

(20)

Linear maps in the plane

An application: The differential $D_p f$ at a fixed point p of a differentiable map $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ (or $f: U \rightarrow U$, where $U \subset \mathbb{R}^2$) or $f: M \rightarrow M$, where M is a smooth manifold of dim. 2.

A linear map $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is given by $F(x) = Ax$, where $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$.
 0 is a fixed point for F .

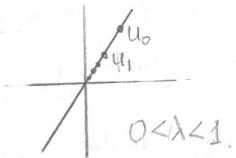
Eigenvalues of A : $0 = \det(A - \lambda I) = \begin{vmatrix} a-\lambda & b \\ c & d-\lambda \end{vmatrix} = \lambda^2 - (\text{Tr } A)\lambda + \det A$.
 $D = (\text{Tr } A)^2 - 4 \det A$.

- $D > 0$ 2 distinct real e.values, λ and μ , A is similar to $\begin{pmatrix} \lambda & 0 \\ 0 & \mu \end{pmatrix}$
- $D = 0$ 1 real e.value of multiplicity 2, A is similar to $\begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix}$ or $\begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix}$
- $D < 0$ 2 complex conjugate e.values, $\alpha + \beta i$ and $\alpha - \beta i$,
and A is similar to $\begin{pmatrix} \alpha - \beta & \beta \\ \beta & \alpha \end{pmatrix} = \sqrt{\alpha^2 + \beta^2} \begin{pmatrix} \alpha/\Gamma & -\beta/\Gamma \\ \beta/\Gamma & \alpha/\Gamma \end{pmatrix} = r \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$

The action of the "model" matrices on \mathbb{R}^2 .

(1) $A = \begin{pmatrix} \lambda & 0 \\ 0 & \lambda \end{pmatrix} = \lambda \text{Id}$, $\lambda \neq 0$. $F(u) = \lambda u$.

Every straight line through 0 is mapped to itself. So these lines are invariant under F . all iterates of $u \neq 0$ lie on the same line.



(2) $A = \begin{pmatrix} \lambda & 0 \\ 0 & \mu \end{pmatrix}$, where $\lambda \neq \mu$ and $\lambda, \mu \neq 0$.

x-axis and y-axis are invariant, but no other lines through 0 are.

Prop. The curves $|y| = C|x|^{\alpha}$, where α is so that $|\lambda|^{\alpha} = |\mu|$ are invariant under F .

Pf. Check that if $|y| = C|x|^{\alpha}$, then $|\mu y| = C|\lambda x|^{\alpha}$. \square .

(2a) $0 < |\mu| < |\lambda| < 1$, so $\alpha > 1$.

F is a contraction with $\lambda_{\text{contr.}} = |\lambda|$.

The curve $|y| = C|x|^{\alpha}$

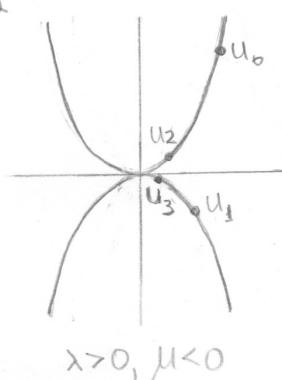
has 4 branches.

If $\lambda, \mu > 0$, then

$u_n = F^n(u)$ remain on one branch.

Otherwise, u_n

jumps between branches.



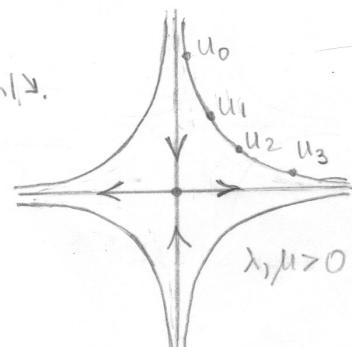
(2b) $0 < |\mu| < 1 < |\lambda|$, so $\alpha < 0$.

Such A is called hyperbolic.

In this case,

$|x_n| \uparrow$ and $|y_n| \downarrow$.

$|y| = C|x|^{\alpha}$,
with $\alpha < 0$:

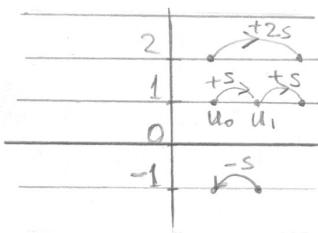


$\lambda, \mu > 0$

$$(3) A = \begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix}, \lambda \neq 0. \quad A = \lambda \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

$$(3a) A = \begin{pmatrix} 1 & s \\ 0 & 1 \end{pmatrix}, s \neq 0. \quad F(\vec{y}) = \begin{pmatrix} x+sy \\ y \end{pmatrix}$$

The x -axis is fixed, horizontal lines are invariant. This map is called a shear.



$$A = \begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix} \text{ is similar to } B = \begin{pmatrix} \lambda & \lambda \\ 0 & \lambda \end{pmatrix} = \lambda \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}. \quad B^n = \lambda^n \begin{pmatrix} 1 & n \\ 0 & 1 \end{pmatrix}, \text{ so}$$

$$B^n \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \lambda^n(x+ny) \\ \lambda^n y \end{pmatrix} = \begin{pmatrix} x_n \\ y_n \end{pmatrix} \quad \text{For } |\lambda| < 1, |x_n| \rightarrow 0 \text{ and } |y_n| \rightarrow 0, \text{ and } |y_n| \text{ is decreasing.}$$

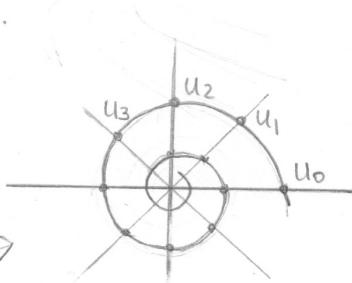
There are invariant curves for this case as well.

$$(4) A = r \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}, r > 0, \theta \neq \pi k.$$

Clockwise rotation by θ and scaling by r . Invar. curves are spirals.

For example, let $\theta = \frac{\pi}{4}$ and $r < 1$.

If $r=1$, the invariant curves are circles centered at 0.

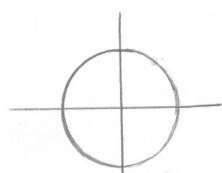


Let A be a matrix with non-zero eigenvalues.

Then $\tilde{A} = C^{-1}AC$ for a model matrix \tilde{A} , and C gives a linear conjugacy between the linear maps $(\vec{x}) \mapsto \tilde{A}(\vec{x})$ and $(\vec{x}) \mapsto A(\vec{x})$.

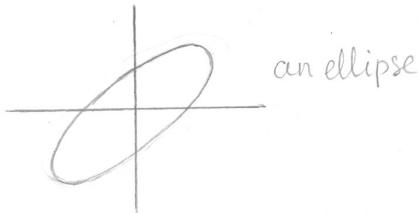
$$\tilde{A} = C^{-1}AC$$

$$A = C \tilde{A} C^{-1}$$

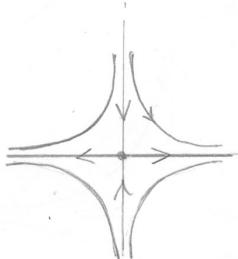


$$(4) r=1$$

$$\xrightarrow{C} \xleftarrow{C^{-1}}$$



an ellipse



$$(2b) 0 < r < 1$$

$$\xrightarrow{C} \xleftarrow{C^{-1}}$$

