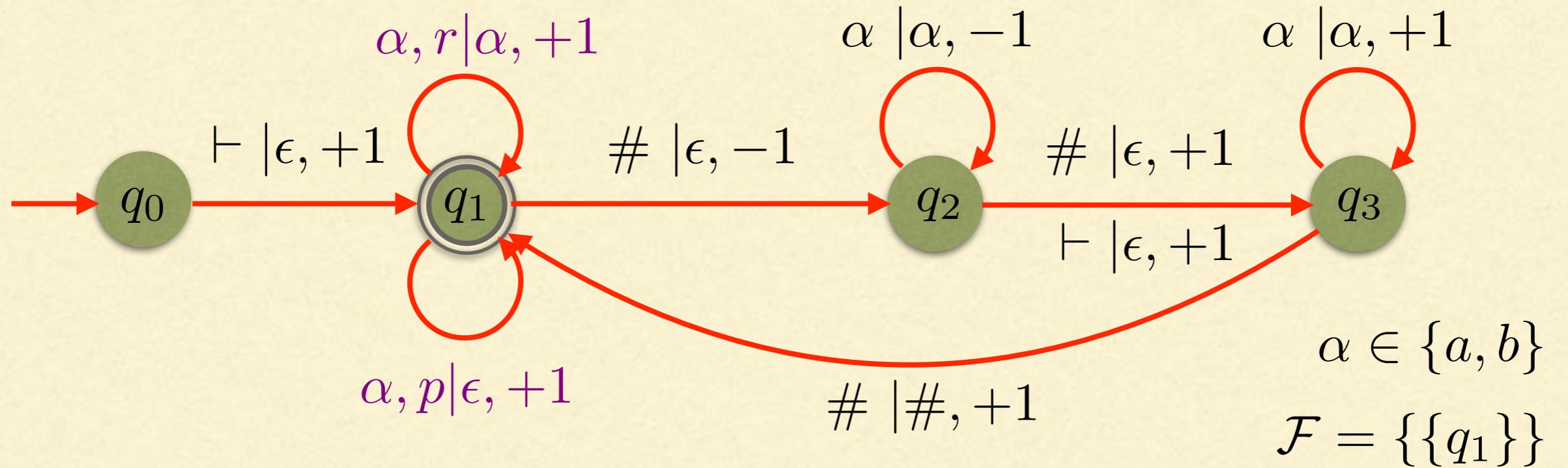
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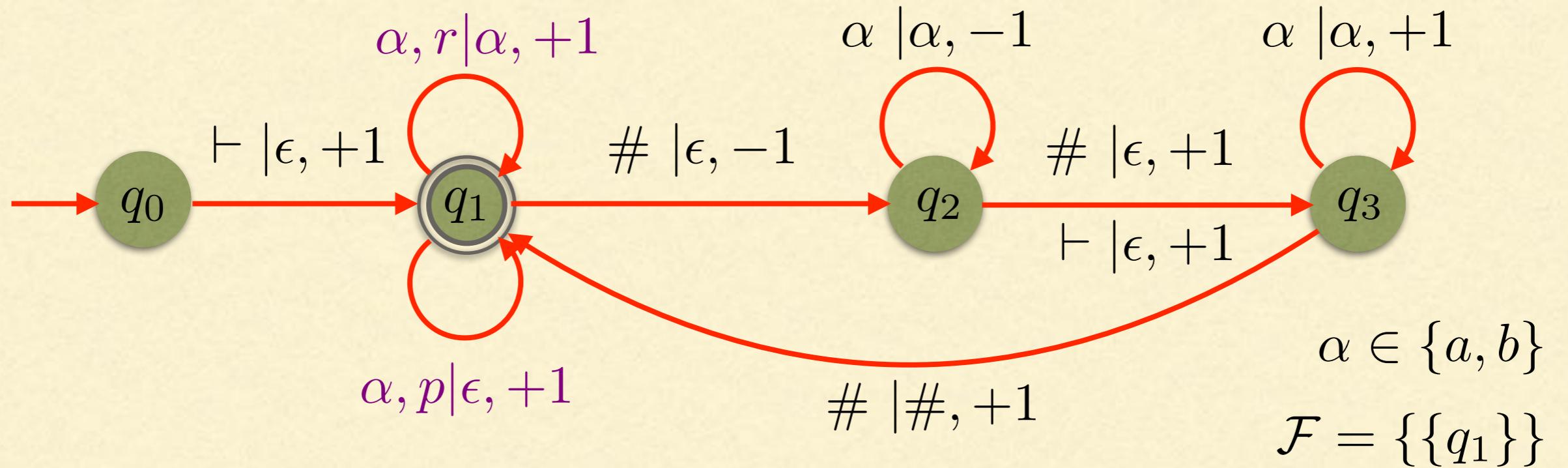


\vdash a b b $\#$ $(a + b)^\omega$
 \uparrow

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

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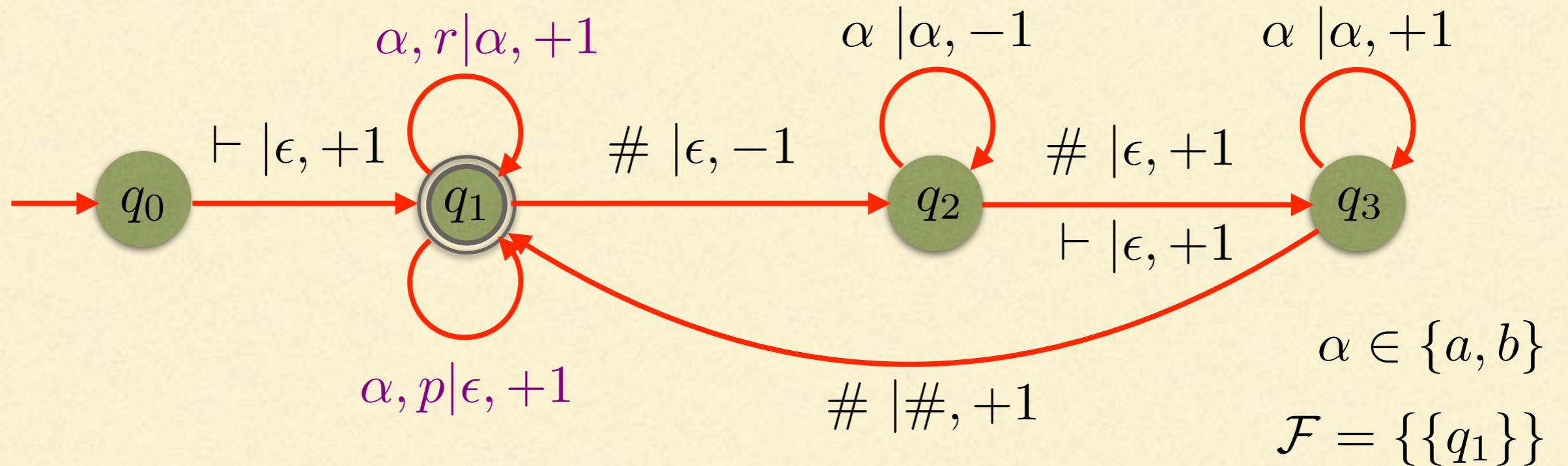
$\vdash \quad a \quad b \quad b \quad \# \quad (a + b)^\omega$



$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

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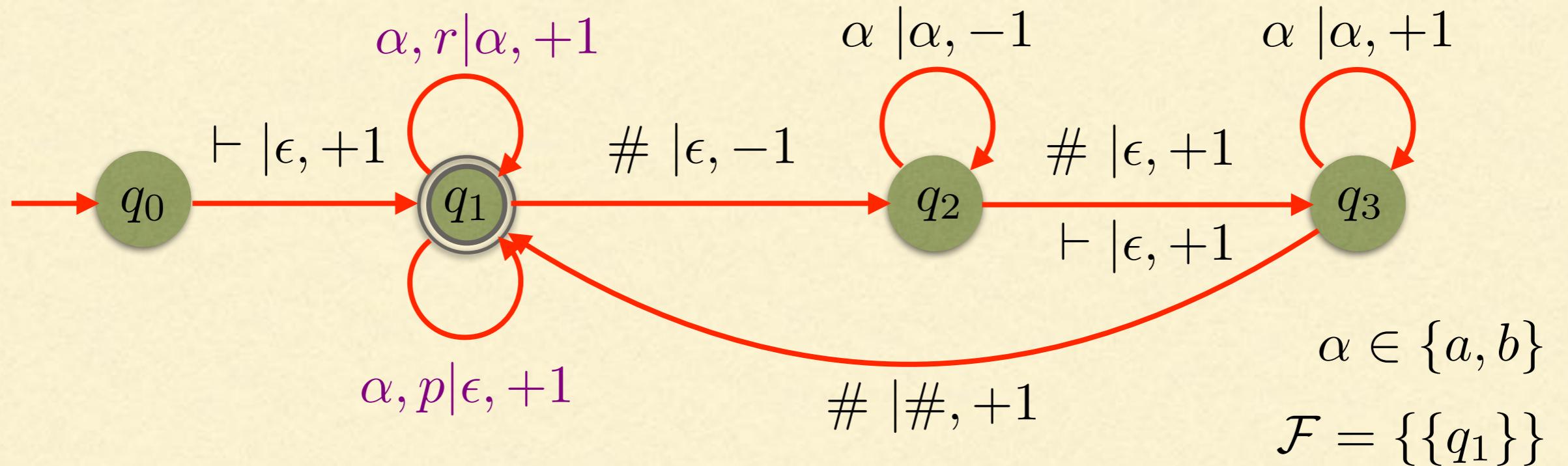
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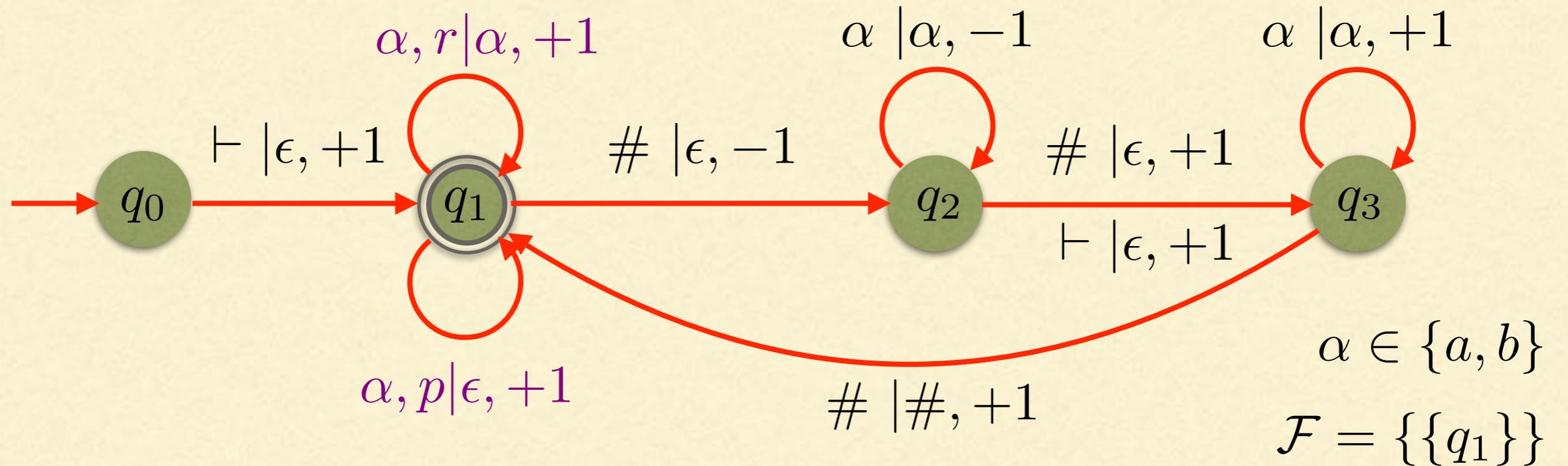
\vdash a b b $\#$ $(a + b)^\omega$

↑

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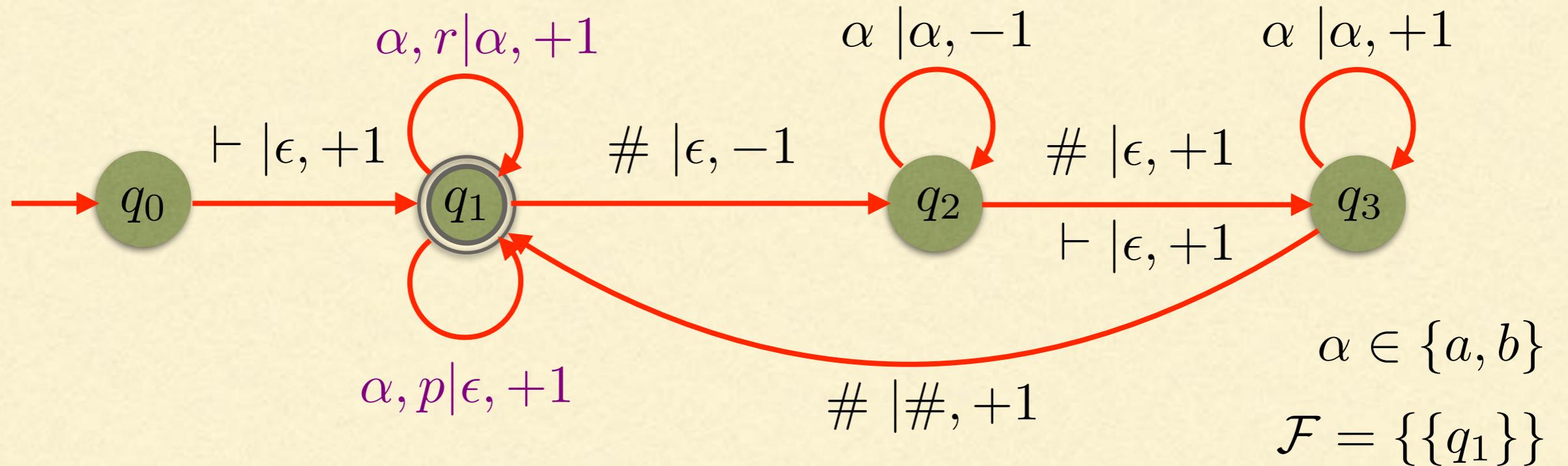


\vdash a b b $\#$ $(a + b)^\omega$
 ↕
 b b a

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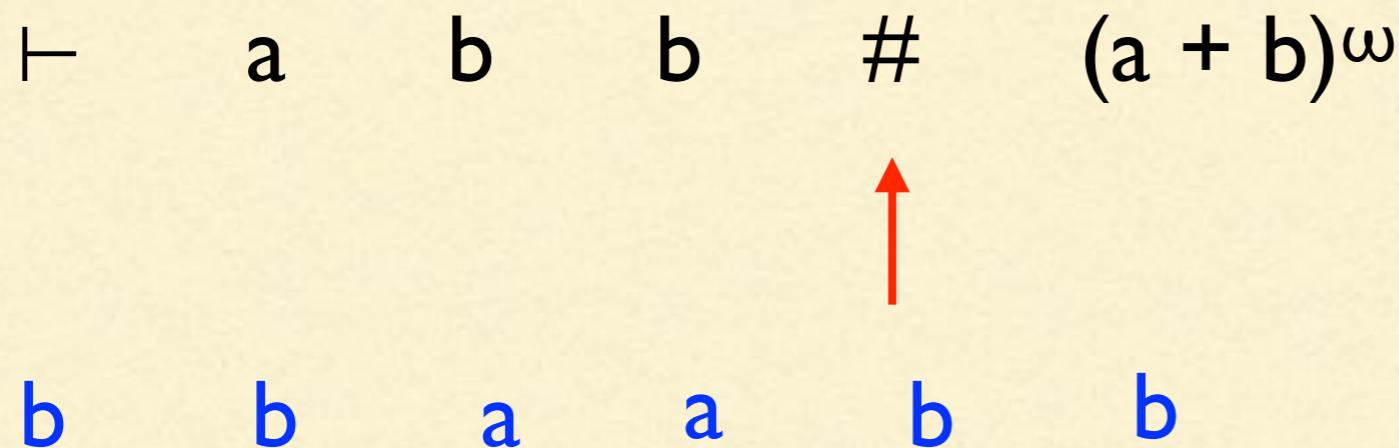
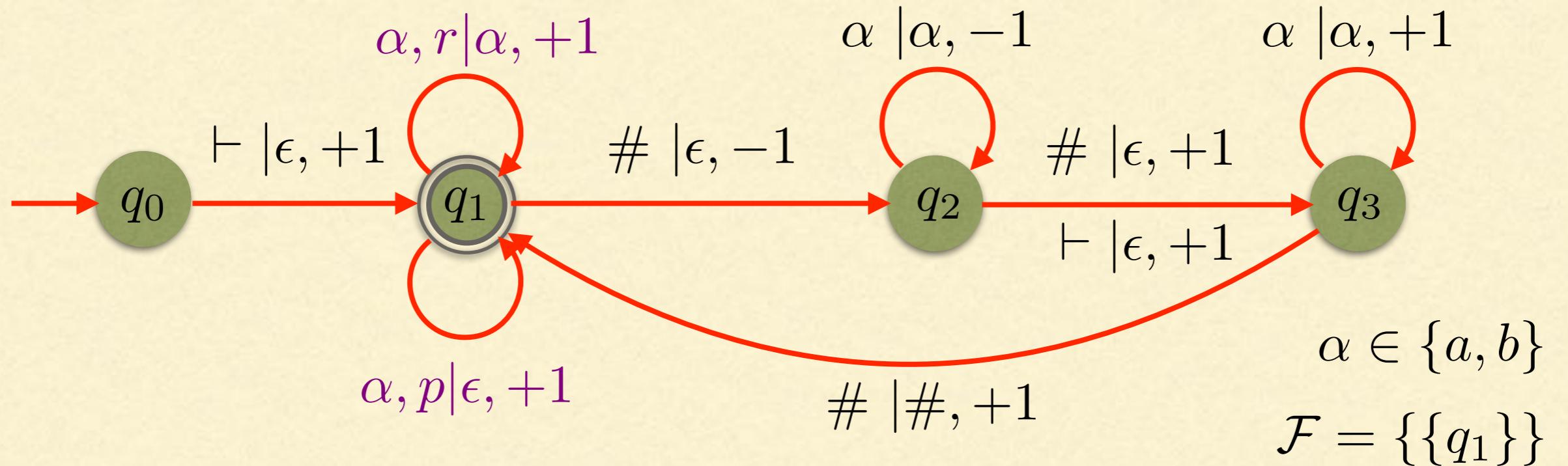


\vdash a b b # $(a + b)^\omega$
 b b a

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

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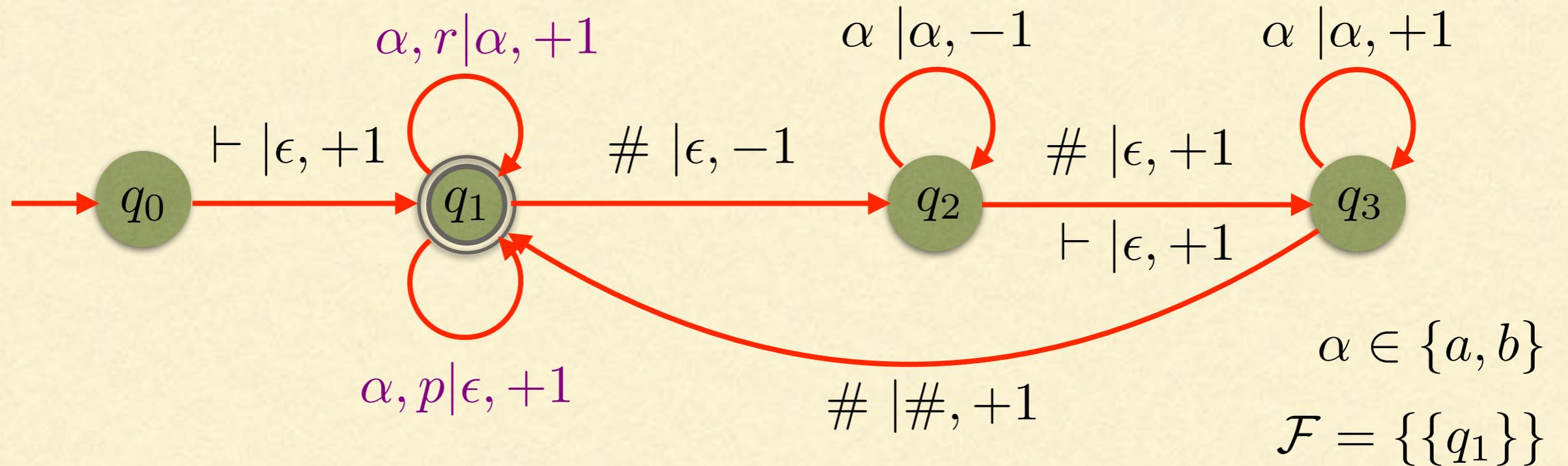
Two way Transducer (2WST)



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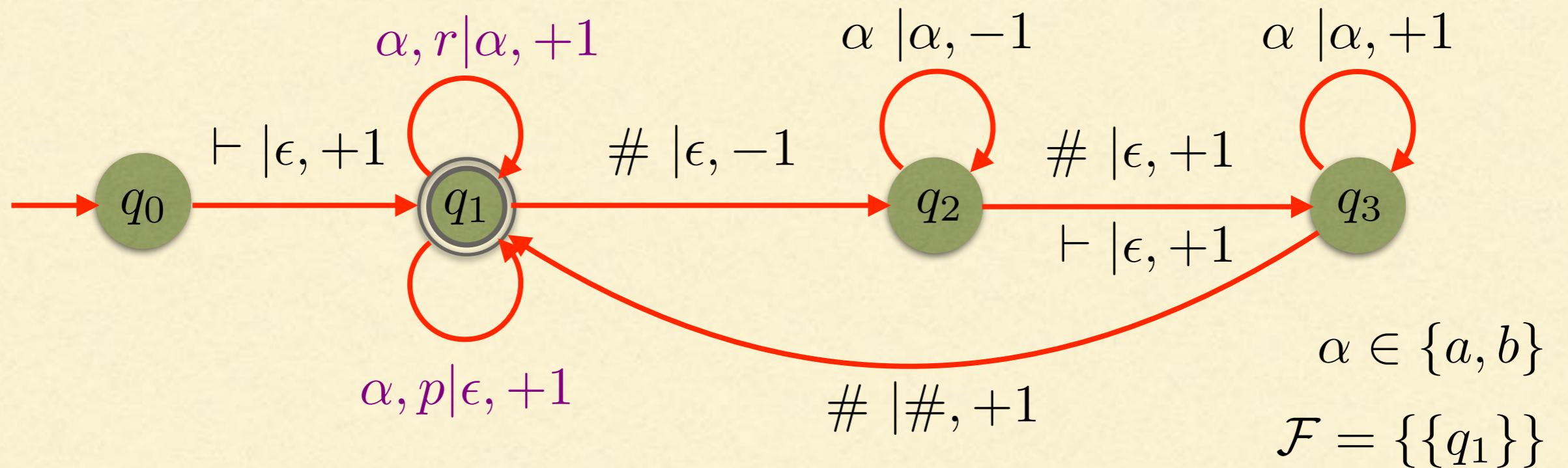


\vdash	a	b	b	#	$(a + b)^\omega$	
b	b	a	a	b	b	#

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

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Two way Transducer (2WST)



$\vdash \quad a \quad b \quad b \quad \# \quad (a + b)^\omega$

$b \quad b \quad a \quad a \quad b \quad b \quad \# \quad (a + b)^\omega$



One way machine with finite registers

One way machine with finite registers

[Alur, Černý'10]

One way machine with finite registers

[Alur, Černý'10]

input :

a_1

a_2

a_3

a_4

One way machine with finite registers

[Alur, Černý'10]

input :

a_1

a_2

a_3

a_4

registers : $x, y, z\dots$

One way machine with finite registers

[Alur, Černý'10]

input :

a_1

a_2

a_3

a_4

			
$x = ax$	$x = \epsilon$	$x = ax$	$x = \epsilon$
$y = bycz$	$y = cz$	$y = bycz$	$y = cz$
$z = c$	$z = by$	$z = c$	$z = by$

registers : $x, y, z\dots$

One way machine with finite registers

[Alur, Černý'10]

input :

a_1

a_2

a_3

a_4



$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \epsilon$$

$$y = cz$$

$$z = by$$

$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \epsilon$$

$$y = cz$$

$$z = by$$

registers : $x, y, z\dots$

output : $x\ a\ y\ z$

One way machine with finite registers

[Alur, Černý'10]

input :

a_1

a_2

a_3

a_4



$$x = ax$$

$$y = bycz$$

$$z = c$$

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$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \epsilon$$

$$y = cz$$

$$z = by$$

registers : $x, y, z\dots$

output : $x\ a\ y\ z$

copyless update :

One way machine with finite registers

[Alur, Černý'10]

input :

a_1

a_2

a_3

a_4



$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \epsilon$$

$$y = cz$$

$$z = by$$

$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \epsilon$$

$$y = cz$$

$$z = by$$

registers : $x, y, z\dots$

output : $x \ a \ y \ z$

copyless update :

$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = a\textcolor{red}{x}$$

$$y = bycz$$

$$z = c\textcolor{red}{x}$$

One way machine with finite registers

[Alur, Černý'10]

input :

a_1

a_2

a_3

a_4



$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \epsilon$$

$$y = cz$$

$$z = by$$

$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \epsilon$$

$$y = cz$$

$$z = by$$

registers : $x, y, z\dots$

output : $x \ a \ y \ z$

copyless update :

$$\begin{aligned}x &= ax \\y &= bycz \quad \checkmark \\z &= c\end{aligned}$$

$$\begin{aligned}x &= a\cancel{x} \\y &= bycz \\z &= c\cancel{x}\end{aligned}$$

One way machine with finite registers

[Alur, Černý'10]

input :

a_1

a_2

a_3

a_4



$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \epsilon$$

$$y = cz$$

$$z = by$$

$$x = ax$$

$$y = bycz$$

$$z = c$$

$$x = \epsilon$$

$$y = cz$$

$$z = by$$

registers : $x, y, z\dots$

output : $x \ a \ y \ z$

copyless update :

$$\begin{aligned}x &= ax \\y &= bycz \quad \checkmark \\z &= c\end{aligned}$$

$$\begin{aligned}x &= ax \\y &= bycz \quad \text{X} \\z &= cx\end{aligned}$$

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

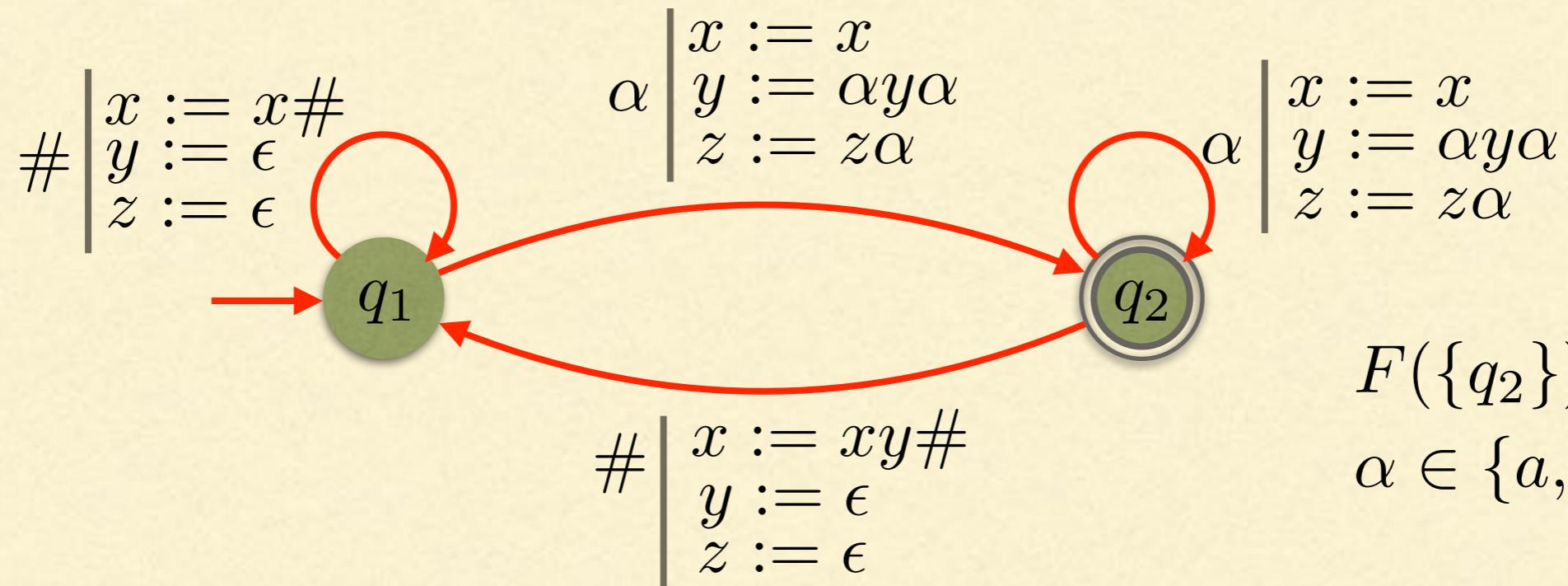
where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

Streaming String Transducer (SST)

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

Streaming String Transducer (SST)

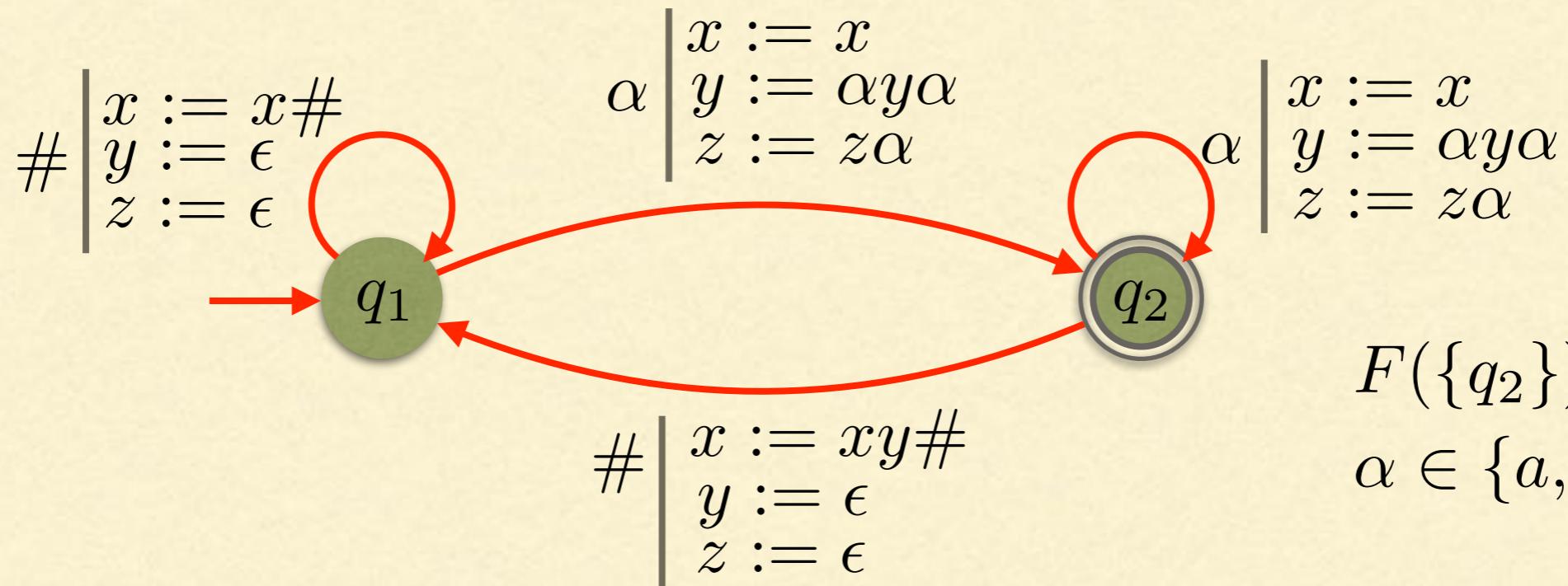


$$\begin{aligned} F(\{q_2\}) &= xz \\ \alpha &\in \{a, b\} \end{aligned}$$

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

Streaming String Transducer (SST)



$$\begin{aligned} F(\{q_2\}) &= xz \\ \alpha &\in \{a, b\} \end{aligned}$$

$$\text{a} \quad \text{b} \quad \text{b} \quad \# \quad (a + b)^\omega$$

$$x: \quad \epsilon$$

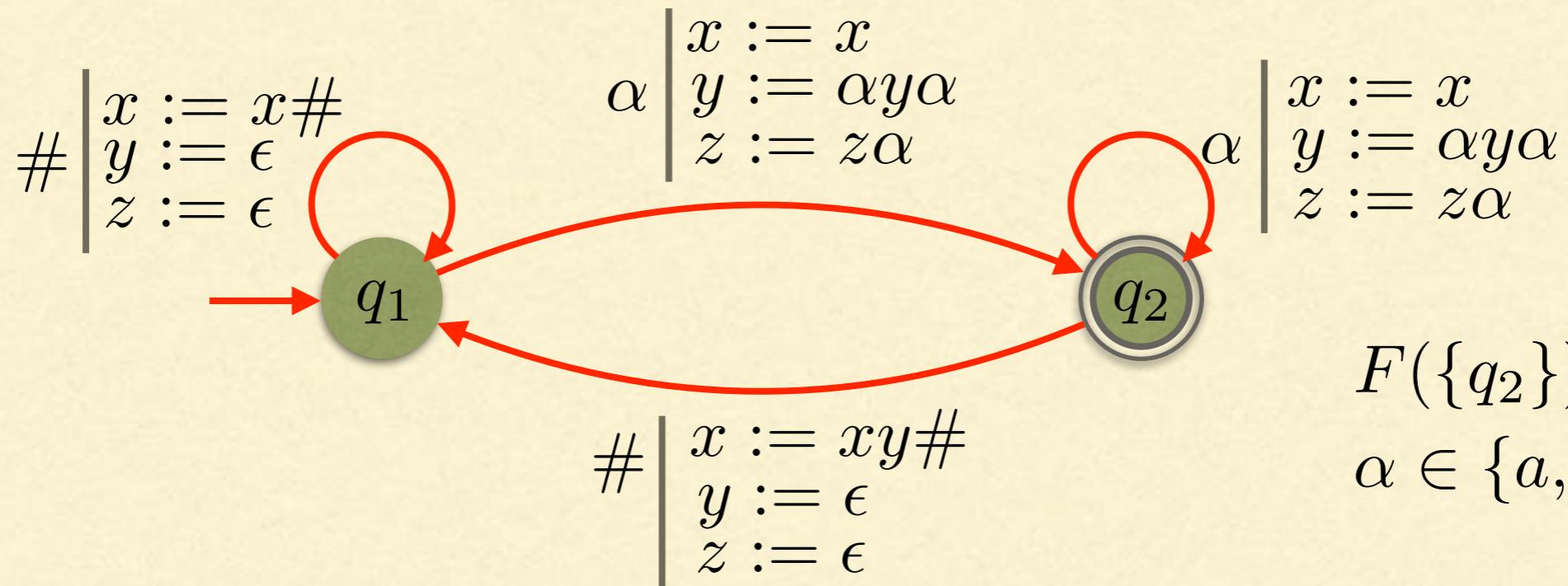
$$y: \quad \epsilon$$

$$z: \quad \epsilon$$

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

Streaming String Transducer (SST)



$$\begin{aligned} F(\{q_2\}) &= xz \\ \alpha &\in \{a, b\} \end{aligned}$$

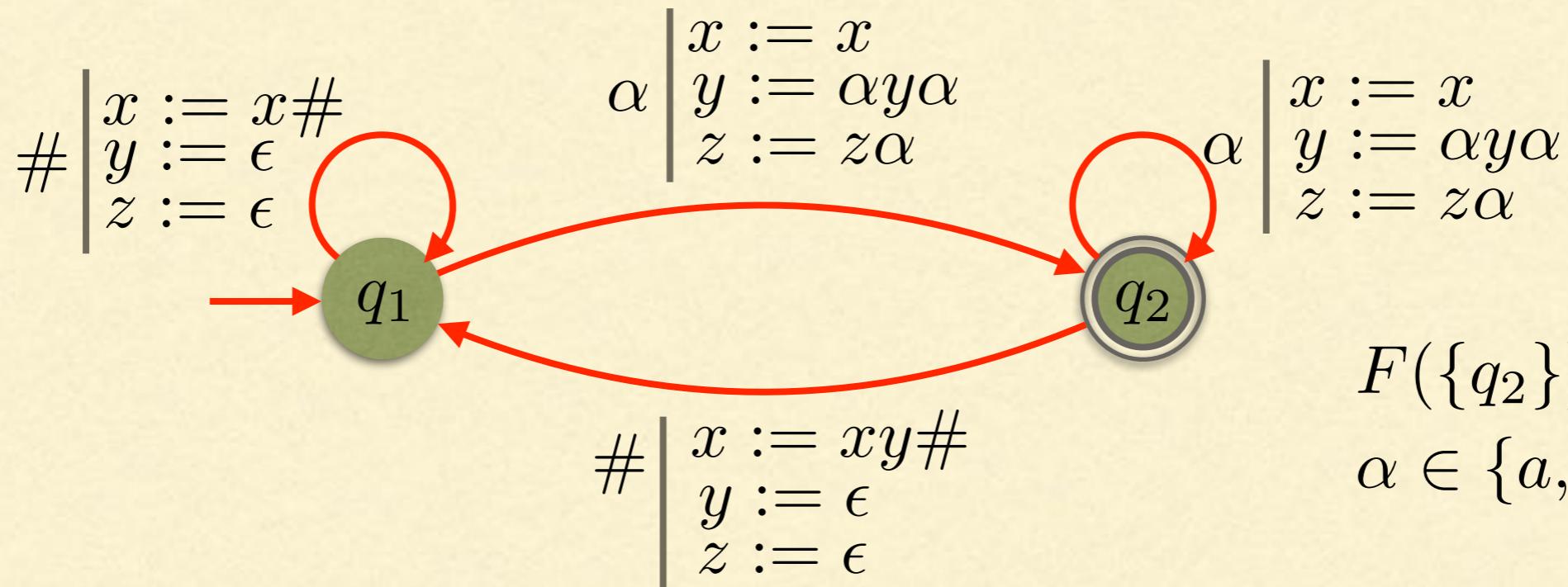
a b b # $(a + b)^\omega$

x:	ϵ	ϵ
y:	ϵ	aa
z:	ϵ	a

$$f(u_1 \# u_2 \# \dots \# u_n \# v) = u_1^R u_1 \# u_2^R u_2 \# \dots \# u_n^R u_n \# v$$

where $u_i \in \{a, b\}^*$ and $v \in \{a, b\}^\omega$

Streaming String Transducer (SST)



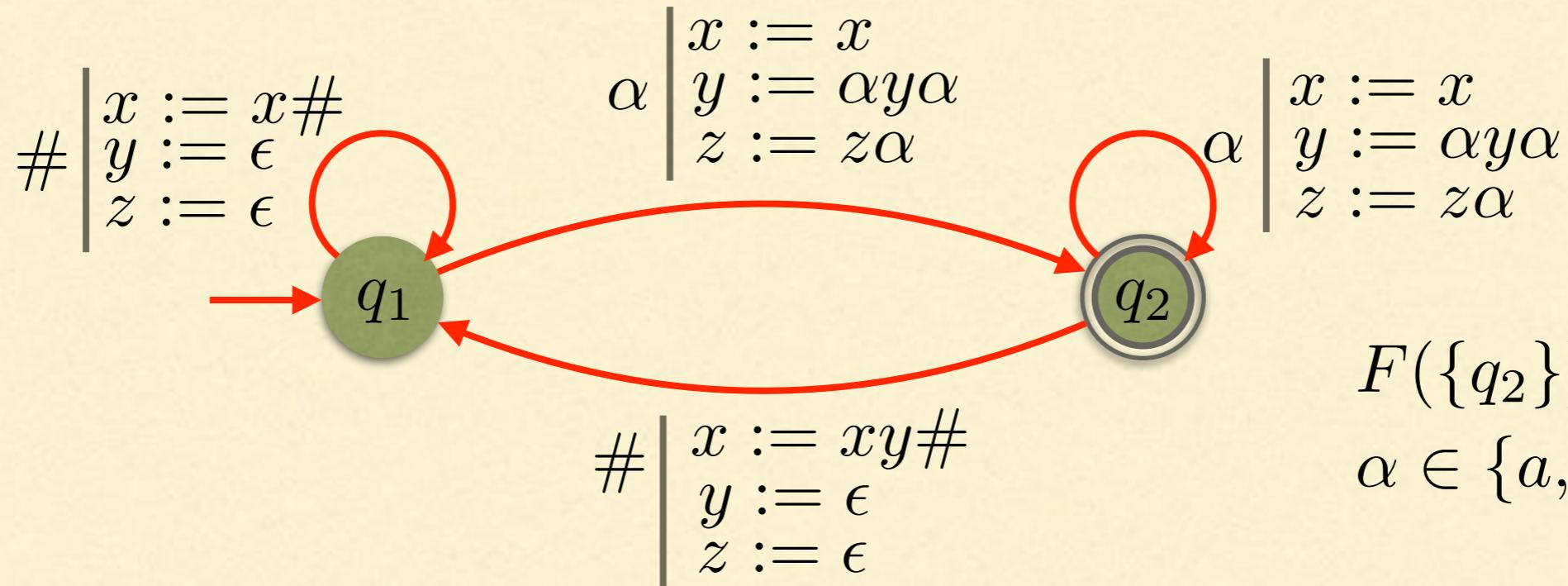
$$\begin{aligned} F(\{q_2\}) &= xz \\ \alpha &\in \{a, b\} \end{aligned}$$

	a	b	b	#	$(a + b)^\omega$
x:	ϵ	ϵ	ϵ	ϵ	
y:	ϵ	aa	baab	bbaabb	
z:	ϵ	a	ab	abb	

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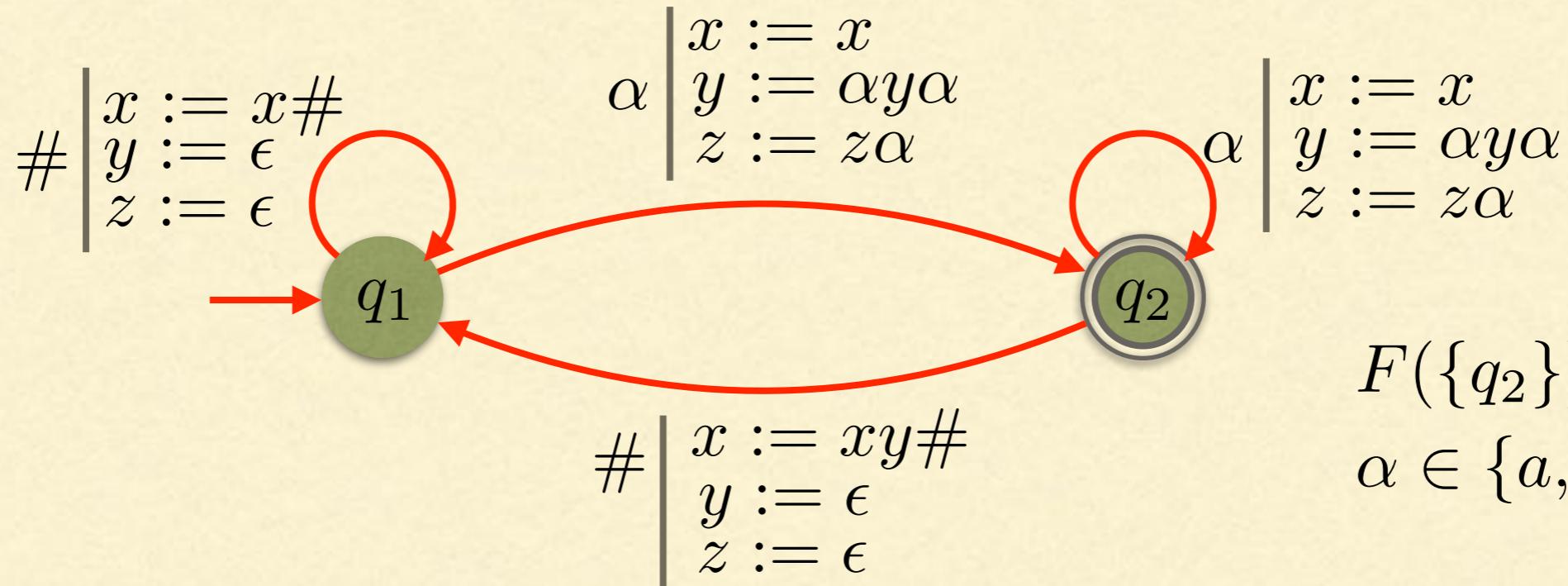
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x:	ϵ	ϵ	ϵ	ϵ	bbaabb#
y:	ϵ	aa	baab	bbaabb	ϵ
z:	ϵ	a	ab	abb	ϵ

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Streaming String Transducer (SST)



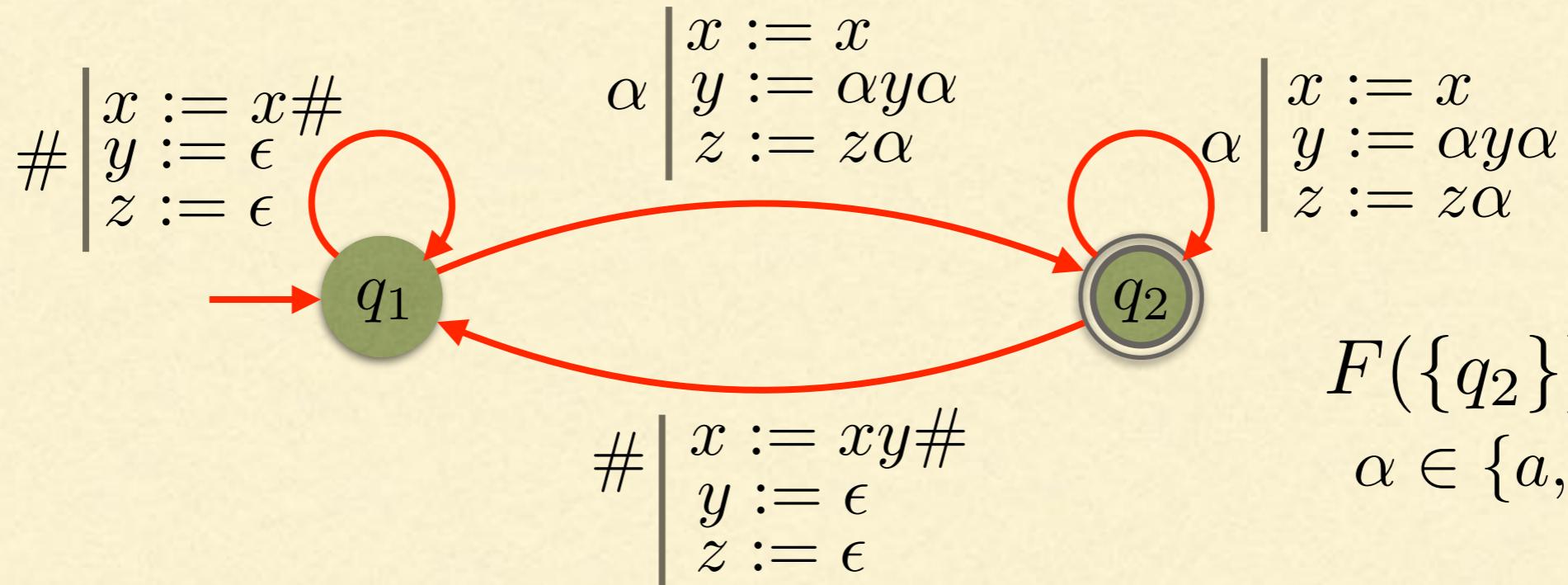
$$\begin{aligned} F(\{q_2\}) &= xz \\ \alpha &\in \{a, b\} \end{aligned}$$

	a	b	b	#	$(a + b)^\omega$
x:	ϵ	ϵ	ϵ	ϵ	bbaabb#
y:	ϵ	aa	baab	bbaabb	ϵ
z:	ϵ	a	ab	abb	ϵ
					$(a + b)^\omega$

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Streaming String Transducer (SST)

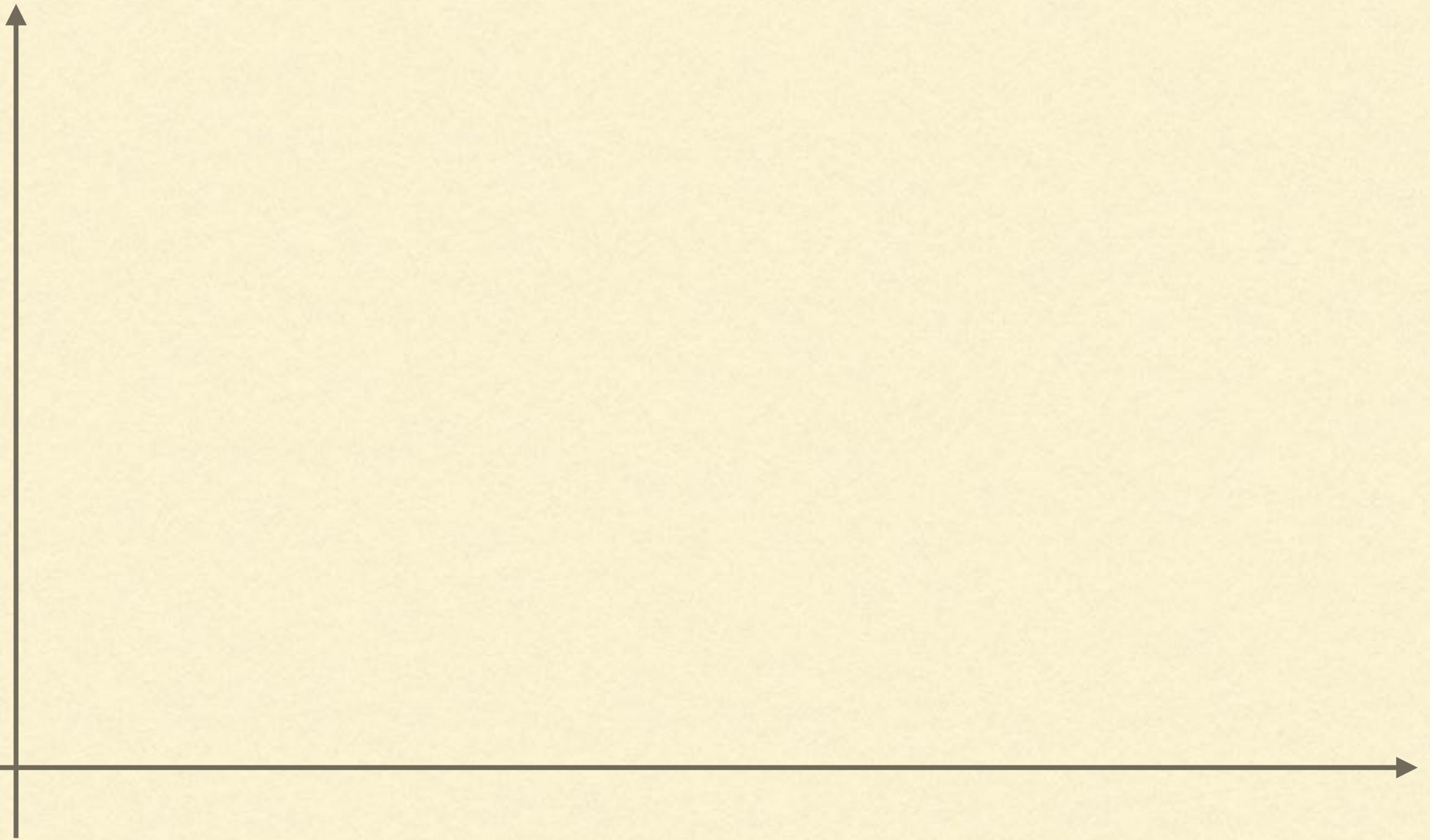


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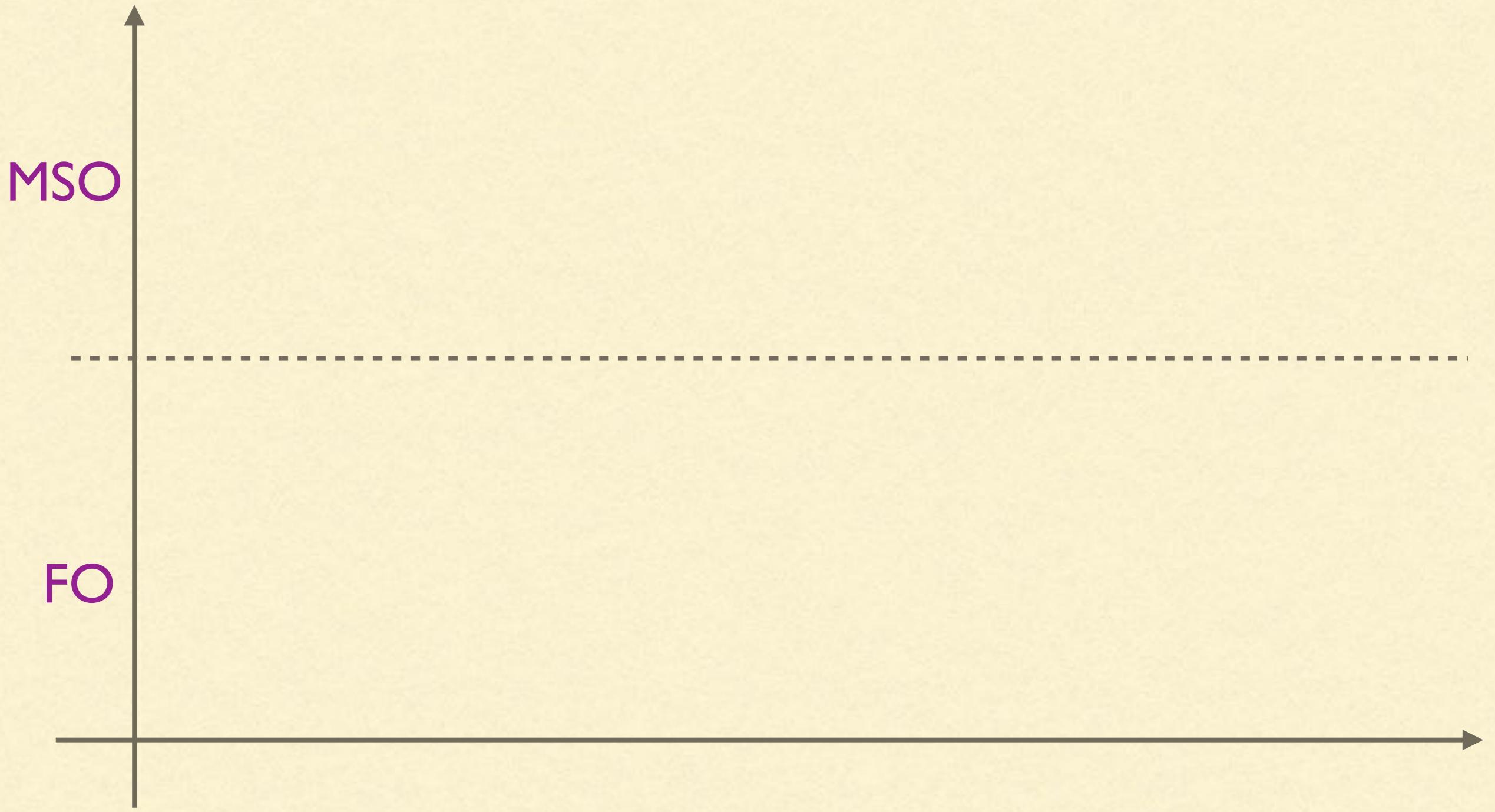
	a	b	b	#	$(a + b)^\omega$
x:	ϵ	ϵ	ϵ	ϵ	bbaabb#
y:	ϵ	aa	baab	bbaabb	ϵ
z:	ϵ	a	ab	abb	ϵ

Related Work

Related Work



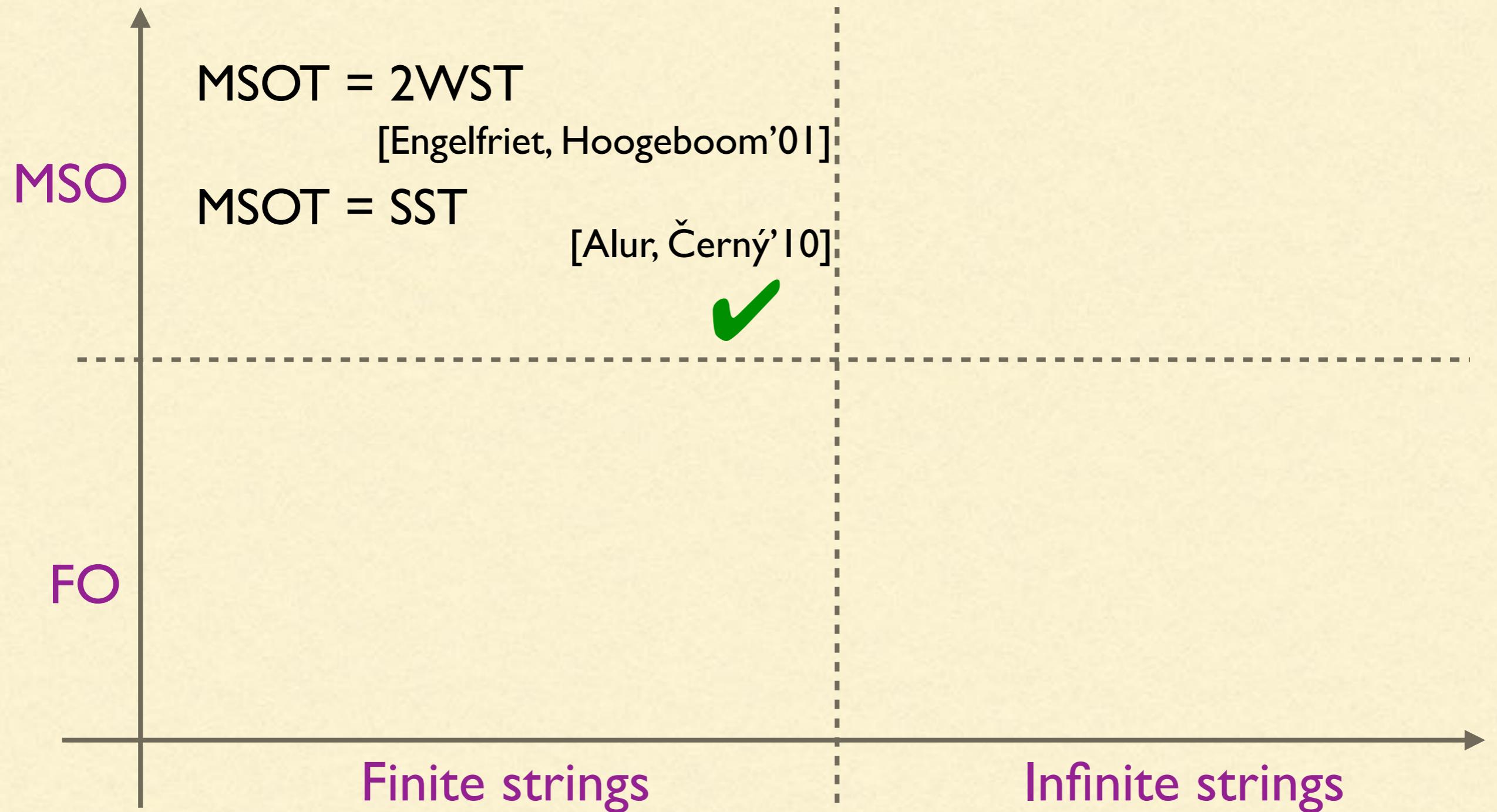
Related Work



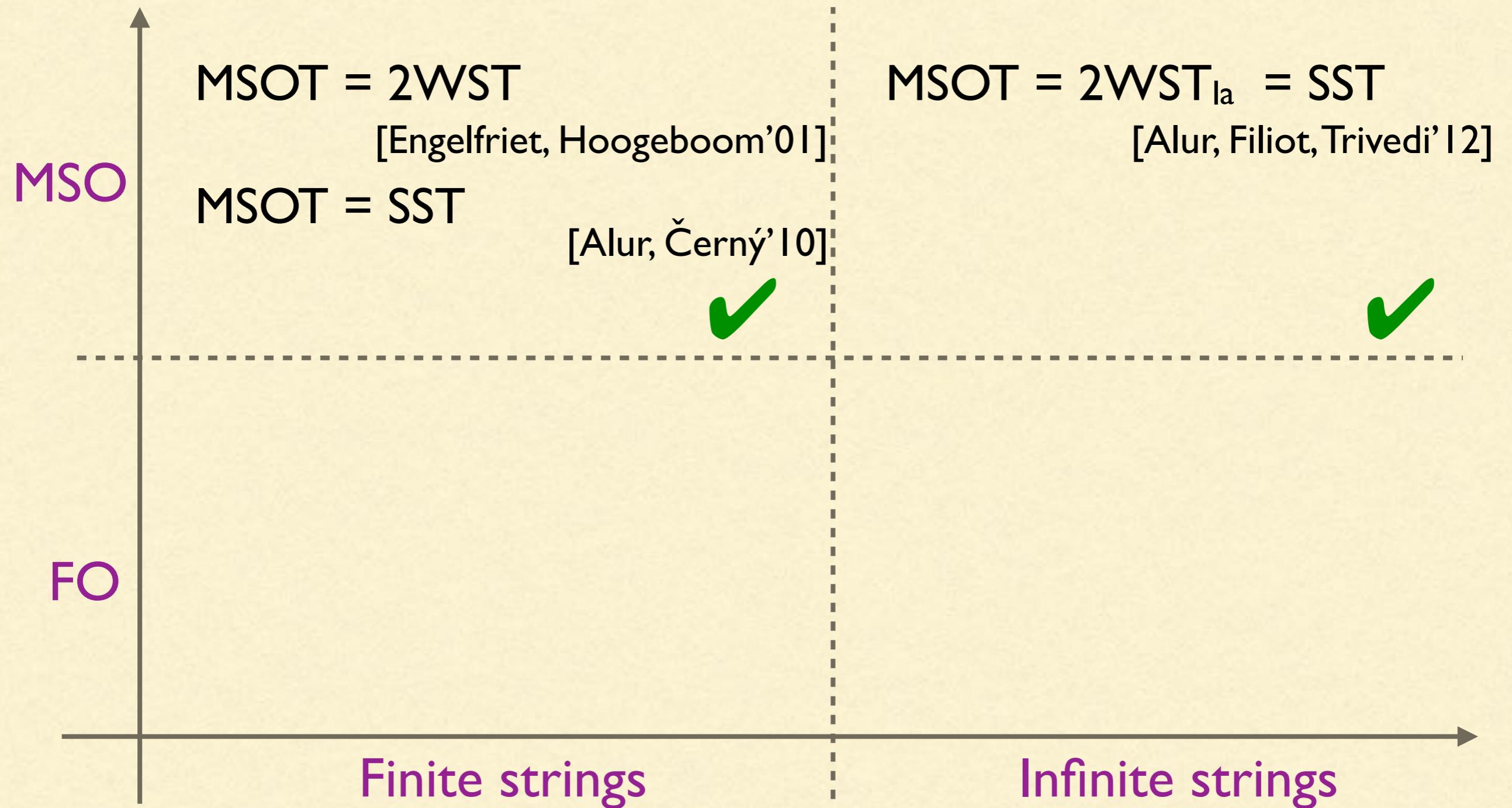
Related Work



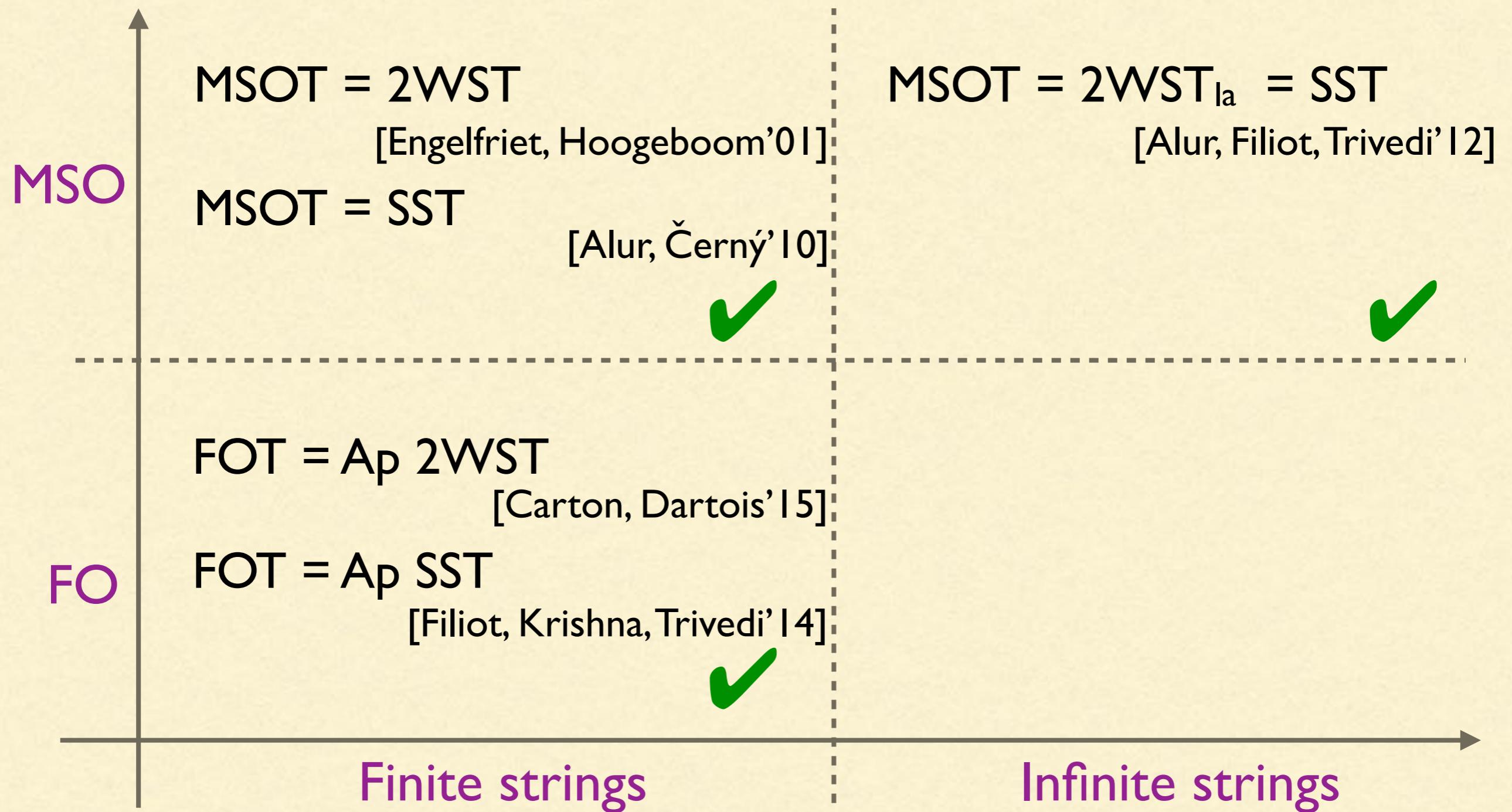
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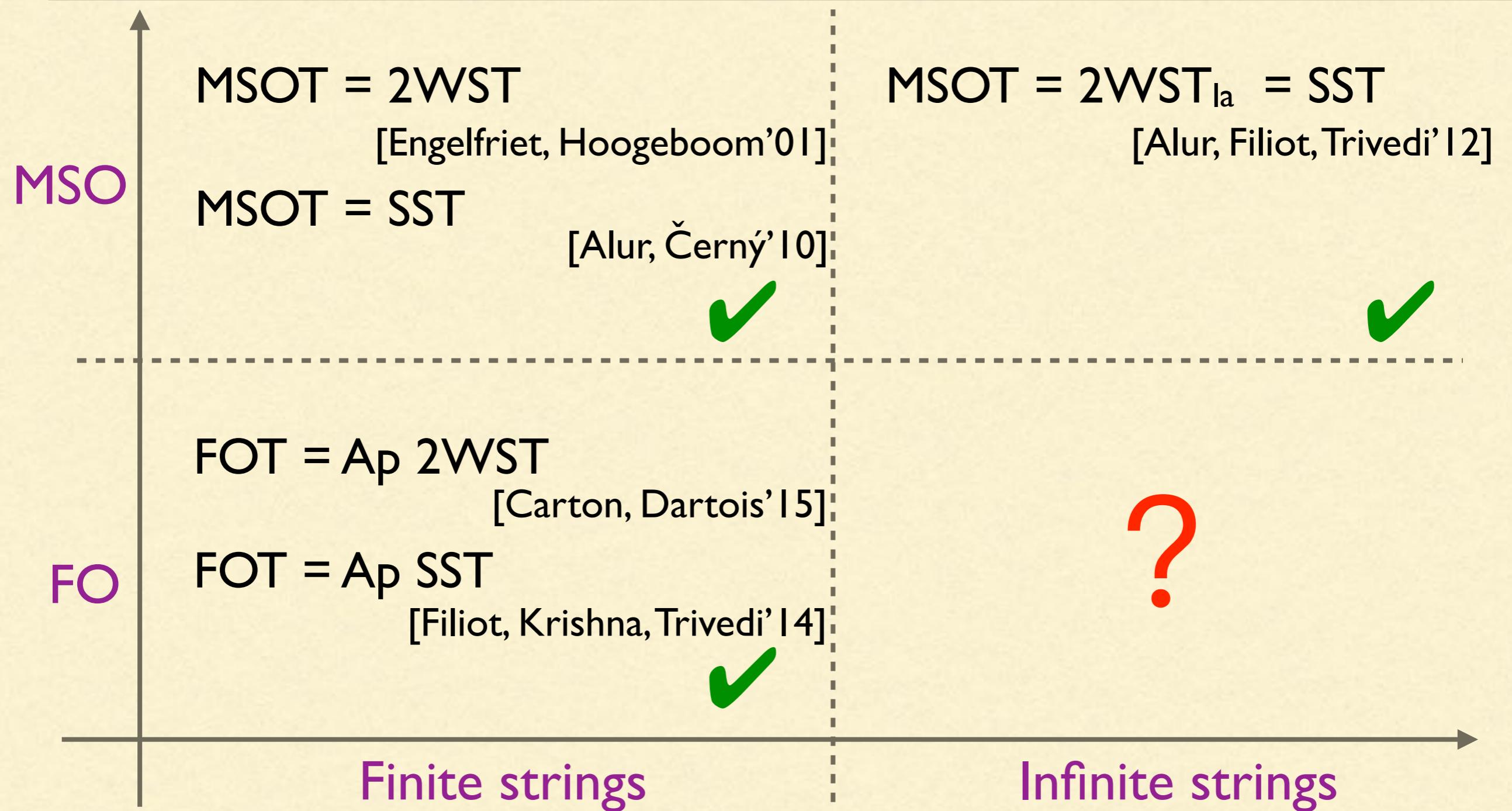
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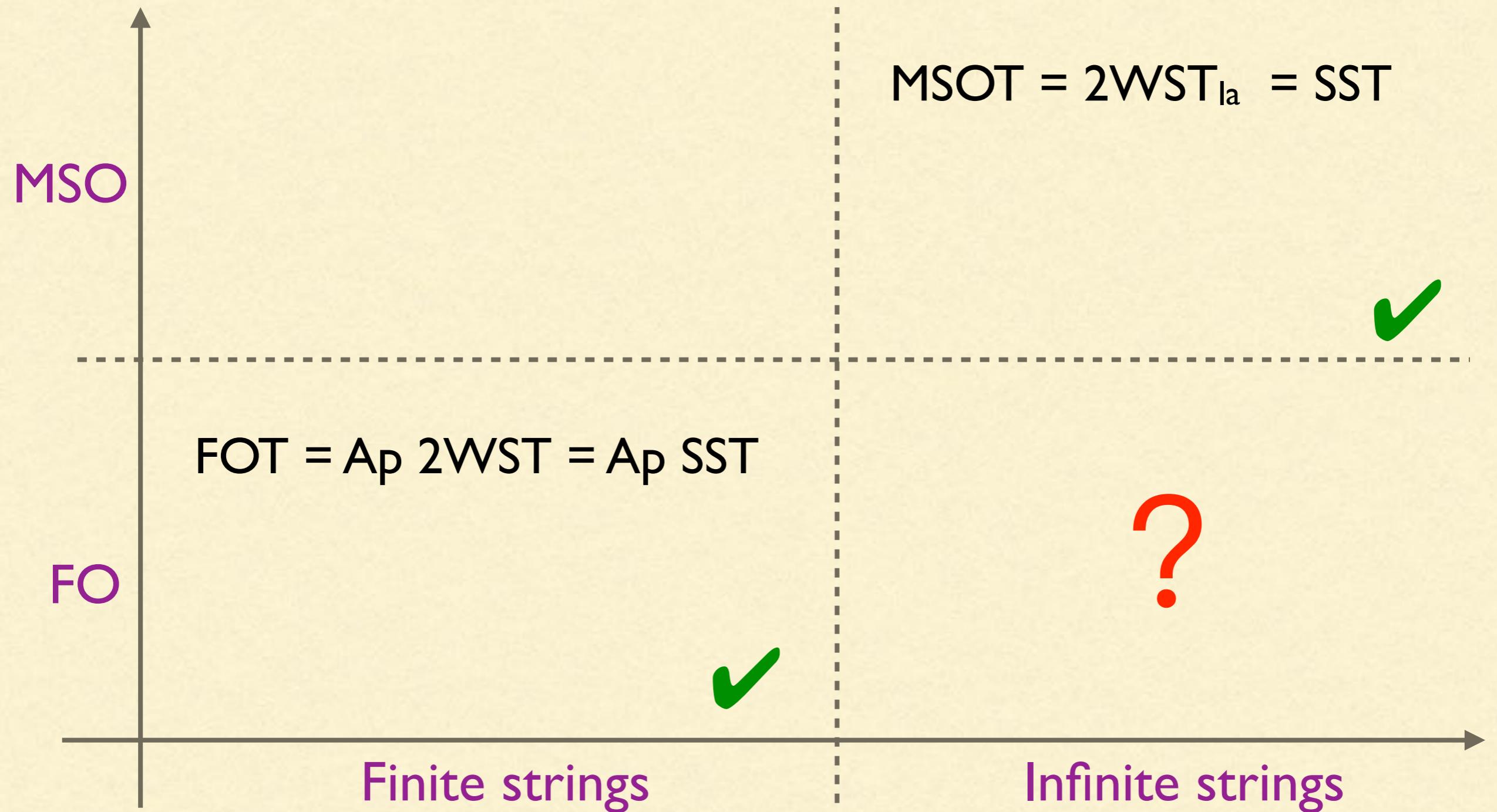
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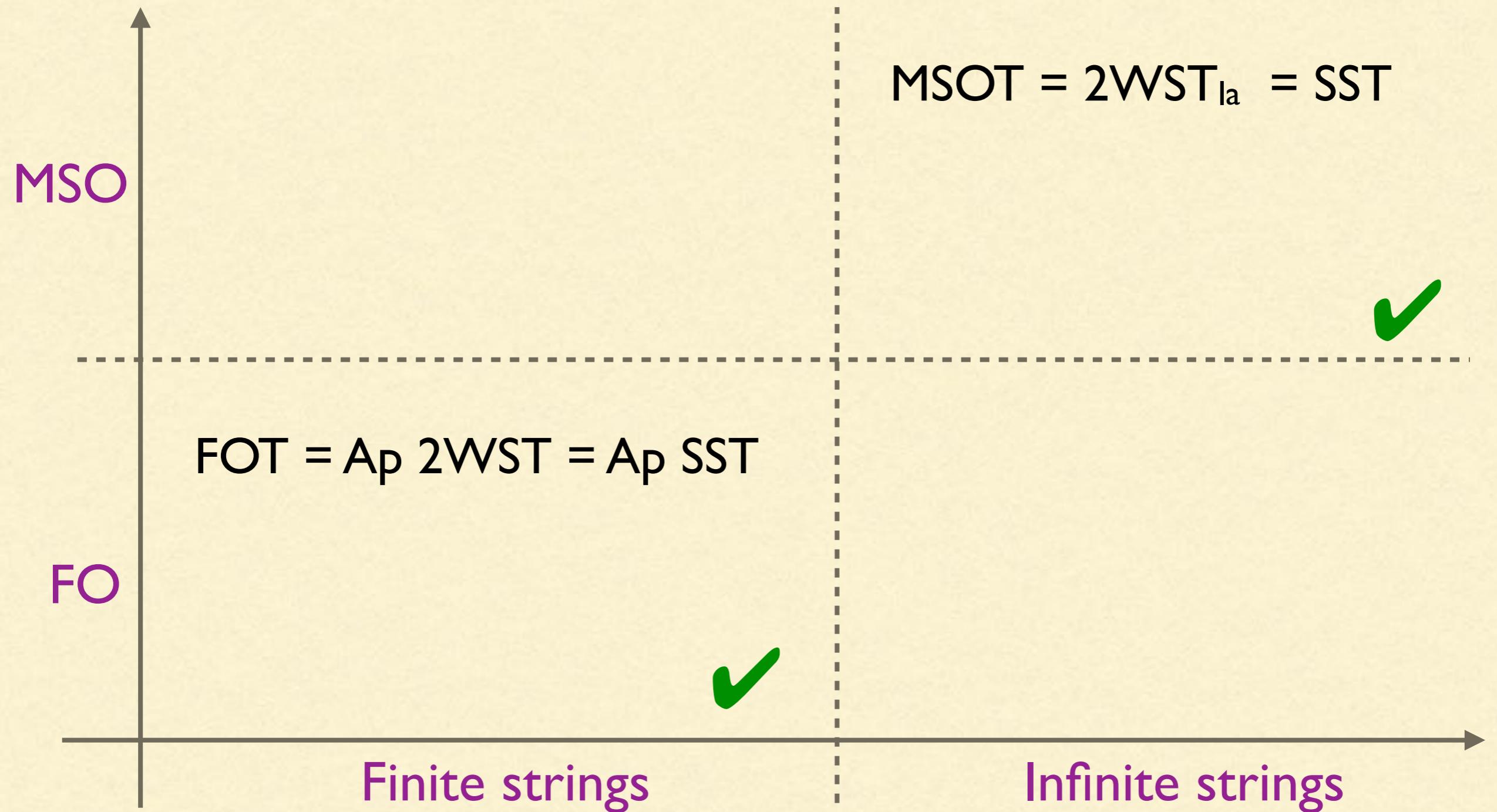
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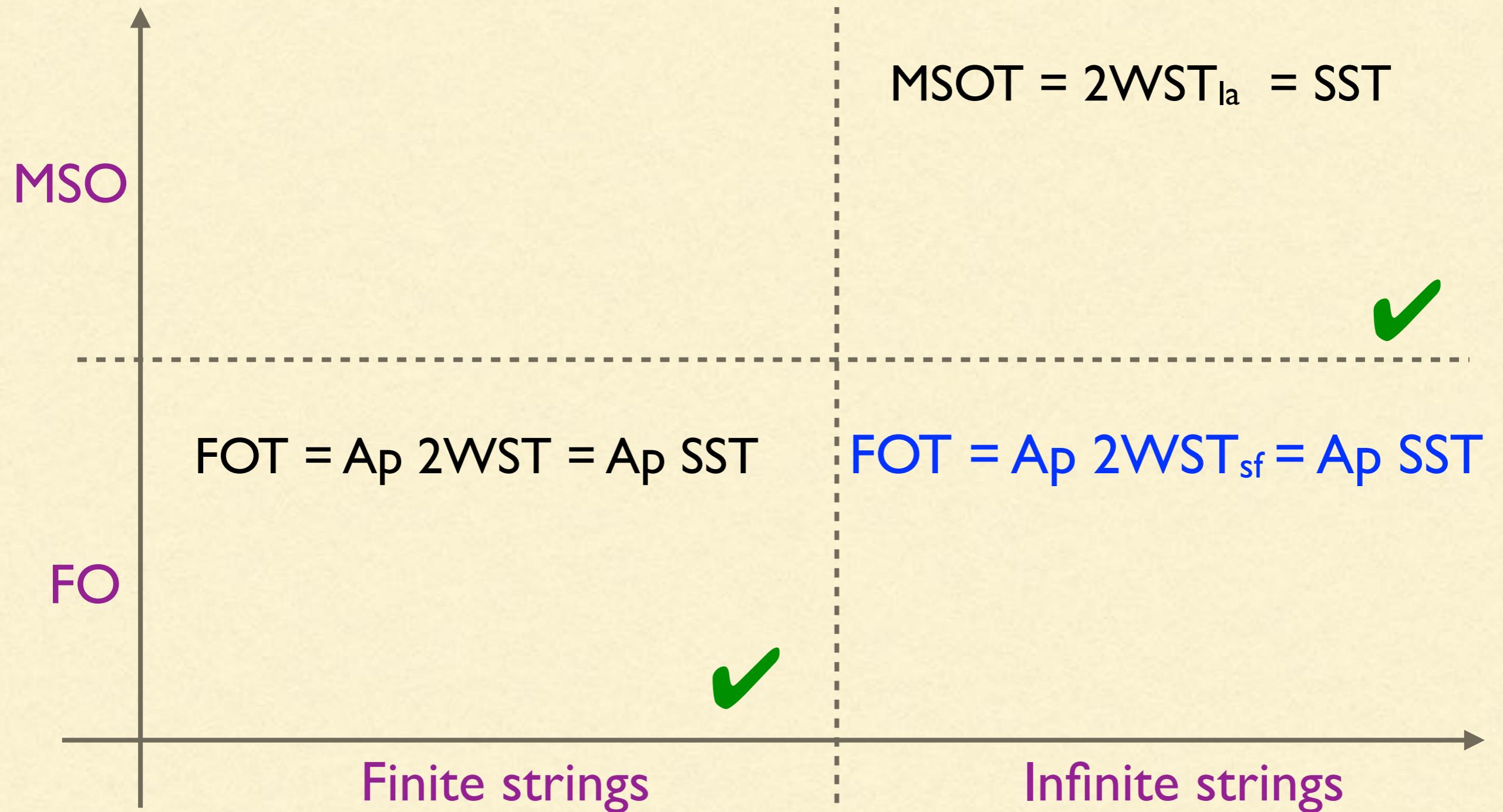
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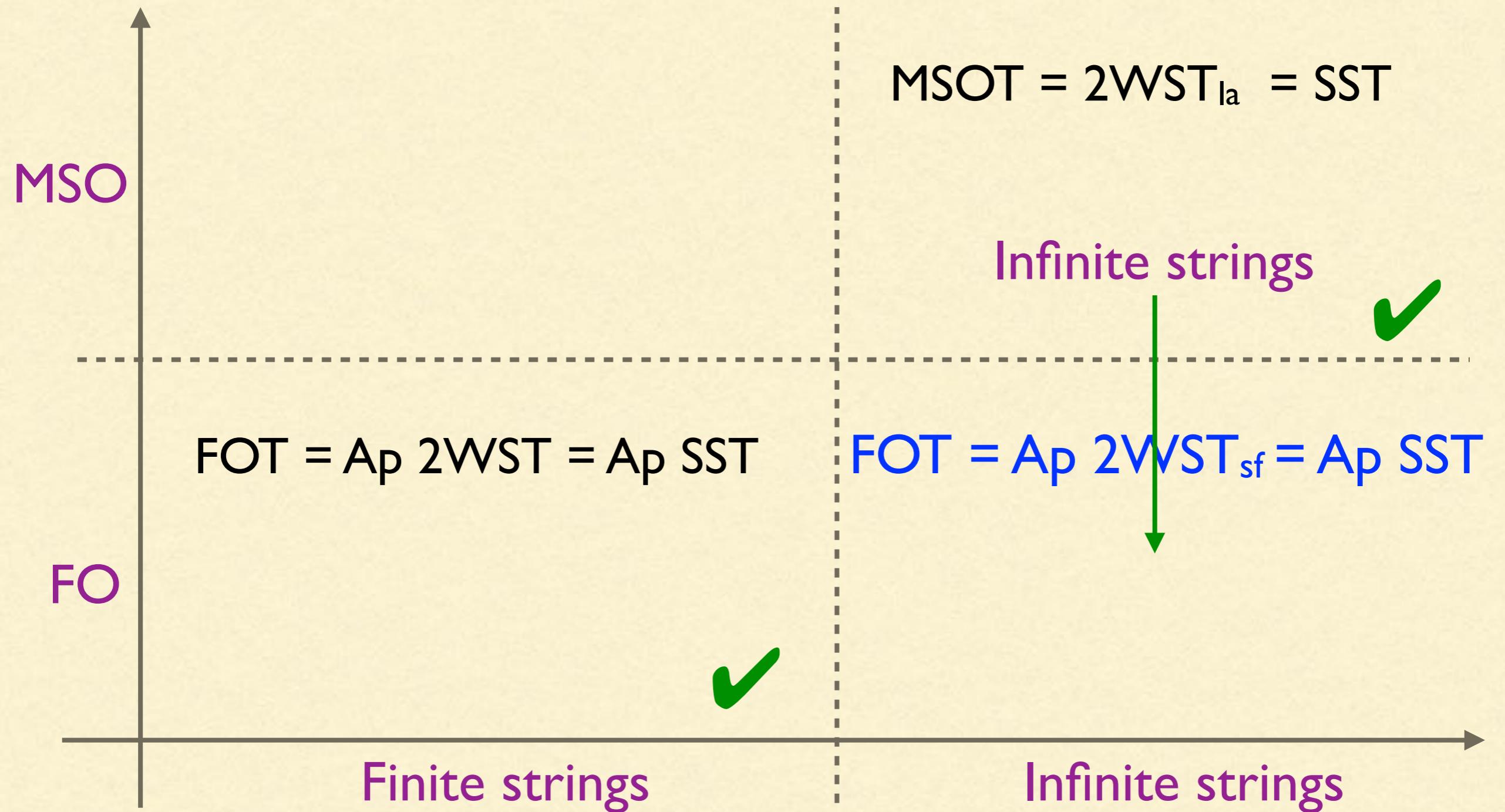
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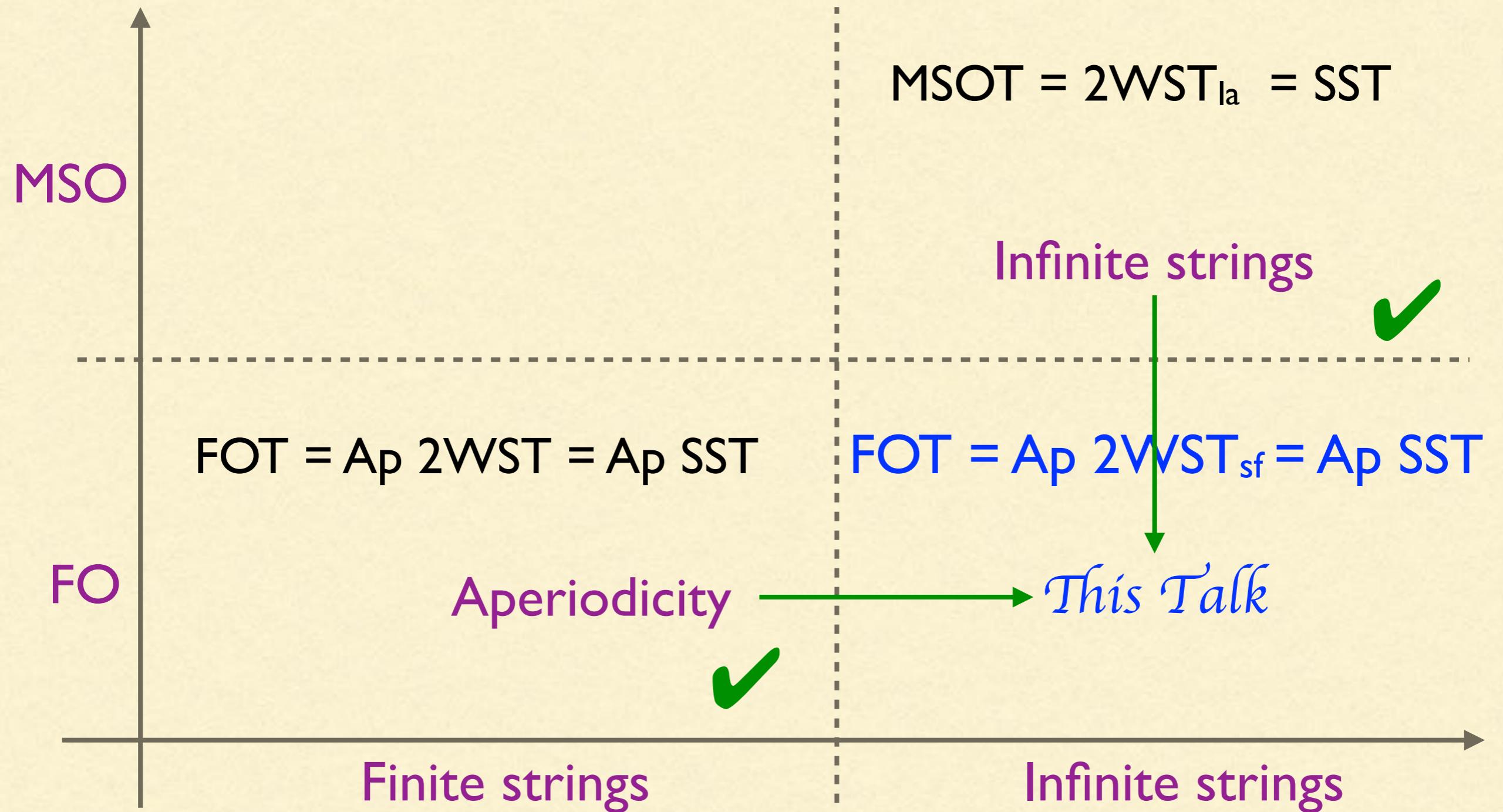
Related Work



Related Work



Related Work



Outline

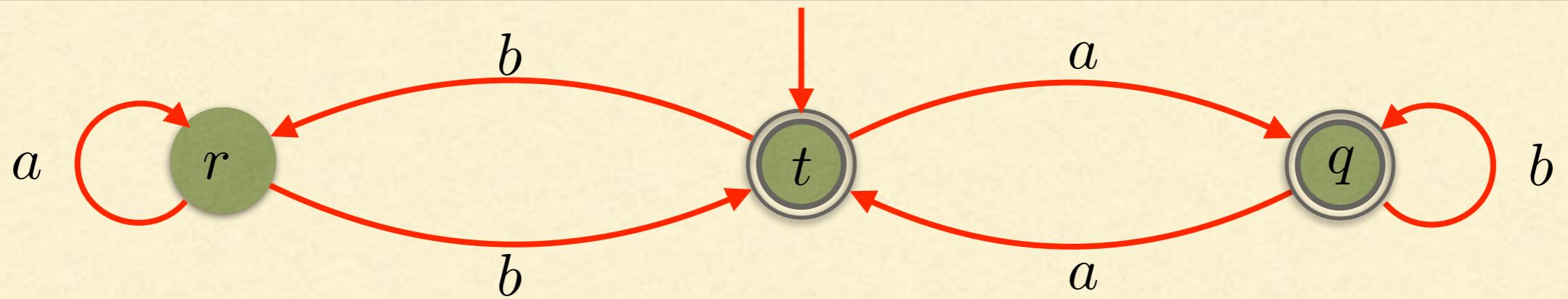
- Introduction
 - Three formalisms for transductions
 - Related work
- Aperiodic transformations for Infinite strings
 - Aperiodic two way transducer
 - Aperiodic streaming string transducer
- Equivalence results and Proof ideas
 - $\text{SST}_{\text{sf}} \subset \text{FOT} = 2\text{WST}_{\text{sf}} \subset \text{SST}_{\text{sf}}$
- Conclusion

Transition monoid of a Finite state automaton

[Schutzenberger'65]

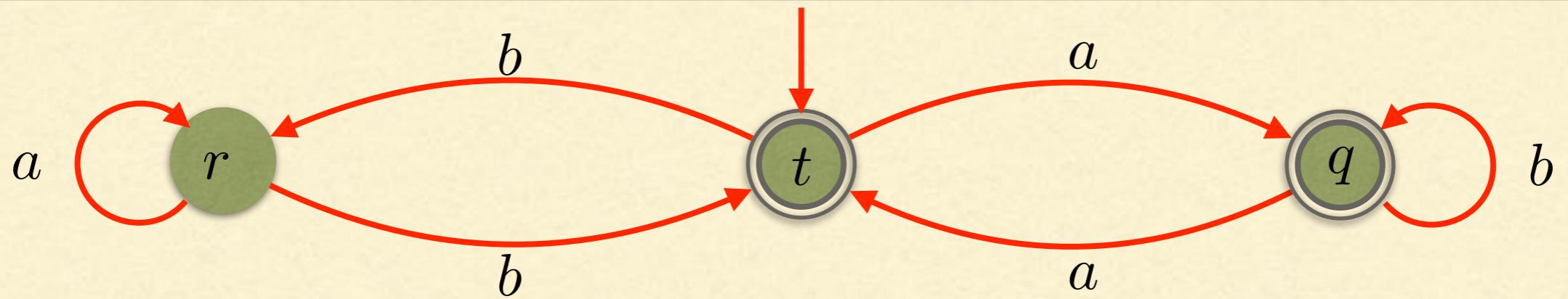
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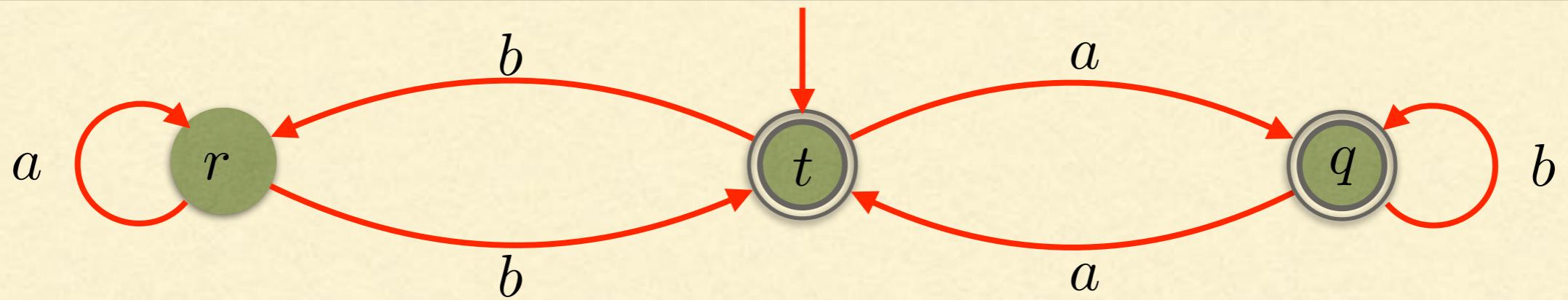


$$\mathcal{M}_{\mathcal{A}} = (M_{\mathcal{A}}, \times, 1)$$

$$M_{\mathcal{A}} \subseteq \{0, 1\}^{|Q| \times |Q|}$$

Transition monoid of a Finite state automaton

[Schutzenberger'65]



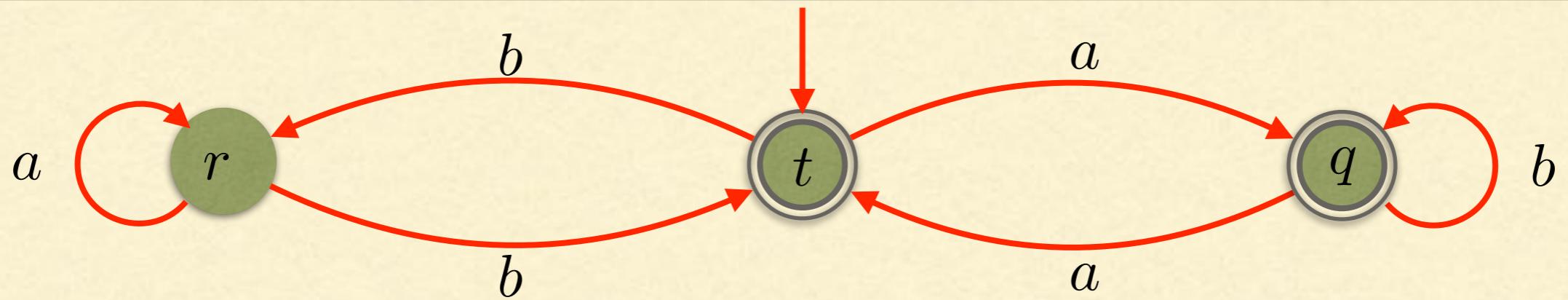
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$$M_{abb} = \begin{pmatrix} & t & q & r \\ t & & & \\ q & & & \\ r & & & \end{pmatrix}$$

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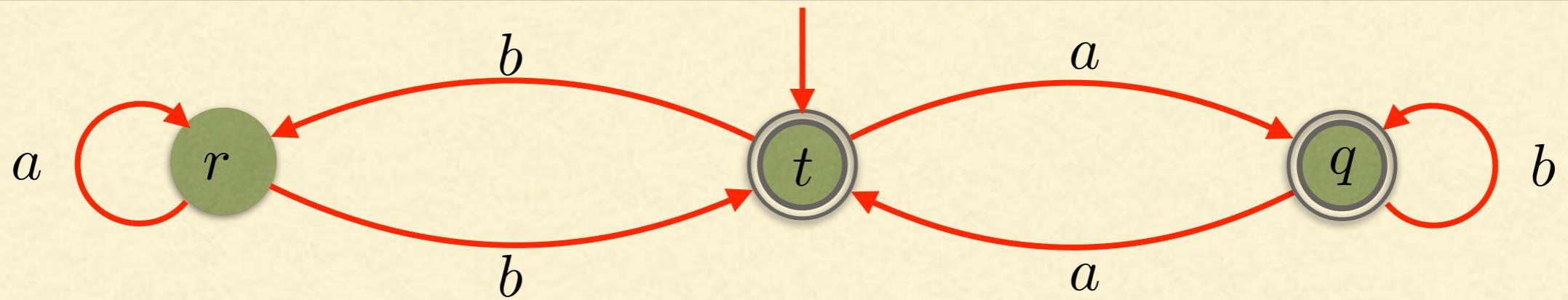
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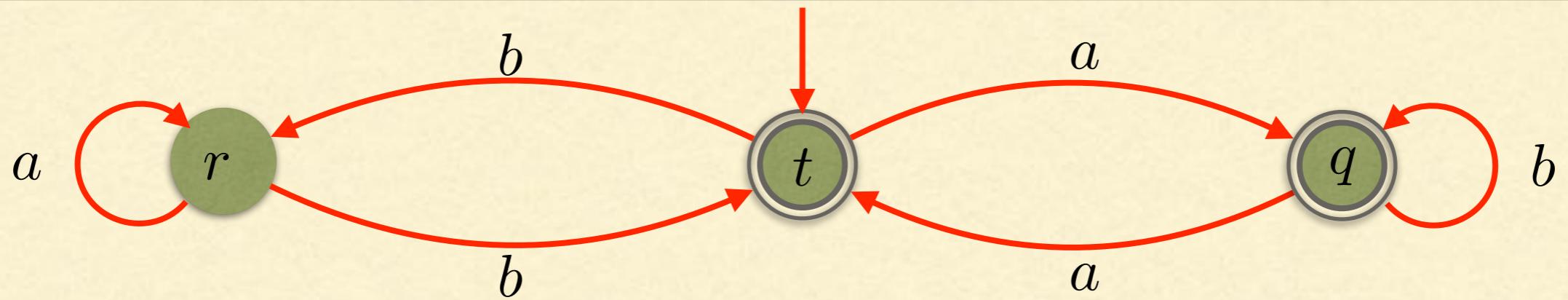
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$$M_{w_1 w_2} = M_{w_1} \times M_{w_2}$$

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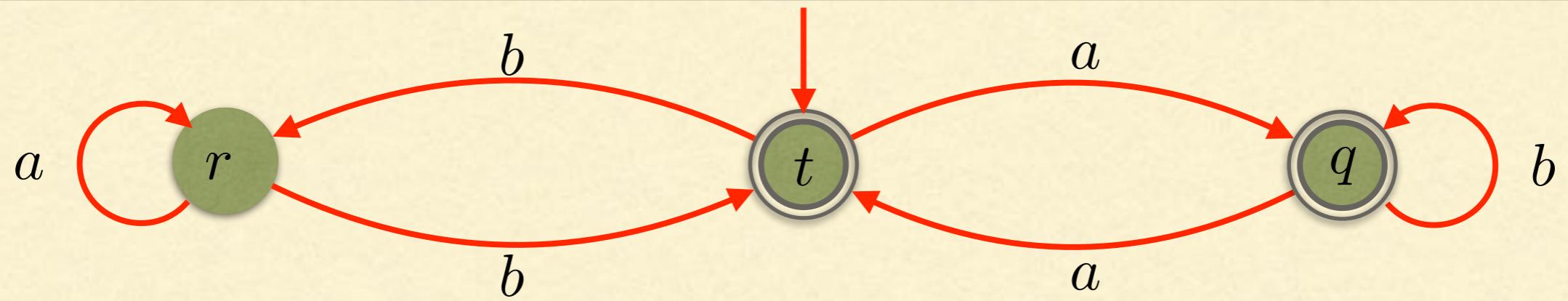
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$$M_{w_1 w_2} = M_{w_1} \times M_{w_2}$$

monoid is aperiodic if $\forall m \in M_{\mathcal{A}} \exists x \in \mathbb{N}$ s.t. $m^x = m^{x+1}$

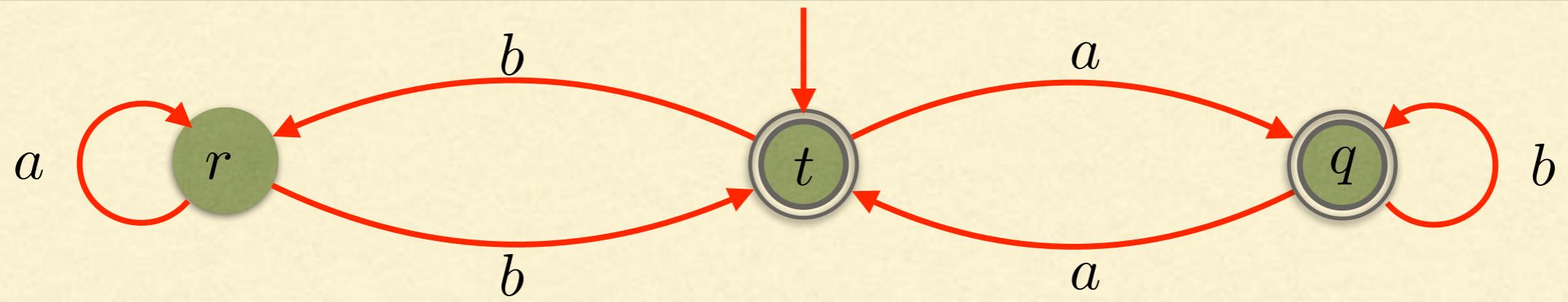
Transition monoid for Muller automaton example

Transition monoid for Muller automaton example



$$\mathcal{F} = \{\{q\}, \{q, t\}\}$$
$$F_1 \quad F_2$$

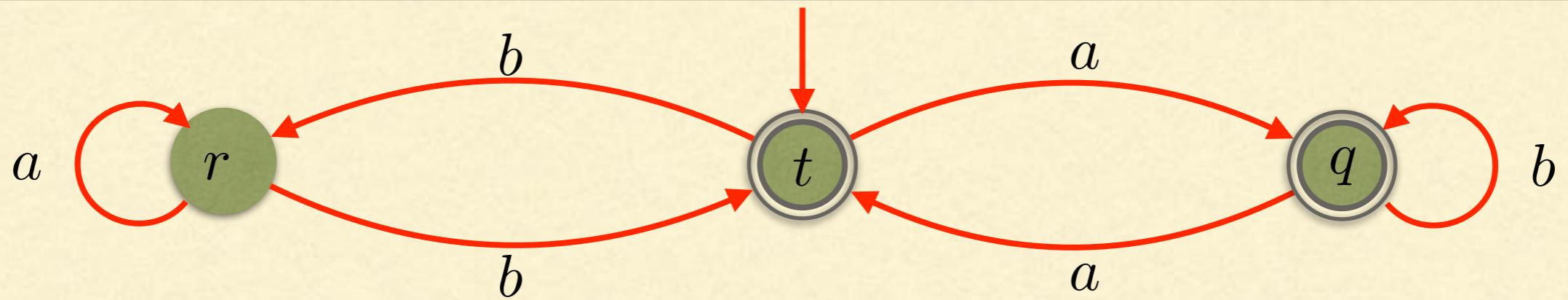
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Transition monoid for Muller automaton example

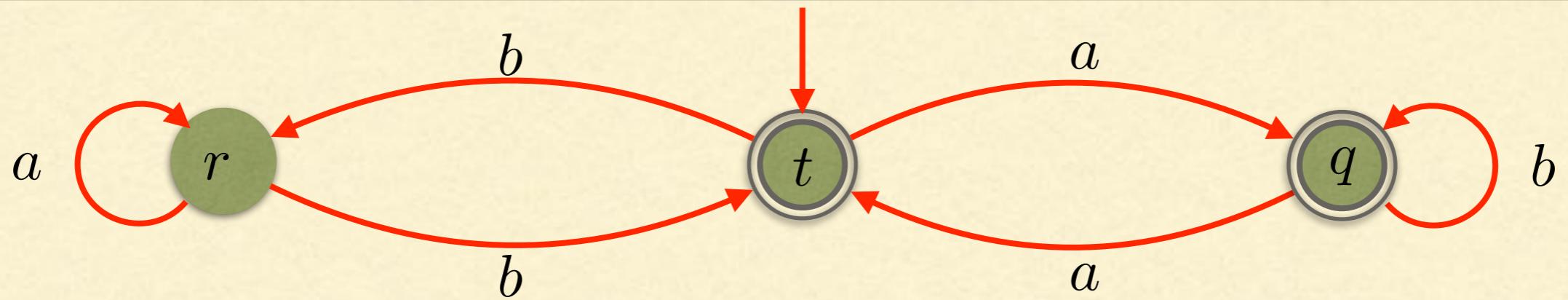


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$$M_{\mathcal{A}} - |Q| \times |Q| \text{ over } (\{0, 1\} \cup 2^Q)^n \cup \{\perp\}.$$

Transition monoid for Muller automaton example



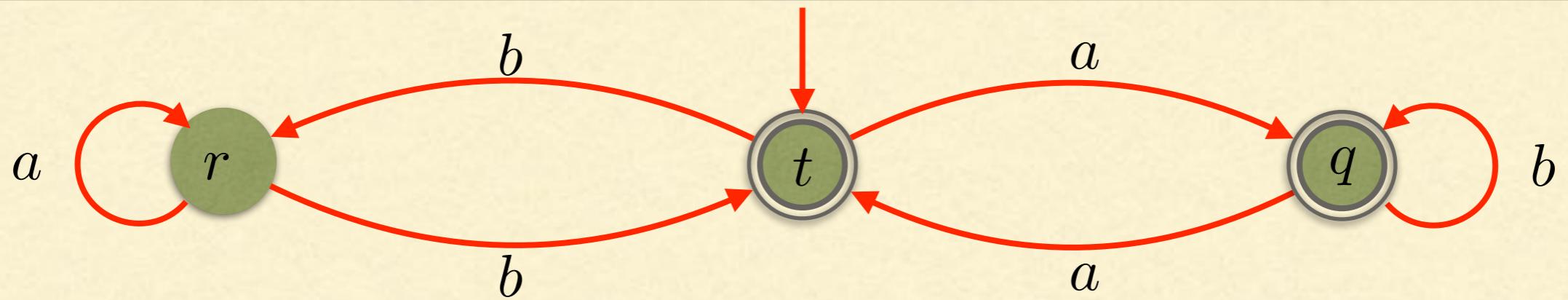
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$$M_{bb} = \begin{array}{ccc} q & r & t \\ \left(\begin{array}{c} q \\ r \\ t \end{array} \right) & & \left(\begin{array}{c} q \\ r \\ t \end{array} \right) \end{array}$$

Transition monoid for Muller automaton example



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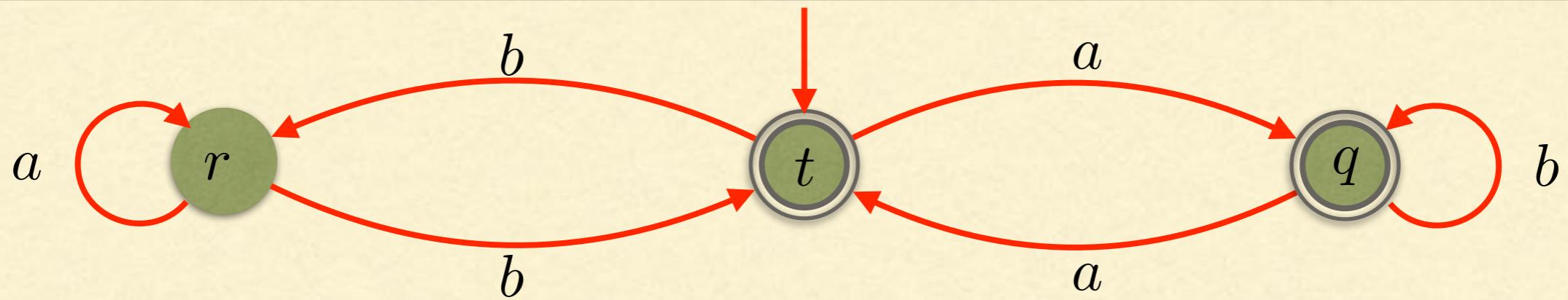
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Transition monoid for Muller automaton example



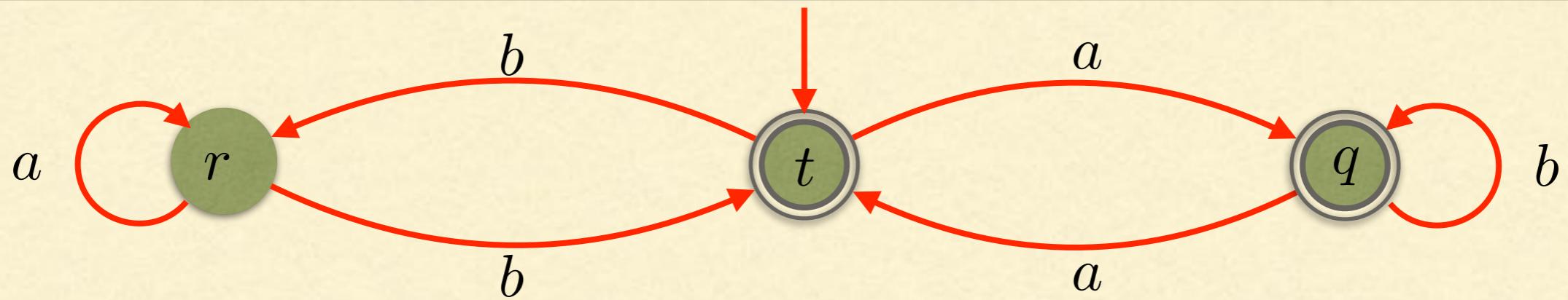
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Transition monoid for Muller automaton example



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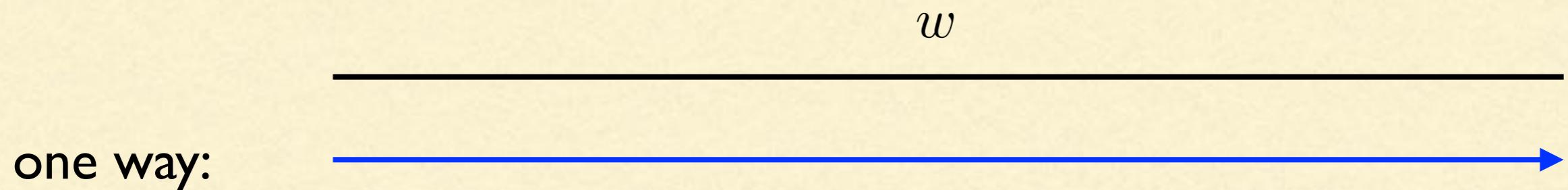
$$M_{bb} = \begin{array}{ccc} & q & r & t \\ \begin{matrix} q \\ r \\ t \end{matrix} & \left(\begin{array}{ccc} (1, \{q\}) & \perp & \perp \\ \perp & (0, 0) & \perp \\ \perp & \perp & (0, 0) \end{array} \right) \end{array}$$

Partial runs for two way automaton

Partial runs for two way automaton

w

Partial runs for two way automaton



Partial runs for two way automaton

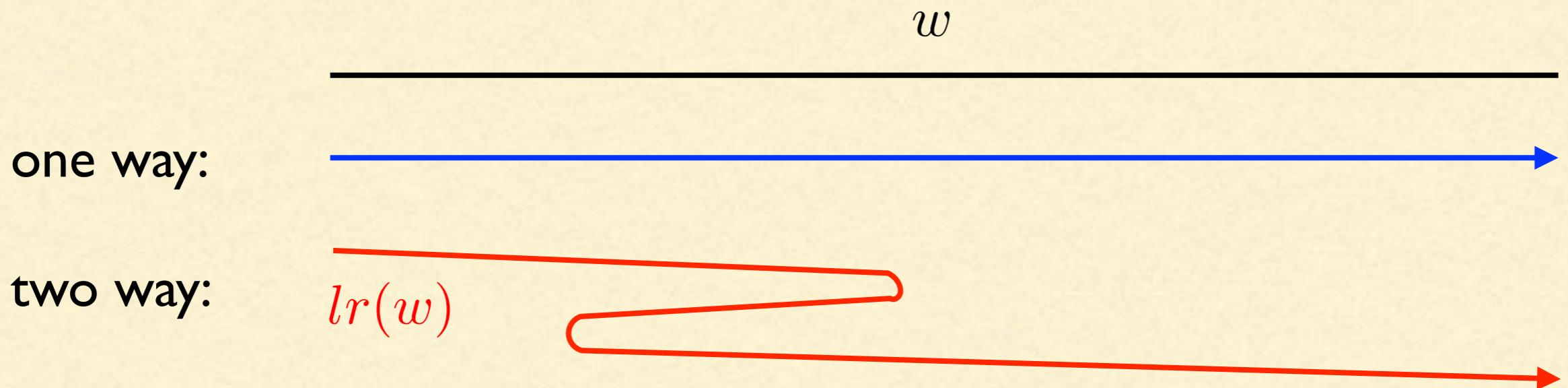
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one way:

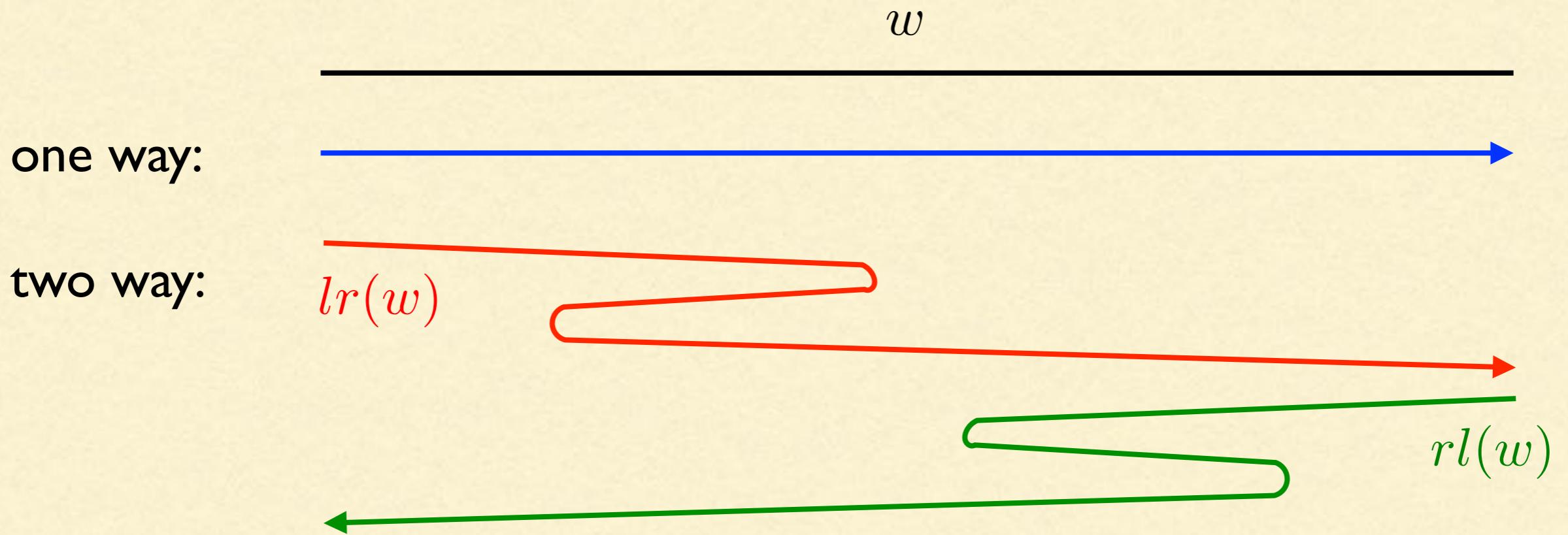


two way:

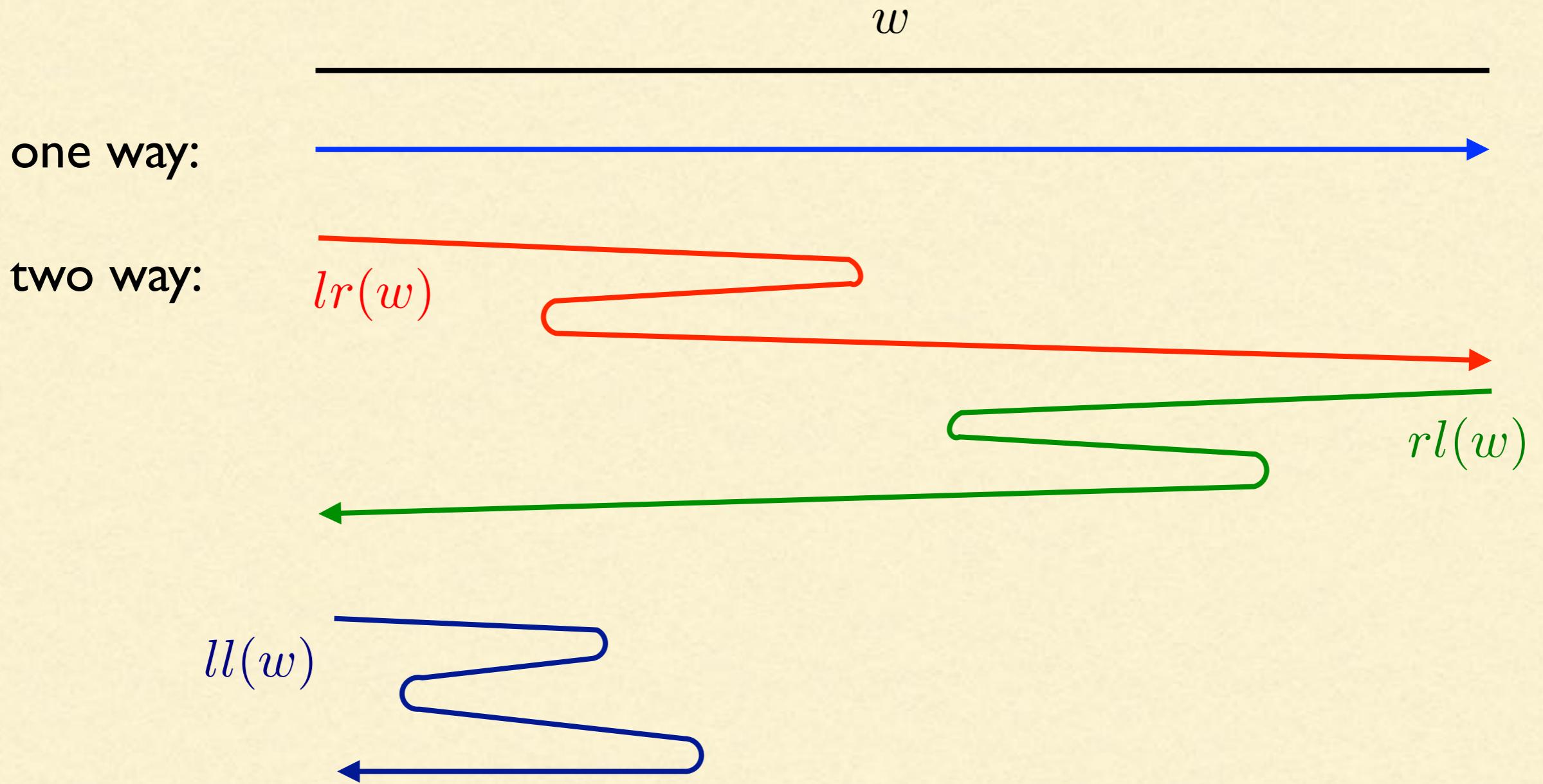
Partial runs for two way automaton



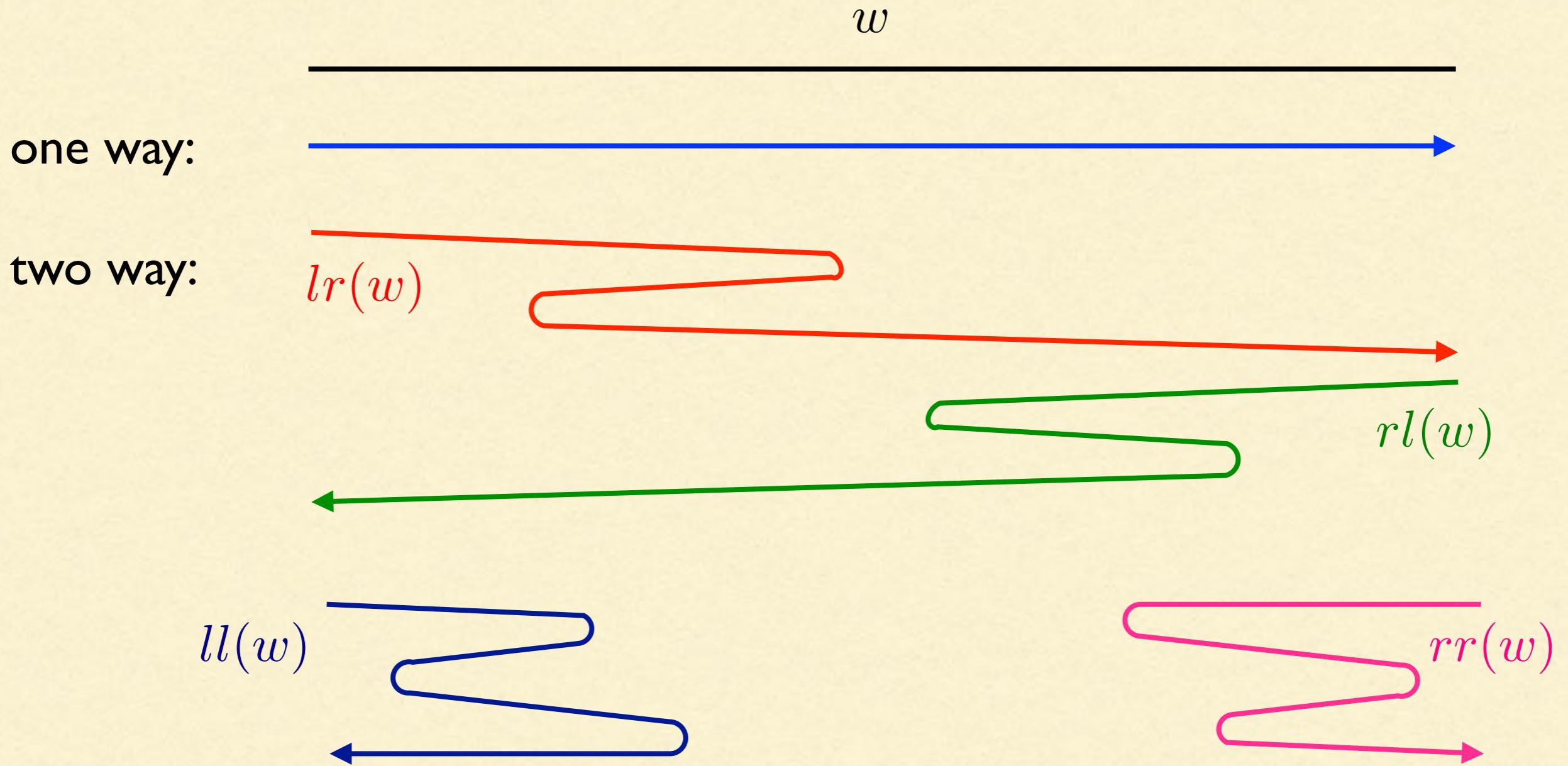
Partial runs for two way automaton



Partial runs for two way automaton

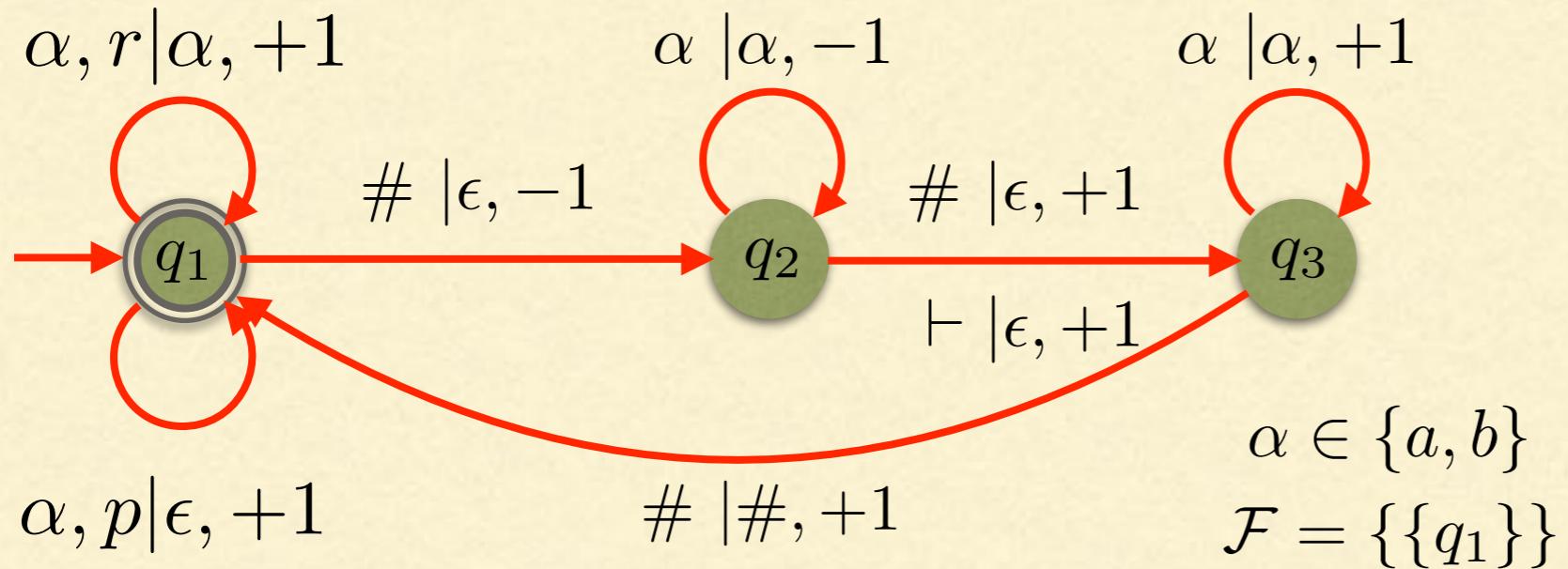


Partial runs for two way automaton

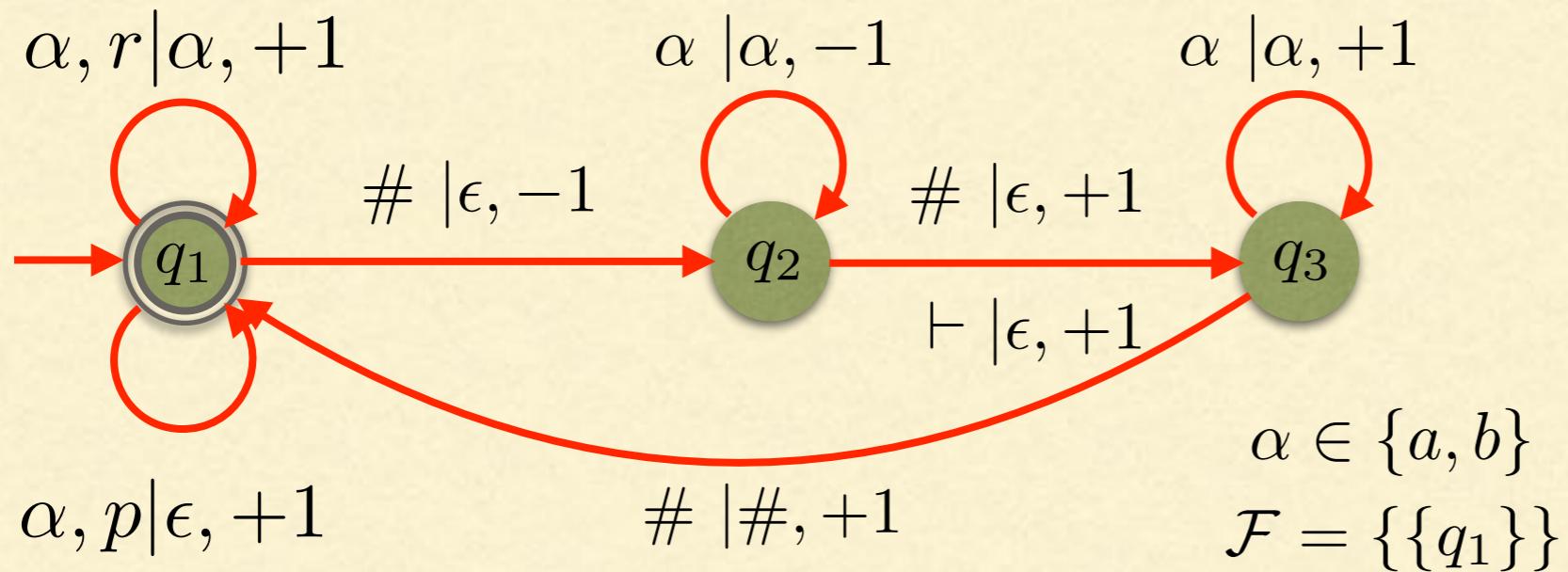


Transition monoid for Two Way Transducer for ω strings

Transition monoid for Two Way Transducer for ω strings



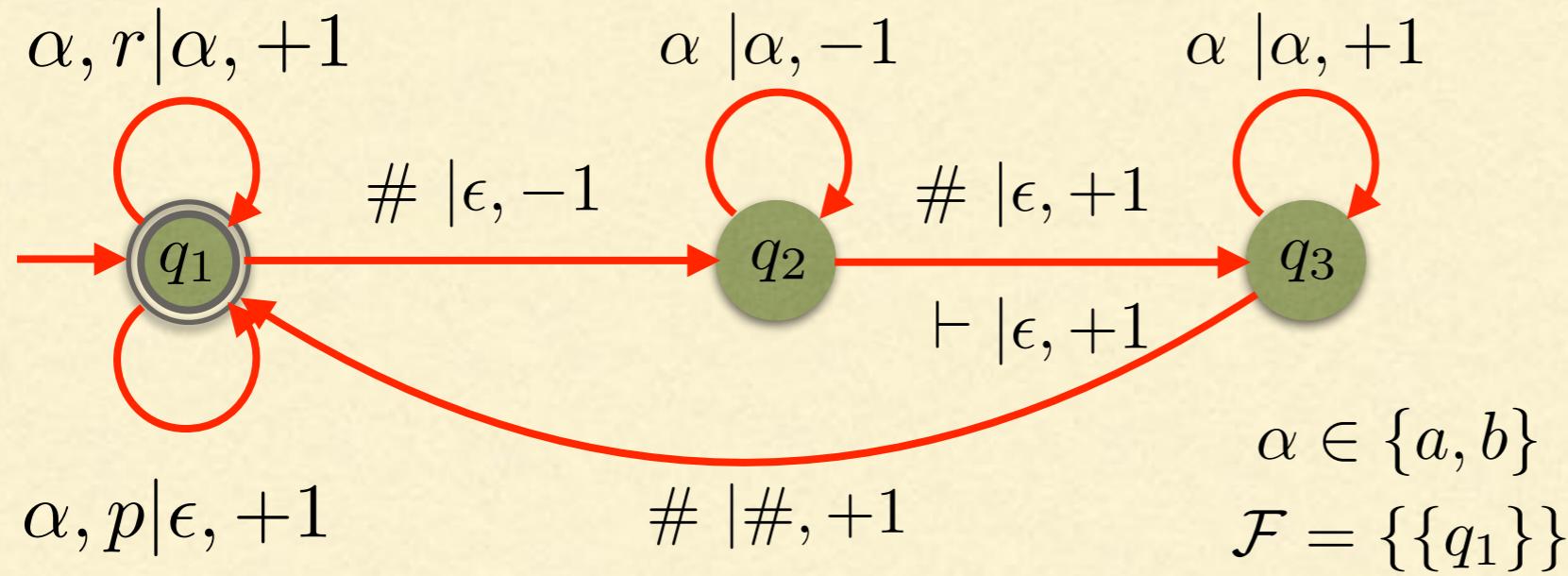
Transition monoid for Two Way Transducer for ω strings



$$\begin{aligned}\alpha &\in \{a, b\} \\ \mathcal{F} &= \{\{q_1\}\}\end{aligned}$$

$$M_s = \begin{pmatrix} M_s^{ll} & M_s^{lr} \\ M_s^{rl} & M_s^{rr} \end{pmatrix}$$

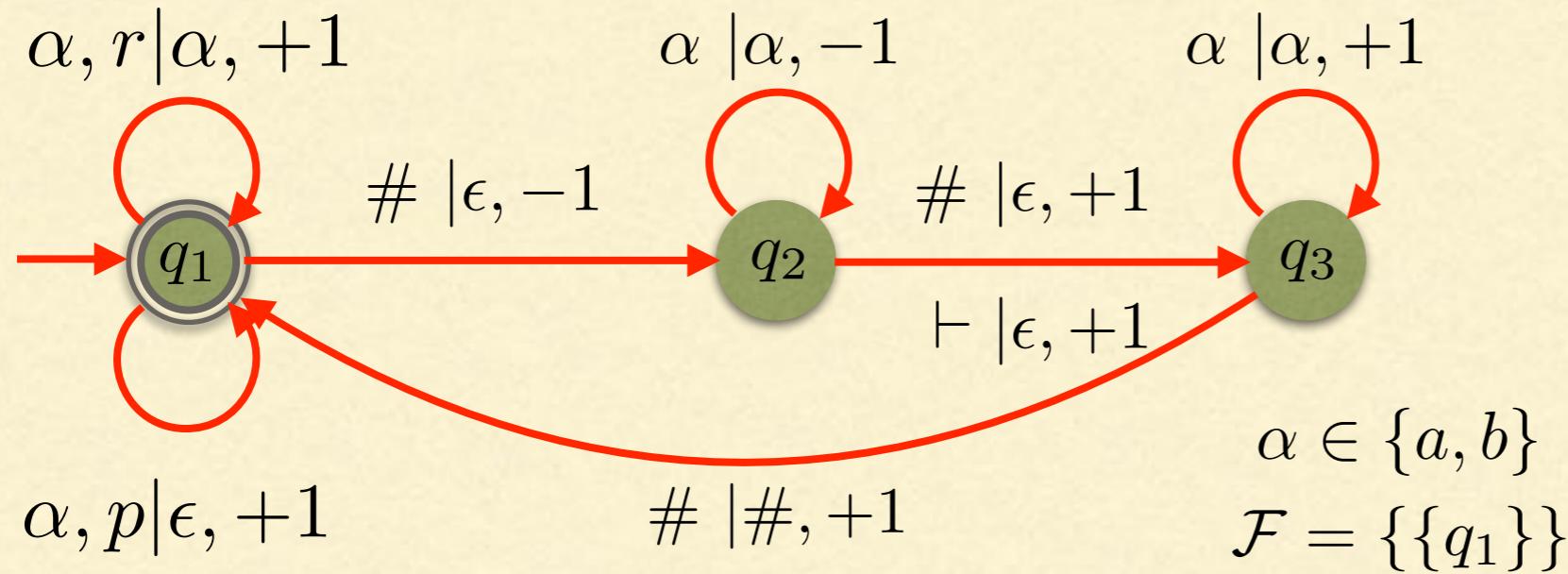
Transition monoid for Two Way Transducer for ω strings



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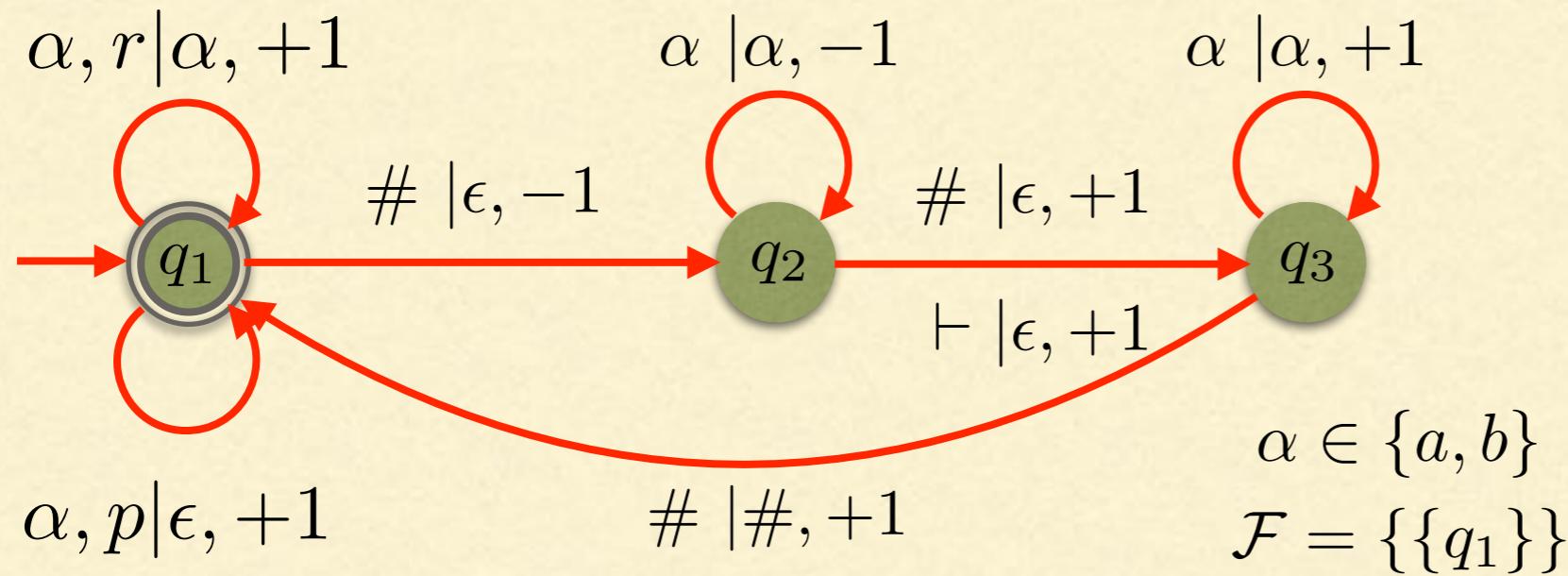
Transition monoid for Two Way Transducer for ω strings



$$M_s = \begin{pmatrix} M_s^{ll} & M_s^{lr} \\ M_s^{rl} & M_s^{rr} \end{pmatrix}$$

$$M_{ab\#}^{lr} = q_2 \left(\begin{array}{cc} & \\ q_1 & \left(\begin{array}{cc} \perp & \perp \end{array} \right) \\ & \\ q_3 & \end{array} \right)$$

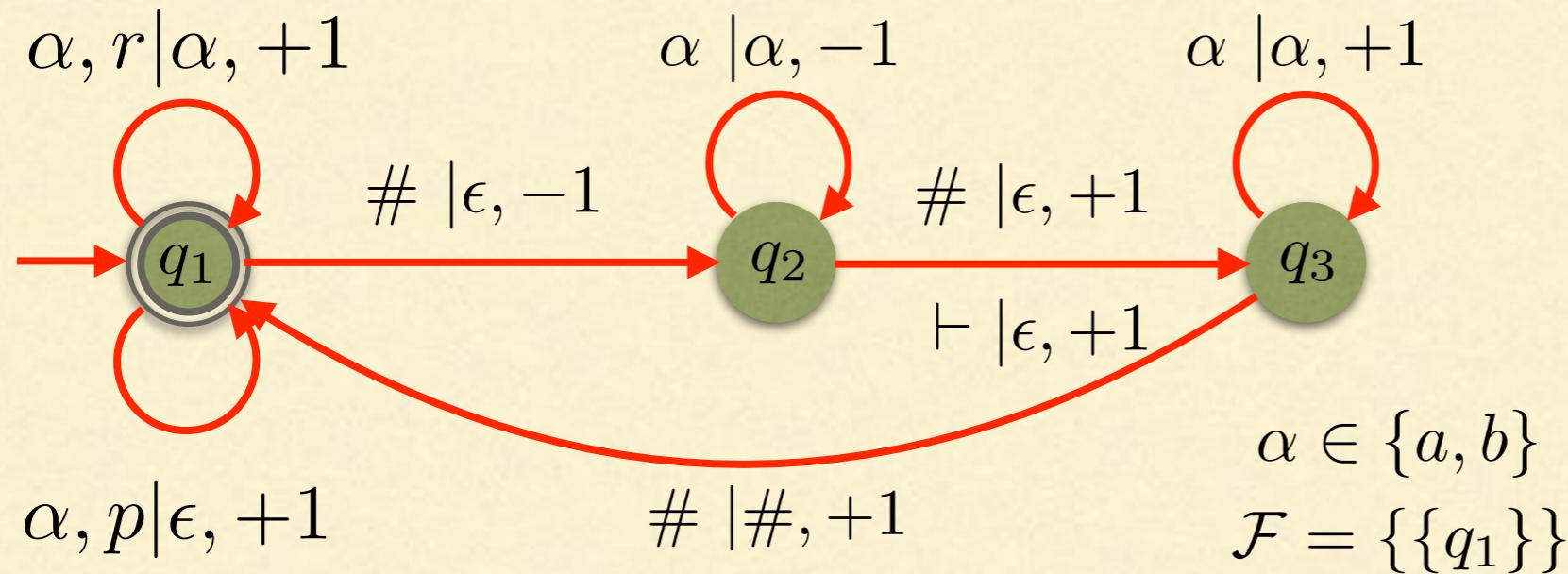
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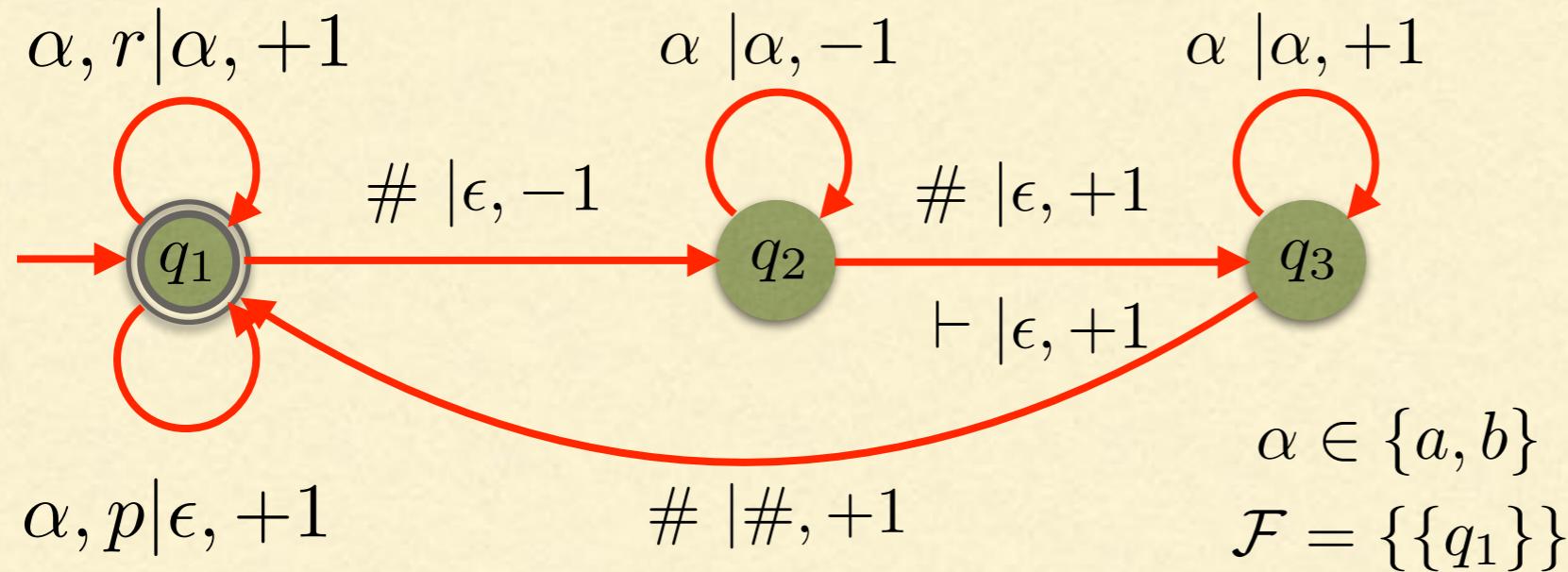
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Transition monoid for Two Way Transducer for ω strings

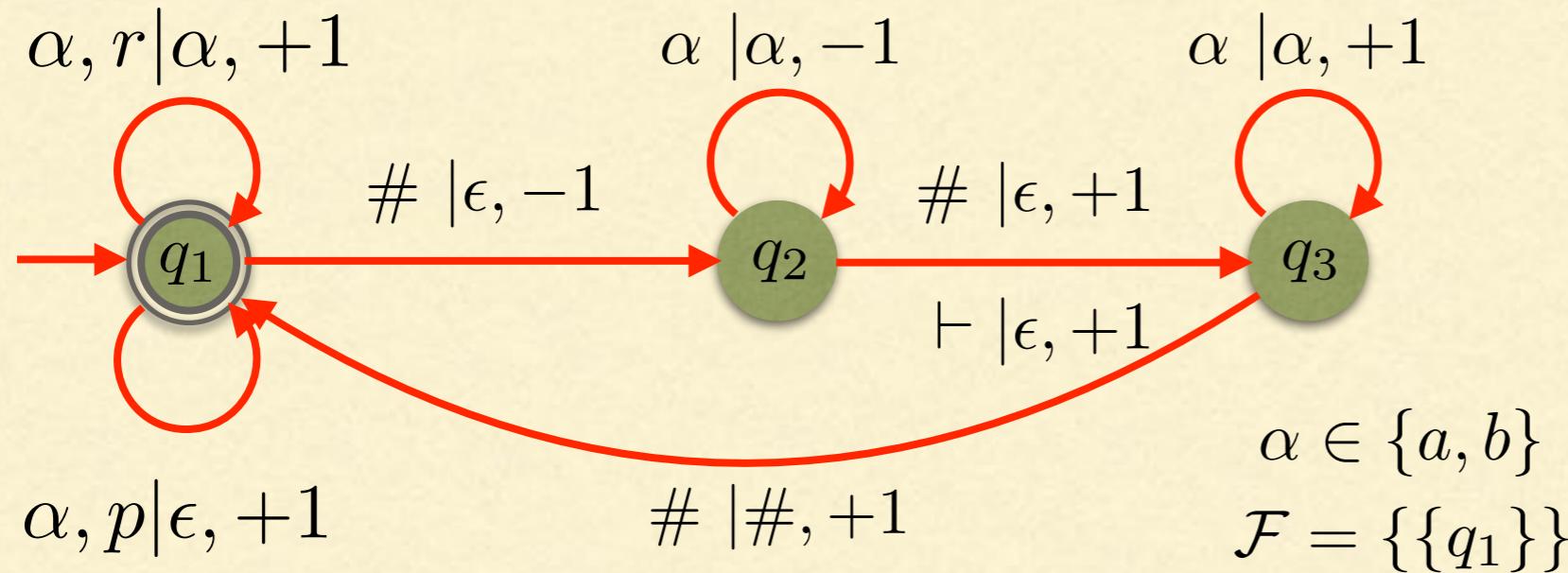


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Transition monoid for Two Way Transducer for ω strings

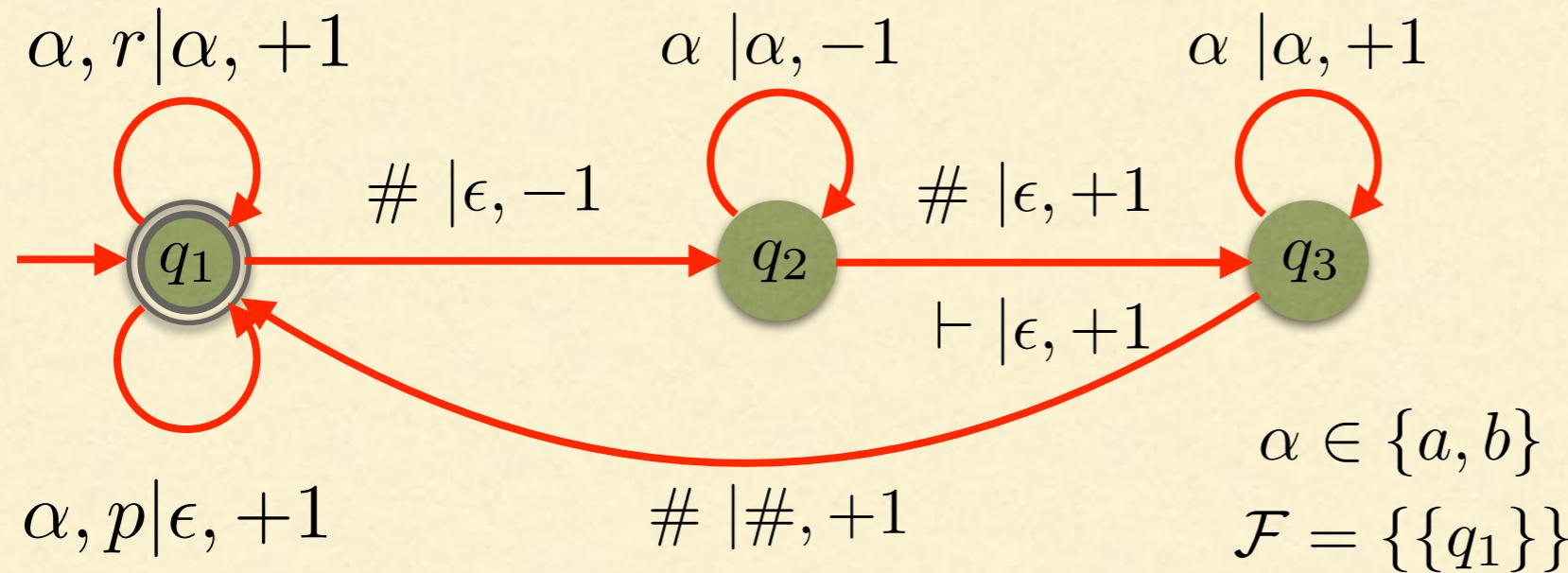


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Transition monoid for Two Way Transducer for ω strings

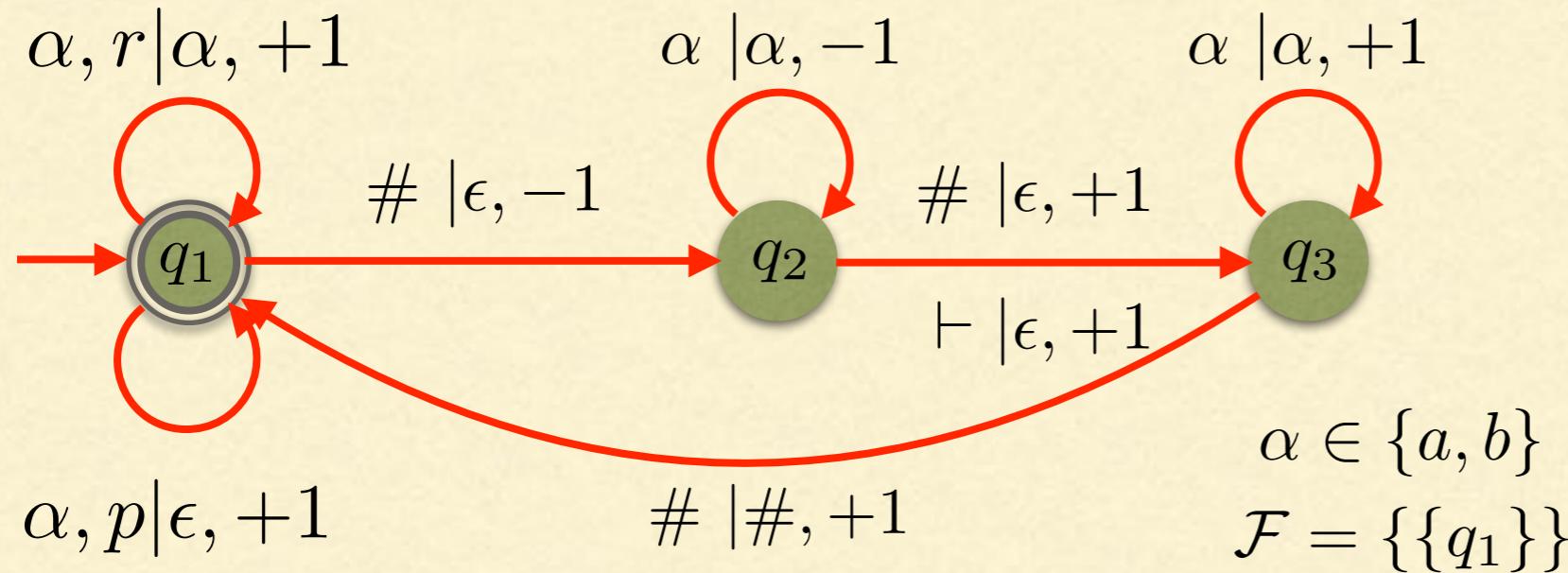


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$$M_{ab\#}^{rr} = \begin{matrix} & q_1 & q_2 & q_3 \\ q_1 & \left(\begin{array}{ccc} (0) & \perp & \perp \end{array} \right) \\ q_2 & \left(\begin{array}{ccc} \perp & \perp & \perp \end{array} \right) \\ q_3 & \left(\begin{array}{ccc} \perp & \perp & \perp \end{array} \right) \end{matrix}$$

Transition monoid for Two Way Transducer for ω strings



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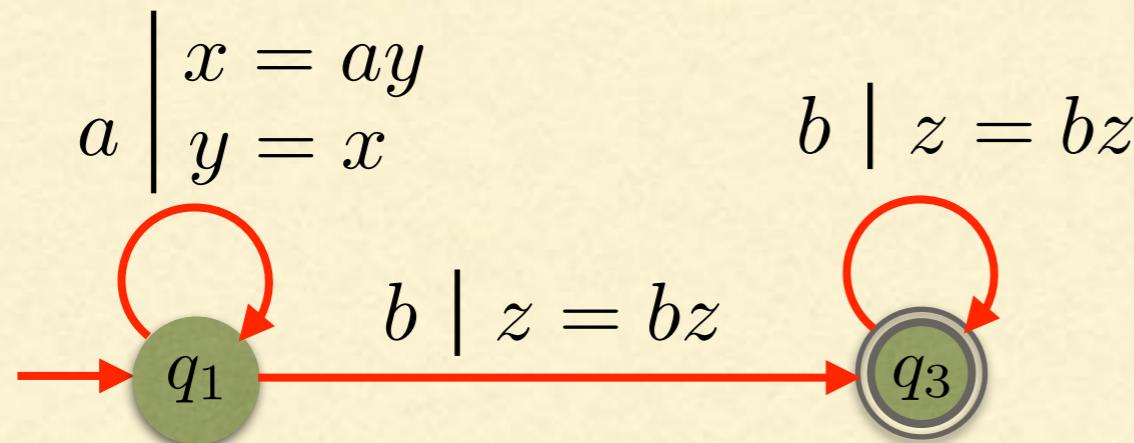
Transition monoid for Streaming String Transducer for ω strings

Transition monoid for Streaming String Transducer for ω strings

$$f(a^n b^\omega) = a^{\lceil n/2 \rceil} b^\omega$$

Transition monoid for Streaming String Transducer for ω strings

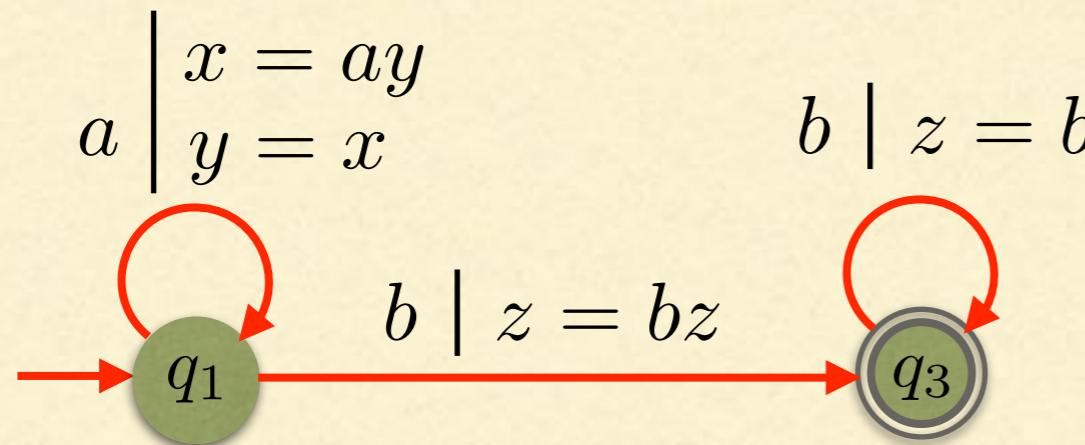
$$f(a^n b^\omega) = a^{\lceil n/2 \rceil} b^\omega$$



$$F(\{q_3\}) = xz$$

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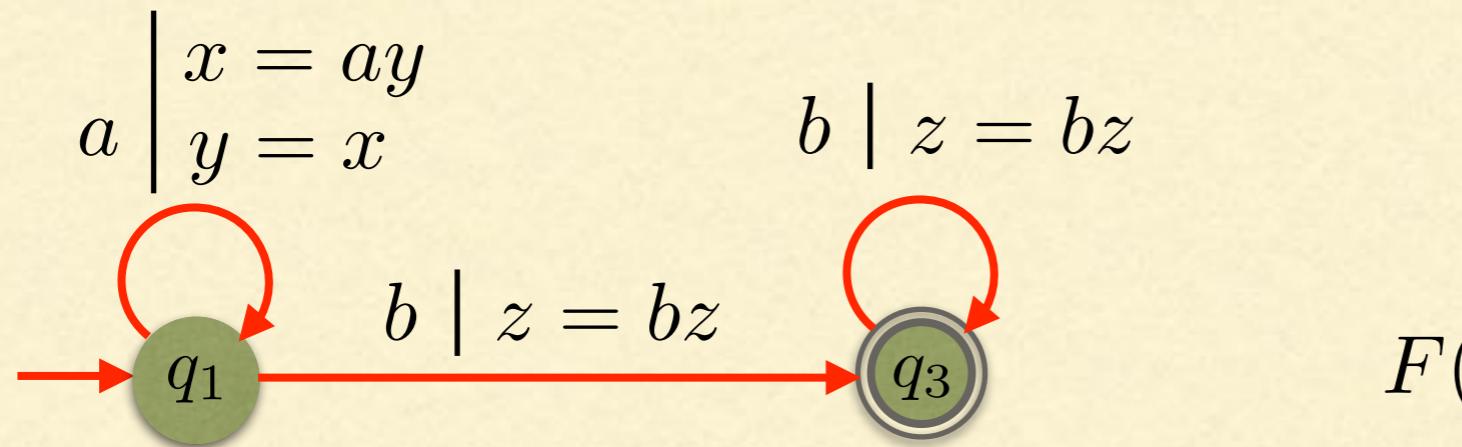


$$F(\{q_3\}) = xz$$

domain language : $a^* b^\omega$ aperiodic ✓

Transition monoid for Streaming String Transducer for ω strings

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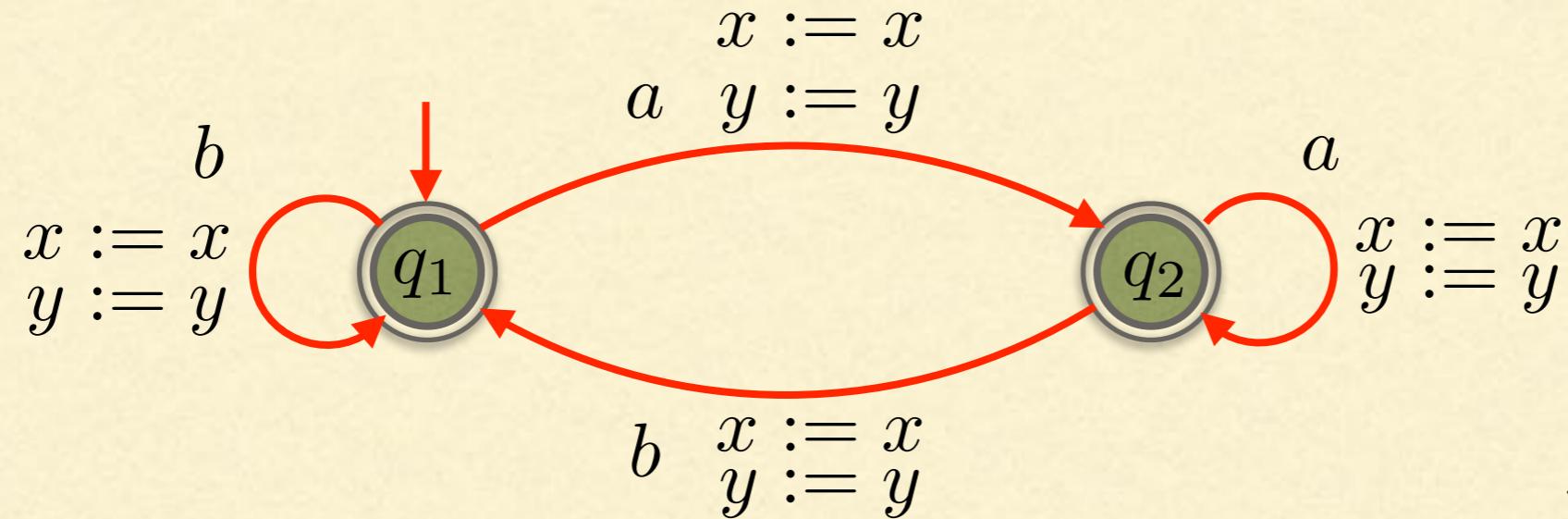


domain language : $a^* b^\omega$ aperiodic ✓

transformation : FO- definable ✗

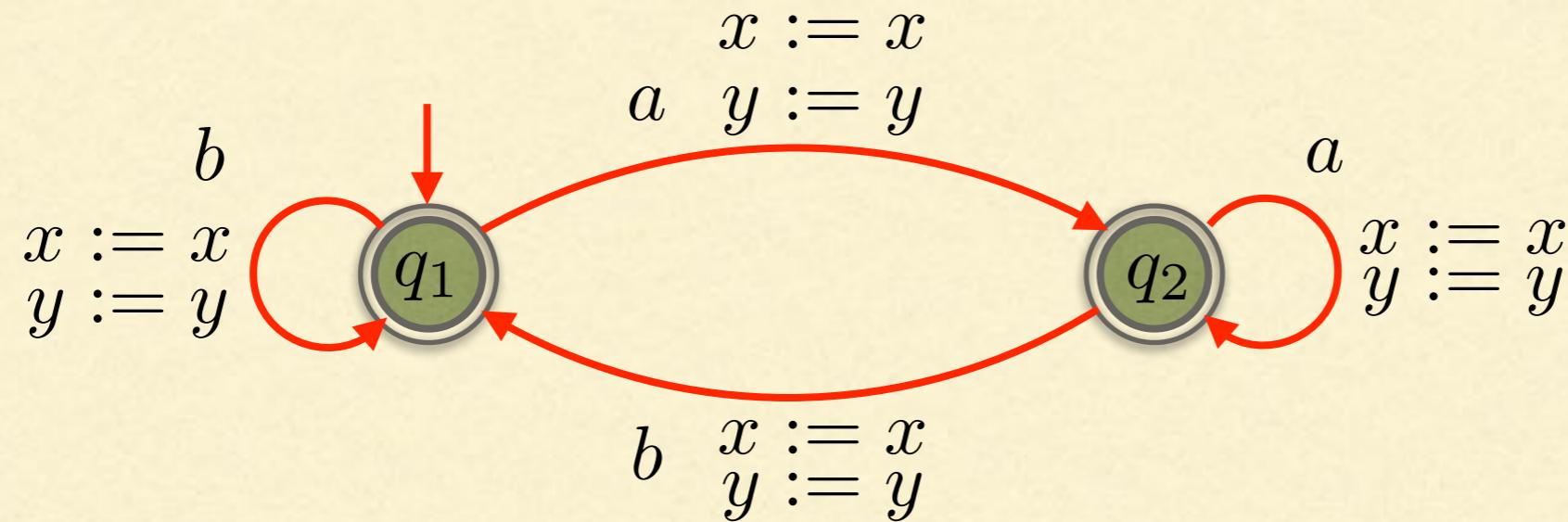
Transition monoid for Streaming String Transducer for ω strings

Transition monoid for Streaming String Transducer for ω strings



$$\mathcal{F} = \{\{q_1, q_2\}\}$$

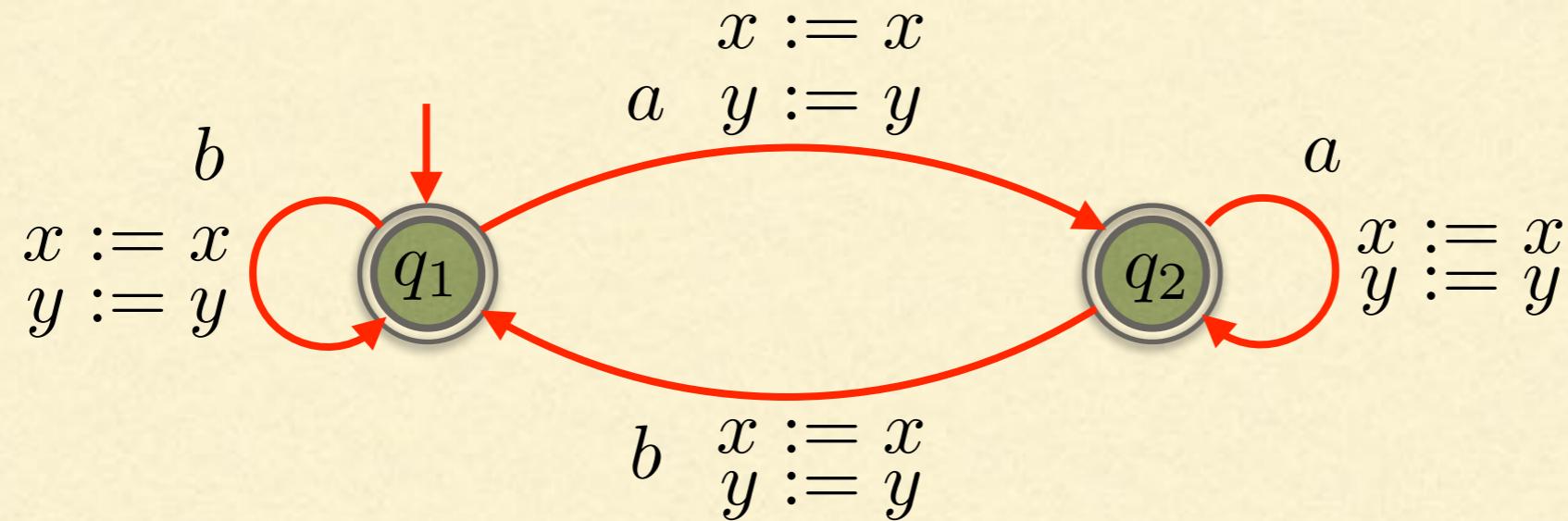
Transition monoid for Streaming String Transducer for ω strings



$$\mathcal{F} = \{\{q_1, q_2\}\}$$

$$M_b = \begin{pmatrix} & (q_1, x) & (q_1, y) & (q_2, x) & (q_2, y) \\ (q_1, x) & & & & \\ (q_1, y) & & & & \\ (q_2, x) & & & & \\ (q_2, y) & & & & \end{pmatrix}$$

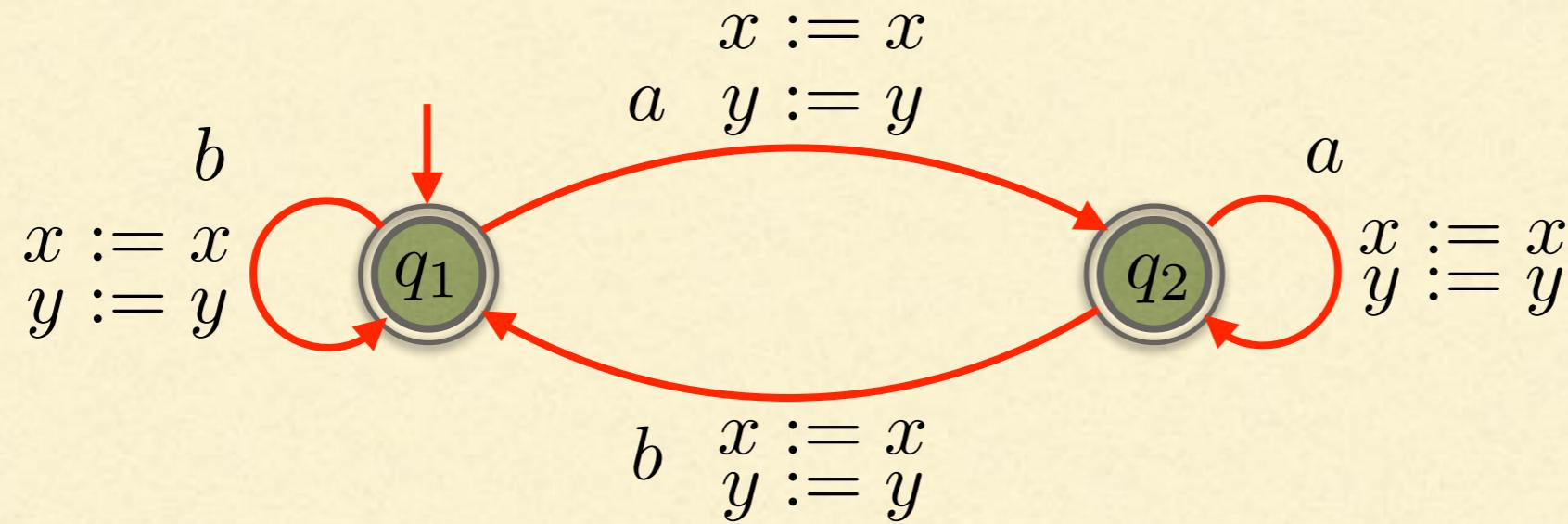
Transition monoid for Streaming String Transducer for ω strings



$$\mathcal{F} = \{\{q_1, q_2\}\}$$

$$M_b = \begin{pmatrix} & (q_1, x) & (q_1, y) & (q_2, x) & (q_2, y) \\ (q_1, x) & & & \perp & \perp \\ (q_1, y) & & & \perp & \perp \\ (q_2, x) & & & \perp & \perp \\ (q_2, y) & & & \perp & \perp \end{pmatrix}$$

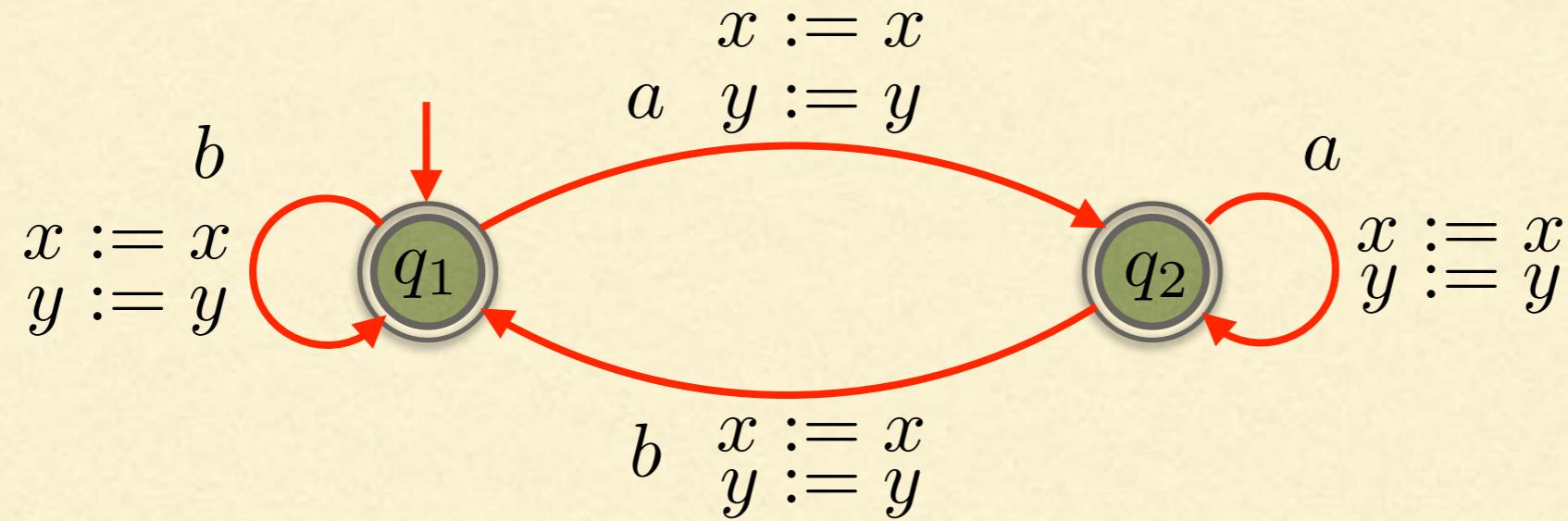
Transition monoid for Streaming String Transducer for ω strings



$$\mathcal{F} = \{\{q_1, q_2\}\}$$

$$M_b = \begin{pmatrix} & (q_1, x) & (q_1, y) & (q_2, x) & (q_2, y) \\ (q_1, x) & 1(\{q_1\}) & 0(\{q_1\}) & \perp & \perp \\ (q_1, y) & 0(\{q_1\}) & 1(\{q_1\}) & \perp & \perp \\ (q_2, x) & & & & \\ (q_2, y) & & & & \end{pmatrix}$$

Transition monoid for Streaming String Transducer for ω strings



$$M_b = \begin{pmatrix} & (q_1, x) & (q_1, y) & (q_2, x) & (q_2, y) \\ (q_1, x) & 1(\{q_1\}) & 0(\{q_1\}) & \perp & \perp \\ (q_1, y) & 0(\{q_1\}) & 1(\{q_1\}) & \perp & \perp \\ (q_2, x) & 1(1) & 0(1) & \perp & \perp \\ (q_2, y) & 0(1) & 1(1) & \perp & \perp \end{pmatrix}$$

Outline

- Introduction
 - Three formalisms for transductions
 - Related work
- Aperiodic transformations for Infinite strings
 - Aperiodic two way transducer
 - Aperiodic streaming string transducer
- Equivalence results and Proof ideas
 - $\text{SST}_{\text{sf}} \subset \text{FOT} = 2\text{WST}_{\text{sf}} \subset \text{SST}_{\text{sf}}$
- Conclusion

Equivalence results

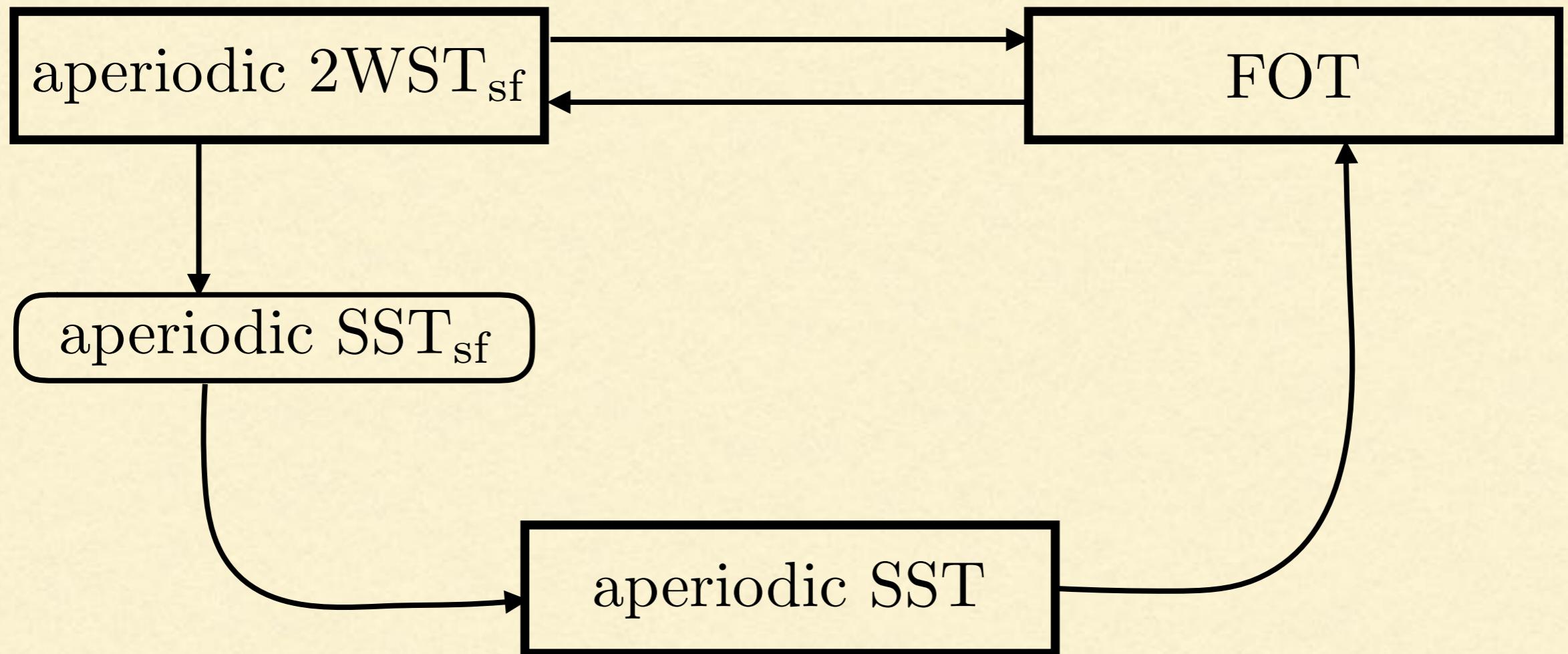
Equivalence results

aperiodic 2WST_{sf}

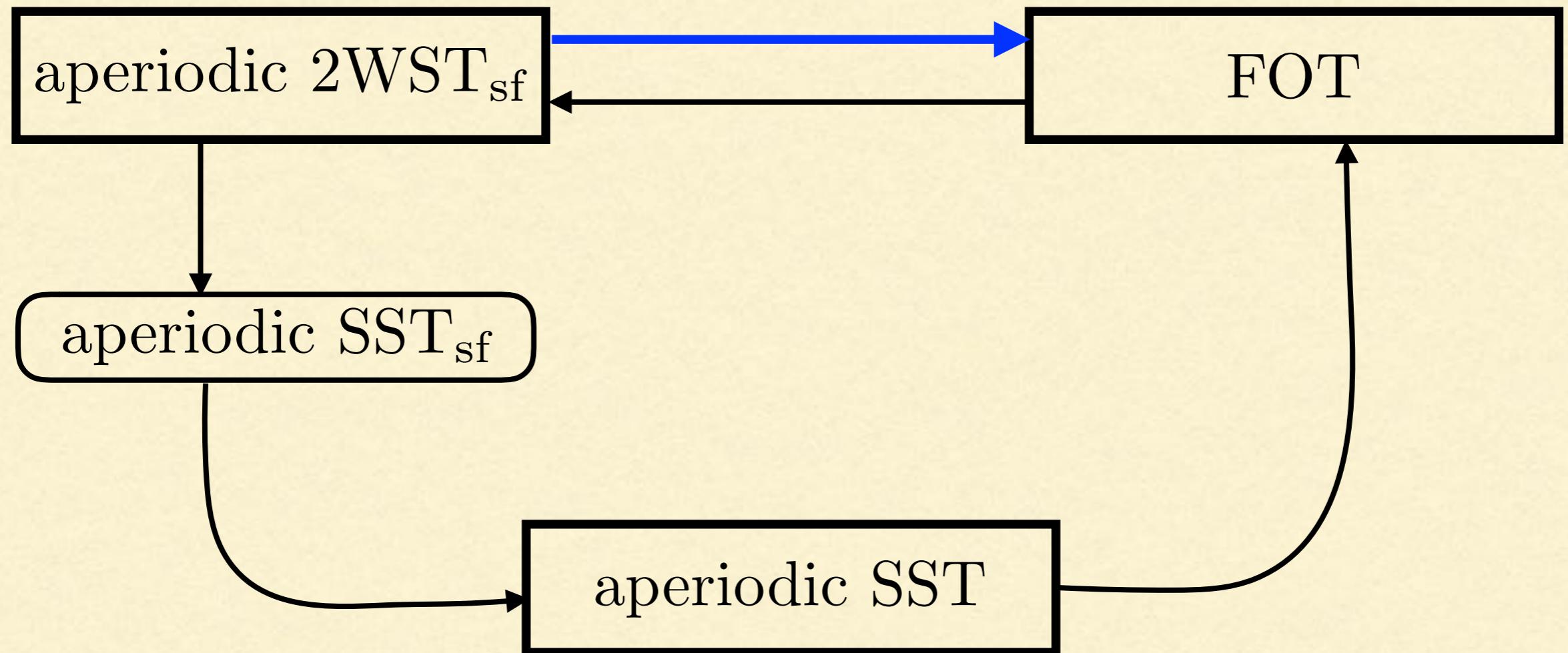
FOT

aperiodic SST

Equivalence results



Results



aperiodic 2WST_{sf} ⊆ FOT

aperiodic 2WST_{sf} ⊆ FOT

input

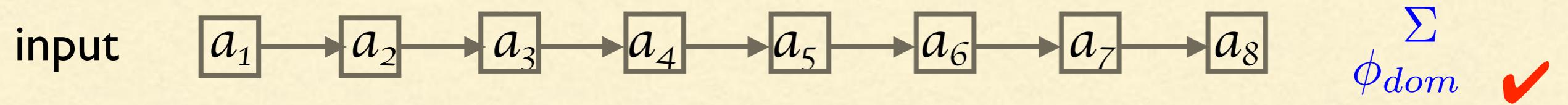
aperiodic 2WST_{sf} ⊆ FOT

input a_1 a_2 a_3 a_4 a_5 a_6 a_7 a_8

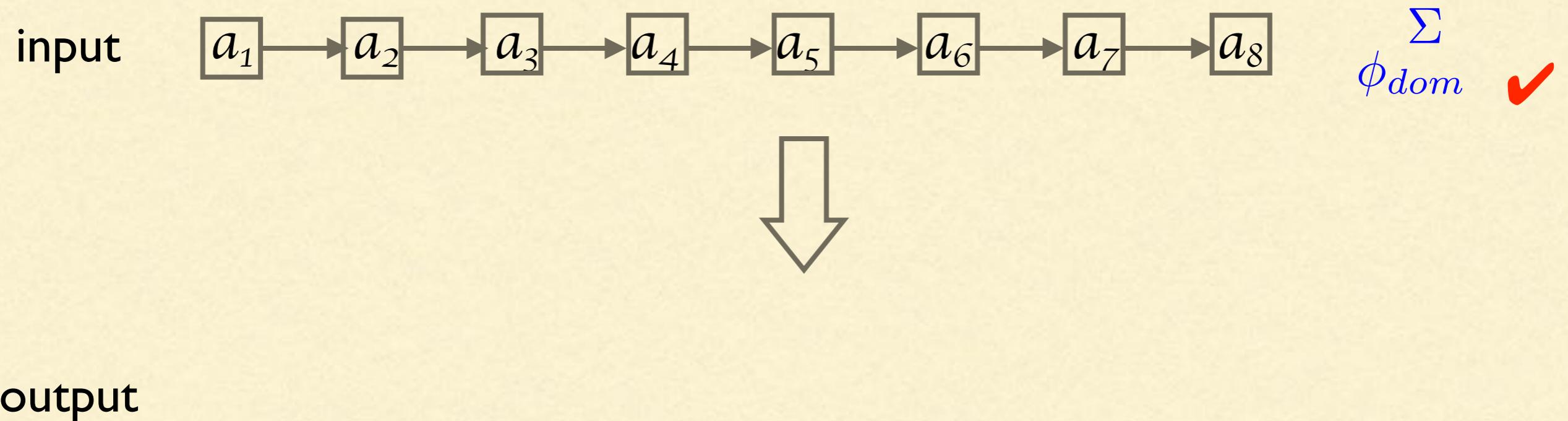
aperiodic 2WST_{sf} ⊆ FOT

input a_1 a_2 a_3 a_4 a_5 a_6 a_7 a_8 ϕ_{dom}^{Σ} 

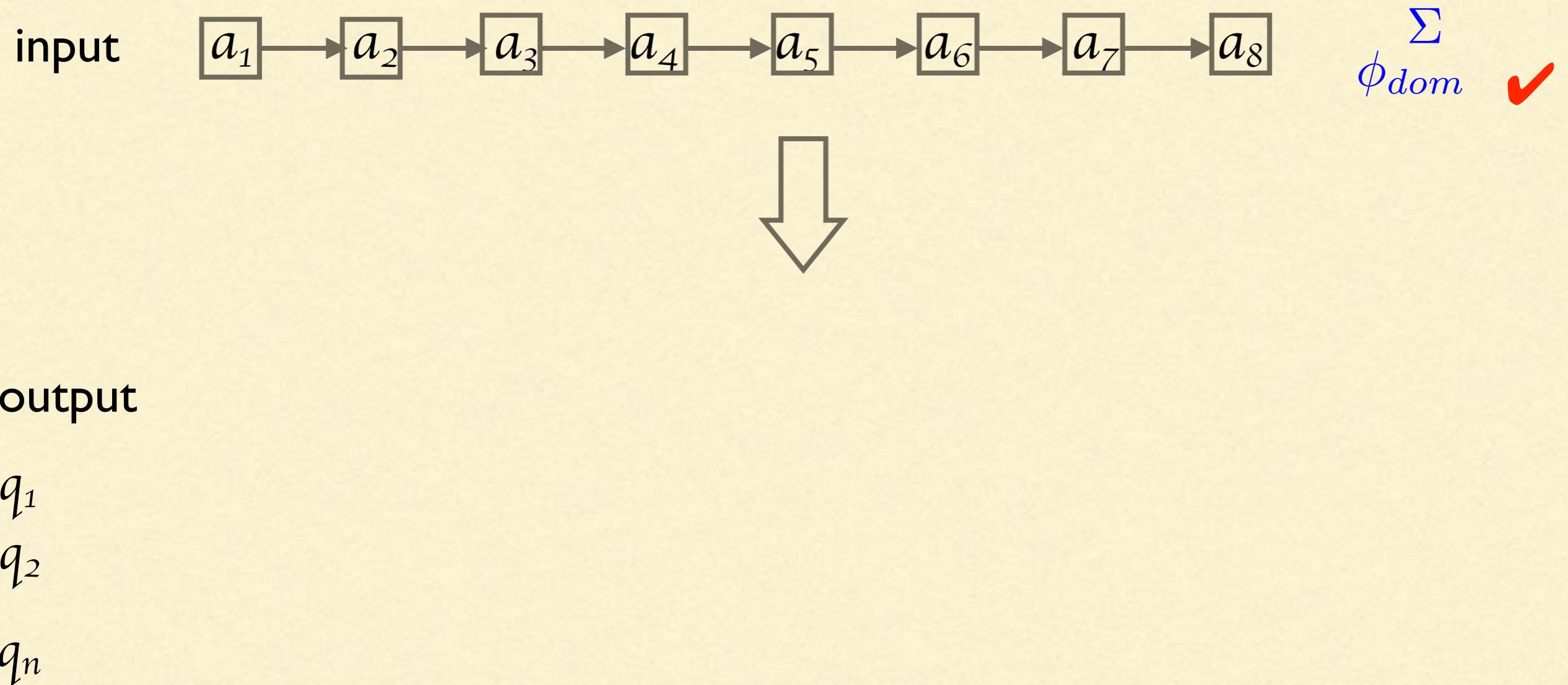
aperiodic 2WST_{sf} ⊆ FOT



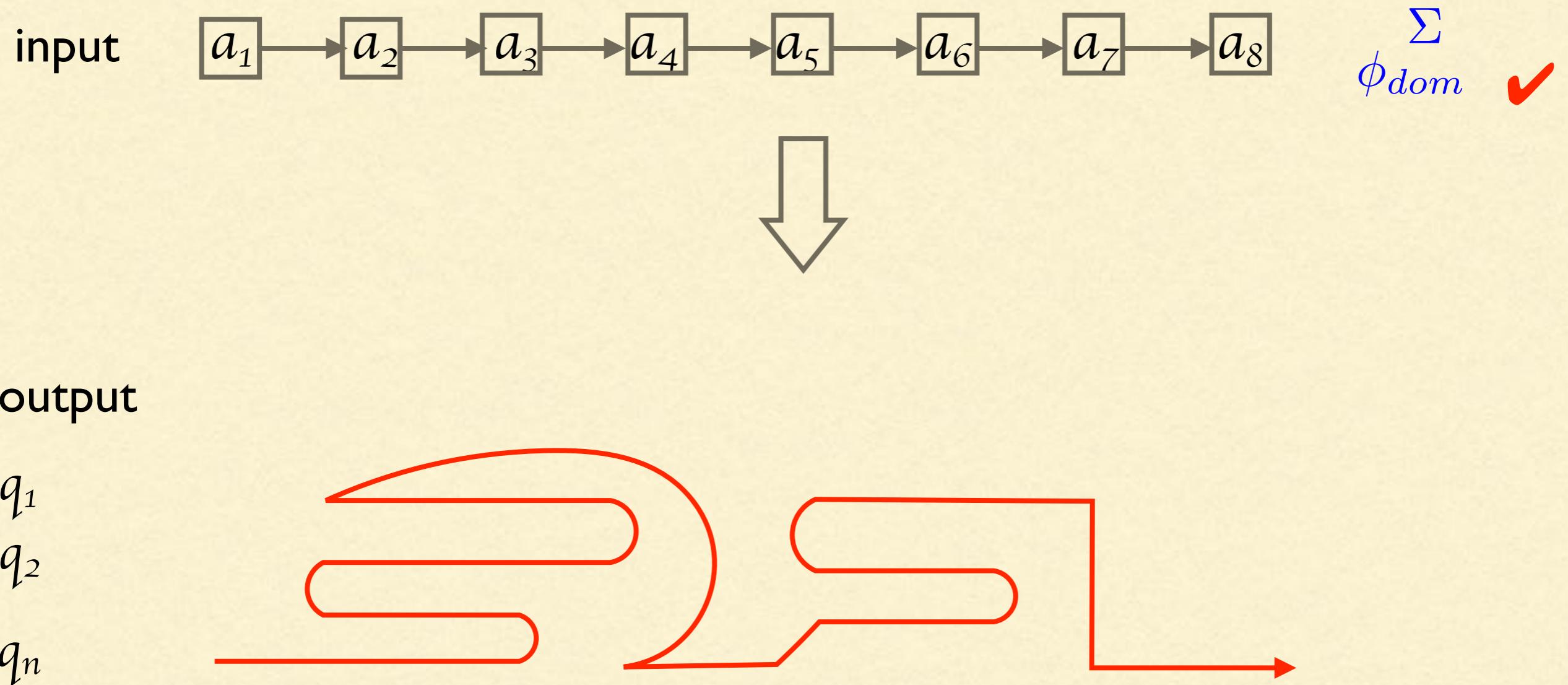
aperiodic 2WST_{sf} ⊆ FOT



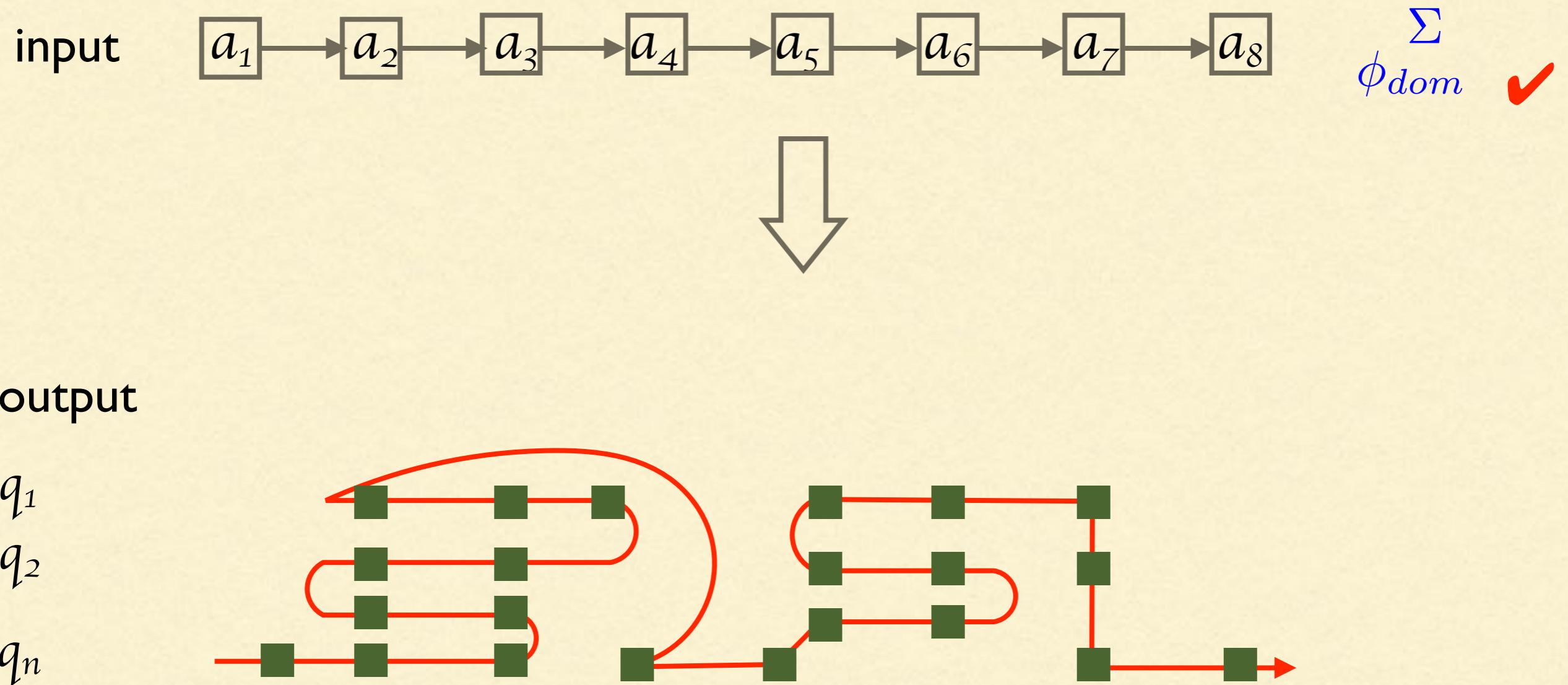
aperiodic 2WST_{sf} ⊆ FOT



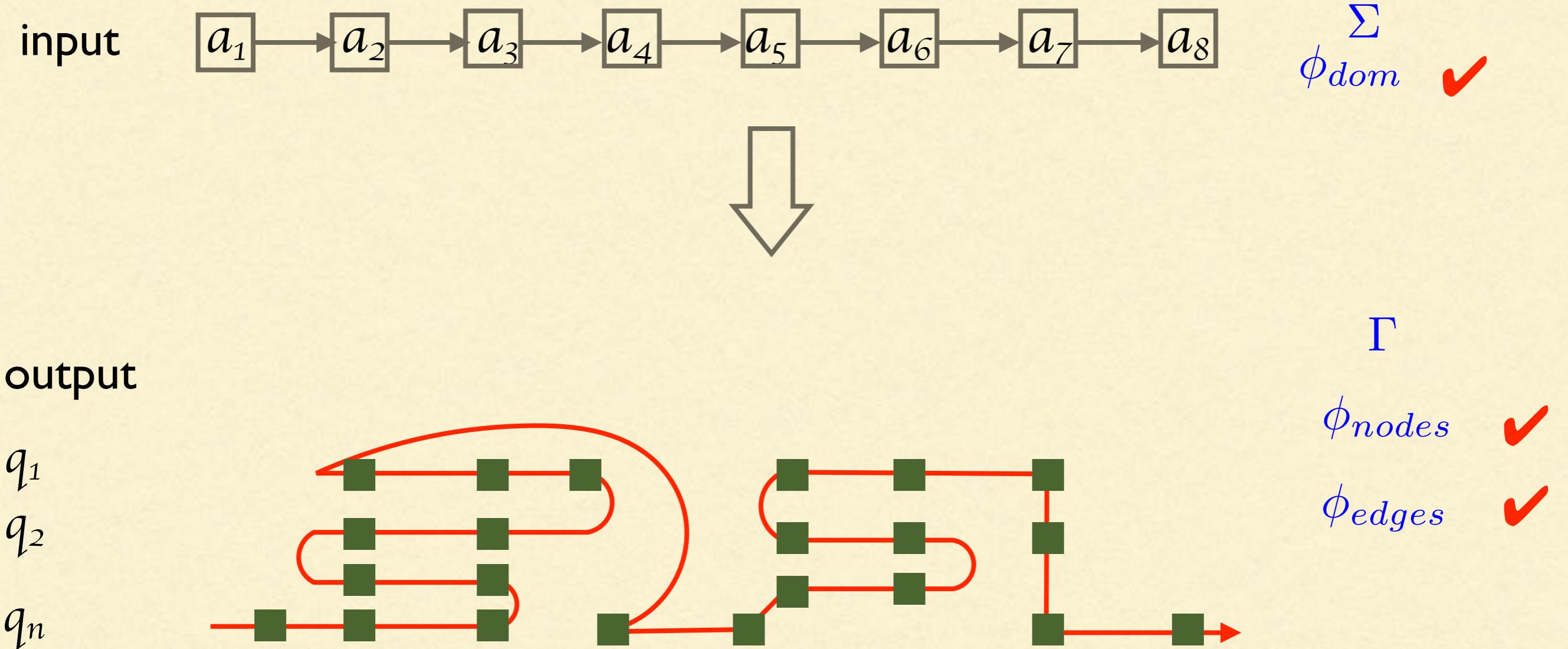
aperiodic 2WST_{sf} ⊆ FOT



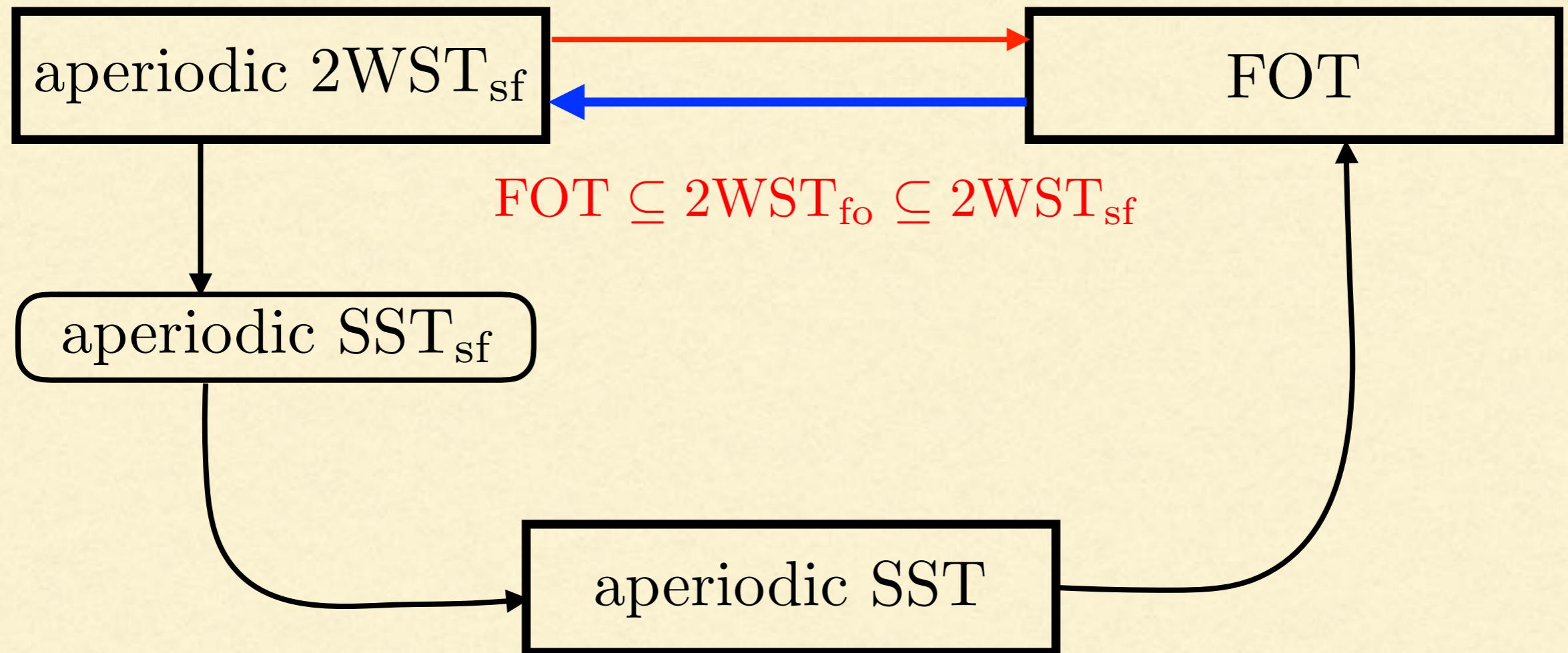
aperiodic 2WST_{sf} ⊆ FOT



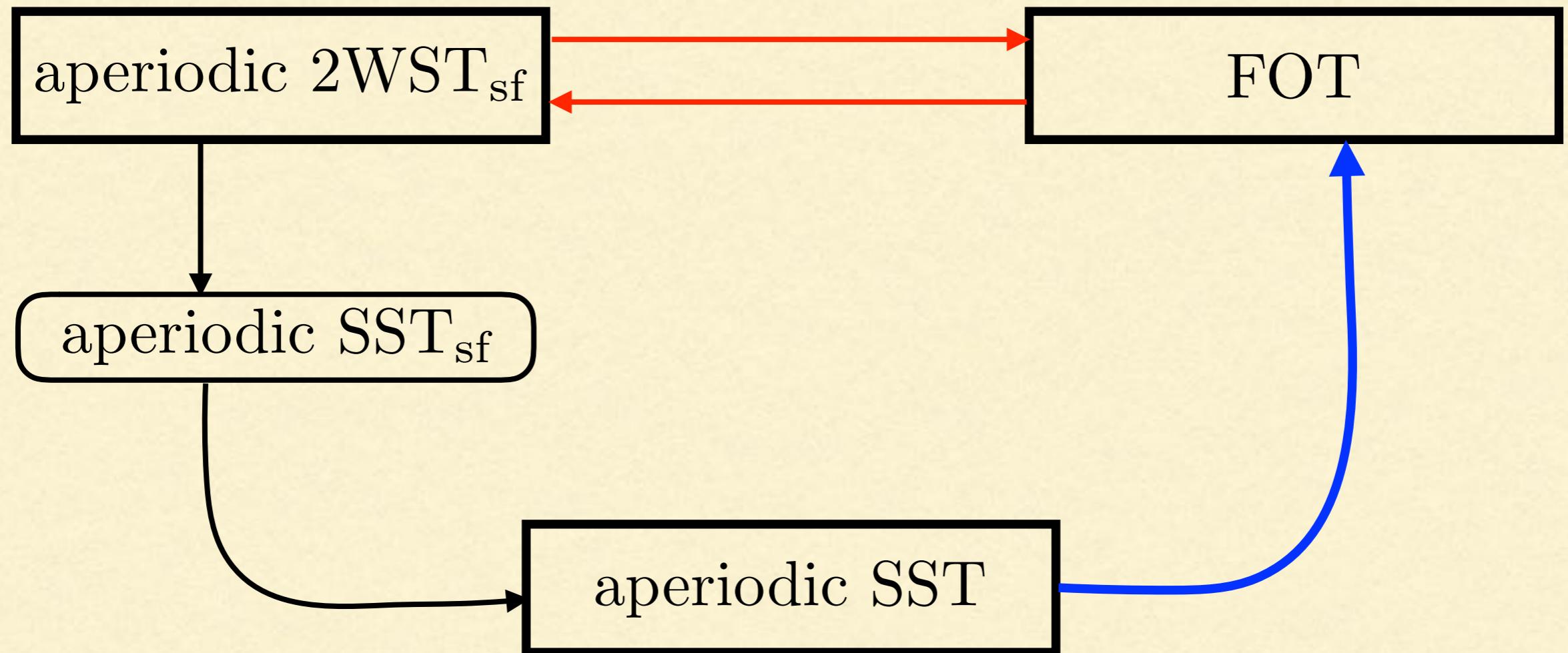
aperiodic 2WST_{sf} ⊆ FOT



Results



Results



Aperiodic SST \subset FOT

[FKT'14]

Aperiodic SST \subset FOT

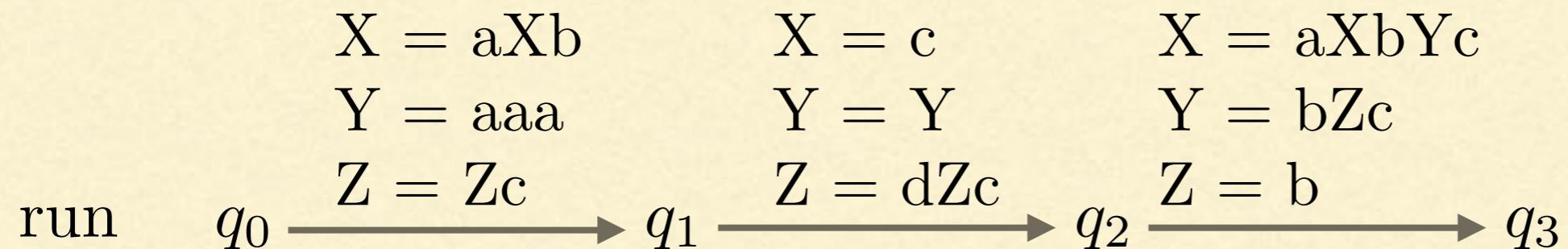
SST output structure :

[FKT'14]

Aperiodic SST \subset FOT

SST output structure :

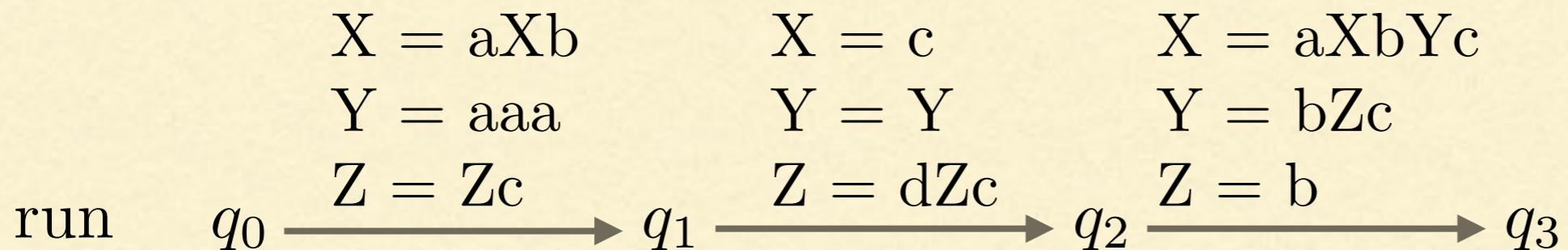
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

[FKT'14]



X^{in}

X^{out}

Y^{in}

Y^{out}

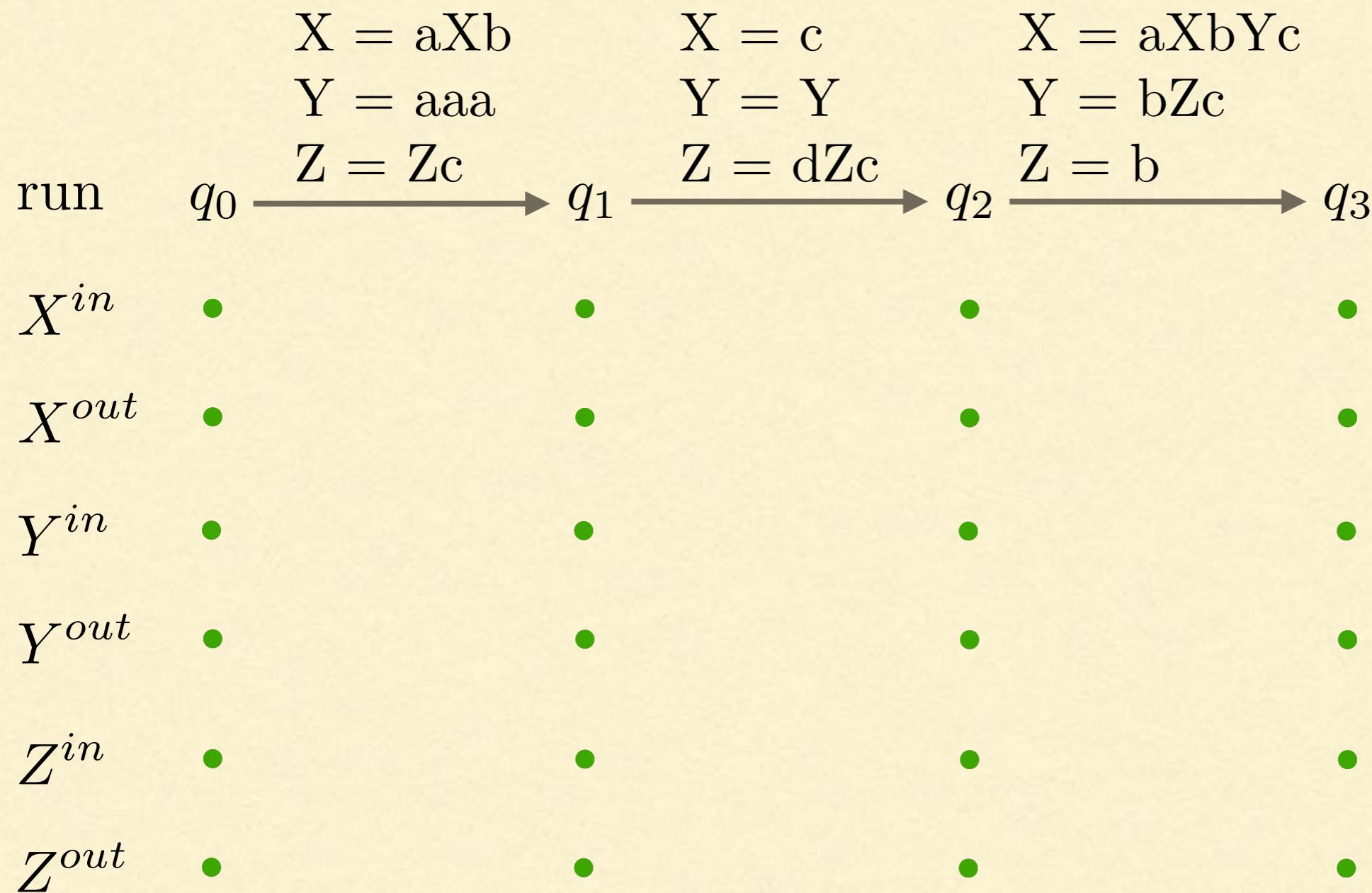
Z^{in}

Z^{out}

Aperiodic SST \subset FOT

SST output structure :

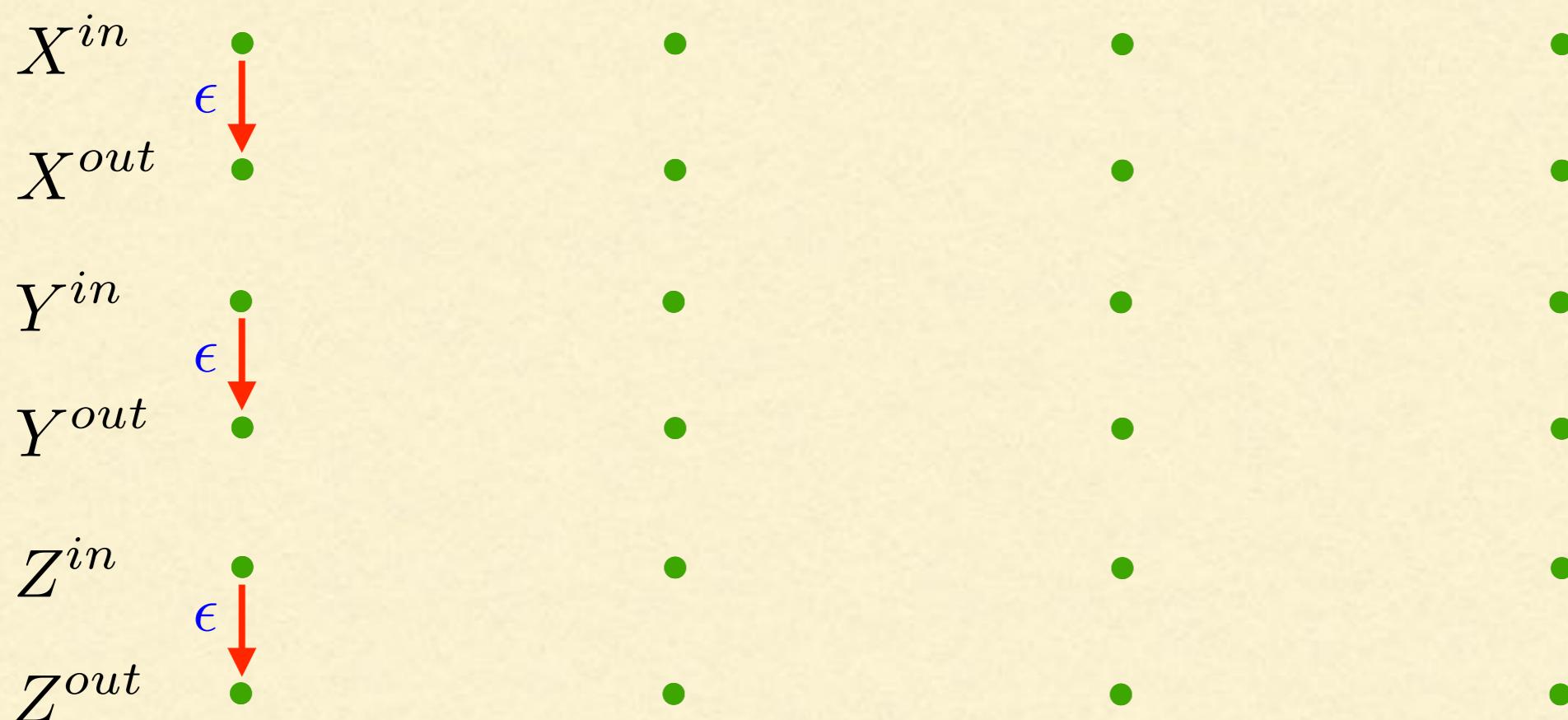
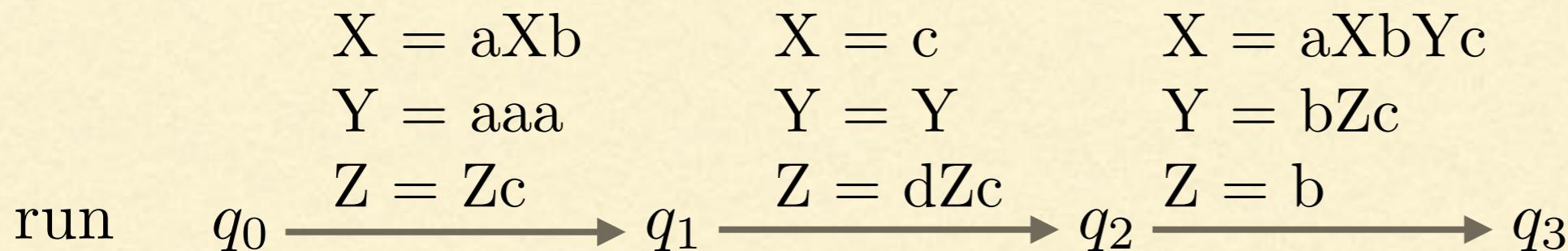
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

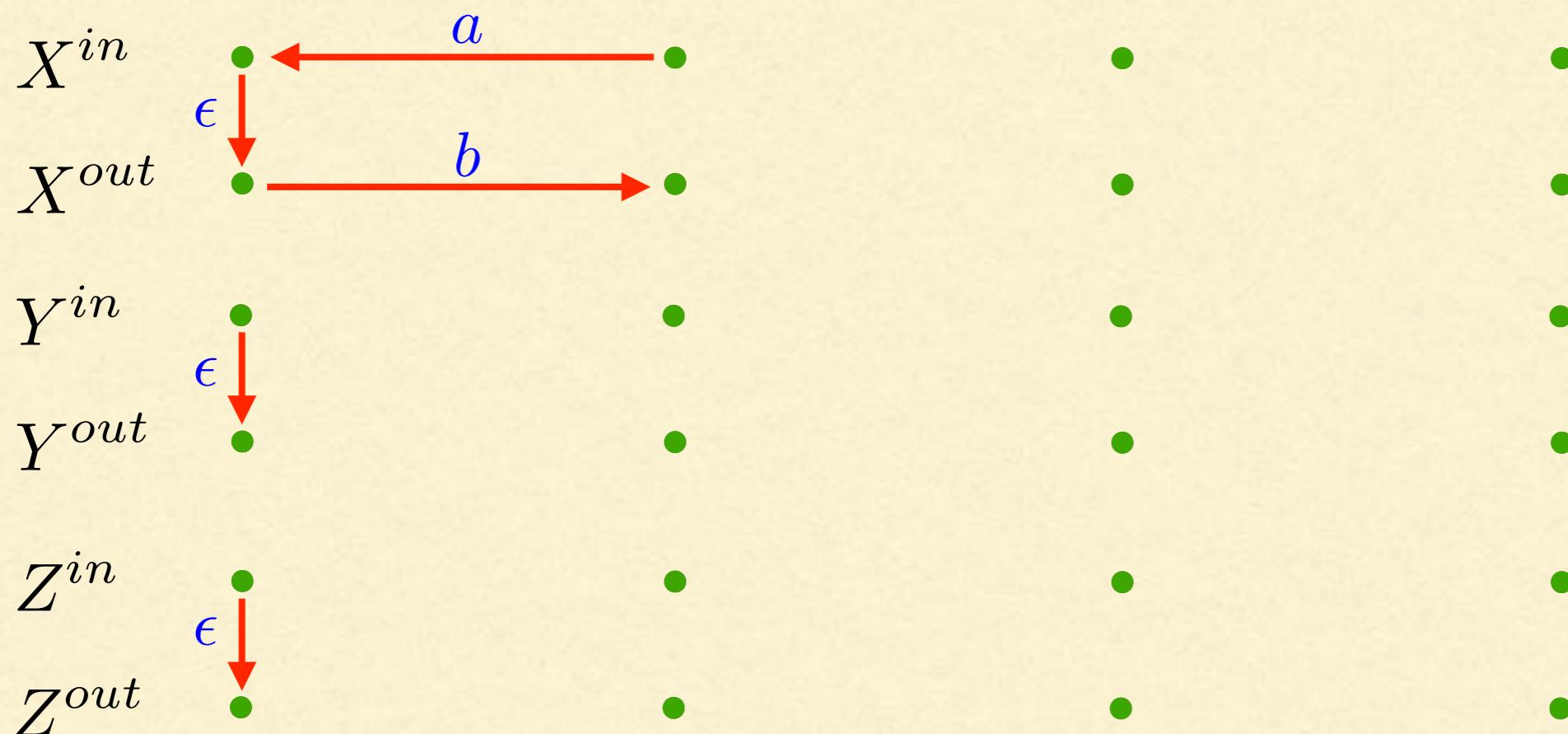
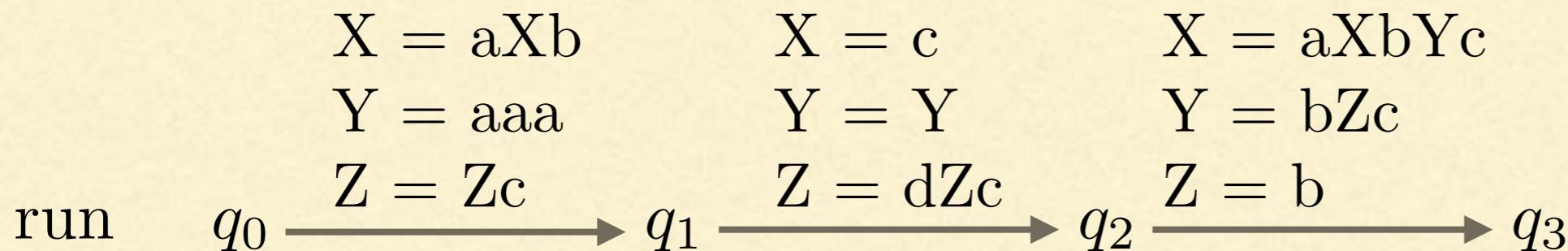
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Aperiodic SST \subset FOT

SST output structure :

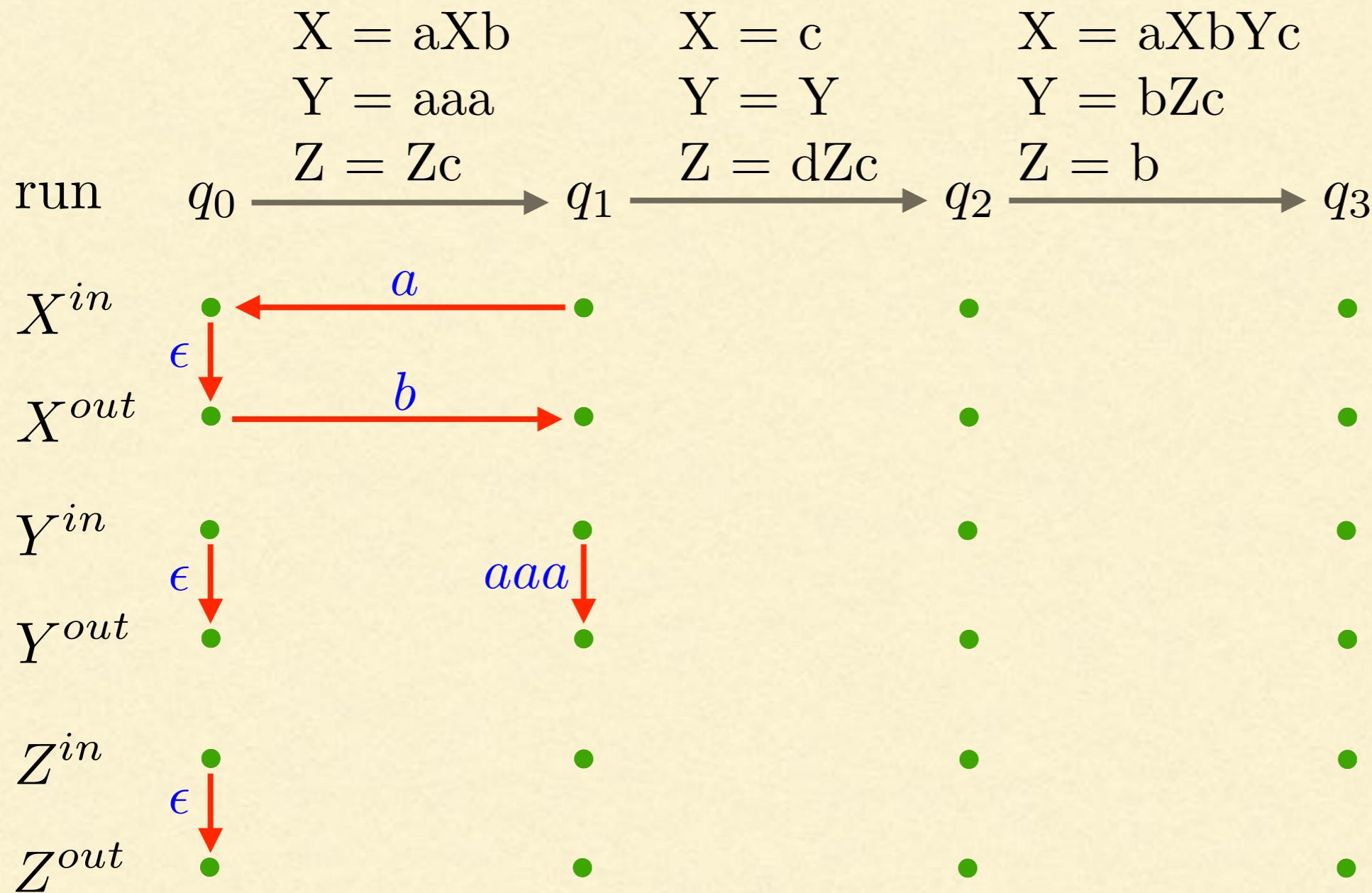
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

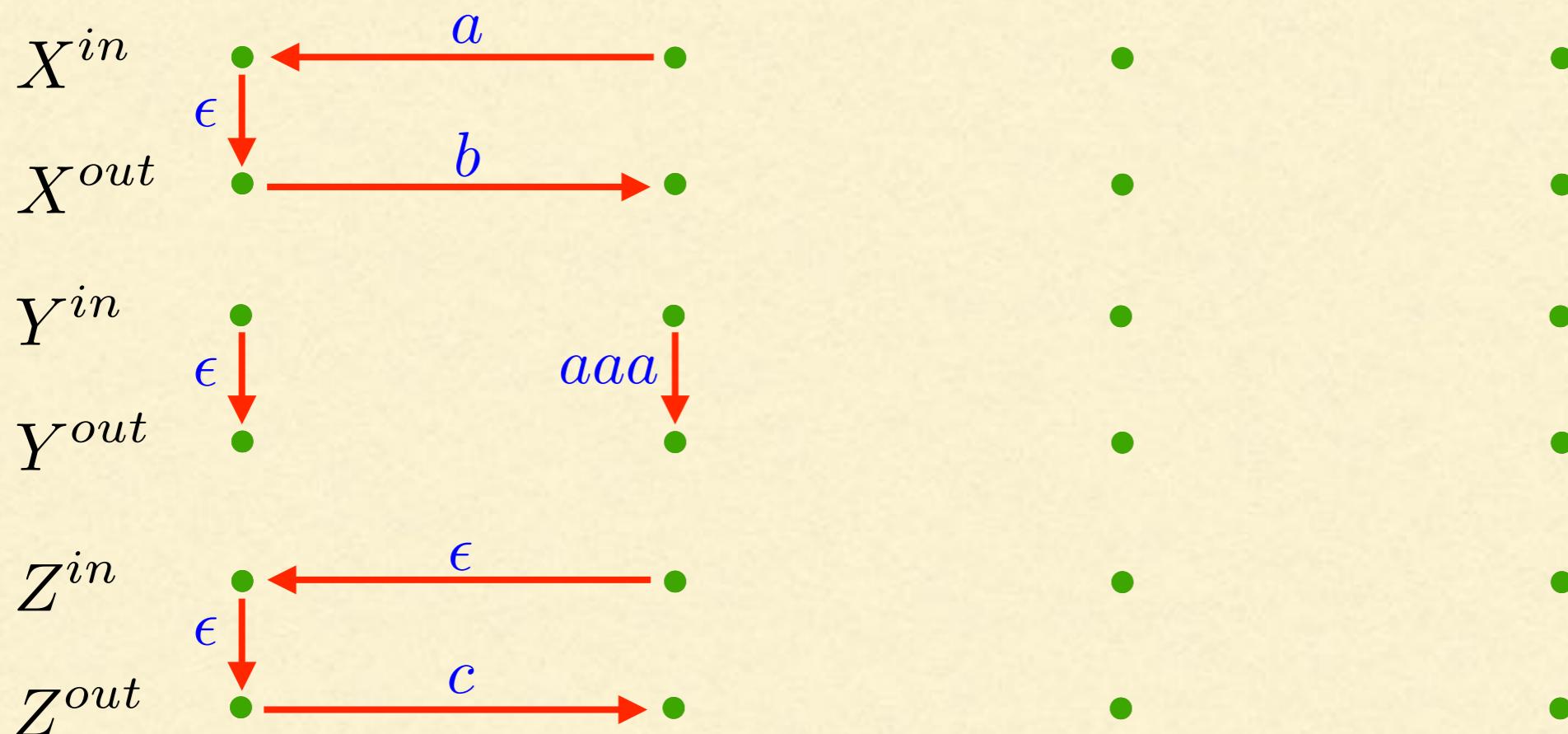
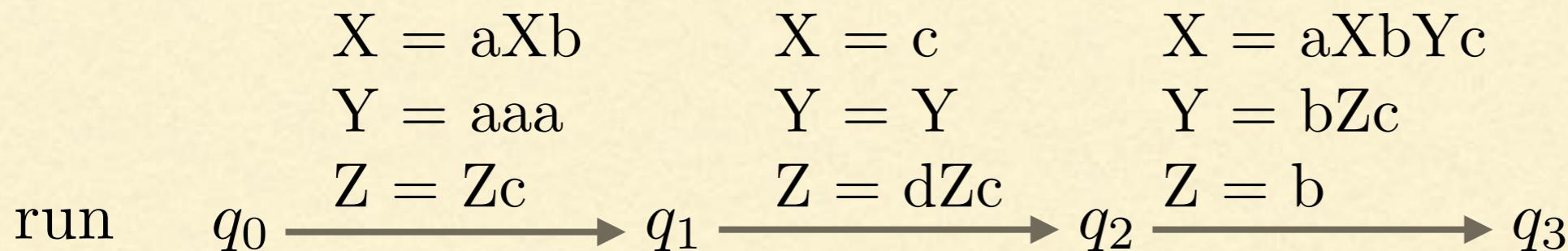
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

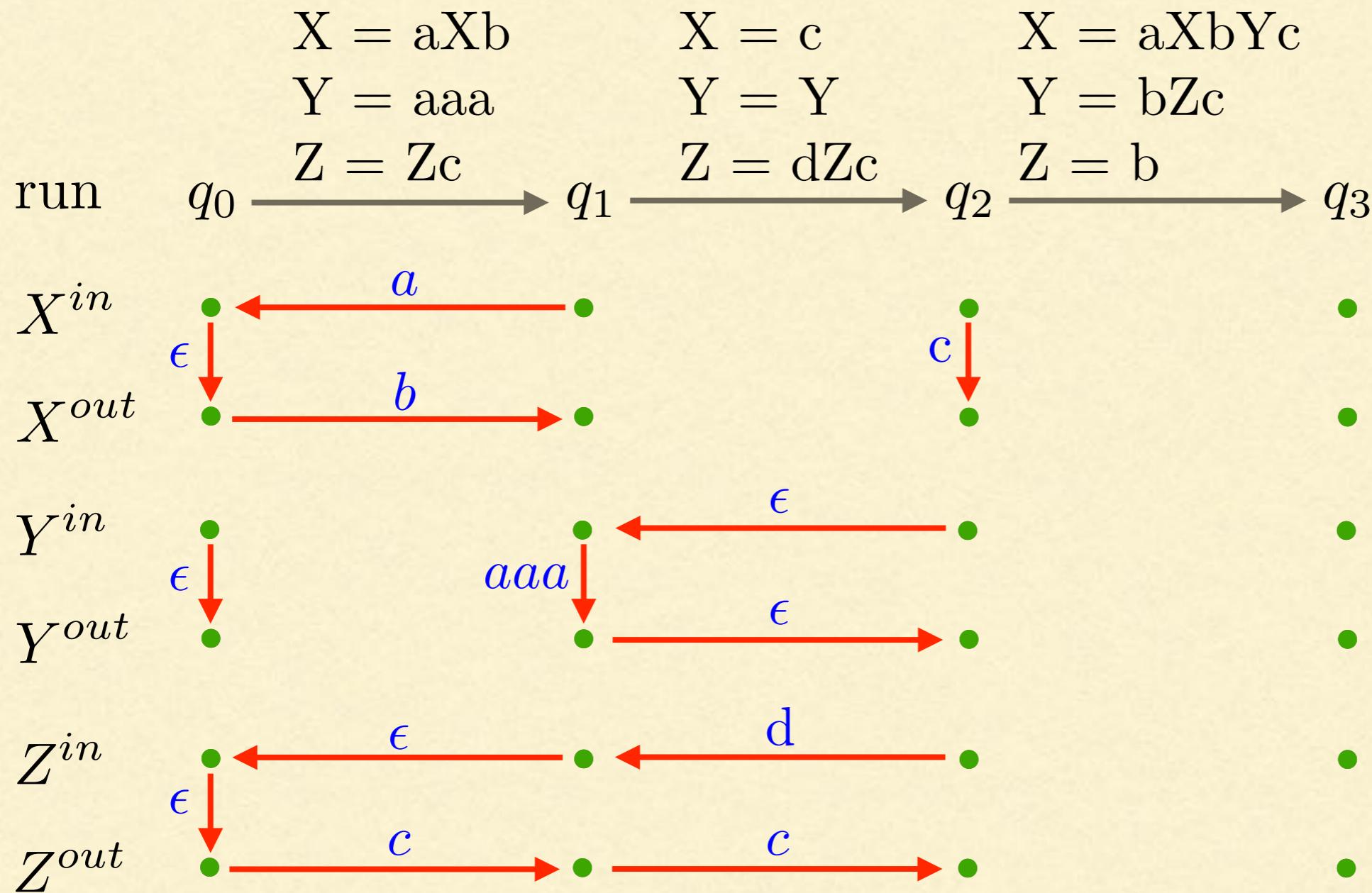
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

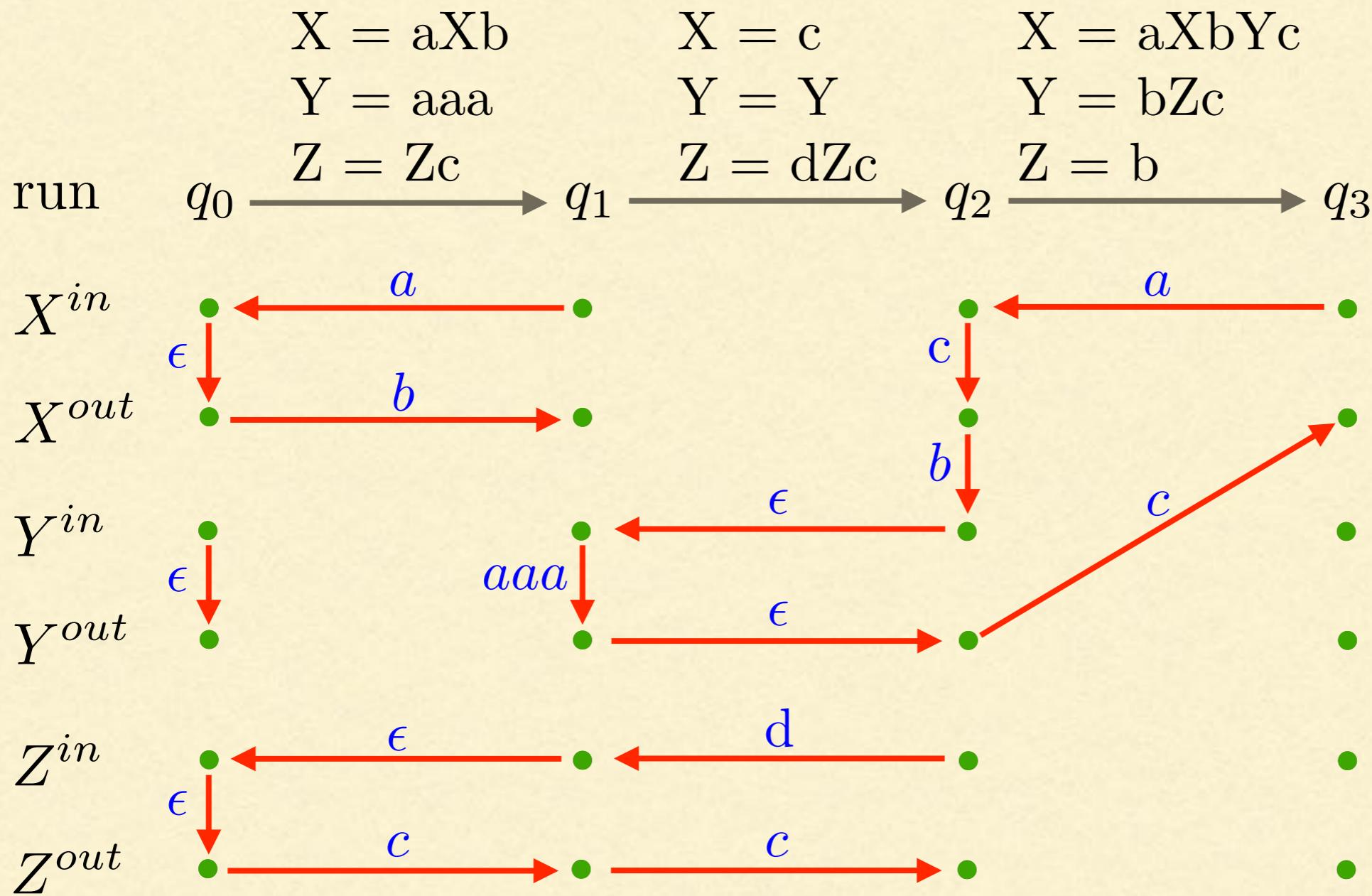
[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

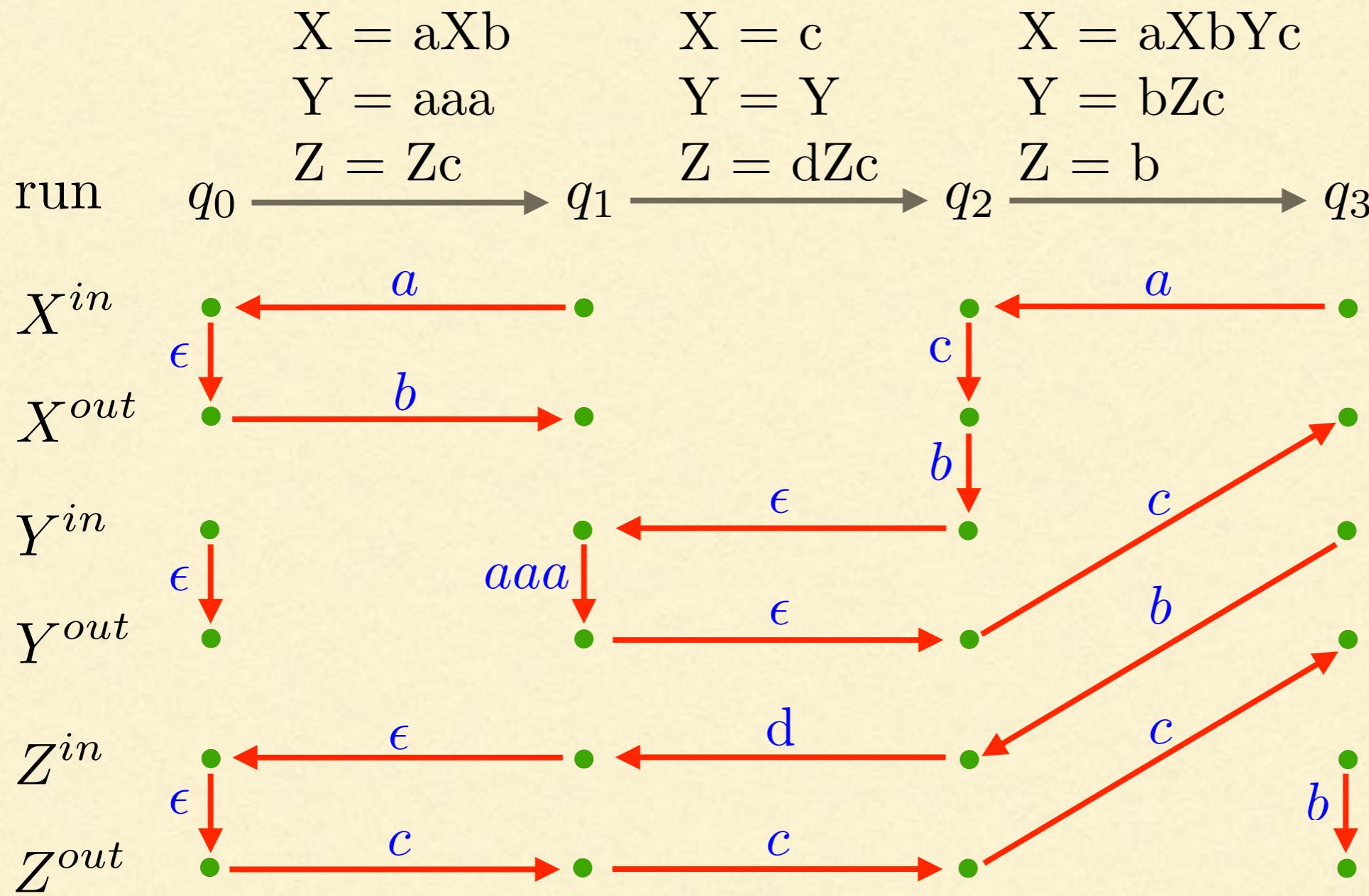
[FKT'14]



Aperiodic SST \subset FOT

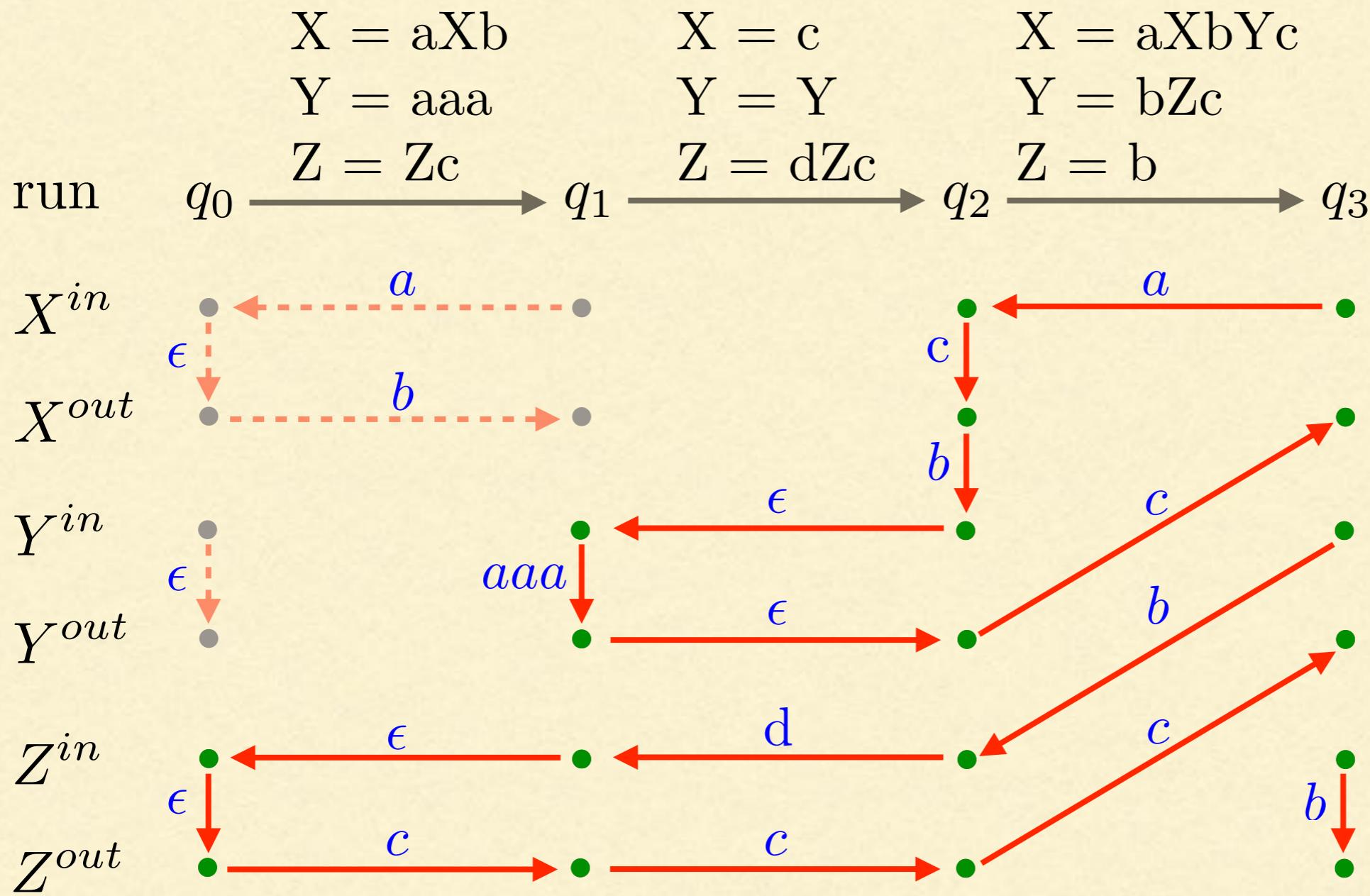
SST output structure :

[FKT'14]



Aperiodic SST \subset FOT

SST output structure :

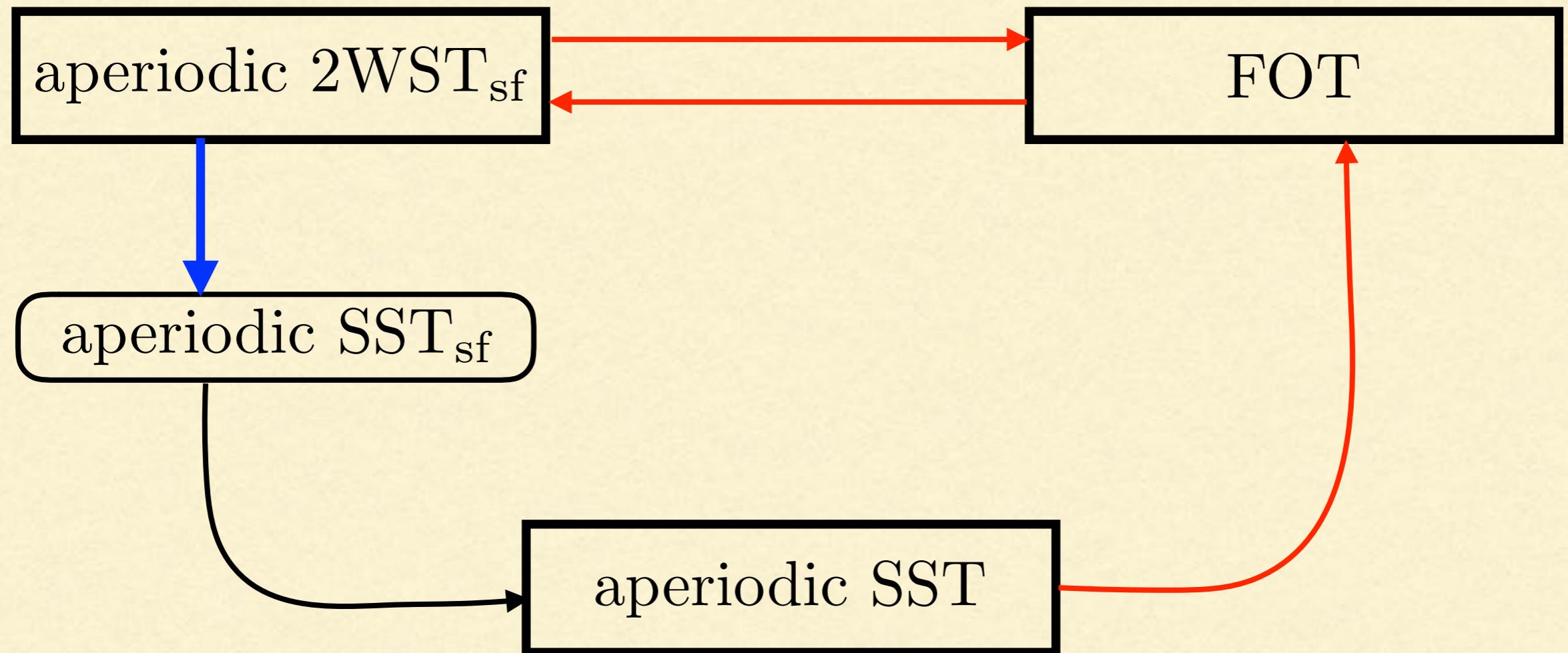


Aperiodic SST \subset FOT

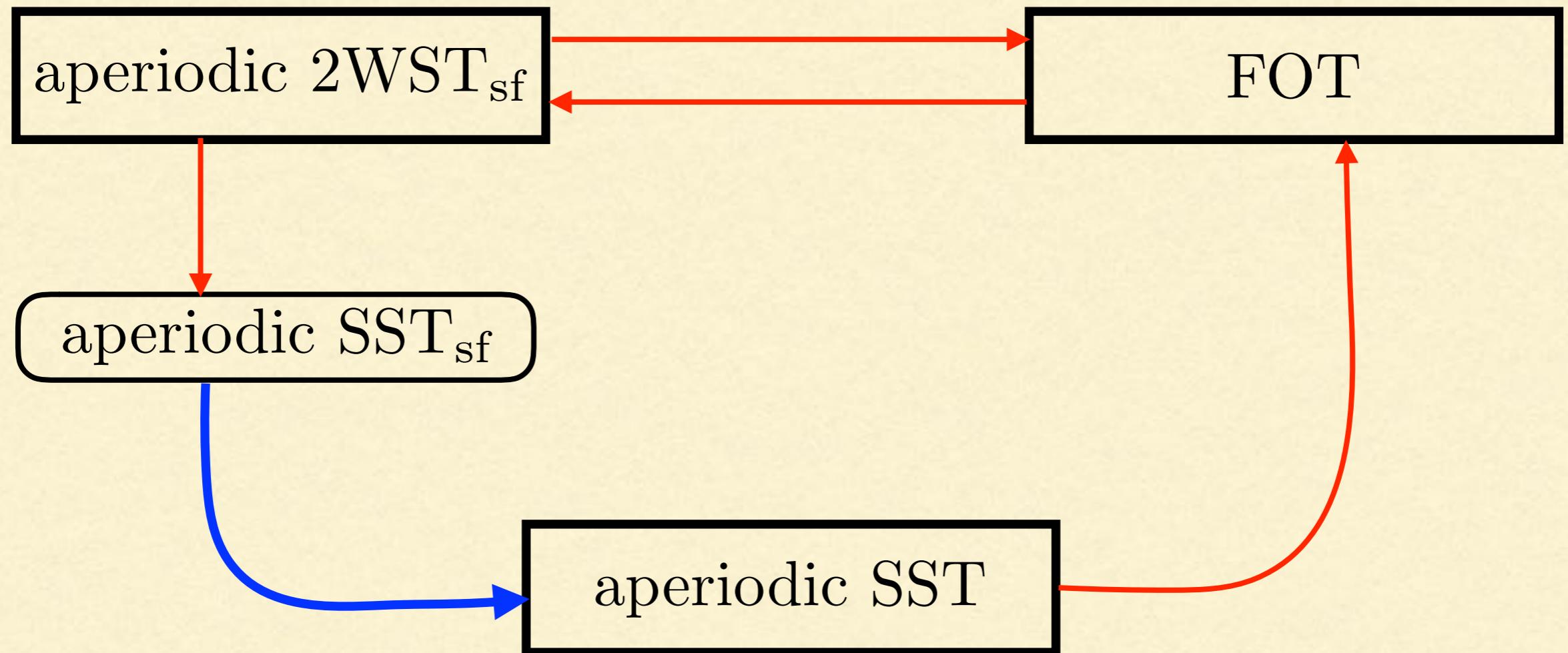
Claim 1: $\forall X, Y \in \mathcal{X}, \forall d, e \in \{in, out\}, \forall s \in \text{dom}(T), \forall i, j \in \text{dom}(s),$
 $(X^d, i) \rightsquigarrow (Y^e, j)$ is FO-definable.

Claim 2: $\phi_q(x)$ is FO definable

Results



Results



Conclusion

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Language :

FO logic

\equiv

Aperiodic Automata

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Language :

FO logic

\equiv

Aperiodic Automata

Transducers :

FO transducer

\equiv

Aperiodic Transducer

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