

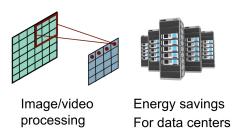
### NAP: Noise-Based Sensitivity Analysis for Programs

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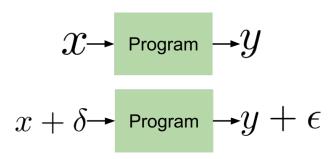
### Approximate computing

- Trade off between speed and accuracy
- Broadly applicable
- NAP gives sensitivity analyses for approximate computing



## Navigating the space of approximations

Sensitivity analysis of numerical programs





# Region-based Sensitivity

- If  $\delta, \gamma \sim \mathcal{N}(0, \vec{\sigma}^2)$  then termed noisy programs
- Approximate program from noisy programs

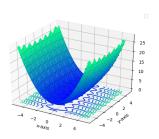
$$x + \delta \longrightarrow \Pr{\text{Program}} \longrightarrow y + \epsilon$$

$$x' \longrightarrow \Pr{\text{program}'} \longrightarrow y'$$



## Region-based sensitivities

- Variances of Gaussian distributions
- Compared with ADAPT and Hessian sensitivity [1,3]
- Derivatives may be too local!



The plot of 
$$z = x^2 + \frac{1}{10}y^2 + \sin(5y)$$



# Adding noise

Quadratic equation

$$f(x) = x^2 + 2x + 1.$$

Indexing operators gives

$$f(x, \{\times_0, +_1, \times_2, +_3\}) = x \times_0 x +_1 2 \times_2 x +_3 1.$$

Adding in noise parameters

$$g(x; \vec{\epsilon}) = [(x + \epsilon_x)(x + \epsilon_x) + \epsilon_0] + \epsilon_1 + [2(x + \epsilon_x) + \epsilon_2] + \epsilon_3 + 1.$$

where

$$\epsilon_i \sim \mathcal{N}(0, \sigma_i^2)$$



# Optimization problem

$$\max_{\vec{\sigma}} \left( \underbrace{\sum_{i} \log(\sigma_{i})}_{\text{noise envelope}} - \lambda \underbrace{\mathbb{E}}_{\substack{\mathbf{x} \sim \mathcal{D}, \vec{\epsilon} \sim \mathcal{N}(\vec{0}, \vec{\sigma}^{2})}} \mathcal{L}(\mathbf{x}, \vec{\epsilon}) \right)$$

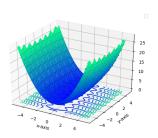
where  $x \sim \mathcal{D}$  and the domain-specific loss is

$$\mathcal{L}(x,\vec{\epsilon}) = \left(g(x;\vec{0}) - g(x;\vec{\epsilon})\right)^2$$



### Region-based sensitivities

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# Breaking from tradition

#### Expected **better than** maximum error:

- Improved common case
- Less sensitive to extremes
- Specialize to a data distribution

#### Expected worse than maximum error:

- Not for mission-critical
- More difficult to reason about

$$\max_{\vec{\sigma}} \left( \underbrace{\sum_{i} \log(\sigma_{i})}_{\text{noise envelope}} - \lambda \underbrace{\mathbb{E}}_{\substack{\mathbf{x} \sim \mathcal{D}, \vec{\epsilon} \sim \mathcal{N}(\vec{\mathbf{0}}, \vec{\sigma}^{2})}} \mathcal{L}(\mathbf{x}, \vec{\epsilon}) \right)$$



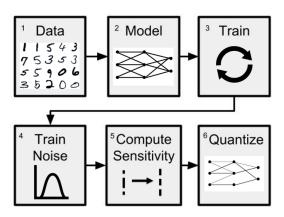
## Comparison with FPTuner/FPTaylor

Generated mixed-precision approximate version of numerical programs from FPBench benchmarks.

Benchmarks	FPTuner	RMSE	Mean Bits
verlhulst	3.79e-16	3.72e-16	50
sineOrder3	1.17e-15	7.90e-16	50
predPrey	1.99e-16	1.73e-16	50
sine	8.73e-16	8.34e-17	51
doppler1	1.82e-13	7.75e-14	51
doppler2	3.20e-13	1.07e-13	51
doppler3	1.02e-13	5.10e-14	51
rigidbody1	3.86e-13	1.37e-13	51
sqroot	7.45e-16	4.00e-16	50
rigidbody2	5.23e-11	6.08e-12	51
turbine2	4.13e-14	2.35e-14	50
carbon gas	1.51e-08	3.01e-09	49
turbine1	3.16e-14	1.13e-14	51
turbine3	1.73e-14	1.40e-14	50
jet	2.68e-11	1.07e-11	50



### **Neural Network Quantization**



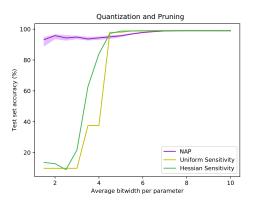
## FPTuner's scalibility

$$\begin{bmatrix}
A_{x} & A_{y} & A_{z} \\
B_{y} \\
B_{z}
\end{bmatrix} = A_{x}B_{x} + A_{y}B_{y} + A_{z}B_{z}$$

$$50 \times 50$$
(A)
(B)

FPTuner timed-out after 15 hours in both programs

### Space-accuracy tradeoff



$$f(\sigma) = \lfloor c - \log(\sigma) \rfloor$$
 for a constant  $c$ 



### Conclusions

- Broadly applicable sensitivity analysis
- Provides expected error over a data distribution
- Scales well to large computations
- Future work to incorporate generalization bounds.



#### **Bibliography**

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(3)

