## From Scenarios To Optimally Allocated Timed Automata

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### Table of contents

- 1. Introduction
- 2. Background
- 3. Synthesis Of Timed Automata From Scenarios
- 4. Optimal Clock Allocation of Timed Automata
- 5. Case Studies
- 6. Conclusion

## **Objectives Of The Research**

Our main focus of the research is,

- 1. To synthesize a timed automaton from a set of scenarios.
- 2. To optimally allocate clocks in the constructed timed automaton.

- Model-based design is a very effective method for designing real-time systems.
- Building formal models for systems is challenging because of the lack of good formal requirements specifications.
- In many real-time systems where safety is critical.
- Modeling a system formally can help us to understand the desired and undesired behaviours of the system.

- To construct a formal model, the following questions are to be answered first:
  - 1. How the requirements should be expressed formally, and
  - 2. How the formal model of a real-time system can be constructed from requirements.

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  - 1. How the requirements should be expressed formally, and
  - 2. How the formal model of a real-time system can be constructed from requirements.
- The formal model that we build is timed automata [1].

- We use scenarios to build a formal model. A scenario is a partial description of the behaviour of a system.
- We introduce Timed Event Sequences (TES) to formally represent the scenarios formaly.
- We use mode graphs to specify the legal events that can in the system.

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- We use mode graphs to specify the legal events that can in the system.

We synthesize a *minimal*, *acyclic* and *deterministic* timed automaton using TES and mode graph.

Our timed automaton belongs to a class of timed automata that satisfies the following properties:

- A clock t<sub>j</sub> can be reset only on the transitions emanating from a state labelled j and,
- A clock in a clock constraint on a transition r from a state q can
  only refer to a clock that has been reset on a transition leaving a
  state that dominates q. We call this dominance assumption.

- Given a timed automaton  $\mathcal{A}$ , the problem of deciding whether there exists another timed automaton  $\mathcal{B}$  that accepts the same language as that of  $\mathcal{A}$  but with fewer number of clocks is undecidable.
- Moreover, the number of clocks in a given timed automaton has a direct impact on verification of the system.

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Given a timed automaton that belongs to our class, we use *liveness* analysis of clocks to optimally allocate clocks.

## Background

### Real-time systems

- A real-time system takes input from its surrounding environment and produces results within a stipulated amount of time.
- In the real world, the behaviour of almost every system changes according to time.
- We can model such real time systems with the help of timed automata.

## **Modeling Time**

There are three approaches for modeling time [1].

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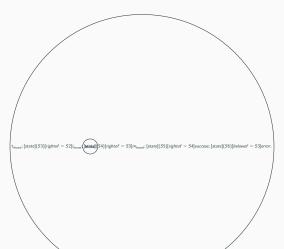
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- <u>Dense time model</u>: In this model, the domain of time is considered
  as a dense set and the time of occurrences of events as real
  numbers, which increase monotonically without any limit. Difficulty
  in transforming dense time traces into formal languages.

### Finite State Automata

A finite state automaton (FSA) or a finite state machine (FSM) is an abstract machine which has a finite number of states. On an input, the machine changes from one state to another state: this is called a transition.



### **Timed Automata**

- A timed automaton [1] is a finite state automaton extended with a finite set of real-valued clocks.
- Upon an input, the selection of next state is based not only on the input symbol but also on the time of the current symbol with respect to the formerly read symbols.

**Example:** Consider a simple timed automaton in Figure 2. This automaton accepts an input sequence 'a' followed by 'b' such that, there is 2 units of time difference between any two consecutive a's and b's.

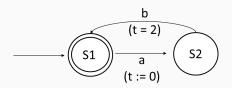


Figure 2: Simple Timed Automaton

# Synthesis Of Timed Automata From Scenarios

### **Synthesis Of Timed Automata From Scenarios**

- Constructing a time annotated graph from scenarios, and
- Constructing a timed automaton from time annotated graph.

- 1. Determining the required number of clocks,
- 2. Adding clock resets,
- 3. Replacing the time annotations with the clock constraints

content...

```
minitial: card-not-inserted
                                                     minitial: card-not-inserted
(insert-card, {})
( enter-pin, \{W - t_0 > 5, W - t_0 < 60\})
(incorrect-pin, {})
                                                     (insert-card, {})
( re-enter-pin, \{W - t_0 \ge 5, W - t_0 \le 60\})
                                                     ( enter-pin, \{W - t_0 \ge 5, W - t_0 \le 60\})
(correct-pin, {})
                                                     ( correct-pin, {})
( request-data-from-bank, {})
                                                     ( request-data-from-bank, {})
(display-menu, \{W - t_4 < 5\})
                                                     (display-menu, \{W - t_4 < 5\})
mfinal: menu-displayed
                                                     mfinal: menu-displayed
             TFS of Scenario 1
                                                                 TES of Scenario 2
```

Figure 3: Timed Event Sequences of the ATM

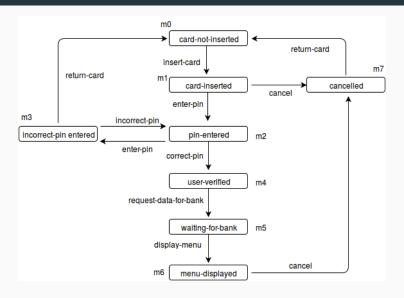


Figure 4: Mode Graph for ATM



Figure 5: Time annotated graph synthesized from two TES in Figure ??

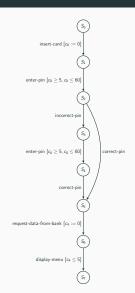


Figure 6: Timed automaton constructed from time annotated graph

**Optimal Clock Allocation of** 

**Timed Automata** 

## **Optimal Clock Allocation of Timed Automata**

- Liveness analysis
- Clock allocation

## Liveness Range Analysis

- clock\_ref: clock\_ref(r) is the set of clocks which are referred to in the clock constraints on r.
- born: born(r) identifies a clock that is reset on r whose value can be used on some transition reachable from r.
- active: active(r) identifies clocks that are "alive" on r (i.e., their values may be subsequently used). Notice that  $born(r) \subseteq active(r)$ .
- **needed**: Maps transition r to  $active(r) \cup clock\_ref(r)$ .

## **Liveness Range Analysis Example**

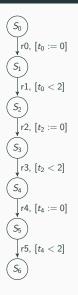


Table 1: born and active values

Transition	Born	Active
$r_0$	{0}	{0}
$r_1$	$\phi$	$\phi$
$r_2$	{2}	{2}
$r_3$	$\phi$	$\phi$
$r_4$	<b>{4</b> }	<b>{4</b> }
$r_5$	$\phi$	$\phi$

**Figure 7:** A simple timed automaton

## ModeGraph

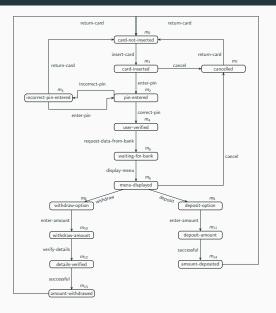


Figure 8: Mode graph of the ATM

## Case Studies

## **Automated Teller Machine (ATM)**

Explain original scenario

## **Automated Teller Machine (ATM)**

```
minitial: card-not-inserted
                                                     minitial: card-not-inserted
(insert-card, {})
( enter-pin, \{W - t_0 > 5, W - t_0 < 60\})
(incorrect-pin, {})
                                                     (insert-card, {})
( re-enter-pin, \{W - t_0 \ge 5, W - t_0 \le 60\})
                                                     ( enter-pin, \{W - t_0 \ge 5, W - t_0 \le 60\})
(correct-pin, {})
                                                     (correct-pin, {})
( request-data-from-bank, {})
                                                     ( request-data-from-bank, {})
(display-menu, \{W - t_4 < 5\})
                                                     (display-menu, \{W - t_4 < 5\})
mfinal: menu-displayed
                                                     mfinal: menu-displayed
             TFS of Scenario 1
                                                                 TES of Scenario 2
```

Figure 9: Timed Event Sequences of the ATM

## **Automated Teller Machine (ATM)**

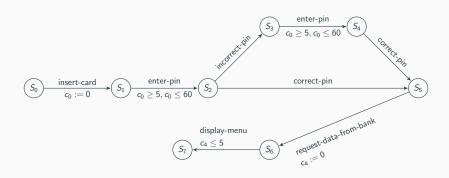


Figure 10: Timed automaton synthesized from Scenario 1 and Scenario 2

# **Automated Teller Machine (ATM)**

Explain extended scenario

# Automated Teller Machine (ATM)

```
minitial: menu-displayed
( withdraw, {})
( enter-amount, \{W - t_6 \le 20\})
(verify-details, {})
( successful, \{W - t_{10} < 10\})
( return-card, {})
m<sup>final</sup>: card-not-inserted
        TES of Scenario 4
```

**Figure 11:** Timed Event Sequences of the ATM with withdraw and deposit option

# **Automated Teller Machine (ATM)**

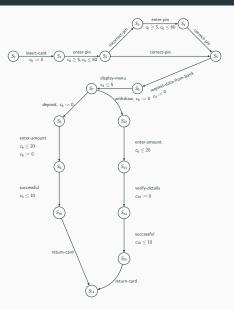


Figure 12: The synthesized timed automaton of the ATM

# **Light Control System**

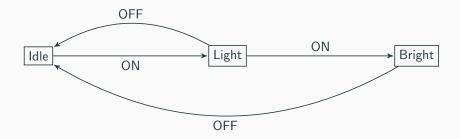


Figure 13: Mode graph of the Light Control System

#### **Light Control System**

```
m^{initial}: Idle \ (ON, \{\}) \ (OFF, \{w-t0 > 3\}) \ (ON, \{\}) \ (ON, \{w-t0 <= 3\}) \ (OFF, \{\}) \ m^{final}: Idle \ Scenario 1
```

```
m^{initial}: Bright (OFF, \{\}) (ON, \{\}) (ON, \{w - t0 <= 3\}) (OFF, \{\}) m^{final}: Idle
```

Figure 14: Timed Event Sequences of the Light Control System

### **Light Control System**

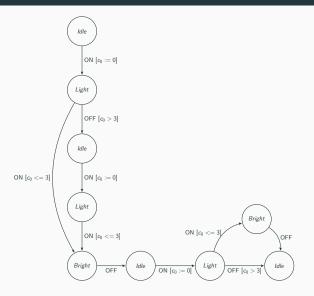


Figure 15: Timed automaton of the Light Control System

#### **Traffic Light**

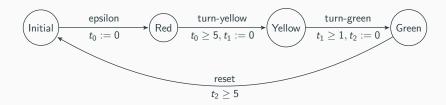


Figure 16: Timed automaton of the Traffic Light

#### **Traffic Light**

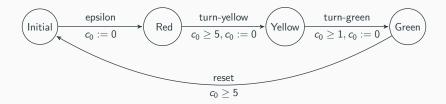


Figure 17: The optimally allocated timed automaton of the Traffic Light

### CSMA/CD Protocol

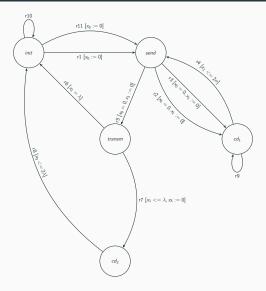
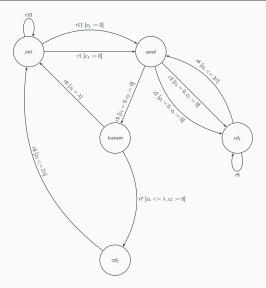


Figure 18: The timed automaton for the sender in CSMA/CD protocol

#### **CSMA/CD Protocol**



**Figure 19:** The optimally allocated timed automaton for the sender in CSMA/CD protocol

# Conclusion

### Conclusion

conclude here [2] [3]

THANK PROFESSORS??? Neda and Committee mem??



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