

Figure 27: /users/visheshsaharan/Desktop/Screen Shot 2019-03-14 at 11.16.08 PM.png

- If  $\alpha c < 8\mu$ , equilibria:  $(K, 0)$  stable.
- If  $\alpha c > 8\mu$  and  $K < n_1^* < n_2^*$ , equilibria:  $(K, 0)$  stable (Fig. 2(d)).
- If  $\alpha c > 8\mu$  and  $n_1^* < K < n_2^*$ , equilibria:  $(n_1^*, p_1^*)$  stable and  $(K, 0)$  unstable (Fig. 2(c)).
- If  $\alpha c > 8\mu$  and  $n_1^* < K$ , equilibria:  $(n_1^*, p_1^*)$  stable,  $(n_1^*, p_1^*)$  unstable and  $(K, 0)$  stable.

Results from Model 2

Figure 28: /users/visheshsaharan/Desktop/Screen Shot 2019-03-14 at 11.16.54 PM.png

- If  $K < n_3^*$ , equilibria:  $(K, 0)$  stable (Figs. 1(b) and 2(b)).
- If  $K > n_3^*$ , equilibria:  $(n_3^*, p_{31}^*)$  stable and  $(K, 0)$  unstable (Figs. 1(a) and 2(a)).

There is a relationship between prey density (carrying capacity) and the strategy adopted by predators. Hawk behavior is a strategy in high prey densities, whereas a polymorphism with the presence of both doves and hawks, is found in low densities.



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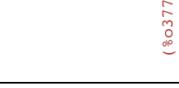
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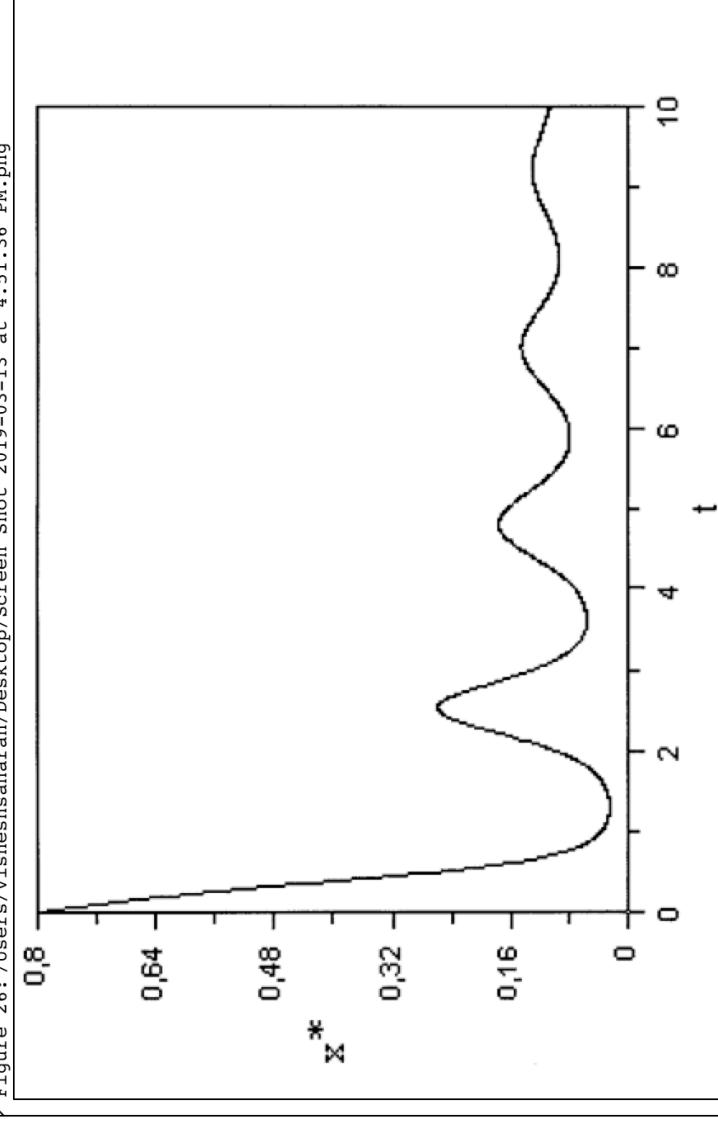


wxMaxima Project.wxmax

Maxima Project.wxmax



Figure 26: /users/visheshsaharan/Desktop/screen Shot 2019-03-13 at 4:51:36 PM.png



Results from Model 1



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Maxima Project.wxmax



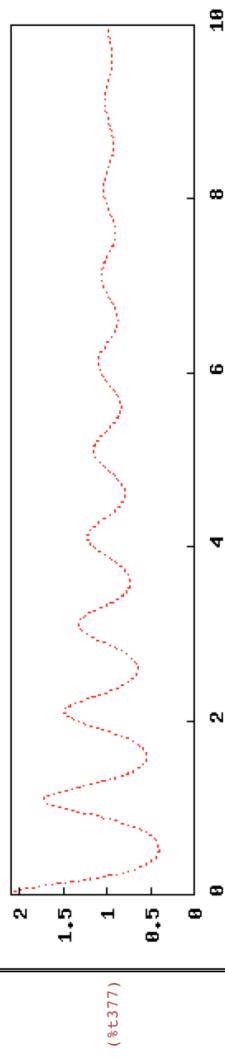
The time evolution of the proportion of hawks when the trajectory of the aggregated model is slowly spiraling to the polymorphic stable eq of (n1\*,p1\*) of Model II.

```
--> params5:[r=20,K=30,a=1,a1=4.2,C=0.5,u=1];
(%o353) [ r = 20 , K = 30 , a = 1 , a1 = 4.2 , C = 0.5 , u = 1 ]
```

```
--> rkf45(subst(params5,aggmodel),[n,p],[2.1,18.4],[t,0,10]);
```

```
--> wxdraw2d(proportional_axes=xy,
      line_type=dots,line_width=0.5,
      color=red,
      implicit(subst(params5,zii[1]),n,0,10,p,0,1),
      sol_points(f,first,second))
```

Fontconfig error: Cannot load default config file fontconfig: Couldn't find font. when opening font "arial", using internal non-scalable font  
"/Users/visheshsaharan/maxout\_24555.gnuplot", line 37: warning: Skipping data file with no valid points



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Apple wxMaxima File Edit Cell Maxima Equations Algebra Calculus Simplify Plot Numeric Help ☰ 55% 🔍 55% 🔍 55% 🔍 Sat Jan 22 4:24:54 PM Q ⚡

Maxima Project.wxmax



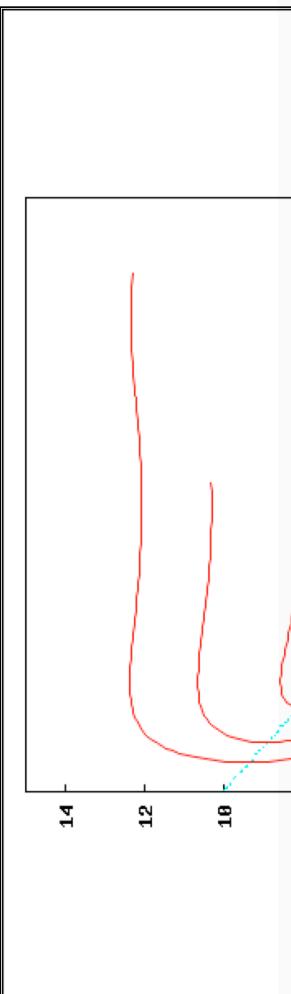
In Fig. 2B, there is a separatrix. Based on initial conditions, the predator and prey coexist at a low density or the predator goes to extinction and the prey tends towards its carrying capacity

```
--> params4:[r=10,K=11,a=1,al=1,c=10,u=1];
(%o76) [r=10,K=11,a=1,al=1,c=10,u=1]

--> sd1:rkf45(subst(params4,argmodel),[n,p],[9.3,8.1],[t,0,40]);
--> sd2:rkf45(subst(params4,argmodel),[n,p],[3.3,2.1],[t,0,40]);
--> sd3:rkf45(subst(params4,argmodel),[n,p],[7.8,10.3],[t,0,40]);
--> sd4:rkf45(subst(params4,argmodel),[n,p],[12.6,3.1],[t,0,40]);
--> sd5:rkf45(subst(params4,argmodel),[n,p],[13.1,12.3],[t,0,40]);
--> sd6:rkf45(subst(params4,argmodel),[n,p],[7.1,4.3],[t,0,40]);

--> wxdraw2d(proportional_axes=xy,
  line_type=dots, line_width=0.5,
  color=cyan,
  implicit(subst(params4,zi1[1]),n,0,15,p,0,15),
  color=magenta,
  implicit(subst(params4,zi2[1]),n,0,15,p,0,15),
  line_type=solid, points_joined=true, point_type=0, color=red,
  sol_points(sd1,second,third),sol_points(sd2,second,third),
  sol_points(sd3,second,third),sol_points(sd4,second,third),
  sol_points(sd5,second,third),sol_points(sd6,second,third));
;
```

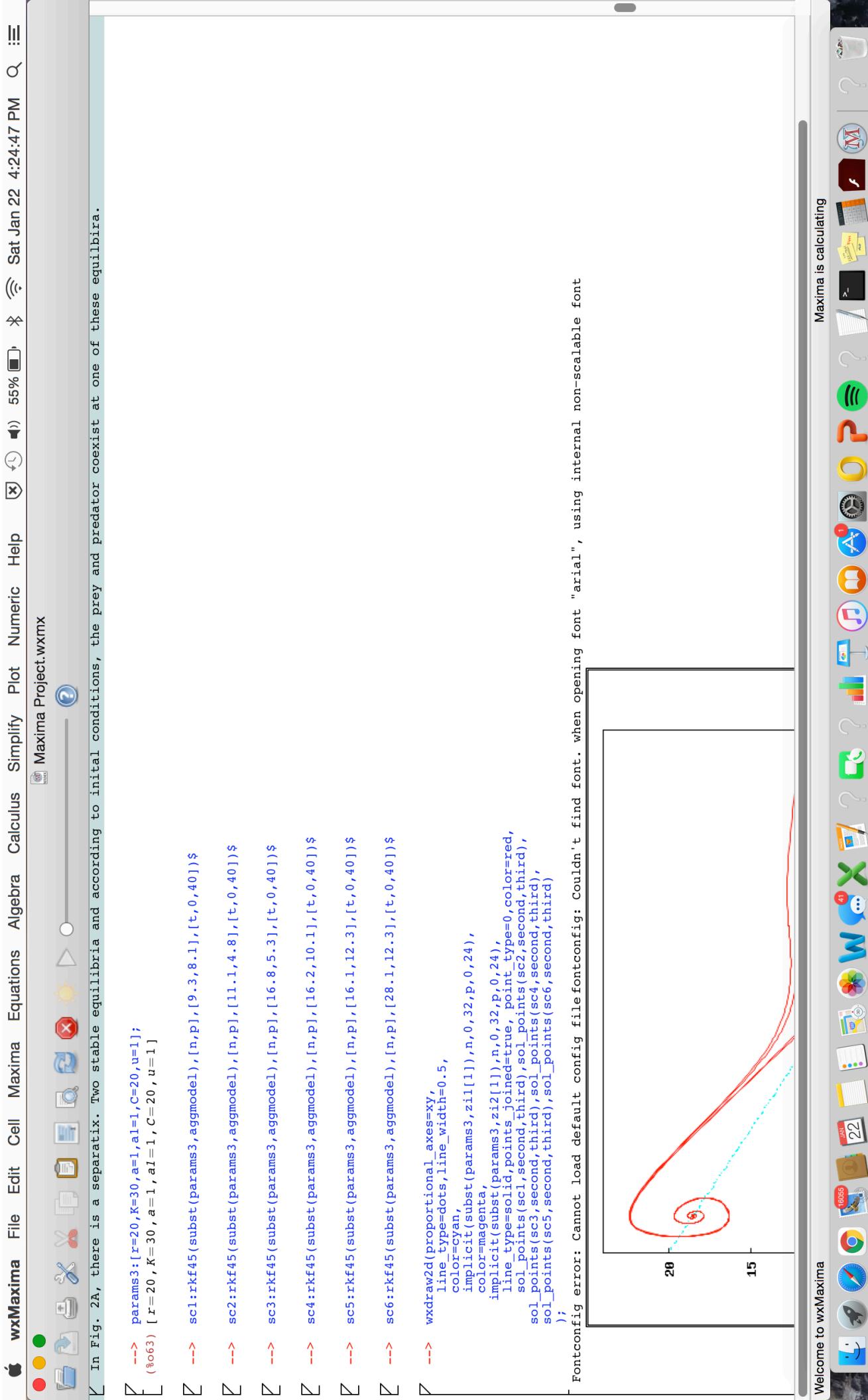
Fontconfig error: Cannot load default config file fontconfig: Couldn't find font. when opening font "arial", using internal non-scalable font



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```

[--> sb3:rkf45(subst(params2,argmodel),[n,p],[2.8,3.3],[t,0,40])$  

[--> sb4:rkf45(subst(params2,argmodel),[n,p],[0.2,6.3],[t,0,40])$  

[--> sb5:rkf45(subst(params2,argmodel),[n,p],[0.1,4.3],[t,0,40])$  

[--> sb6:sb1:rkf45(subst(params2,argmodel),[n,p],[0.3,5.1],[t,0,40])$  

[--> wxdraw2d(proportional_axes=xy,  

    line_type=dots, line_width=0.5,  

    color=cyan,  

    implicit(subst(params2,zi1[1]),n,0,8,p,0,10),  

    color=magenta,  

    implicit(subst(params2,zi2[1]),n,0,8,p,0,10),  

    line_type=solid, points_joined=true, point_type=0,color=red,  

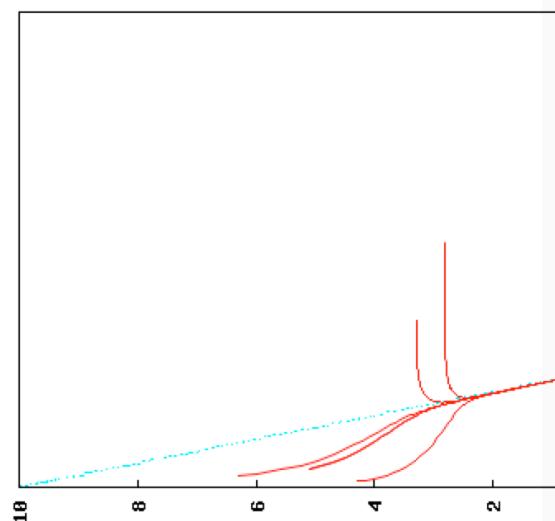
    sol_points(sb1,second,third),sol_points(sb2,second,third),  

    sol_points(sb3,second,third),sol_points(sb4,second,third),  

    sol_points(sb5,second,third),sol_points(sb6,second,third)
);

```

Fontconfig error: Cannot load default config file fontconfig: Couldn't find font. when opening font "arial", using internal non-scalable font

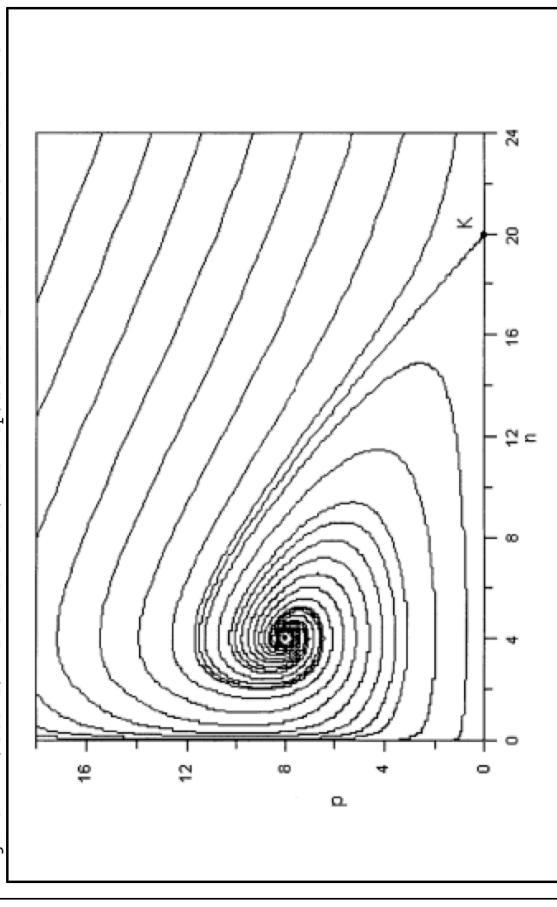


(%t61)

Maxima Project.wxmax



Figure 22: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-13 at 10:31:24 AM.png



Let us now look at predator exclusion. Fig. 1B and Fig. 2D show the predator going to extinction and the prey tends to its carrying capacity.

```
--> params2:[r=10,K=2,a=1,al=1,C=10,u=1];
(%o10) [ r=10 , K=2 , a=1 , al=1 , C=10 , u=1 ]

--> sb1:rkf45(subst(params2,argmodel),[n,p],[9.17,1.1],[t,0,40])$
```

```
--> sb2:rkf45(subst(params2,argmodel),[n,p],[4.1,2.8],[t,0,40])$
```

```
--> sb3:rkf45(subst(params2,argmodel),[n,p],[2.8,3.3],[t,0,40])$
```

```
--> sb4:rkf45(subst(params2,argmodel),[n,p],[0.2,6.3],[t,0,40])$
```

```
--> sb5:rkf45(subst(params2,argmodel),[n,p],[0.1,4.3],[t,0,40])$
```

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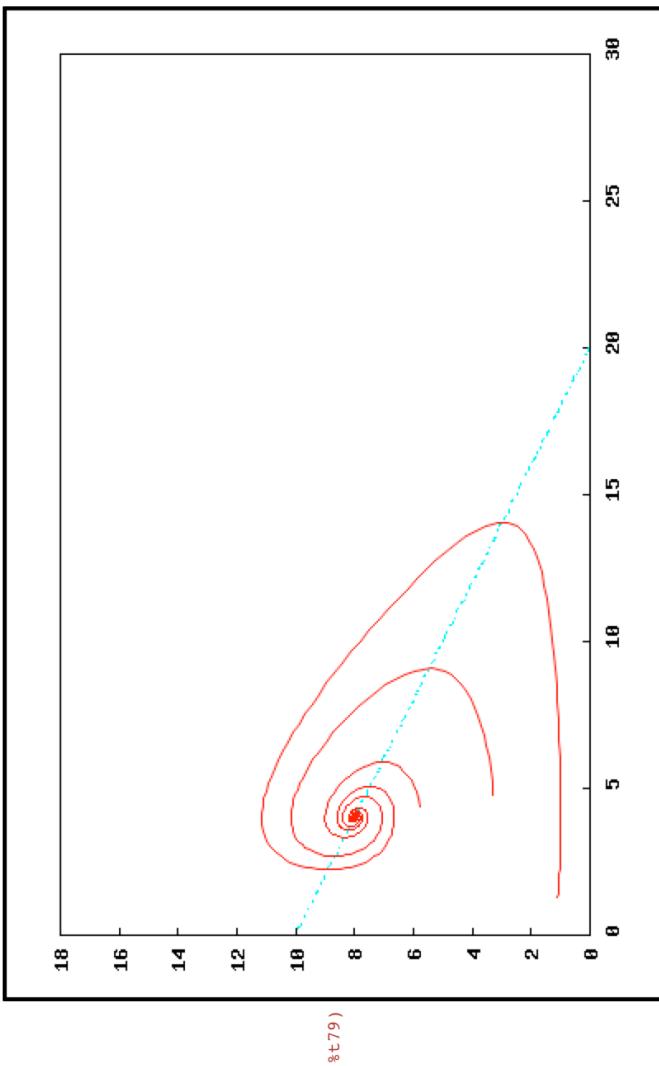
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```
--> wxdraw2d(proportional_axes=xy,
           line_type=dots, line_width=0.5,
           color=cyan,
           implicit(subst(params1, z1||1), n, 0, 30, p, 0, 18),
           line_type=solid, points_joined=true, point_type=0, color=red,
           sol_points(s1, second, third), sol_points(s2, second, third),
           sol_points(s3, second, third))
);
```

Fontconfig error: Cannot load default config file fontconfig: Couldn't find font. when opening font "arial", using internal non-scalable font



(%o79)

Figure 22: /users/visheshsaharan/Desktop/Screen Shot 2019-03-13 at 10.31.24 AM.png



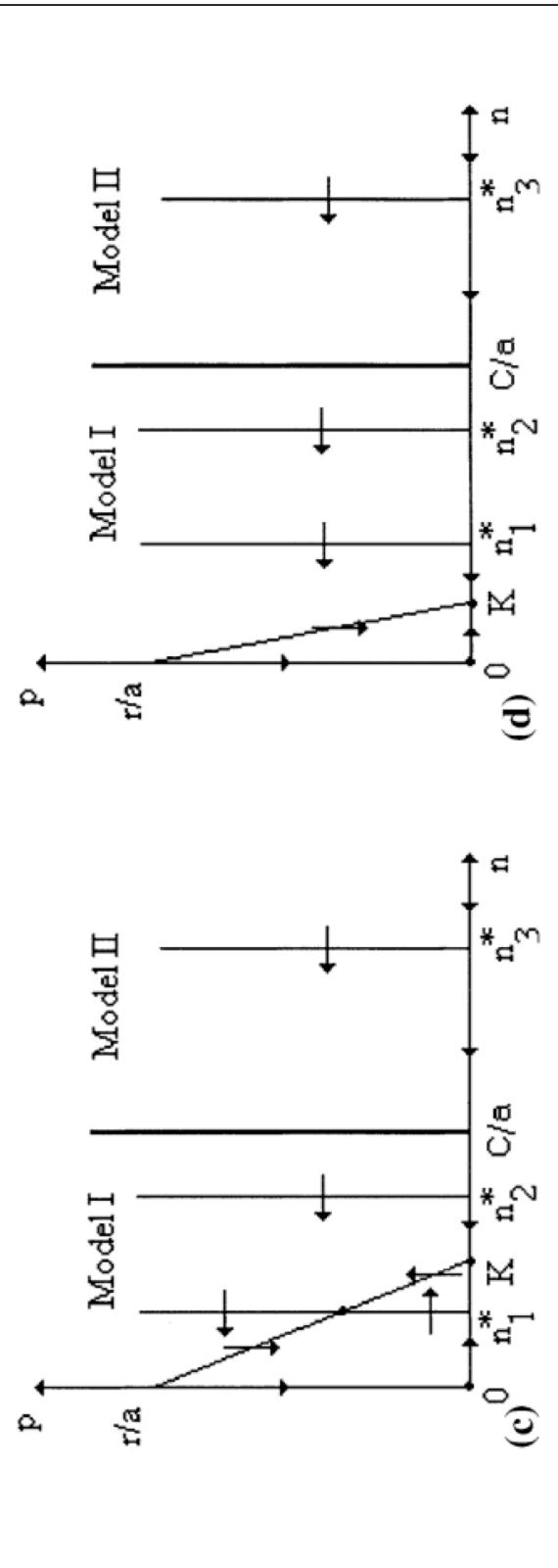
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Figure 21: /Users/visheshsaharan/Desktop/Screen Shot 2019-03-14 at 10.05.18 PM.png



We have 6 different phase portraits, so let's take into account four possibilities concerning the stability. Let's look at coexistence, predator exclusion, coexistence or predator exclusion based on initial conditions, and coexistence at two different density levels based on initial conditions.

First, let's look at coexistence. We can see that Fig. 1A and Fig. 2C demonstrate coexistence, so we can make a phase plot of these cases.

```
--> params1;
(%o69) [r=10, K=20, a=1, a1=1, c=2, u=1]
--> salrkf45(subst(params1,agmodel),[n,p],[1.3,1.1],[t,0,40])$  

--> sa2:rkf45(subst(params1,agmodel),[n,p],[4.4,5.8],[t,0,40])$  

--> sa3:rkf45(subst(params1,agmodel),[n,p],[4.8,3.3],[t,0,40])$
```

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Maxima Project.wxmx

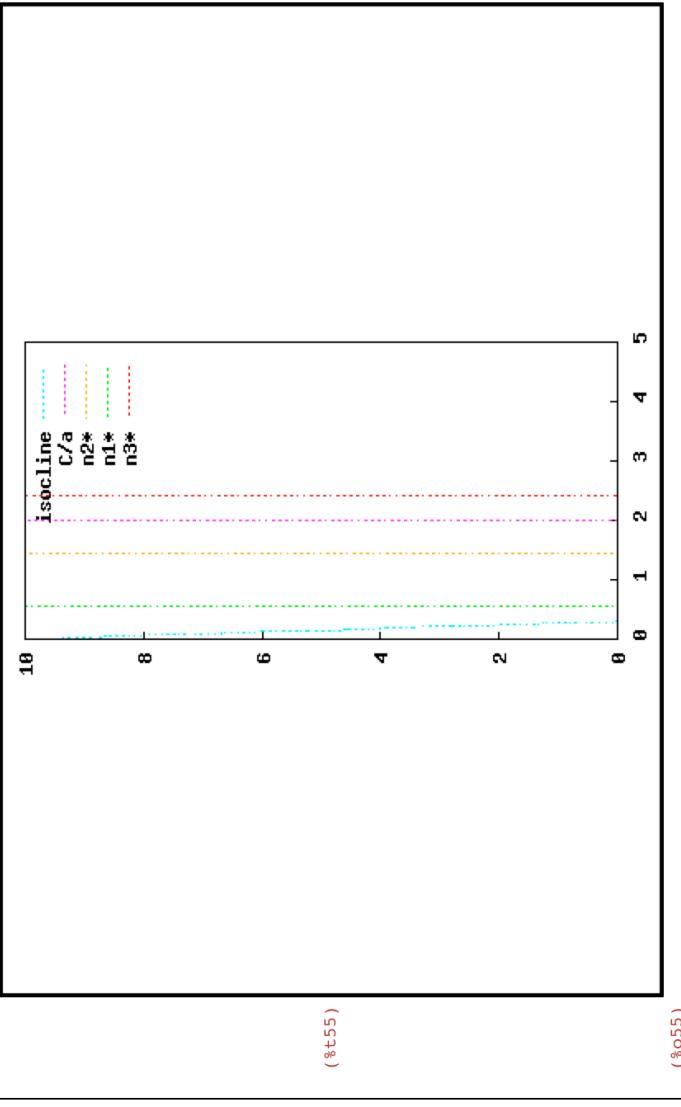
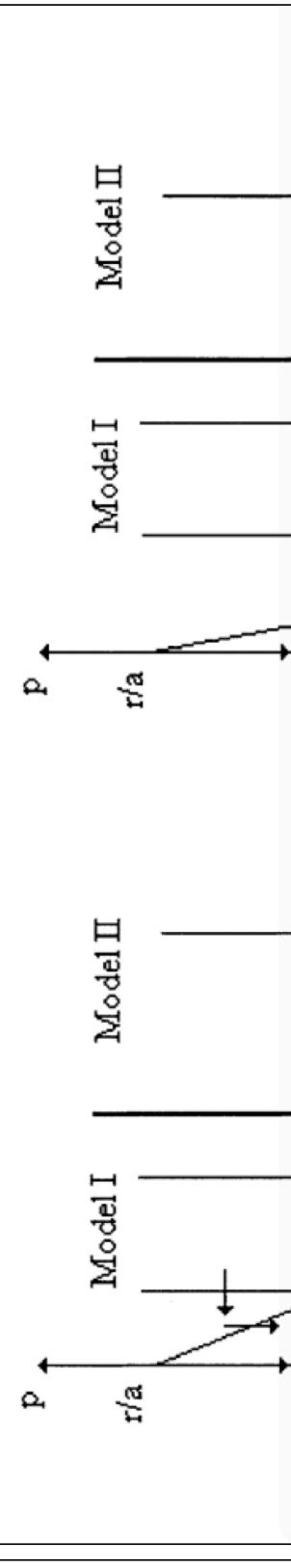


Figure 21: /Users/VisheshSaharan/Desktop/Screen Shot 2019-03-14 at 10.05.18 PM.png



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Maxima Project.wxmax



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→ params1d:[r=10,K=0.3,a=1,a1=5,C=2,u=1];

(%o42) [ r=10 , K=0.3 , a=1 , a1=5 , C=2 , u=1 ]

→ eq1d:solve(subst(params1d,mode11),[n,p]);  
rat: replaced -3.33333333333333 by -10/3 = -3.33333333333333

(%o44) [ [ n=0 , p=0 ] , [ n=  $\frac{3}{10}$  , p=0 ] , [ n=-  $\frac{\sqrt{5}-5}{5}$  , p=  $\frac{4 \cdot 5^{3/2}-70}{3}$  ] , [ n=  $\frac{\sqrt{5}+5}{5}$  , p=  $\frac{4 \cdot 5^{3/2}+70}{3}$  ] ]

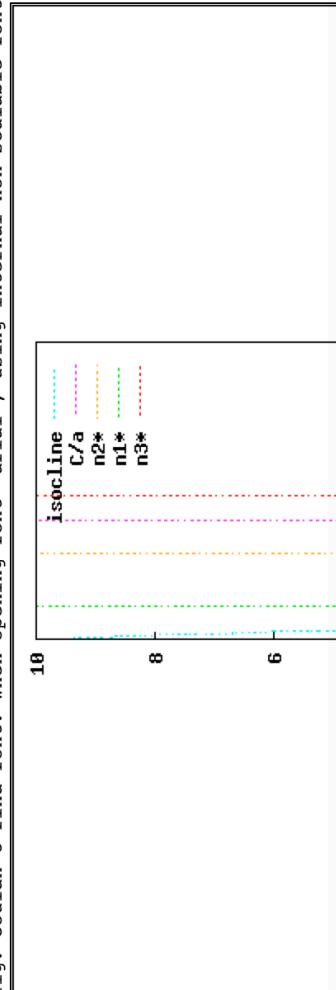
→ eq2d:solve(subst(params1d,mode12),[n,p]);  
rat: replaced -3.33333333333333 by -10/3 = -3.33333333333333

(%o45) [ [ n=0 , p=0 ] , [ n=  $\frac{3}{10}$  , p=0 ] , [ n=  $\frac{12}{5}$  , p= -70 ] ]

→ wxdraw2d(proportional\_axes=xy,  
line\_type=dots, line\_width=0.5,  
color=cyan, key="isocline",  
implicit(subst(params1d,z1[[1]],n,0,5,p,0,10),  
color=magenta, key="C/a",  
implicit(n=2,n,0,5,p,0,10),  
color=orange, key="n2\*", implicit(n=sqrt(5)/5+1,n,0,5,p,0,10),  
color=green, key="n1\*", implicit(n=-sqrt(5)/5+1,n,0,5,p,0,10),  
color=red, key="n3\*", implicit(n=12/5,n,0,5,p,0,10),  
line\_type=solid, points\_joined=true, point\_type=0, color=red  
);

rat: replaced -3.33333333333333 by -10/3 = -3.33333333333333 rat: replaced 3.0 by 3/1 = 3.0 rat: replaced 2.2360679749979 by 16692641/7465176 = 2.236067977499794

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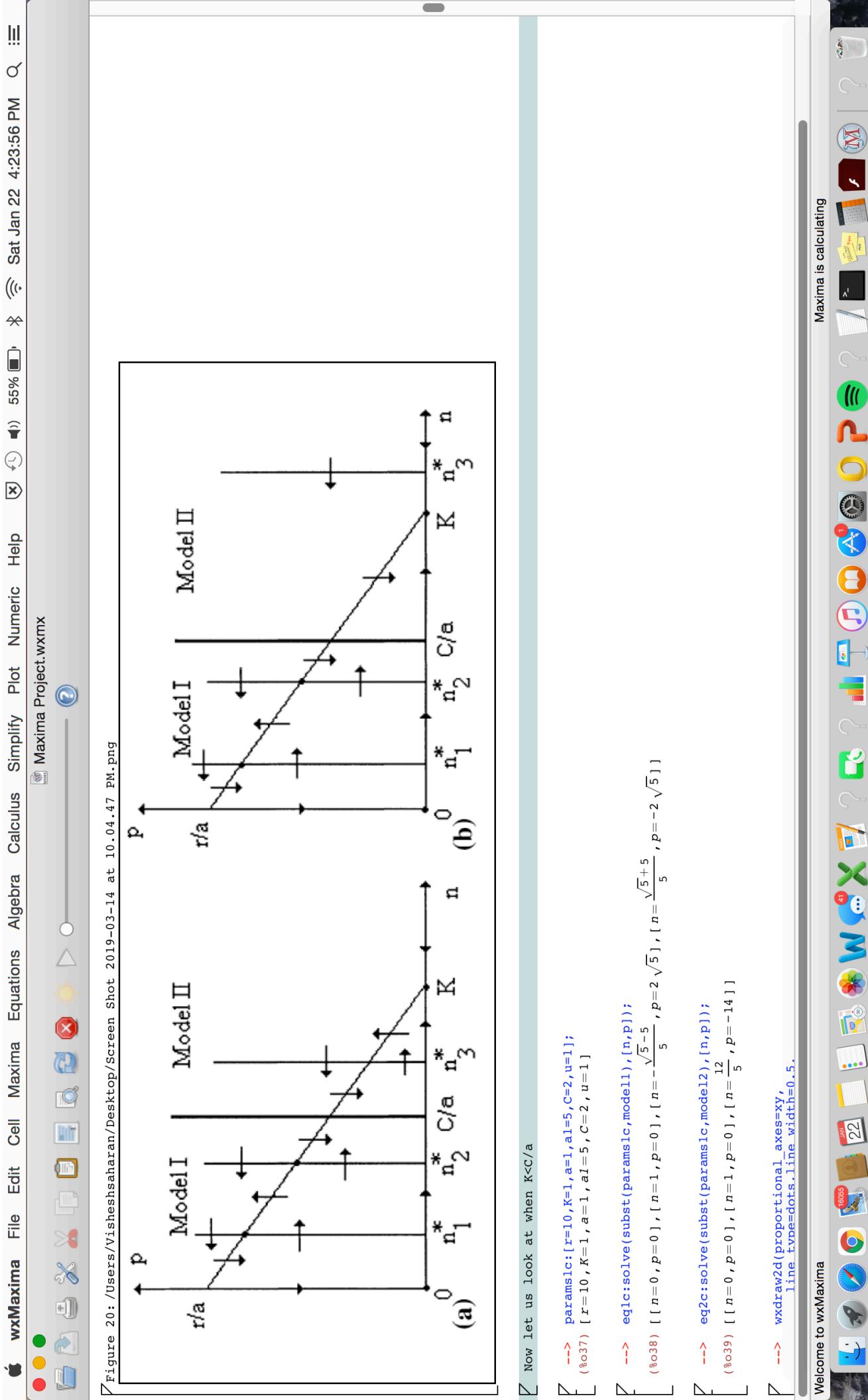
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## Maxima Project.wxmaxx



```
--> params4:[r=10,K=11,a=1,a1=1,C=10,u=1];
(%o60) [ r=10 , K=11 , a = 1 , a1 = 1 , C = 10 , u = 1 ]
```

```
--> eq14:solve(subst(params4,modell1),[n,p]);
```

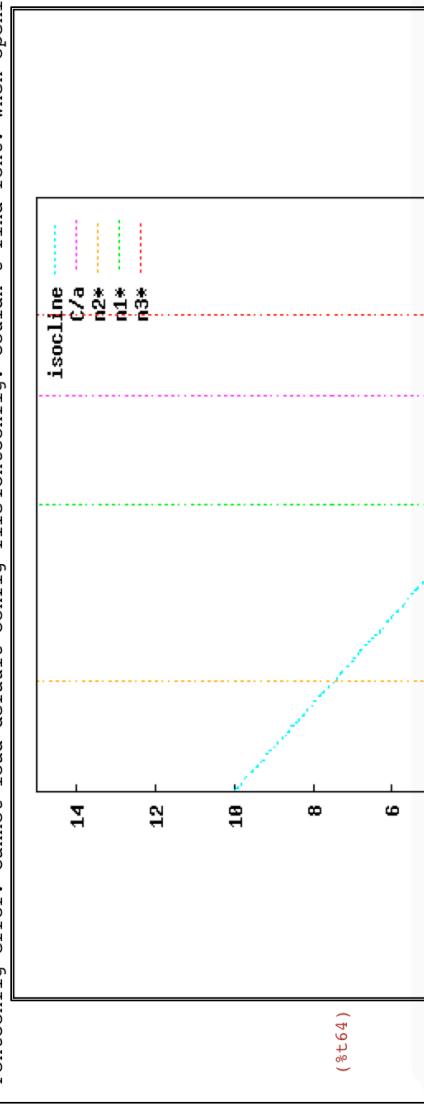
```
(%o61) [ [ n = 0 , p = 0 ] , [ n = 11 , p = 0 ] , [ n = 5 - √5 , p = - 2 5 3 / 2 + 60 / 11 ] , [ n = √5 + 5 , p = - 2 5 3 / 2 - 60 / 11 ] ]
```

```
--> eq24:solve(subst(params4,modell2),[n,p]);
```

```
(%o62) [ [ n = 0 , p = 0 ] , [ n = 11 , p = 0 ] , [ n = 12 , p = - 10 / 11 ] ]
```

```
--> wxdraw2d(proportional_axes=xy,
           line_type=dots, line_width=0.5,
           color=cyan, key="isocline",
           implicit(subst(params4,zii[1]),n,0,15,p,0,15),
           color=magenta, key="c/a",
           implicit(n=10,n,0,15,p,0,15),
           color=orange, key=n2*, implicit(n=5-sqrt(5),n,0,15,p,0,15),
           color=green, key=n1*, implicit(n=5+sqrt(5),n,0,15,p,0,15),
           color=red, key=n3*, implicit(n=12,n,0,15,p,0,15),
           line_type=solid, points_joined=true, point_type=0, color=red)
```

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```
--> zi2;
(%o68) [ p =  $\frac{r K - n r}{a K}$  ]
```

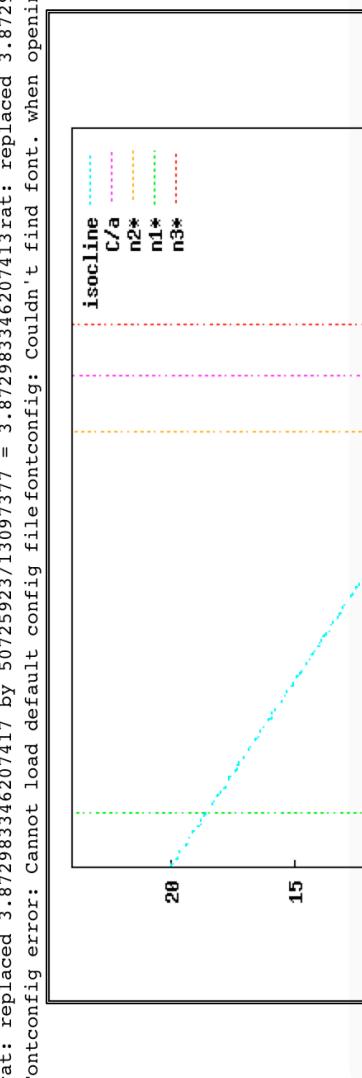
```
--> params3:[r=20,K=30,a=1,a1=1,c=20,u=1];
(%o48) [ r=20 , K=30 , a=1 , a1=1 , c=20 , u=1 ]
```

```
--> eq13:solve(subst(params3,modell1),[n,p]);
(%o50) [ [ n=0 , p=0 ] , [ n=30 , p=0 ] , [ n=10 - 2  $\sqrt{15}$  , p =  $\frac{4 \sqrt{3} \sqrt{5} + 40}{3}$  ] , [ n=2  $\sqrt{15}$  + 10 , p =  $-\frac{4 \sqrt{3} \sqrt{5} - 40}{3}$  ] ]
```

```
--> eq23:solve(subst(params3,modell1),[n,p]);
(%o51) [ [ n=0 , p=0 ] , [ n=30 , p=0 ] , [ n=10 - 2  $\sqrt{15}$  , p =  $\frac{4 \sqrt{3} \sqrt{5} + 40}{3}$  ] , [ n=2  $\sqrt{15}$  + 10 , p =  $-\frac{4 \sqrt{3} \sqrt{5} - 40}{3}$  ] ]
```

```
--> wxdraw2d(proportional_axes=xy,
    line_type=dots, line_width=0.5,
    color=cyan, key="isocline",
    implicit(subst(params3,zi1(1)),n,0,30,p,0,24),
    color=magenta, key="C/a",
    implicit(n=20,n,0,30,p,0,24),
    color=orange, key="n2*", implicit(n=2*sqrt(15)+10,n,0,30,p,0,24),
    color=green, key="n1*", implicit(n=10-2*sqrt(15),n,0,30,p,0,24),
    color=red, key="n3*", implicit(n=22,n,0,30,p,0,24),
    line_type=solid, points_joined=true, point_type=0, color=red)
```

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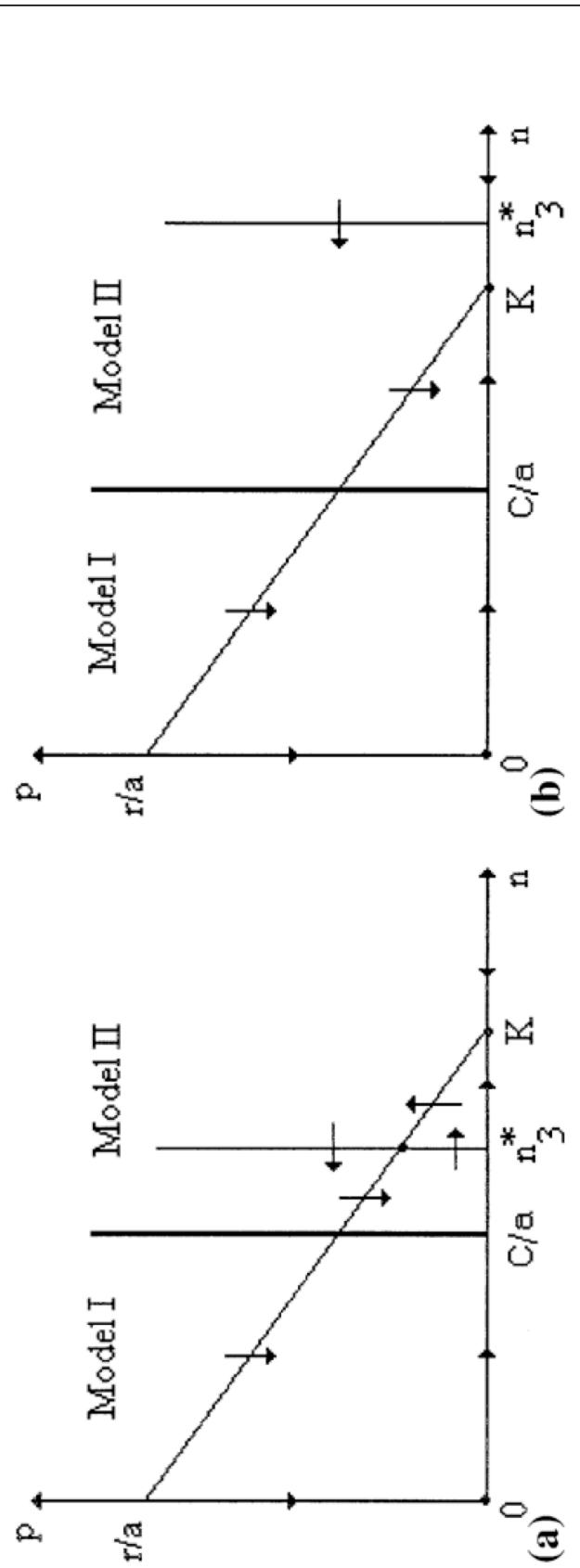


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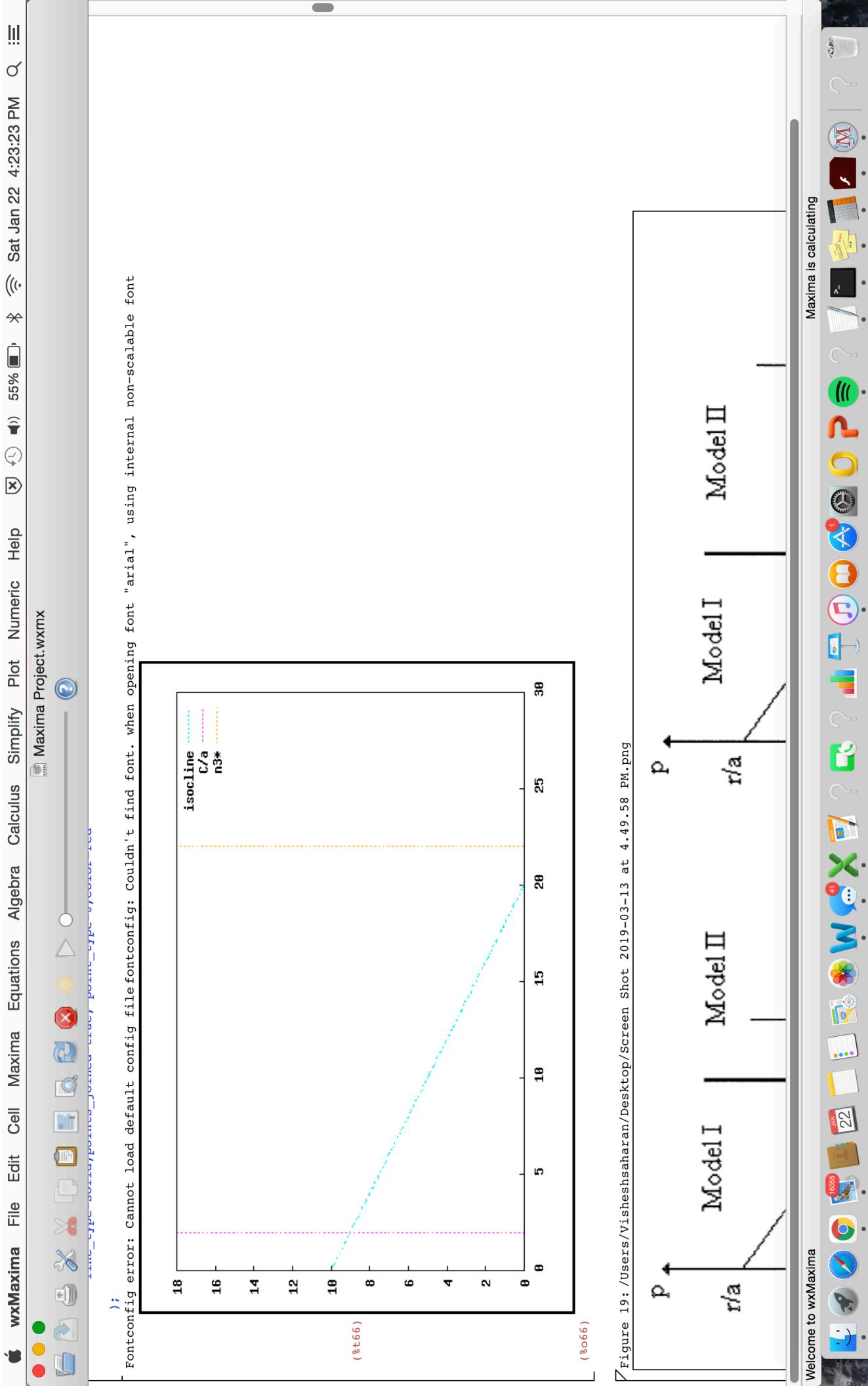


Figure 19: /users/visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4:49:58 PM.png

Fig. 1. Phase portrait of the aggregated system when  $\alpha C < 8\mu$ : (a)  $K > n_3^*$  and (b)  $K < n_3^*$ .

Now let's consider the case of  $\alpha C > 8\mu$ . Because we can use Model I and Model II for this, we will have four cases according to the position of  $K$  with respect to the equilibrium solutions  $n_1^*$ ,  $n_2^*$ , and  $n_3^*$ . Let's observe what happens when we put  $K > C/a$

```
--> zil:solve(model1[1],P);
(%o67) [P = r K - n r
          a K]
```



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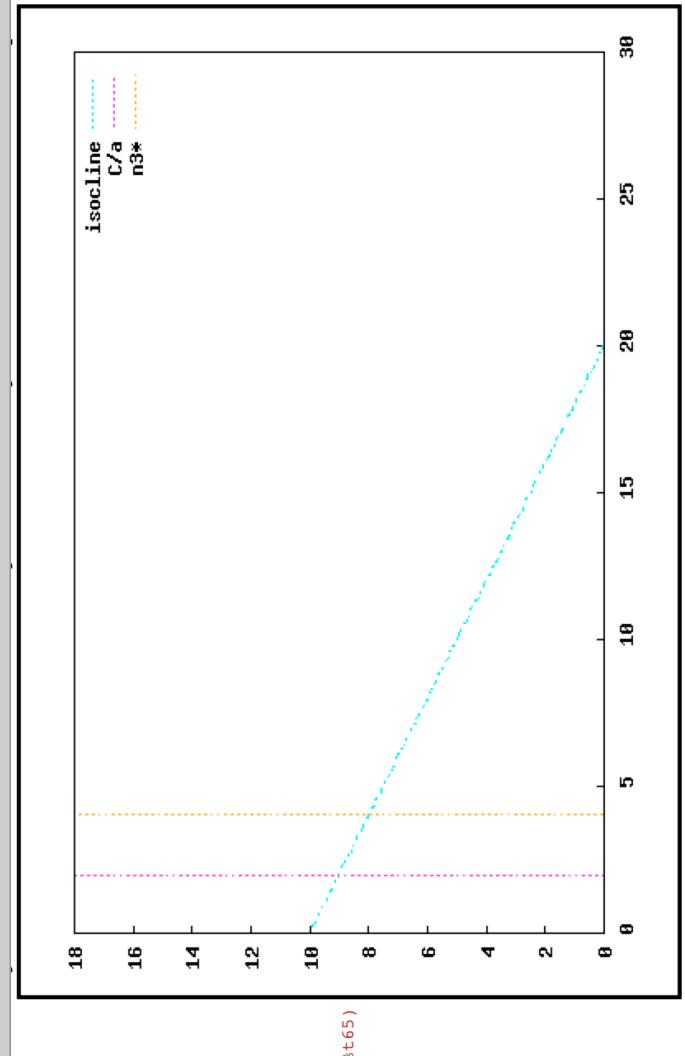
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```
--> params1b:[r=10,K=20,a=1,al=.111,C=2,u=1];
(%o111) [ r=10 , K = 20 , a = 1 , al = 0.111 , C = 2 , u = 1 ]
```

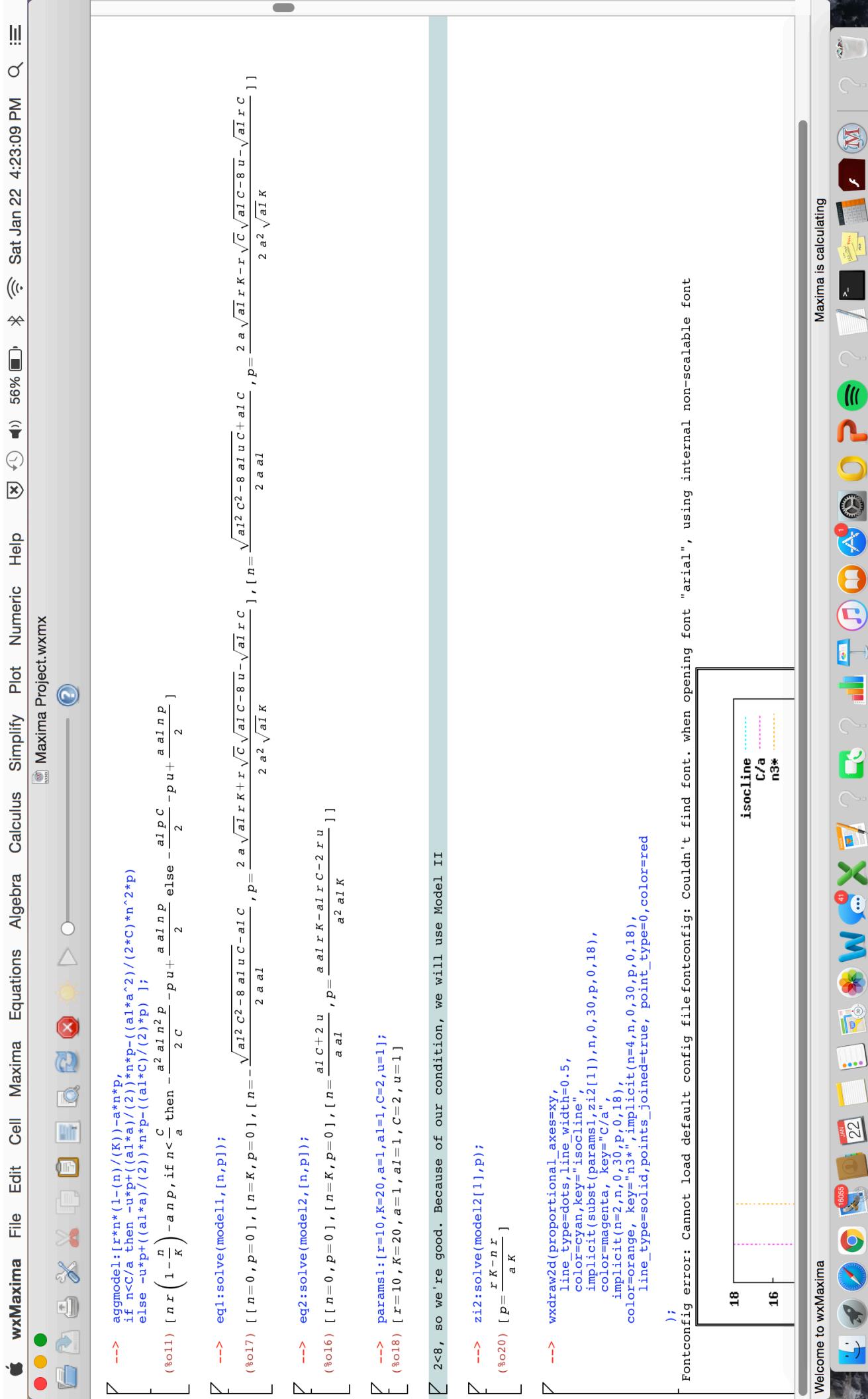
```
--> wxdraw2d(proportional_axes=xy,
  line_type=dots, line_width=0.5,
  color=cyan, key="isocline",
  implicit(subst(params1b,z12[1]),n,0,30,p,0,18),
  color=magenta, key="C/a",
  implicit(n=2,r,0,30,p,0,18),
  color=orange, key="n3*", implicit(n=22,n,0,30,p,0,18),
  line_type=solid, points_joined=true, point_type=0, color=red
);
```

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Figure 17: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4:49.12 PM.png

$$n = n_1^* = \frac{C}{2a} - \frac{\sqrt{\alpha a^2 C (\alpha C - 8\mu)}}{2\alpha a^2}$$

and

$$n = n_2^* = \frac{C}{2a} + \frac{\sqrt{\alpha a^2 C (\alpha C - 8\mu)}}{2\alpha a^2}.$$

For Model II, we have two nullclines,  $p=0$  and the vertical line

Figure 18: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4:49.32 PM.png

$$n = n_3^* = \frac{2\mu + \alpha C}{\alpha a}.$$

Here's where I'll begin some actual Maxima work. Let's consider the case  $\alpha C < 8\mu$  where  $K > n^3$  and  $K < n^3$

```
--> model1:[r*n*(1-(n)/(K))-a*n*p,-u*p+((a1*a)/(2))*n*p-((a1*a^2)/(2*C))*n^2*p];
(%o8) [n r(1 - n K ) - a n p , - a^2 a l n^2 p - p u + a a l n p ]
--> model2:[r*n*(1-(n)/(K))-a*n*p,-u*p+((a1*a)/(2))*n*p-((a1*a^2)/(2*C))*n^2*p];
(%o9) [n r(1 - n K ) - a n p , - a l p c - p u + a a l n p ]
--> aggmodel:[r*n*(1-(n)/(K))-a*n*p,
```

```
--> ,a1*p^2,-p u + a a l n p ]
```

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Figure 16: /users/visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4:48:36 PM.png

*Model I:*  $n < \frac{C}{a}$ ,  $x^* = \frac{an}{C}$  is asymptotically stable in Eq. (12),

$$\begin{cases} \frac{dn}{dt} = rn\left(1 - \frac{n}{K}\right) - anp, \\ \frac{dp}{dt} = -\mu p + \frac{\alpha a}{2}np - \frac{\alpha a^2}{2C}n^2p. \end{cases}$$

*Model II:*  $n > \frac{C}{a}$ ,  $x^* = 1$  is asymptotically stable in Eq. (12),

$$\begin{cases} \frac{dn}{dt} = rn\left(1 - \frac{n}{K}\right) - anp, \\ \frac{dp}{dt} = -\mu p + \frac{\alpha a}{2}np - \frac{\alpha C}{2}p. \end{cases}$$

These two models connect at the vertical line  $n = C/a$  of the phase space  $(n, p)$ .

When looking for nullclines, there are several different cases depending on parameter values. For Model 1, if  $\alpha C > 8\mu$ , the only nullcline is  $p=0$ . If  $\alpha C < 8\mu$ , we have besides  $p=0$ , two more nullclines which are vertical lines

Figure 17: /users/visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4:49:12 PM.png

- $G < C$ ,  $x^* = G/C$  is asymptotically stable for any initial condition  $0 < x(0) < 1$ . In this case, equilibrium, the population is polymorphic with a proportion  $G/C$  of hawks and  $1 - G/C$  doves.
- $G > C$ ,  $G/C$  does not belong to the interval  $[0, 1]$ . The equilibrium  $x^* = 1$  is asymptotically stable. The population is monomorphic and totally hawk at equilibrium.

We have to make the assumption that the fast process is at the fast equilibrium. We substitute the previous fast equilibrium and add the two predator equations to the model above to get.

Figure 14: /Users/visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4:46:36 PM.png

$$p_H = x^* p, \quad p_D = (1 - x^*) p.$$

The two equations govern the total prey and predator densities at the slow time scale. We can call this the aggregated model, which takes into account the behaviors of the

Figure 15: /Users/visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4:48:03 PM.png

$$\begin{cases} \frac{dn}{dt} = rn\left(1 - \frac{n}{K}\right) - anp, \\ \frac{dp}{dt} = -\mu p + \frac{\alpha G}{2}p - \frac{\alpha C}{2}(x^*)^2 p. \end{cases} \quad (14)$$

We can have two possibilities for the fast equilibrium and that the gain depends on the prey density. We can plug this into the equation to get two different aggregated model are valid on two domains of the phase plane.

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### Deviation of aggregated model

The first step is to neglect the small terms of  $\epsilon$  and to look for existence of a stable equilibrium for the fast part of the system.

Figure 12: /users/visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4:45:32 PM.png

$$\begin{cases} \frac{dp_H}{d\tau} = px(\Delta_H - \Delta), \\ \frac{dp_D}{d\tau} = py(\Delta_D - \Delta). \end{cases} \quad (11)$$

Using the fact that  $x+y=1$ , the system can be reduced to

Figure 13: /users/visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4:45:53 PM.png

$$\frac{dx}{dt} = \frac{x}{2}(1-x)(G-Cx). \quad (1)$$

This equation has three equilibria, 0, 1 and  $G/C$ . 0 is always unstable. Let us denote  $x^*$  the stable non-trivial equilibrium. According to parameters values, two cases can occur:

- $G < C$ ,  $x^* = G/C$  is asymptotically stable for any initial condition  $0 < x(0) < 1$ . In this case, equilibrium, the population is polymorphic with a proportion  $G/C$  of hawks and  $1 - G/C$  doves.
- $G > C$ ,  $G/C$  does not belong to the interval  $[0, 1]$ . The equilibrium  $x^* = 1$  is asymptotically stable.

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Figure 9: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4:41.17 PM.png

$$\frac{dp_H}{dt} = -\mu p_H + \left( \alpha \left( \frac{G-C}{2} \right) \frac{p_H}{p} + \alpha G \frac{p_D}{p} \right) p_H, \quad (7)$$

Figure 10: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4:41.46 PM.png

$$\frac{dp_D}{dt} = -\mu p_D + \alpha \frac{G}{2} \frac{p_D}{p} p_D. \quad (8)$$

The complete model combines both fast and slow processes

Figure 11: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4:44.26 PM.png

$$\begin{cases} \frac{dn}{d\tau} = \varepsilon \left( m \left( 1 - \frac{n}{K} \right) - ap \right), \\ \frac{dp_H}{d\tau} = px(\Delta_H - \Delta) + \varepsilon \left( -\mu p_H + \left( \alpha \left( \frac{G-C}{2} \right) \frac{p_H}{p} + \alpha G \frac{p_D}{p} \right) p_H \right), \\ \frac{dp_D}{d\tau} = py(\Delta_D - \Delta) + \varepsilon \left( -\mu p_D + \alpha \frac{G}{2} \frac{p_D}{p} p_D \right). \end{cases} \quad (10)$$

Deviation of aggregated model

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Figure 6: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-14 at 10.46.19 PM.png

$$\Delta = (x \ y) \mathbf{A} \begin{pmatrix} x \\ y \end{pmatrix}.$$

We now try to calculate the difference between the gain of each of them and the average gain of the population. We assume that the hawk-dove game is fast.

Figure 7: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-14 at 10.48.45 PM.png

$$\begin{cases} \frac{dx}{d\tau} = x(\Delta_H - \Delta), \\ \frac{dy}{d\tau} = y(\Delta_D - \Delta). \end{cases}$$

Prey equation can be represented by a classica Lotka-Volterra model.  $r$  is the growth rate,  $K$  is the carrying capacity of the population,  $a$  is a positive predation force parameter, ad  $p$  is the

Figure 8: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-13 at 4.39.51 PM.png

$$\frac{dn}{dt} = rn \left(1 - \frac{n}{K}\right) - anp, \quad (6)$$

For predators, we assume a constant mortality rate  $\mu > 0$  for hawks and doves.  $G$  represents the gain that the predator gets. For hawks, they get the gain  $(G-C)/2$  while doves get gain  $G$ .  $\alpha$  represents a positive conversion coefficient of gain and cost into biomass of predators.

Figure 9: /Users/Visheshsaharan/Desktop/Screen Shot 2019-02-12 at 4.41.17 PM.png

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Figure 2: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-14 at 10.42.43 PM.png

$$p(t) = p_H(t) + p_D(t).$$

Let  $x(t)$  and  $y(t)$  be respectively the hawks and doves proportions in the population of predators at time  $t$ .

Figure 3: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-14 at 10.43.42 PM.png

$$x(t) = \frac{p_H(t)}{p(t)}, \quad y(t) = 1 - x(t) = \frac{p_D(t)}{p(t)}.$$

Using replicator equations that describe that change of tactics of predators that have been described, we can get an average gain of an individual playing the two tactics

Figure 4: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-14 at 10.47.18 PM.png

$$\Delta_H = (1 \ 0) A \begin{pmatrix} x \\ y \end{pmatrix}.$$

Figure 5: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-14 at 10.47.23 PM.png

$$\Delta_D = (0 \ 1) A \begin{pmatrix} x \\ y \end{pmatrix}.$$

Figure 6: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-14 at 10.46.19 PM.png

$$\Delta = (x \ y) A \begin{pmatrix} x \\ y \end{pmatrix}.$$

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Figure 1: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-14 at 8.52.48 PM.png

# A predator-prey model with predators using hawk and dove tactics

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The authors aims to study the effects of individual predator behavior on the dynamics of the predator-prey system. They refer to the two behavioral tactics used by predators as classical hawk and dove tactics. Authors assume two different time scales, fast and slow. Fast time scale corresponds to the disputes and fights between the predators. Slow time scale corresponds to the growth of the prey population, the mortality of the predator and the predator-prey populations. Let  $n(t)$  be the size of the prey population and  $p(t)$  be the size of the predator population.

The total density of predators is given by the following equation, with  $ph(t)$  representing the hawk predator density and  $pd(t)$  representing the dove predator density

Figure 2: /Users/Visheshsaharan/Desktop/Screen Shot 2019-03-14 at 10.42.43 PM.png



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