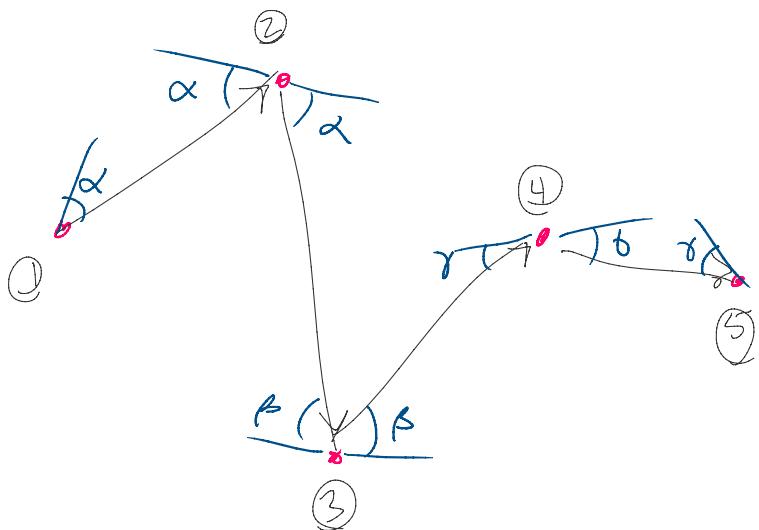


## Curvature Method

Wednesday, January 19, 2022 3:16 PM



$$\vec{C}_0(t) = (1-t)^3 \vec{P}_0 + 3(1-t)^2 t \vec{P}_1 + 3(1-t)t^2 \vec{P}_2 + t^3 \vec{P}_3$$

$$\vec{C}_1(t) = (1-t)^3 \vec{P}_4 + 3(1-t)^2 t \vec{P}_5 + 3(1-t)t^2 \vec{P}_6 + t^3 \vec{P}_7$$

$$C_0' = 3(1-t)^2(-1)\vec{P}_0 + [6(1-t)(-1)t + 3(1-t)^2]\vec{P}_1 + [3(1-t)2t + 3(-1)t^2]\vec{P}_2 + 3t^2\vec{P}_3$$

$$= -3(1-t)^2\vec{P}_0 + [-6(1-t)t + 3(1-t)^2]\vec{P}_1 + [6(1-t)t - 3t^2]\vec{P}_2 + 3t^2\vec{P}_3$$

$$= -3(1-t)^2\vec{P}_0 - 6(1-t)t\vec{P}_1 + 3(1-t)^2\vec{P}_1 + 6(1-t)t\vec{P}_2 - 3t^2\vec{P}_2 + 3t^2\vec{P}_3$$

$$= (1-t)^2(-3\vec{P}_0 + 3\vec{P}_1) + (1-t)t(-6\vec{P}_1 + 6\vec{P}_2) + 3t^2(-\vec{P}_2 + \vec{P}_3)$$

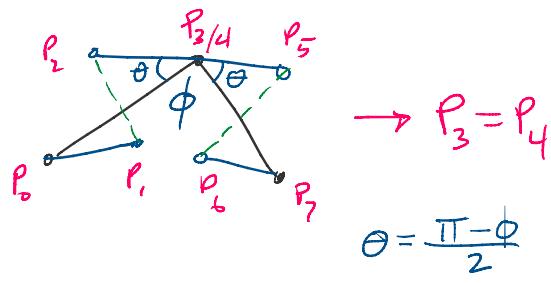
$$= 3(1-t)^2(\vec{P}_1 - \vec{P}_0) + 6t(1-t)(\vec{P}_2 - \vec{P}_1) + 3t^2(\vec{P}_3 - \vec{P}_2)$$

$$C_0' + C_1' = 3(1-t)^2(\vec{P}_1 - \vec{P}_0 + \vec{P}_5 - \vec{P}_4)$$

$$+ 6t(1-t)(\vec{P}_2 - \vec{P}_1 + \vec{P}_6 - \vec{P}_5)$$

$$+ 3t^2(\vec{P}_3 - \vec{P}_2 + \vec{P}_7 - \vec{P}_6)$$

$$C_0'' + C_1'' = -6(1-t)$$



$$\theta = \frac{\pi - \phi}{2}$$

$$C_0'' + C_1'' = -6(1-t)$$

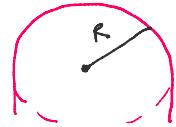
$$+ 6(1-t) - 6t \rightarrow 6(1-t-t) \rightarrow 6(1-2t)$$

$$+ 6t$$

$$C_0'' + C_1'' = -6(1-t)(P_1 - P_3 + P_5 - P_4) \\ + 6t(1-t)(P_2 - P_1 + P_6 - P_5) \\ + 6t(P_3 - P_2 + P_7 - P_6)$$

$$k=0 \Rightarrow$$

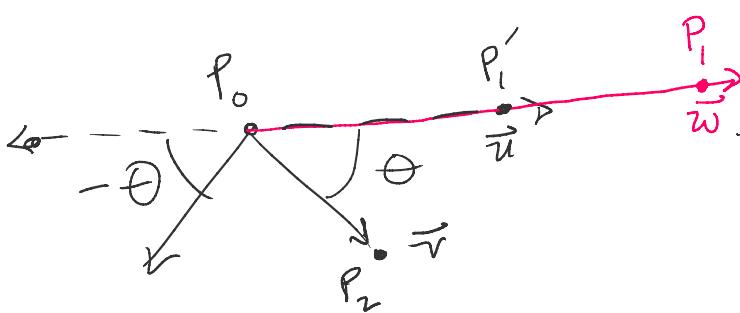
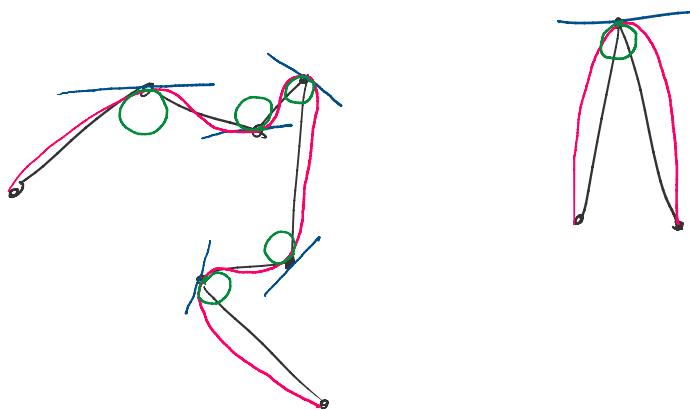
$$k=1 \Rightarrow$$



$$r = \frac{1}{k}$$

$$K = \frac{\|\vec{r}'(t) \times \vec{r}''(t)\|}{\|\vec{r}'(t)\|^3} \quad \text{where } t=0.5$$

$$\text{SET } k = \frac{\pi - \phi}{\pi}$$



$$\vec{w} = \frac{\vec{u}}{|\vec{u}|} l$$

$$\vec{u} = \vec{v} \cos \theta$$

$$\vec{v} = P_f - P_i$$

If  $\vec{v}_0 \rightarrow -\theta$   
 $\vec{v}_1 \rightarrow \theta$

$$P_e = \frac{(P_f - P_i) \cos \theta}{|(P_f - P_i) \cos \theta|} l$$

GIVEN!

... - - - - - ...

$P_L \dots -\theta$

GIVEN!

SETPOINTS —  $P_i$ ,  $i \geq 3 = 0$ , for  $0 \leq i \leq n$

ENDPOINTS —  $P_1 = P_0$ ,  $P_{n-1} = P_n$

$P_L \dots - \Theta$   
 $r'$

$$3(1-t)^2(P_0 - P_0 + P_5 + P_3) \\ + 6t(1-t)(P_2 - P_0 + P_7 - P_5) \\ + 3t^2(P_3 - P_2 + P_7 - P_5)$$

$$r'(t) = 3(1-t)^2(P_4 + P_3) \\ + 6t(1-t)(P_2 - P_0 + P_6 - P_4) \\ + 3t^2(P_3 - P_2)$$

$$r''(t) = -6(1-t)(P_4 + P_3) \\ + 6t(1-t)(P_2 - P_0 + P_6 - P_4) \\ + 6t(P_3 - P_2)$$

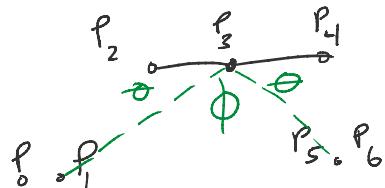
$$P_4 \rightarrow P_3 \\ P_5 \rightarrow P_4 \\ P_6 \rightarrow P_5 \\ P_7 \rightarrow P_6$$

since  $P_4 = P_3$

$$3(1-t)^2(P_1 - P_0 + P_5 - P_4) \\ + 6t(1-t)(P_2 - P_1 + P_6 - P_5) \\ + 3t^2(P_3 - P_2 + P_7 - P_6)$$

$r''$

$$-6(1-t)(P_1 - P_0 + P_5 - P_4) \\ + 6t(1-t)(P_2 - P_1 + P_6 - P_5) \\ + 6t(P_3 - P_2 + P_7 - P_6)$$



$$\phi = \angle P_{31}, P_{35}$$

$$\theta = \frac{\pi - \phi}{2}$$

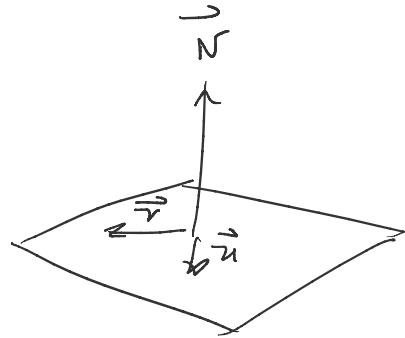
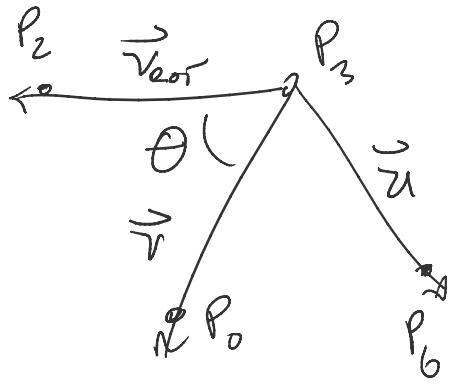
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curvature =
(abs(((3*p0_2)/4 + (3*p1_2)/4 - (3*p5_2)/4 - (3*p6_2)/4 - (3*1*vec30_2*cos(theta))/(4*(abs(vec30_1*cos(theta))^2 + abs(vec30_2
>> solution_1 = solve(curvature == k, 1)
Warning: Unable to find explicit solution. For options, see help.
> In sym/solve (line 317)

solution_1 =
Empty sym: 0-by-1

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$P_2 \xrightarrow{v_h} \dots P_n \xrightarrow{N}$



RODRIGUES' ROTATION FORMULA

$$\vec{v}_{ROT} = \vec{v} \cos \theta + (\vec{k} \times \vec{v}) \sin \theta + \vec{k} (\vec{k} \cdot \vec{v}) (1 - \cos \theta)$$

$$\begin{aligned}\vec{v}' &= \vec{v} \cos \theta + \vec{k} \times (\vec{v} \sin \theta + \vec{k} (\vec{k} \cdot \vec{v}) (1 - \cos \theta)) \\ \vec{v}' &= \frac{\vec{v} \cos \theta + \vec{k} \times (\vec{v} \sin \theta)}{|\vec{v}|}\end{aligned}$$